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PNEUMONIA DETECTION

A Report for the Evaluation 3 of Project 2

Submitted by

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ABSTRACT

The risk of pneumonia is immense for many, especially in developing nations where billions face energy poverty and rely on polluting forms of energy. The WHO estimates that over 4 million premature deaths occur annually from household air pollution-related diseases including pneumonia. Over 150 million people get infected with pneumonia on an annual basis especially children under 5 years old. In such regions, the problem can be further aggravated due to the dearth of medical resources and personnel. For example, in Africa's 57 nations, a gap of 2.3 million doctors and nurses exists. For these populations, accurate and fast diagnosis means everything. It can guarantee timely access to treatment and save much needed time and money for those already experiencing poverty.

This model could help mitigate the reliability and interpretability challenges often faced when dealing with medical imagery.

INTRODUCTION

In recent years, a tremendous amount of enthusiasm for deep learning, a subfield of Machine Learning, where the algorithms are inspired by the working of human brain, has emerged among students, researchers and technologist from every different strata like medical science. All deep learning models use some form of Convolutional Neural Network [9] as their base algorithm. A Convolutional Neural Network(CNN) takes in data, train themselves to recognize the patterns in data and predict the output for a new set of similar data. CNN models exhibit a complex set of interconnections between inputs and outputs in order to preform a variety of tasks such as image recognition, natural language processing, music generation, even medical diagnosis and procedures. Pneumonia is a severe acute respiratory disease which is caused when the air sacks(alveoli) in lungs are infected by some bacteria, virus or fungi to which the patient's body has weak resistance. As a result the alveoli in lungs gets filled with pus and are unable to provide oxygen to the patient's blood. Although it can be treated by medical care and vaccinations , still it's one of the major causes of death worldwide. Figure 1 shows a radio-graph of a healthy pair of lungs.



Figure1: Healthy Lungs

Now in an x-ray image the area of inflammation in lungs caused by pneumonia infection generally shows more translucency than the rest of the area as shown in **Figure 2.**

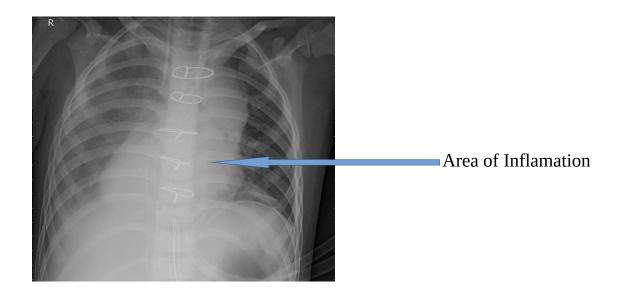


Figure2 Pneumonia Infected lungs.

Still for most radiologists determining whether a patient is suffering from pneumonia infection by analyzing an x-ray image alone can be very difficult given that an x-ray can often be effected by noise generated by radiation scattering, source leakage, sensor errors, electronic devices and implantation. Therefore, building a deep learning model by training a convolutional neural network with thousands of x-ray images to determine whether a patient has pneumonia with high accuracy while taking all the noise generated into the account can be an effective solution to this problem.

Popular Diagnosis Techniques of Pneumonia

Physical exam

Physical examination may sometimes reveal low blood pressure, high heart rate, or low oxygen saturation. The respiratory rate may be faster than normal, and this may occur a day or two before other signs. Examination of the chest may be normal, but it may show decreased chest expansion on the affected side. Harsh breath sounds from the larger airways that are transmitted through the inflamed lung are termed bronchial breathing and are heard on auscultation with a stethoscope. Crackles (rales) may be heard over the affected area during inspiration. Percussion may be dulled over the affected lung, and increased, rather than decreased, vocal resonance distinguishes pneumonia from a pleural effusion.

Imaging

A chest radiograph is frequently used in diagnosis. In people with mild disease, imaging is needed only in those with potential complications, those not having improved with treatment, or those in which the cause is uncertain. If a person is sufficiently sick to require hospitalization, a chest radiograph is recommended. Findings do not always match the severity of disease and do not reliably separate between bacterial infection and viral infection. X-ray presentations of pneumonia may be classified as lobar pneumonia, bronchopneumonia, lobular pneumonia, and interstitial pneumonia. Bacterial, community-acquired pneumonia classically show lung consolidation of one lung segmental lobe, which is known as lobar pneumonia. However, findings may vary, and other patterns are common in other types of pneumonia. Aspiration pneumonia may present with bilateral opacities primarily in the bases of the lungs and on the right side. Radiographs of viral pneumonia may appear normal, appear hyper- inflated, have bilateral patchy areas, or present similar to bacterial pneumonia with lobar consolidation. Radiologic findings may not be present in the early stages of the disease, especially in the presence of dehydration, or may be difficult to be interpreted in the obese or those with a history of lung disease. Complications such as pleural effusion may also be found on chest radiographs. Laterolateral chest radiograph can increase the diagnostic accuracy of lung consolidation and pleural effusion. A CT scan can give additional information in indeterminate cases. CT scan can also provide more details in those with an unclear chest radiograph (for example occult pneumonia in chronic obstructive pulmonary disease) and is able to exclude pulmonary embolism and fungal pneumonia and detecting lung abscess in those who are not responding to treatments. However, CT scan is more expensive, has a higher dose of radiation, and cannot be done at bedside.

Lung ultrasound may also be useful in helping to make the diagnosis. Ultrasound is radiation free and can be done at bedside. However, ultrasound requires specific skills to operate the machine and interpret the findings. It may be more accurate than chest X-ray.

PURPOSE OF THIS PROJECT

The purpose of this project is to study and construct a convolutional neural network model from scratch to extract features from a given chest X-ray image and classify it to determine if a person is infected with pneumonia. This model could help mitigate the reliability and interpretability challenges often faced when dealing with medical imagery.

MOTIVATION AND SCOPE

In recent times, CNN-motivated deep learning algorithms have become the standard choice for medical image classifications although the state-of-the-art CNN-based classification techniques pose similar fixated network architectures of the trial-anderror system which have been their designing principle. The proposed work will help doctors better predict pneumonia in minimal time with high efficiency. The aggregation of this will contribute to the health care system for better patient satisfaction and care. This work is in its early stages and can be improved by adding more images to the dataset, incorporating better architectures, training the model based on more transformations and orientations.

PROPOSED MODEL

Pneumonia in India accounts for 20 percent of the death worldwide caused by pneumonia. This project focuses to develop and train a deep learning neural network in order to determine if a person is infected with pneumonia with maximum accuracy.

The aim is to allocated more than 3000 images to the training set and about 2000 to the validation set to improve validation accuracy. The primary task of this model is to detect pneumonic infection and classify the input X-ray image by analysing it, as given below:



NORMAL

This normal chest X-ray depicts clear lungs without any areas of abnormal opacification in the image.

PNEUMONIA



This chest X-ray depicts Bacterial pneumonia with partial translucency/opacification

EXISTING MODEL

The main aim of our model is to predict the class of an input image with highest accuracy possible. In order to achieve that objective we need to build a custom CNN (Convolutional Neural Network). Our model's convolutional neural network mainly consists four components:

1. Convolutional Layer(Cov2D)

This layer performs a blend of linear and non-linear operations essential to perform feature extraction. Our model consists of 5 convolutionally interconnected layers which uses two dimensional kernel of size 3*3 and 'Relu' activation function . The first cov2d layer is the input layer which provides input data to the system to be processed further by the consecutive layers of neurons. The input shape of our training data is 150 pixels in height , 150 pixels in width and color gamut value as 1 for gray scale (for RGB color gamut the value is 3), represented as 'input_shape = (150,150,1) '.

2. Max-Pooling Layer

A pooling layer provides a typical downsampling operation which reduces the in-plane dimensionality of the feature maps in order to introduce a translation invariance to small shifts and distortions, and decrease the number of subsequent learnable parameters. It is of note that there is no learnable parameter in any of the pooling layers, whereas filter size, stride, and padding are hyperparameters in pooling operations, similar to convolution operations.

This layer typically reduces the dimensionality of the features and decreases the number of trainable parameters[10] to avoid over-fitting. Our model consists of 5 max-pooling layers, each of filter size 2*2.

3. Dense Layer

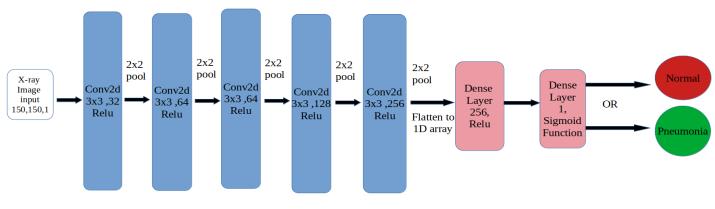
The feature maps[10] are converted into a 1D array after being extracted from the last convolutional or pooling layer, this process is also called flattening. After the flattening process the output are connected to a fully connected layer called the dense layer which also uses 'Relu' as activation function.

4. Output Layer

This layer is the last dense layer of our model .It gives only one output at a time and uses 'sigmoid function' as activation function which gives a probability score from 0 to 1 to the output of the previous layer . The output with the highest probability score is produced by the output layer.

Layer(type)	Output Shape	Param #
Conv2D	(None,150,150,32)	320
MaxPooling2D	(None,75,75,32)	0
Conv2D	(None,75,75,64)	18496
MaxPooling2D	(None,38,38,64)	0
Conv2D	(None,38,38,64)	36928
MaxPooling2D	(None,19,19,64)	0
Conv2D	(None,19,19,128)	73856
MaxPooling2D	(None,10,10,128)	0
Conv2D	(None,10,10,256)	295168
MaxPooling2D	(None,5,5,256)	0
Flatten	(None,6400)	0
Dense	(None,128)	819328
Dropout	(None,128)	0
Dense	(None,1)	129

Neural Network's Configuration

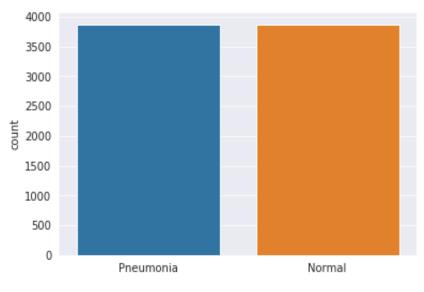


CNN Architecture of our model

METHODOLOGY ADOPTED

1. Dataset Distribution

The original dataset consists of two main folders (i.e., training and validation folders) and two subfolders containing pneumonia (P) and normal (N) chest X-ray images, respectively. A total of 7,750 X-ray images of anterior-posterior chests were carefully chosen from retrospective paediatric patients between 1 and 5 years old. The entire chest X-ray imaging was conducted as part of patients' routine medical care. To balance the proportion of data assigned to the training and validation set, the original data category is modified. It has been rearranged into training and validation set only. A total of 7,750 images are allocated to the training set and 468 images were assigned to the validation set to improve validation accuracy.



Balanced Dataset

Both 'Normal' and 'Pneumonia' class consist of 3875 images as training and 234 images as testing data.

2. Data Preprocessing and Augmentation

1.) **Rescale** - The rescale operation represents image reduction or magnification during the augmentation process.

2.) **Rotation Range -** The rotation range denotes the range in which the images were randomly rotated during training. For example: 40 degrees.

3.) **Width Shift** - Width shift is the horizontal translation of the image.

4.) **Height Shift -** Height shift is the vertical translation of the image.

5.) **Zoom Range** - Zoom range is the difference in magnification from one end of the zoom range to the other.

6.) **Horizontal Flip** - Flipping the image along vertical axis.

7.) **Vertical Flip** – Flipping the image along horizontal axis.

Method	Settings
Rotation range	30 degrees
Zoom range	0.2px
Width shift range	0.1px
Height shift range	0.1px
Horizontal flip	False
Vertical flip	False

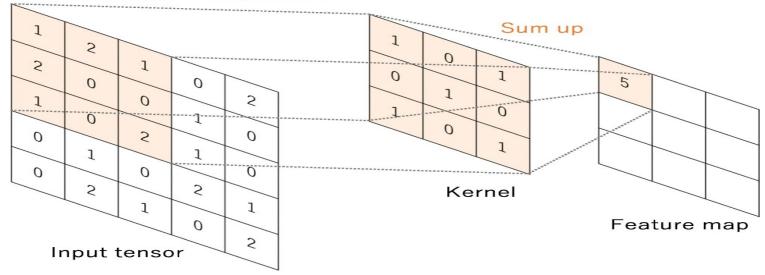
Augmentation Parameters

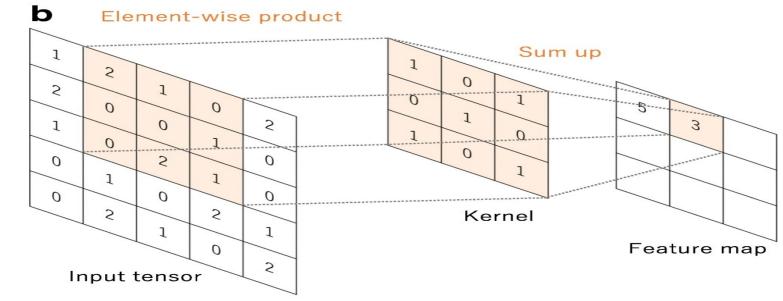
3. Feature Extraction:

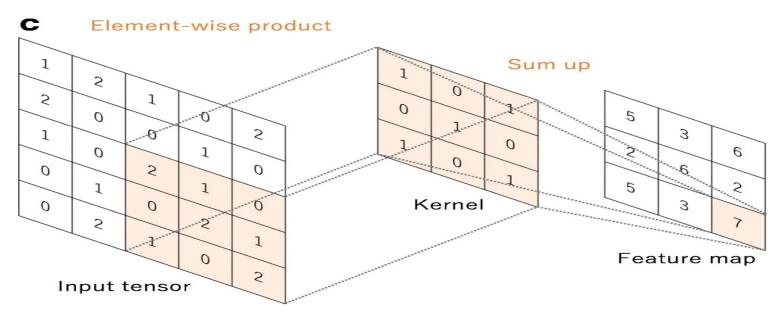
Feature extraction is a process of dimensionality reduction by which an initial set of raw data is reduced to more manageable groups for processing. A characteristic of these large data sets is a large number of variables that require a lot of computing resources to process. The process of feature extraction is useful when you need to reduce the number of resources needed for processing without losing important or relevant information. Feature extraction can also reduce the amount of redundant data for a given analysis. Also, the reduction of the data and the machine's efforts in building variable combinations (features) facilitate the speed of learning and generalization steps in the machine learning process.

Convolution is a specialized type of linear operation used for feature extraction, where a small array of numbers, called a kernel, is applied across the input, which is an array of numbers, called a tensor. An element-wise product between each element of the kernel and the input tensor is calculated at each location of the tensor and summed to obtain the output value in the corresponding position of the output tensor, called a feature map (Fig. <u>3</u>a–c). This procedure is repeated applying multiple kernels to form an arbitrary number of feature maps, which represent different characteristics of the input tensors; different kernels can, thus, be considered as different feature extractors (Fig. <u>3</u>d). Two key hyperparameters that define the convolution operation are size and number of kernels. The former is typically 3×3 , but sometimes 5×5 or 7×7 . The latter is arbitrary, and determines the depth of output feature maps.

Element-wise product



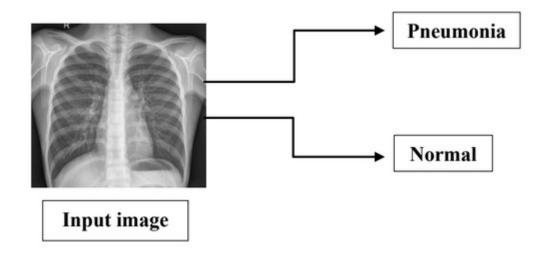




The convolution operation described above does not allow the center of each kernel to overlap the outermost element of the input tensor, and reduces the height and width of the output feature map compared to the input tensor. Padding, typically zero padding, is a technique to address this issue, where rows and columns of zeros are added on each side of the input tensor, so as to fit the center of a kernel on the outermost element and keep the same in-plane dimension through the convolution operation. Modern CNN architectures usually employ zero padding to retain in-plane dimensions in order to apply more layers. Without zero padding, each successive feature map would get smaller after the convolution operation.

4. Classification

Classification is a process of categorizing a given set of data into classes, it can be performed on both structured or unstructured data. The process starts with predicting the class of given data points. The classes are often referred to as target, label or categories.



RESULTS

To measure and validate the performance of the model, we evaluated it's effectiveness on various parameters given as:

1) Precision: Precision is the percentage of positive identifications and total identifications.

 $Precision = \frac{True \ Positive}{True \ Positive + False \ Positive}$

2) Recall: Recall is the percentage of relevant identifications predicted by the algorithm.

Recall= <u>True Positive</u> <u>True Positive</u> + False Negative

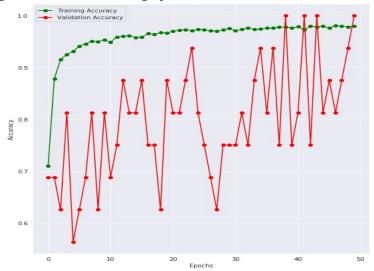
3) F1-score: F1-score represents the harmonic mean of precision and recall.

 $F1score = \frac{2*Precision*Recall}{Precision+Recall}$

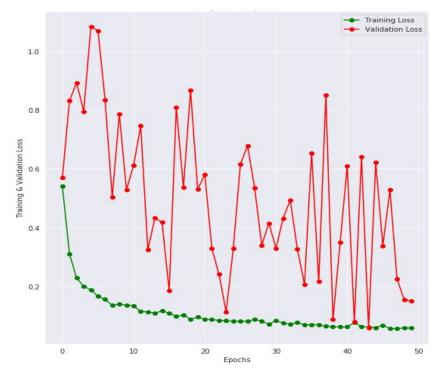
The evaluated scores based parameters mentioned above are give in table below:

Class	Precision	Recall	F1-score
Pneumonia(Class 0)	0.94	0.94	0.94
Normal(Class 1)	0.90	0.89	0.90

The model has been trained till 50 epochs, the training and validation accuracy on every epoch can be seen in graph1 and training and validation loss on graph 2.



Graph1: Training and validation accuracy on each epoch.



Graph2:Training and validation loss on every epoch.

In graph1, we can observe that the average validation accuracy increases with every epoch. In graph 2, we can observe that the average validation loss decreases with every epoch. Minor fluctuations in validation accuracy and loss does not effect the overall performance of the model.

LIMITATIONS

1. Processing and building the model requires fast and efficient processors which is time and cost consuming.

2. 100% accuracy is not achievable.

3. The challenges of large variation in sensing modality which is complicated by human anatomy are faced in medical image analysis.

4. Parameters affecting medical images fluctuate from organ to organ.

5. Medical Images are affected by noise due to sensors, device implantation, electronics leading to inefficiency while detection.

6. The model doesn't take other diagnosis parameters like Blood tests, Pulse Oximetry, Sputum tests into account.

PRACTICAL IMPLEMENTATION

May 7, 2020

```
[2]: import numpy as np
     import pandas as pd
     import os
     import matplotlib.pyplot as plt
     import seaborn as sns
     from tensorflow.keras.models import Sequential
     from tensorflow.keras.layers import Dense, Conv2D , MaxPool2D , Flatten ,
     →Dropout
     from tensorflow.keras.preprocessing.image import ImageDataGenerator
     from sklearn.model_selection import train_test_split
     from sklearn.metrics import classification_report,confusion_matrix
     from tensorflow.keras.callbacks import ReduceLROnPlateau
     from tensorflow.keras.utils import to_categorical
     import cv2
     import os
[3]: data dir='./data/'
     labels = ['PNEUMONIA', 'NORMAL']
     img_size = 150
     def get_training_data(data_dir):
         data = []
         for label in labels:
             path = os.path.join(data_dir, label)
             class_num = labels.index(label)
             for img in os.listdir(path):
                 try:
                     img_arr = cv2.imread(os.path.join(path, img), cv2.
      \rightarrow IMREAD_GRAYSCALE)
                     resized_arr = cv2.resize(img_arr, (img_size, img_size)) #__
      →Reshaping images to preferred size
                     data.append([resized_arr, class_num])
                 except Exception as e:
```

```
print(e)
return np.array(data)
```

```
[4]: train = get_training_data('./data/train')
    test = get_training_data('./data/test')
    val = get_training_data('./data/val')
```

```
OpenCV(3.4.2) /tmp/build/80754af9/opencv-
suite_1535558553474/work/modules/imgproc/src/resize.cpp:4044: error:
(-215:Assertion failed) !ssize.empty() in function 'resize'
```

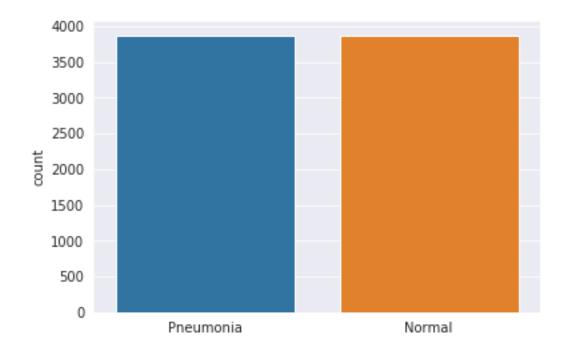
```
OpenCV(3.4.2) /tmp/build/80754af9/opencv-
suite_1535558553474/work/modules/imgproc/src/resize.cpp:4044: error:
(-215:Assertion failed) !ssize.empty() in function 'resize'
```

```
OpenCV(3.4.2) /tmp/build/80754af9/opencv-
suite_1535558553474/work/modules/imgproc/src/resize.cpp:4044: error:
(-215:Assertion failed) !ssize.empty() in function 'resize'
```

```
OpenCV(3.4.2) /tmp/build/80754af9/opencv-
suite_1535558553474/work/modules/imgproc/src/resize.cpp:4044: error:
(-215:Assertion failed) !ssize.empty() in function 'resize'
```

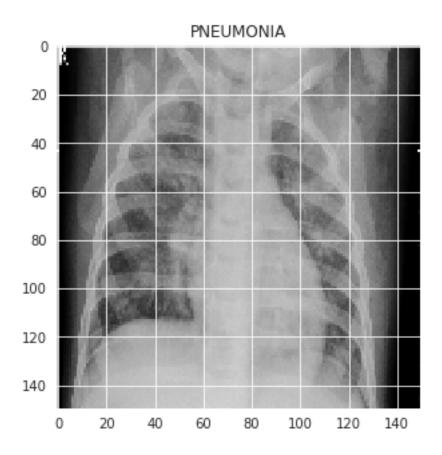
```
[5]: 1 = []
for i in train:
    if(i[1] == 0):
        l.append("Pneumonia")
    else:
        l.append("Normal")
    sns.set_style('darkgrid')
    sns.countplot(1)
```

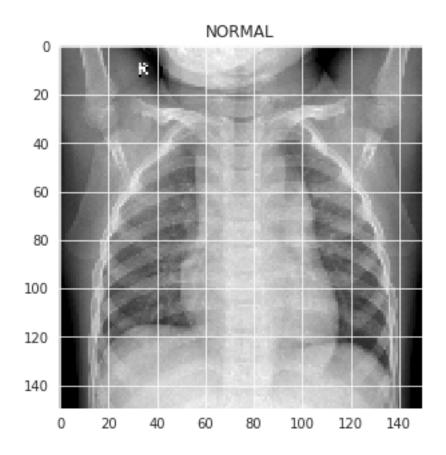
[5]: <matplotlib.axes._subplots.AxesSubplot at 0x7f87787b2290>



```
[6]: plt.figure(figsize = (5,5))
plt.imshow(train[0][0], cmap='gray')
plt.title(labels[train[0][1]])
plt.figure(figsize = (5,5))
plt.imshow(train[-1][0], cmap='gray')
plt.title(labels[train[-1][1]])
```

[6]: Text(0.5, 1.0, 'NORMAL')





```
[7]: x_train = []
y_train = []
x_val = []
y_val = []
x_test = []
y_test = []
for feature, label in train:
x_train.append(feature)
y_train.append(label)
for feature, label in test:
x_test.append(feature)
y_test.append(label)
for feature, label in val:
x_val.append(label)
```

```
[8]: # Normalize the data
x_train = np.array(x_train) / 255
x_val = np.array(x_val) / 255
x_test = np.array(x_test) / 255
x_train.shape
[8]: (7750, 150, 150)
[9]: x_train = x_train.reshape(-1, img_size, img_size, 1)
y_train = np.array(y_train)
x_val = x_val.reshape(-1, img_size, img_size, 1)
y_val = np.array(y_val)
x_test = x_test.reshape(-1, img_size, img_size, 1)
y_test = np.array(y_test)
[13]: datagen = ImageDataGenerator(
    featurewise_center=False, # set input mean to 0 over the dataset
    samplewise_center=False, # set each sample mean to 0
```

```
featurewise_std_normalization=False, # divide inputs by std of the_

→ dataset

samplewise_std_normalization=False, # divide each input by its std

zca_whitening=False, # apply ZCA whitening

rotation_range = 30, # randomly rotate images in the range (degrees, 0,

→ to 180)

zoom_range = 0.2, # Randomly zoom image

width_shift_range=0.1, # randomly shift images horizontally (fraction,

→ of total width)

height_shift_range=0.1, # randomly shift images vertically (fraction,

→ of total height)

horizontal_flip = False, # randomly flip images

vertical_flip=False) # randomly flip images
```

datagen.fit(x_train)

```
model.add(Conv2D(64 , (3,3) , strides = 1 , padding = 'same' , activation = \Box

'relu'))

model.add(MaxPool2D((2,2) , strides = 2 , padding = 'same'))
model.add(Conv2D(128 , (3,3) , strides = 1 , padding = 'same' , activation = \Box

→'relu'))
model.add(MaxPool2D((2,2) , strides = 2 , padding = 'same'))
model.add(Conv2D(256 , (3,3) , strides = 1 , padding = 'same' , activation =__

→'relu'))
model.add(MaxPool2D((2,2) , strides = 2 , padding = 'same'))
model.add(Flatten())
model.add(Dense(units = 128 , activation = 'relu'))
model.add(Dropout(0.2))
model.add(Dense(units = 1 , activation = 'sigmoid'))
model.compile(optimizer = 'adam' , loss = 'binary_crossentropy' , metrics =__
\rightarrow ['accuracy'])
model.summary()
```

```
Model: "sequential_2"
```

Layer (type)	Output Shape	Param #
conv2d_10 (Conv2D)	(None, 150, 150, 32)	320
<pre>max_pooling2d_10 (MaxPooling</pre>	(None, 75, 75, 32)	0
conv2d_11 (Conv2D)	(None, 75, 75, 64)	18496
<pre>max_pooling2d_11 (MaxPooling</pre>	(None, 38, 38, 64)	0
conv2d_12 (Conv2D)	(None, 38, 38, 64)	36928
<pre>max_pooling2d_12 (MaxPooling</pre>	(None, 19, 19, 64)	0
conv2d_13 (Conv2D)	(None, 19, 19, 128)	73856
<pre>max_pooling2d_13 (MaxPooling</pre>	(None, 10, 10, 128)	0
conv2d_14 (Conv2D)	(None, 10, 10, 256)	295168
<pre>max_pooling2d_14 (MaxPooling</pre>	(None, 5, 5, 256)	0
flatten_2 (Flatten)	(None, 6400)	0

dense_4 (Dense) (None, 128) 819328 ----dropout_2 (Dropout) (None, 128) 0 _____ dense_5 (Dense) (None, 1) 129 _____ Total params: 1,244,225 Trainable params: 1,244,225 Non-trainable params: 0 _____ [23]: history = model.fit(datagen.flow(x_train,y_train, batch_size = 64) ,epochs = 50 →, validation_data = datagen.flow(x_val, y_val)) WARNING:tensorflow:sample_weight modes were coerced from to ['...'] WARNING:tensorflow:sample_weight modes were coerced from to ['...'] Train for 122 steps, validate for 1 steps Epoch 1/50 accuracy: 0.7097 - val_loss: 0.5690 - val_accuracy: 0.6875 Epoch 2/50 accuracy: 0.8779 - val_loss: 0.8320 - val_accuracy: 0.6875 Epoch 3/50 accuracy: 0.9150 - val_loss: 0.8922 - val_accuracy: 0.6250 Epoch 4/50 accuracy: 0.9250 - val_loss: 0.7951 - val_accuracy: 0.8125 Epoch 5/50 accuracy: 0.9308 - val_loss: 1.0835 - val_accuracy: 0.5625 Epoch 6/50 accuracy: 0.9410 - val_loss: 1.0698 - val_accuracy: 0.6250 Epoch 7/50 122/122 [======] - 13s 106ms/step - loss: 0.1546 accuracy: 0.9454 - val_loss: 0.8340 - val_accuracy: 0.6875 Epoch 8/50 accuracy: 0.9506 - val_loss: 0.5024 - val_accuracy: 0.8125

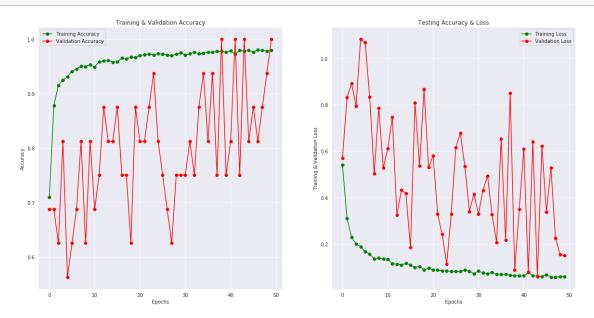
Epoch 9/50 accuracy: 0.9498 - val_loss: 0.7865 - val_accuracy: 0.6250 Epoch 10/50 accuracy: 0.9526 - val_loss: 0.5283 - val_accuracy: 0.8125 Epoch 11/50 accuracy: 0.9489 - val_loss: 0.6110 - val_accuracy: 0.6875 Epoch 12/50 accuracy: 0.9586 - val_loss: 0.7464 - val_accuracy: 0.7500 Epoch 13/50 accuracy: 0.9599 - val_loss: 0.3248 - val_accuracy: 0.8750 Epoch 14/50 122/122 [======] - 13s 106ms/step - loss: 0.1088 accuracy: 0.9609 - val_loss: 0.4320 - val_accuracy: 0.8125 Epoch 15/50 accuracy: 0.9578 - val_loss: 0.4174 - val_accuracy: 0.8125 Epoch 16/50 accuracy: 0.9585 - val_loss: 0.1841 - val_accuracy: 0.8750 Epoch 17/50 122/122 [==========] - 13s 106ms/step - loss: 0.0973 accuracy: 0.9653 - val_loss: 0.8082 - val_accuracy: 0.7500 Epoch 18/50 122/122 [===============] - 13s 106ms/step - loss: 0.1018 accuracy: 0.9632 - val_loss: 0.5360 - val_accuracy: 0.7500 Epoch 19/50 accuracy: 0.9671 - val_loss: 0.8666 - val_accuracy: 0.6250 Epoch 20/50 accuracy: 0.9663 - val_loss: 0.5295 - val_accuracy: 0.8750 Epoch 21/50 122/122 [======] - 13s 106ms/step - loss: 0.0866 accuracy: 0.9698 - val_loss: 0.5800 - val_accuracy: 0.8125 Epoch 22/50 accuracy: 0.9712 - val_loss: 0.3279 - val_accuracy: 0.8125 Epoch 23/50 122/122 [===============] - 13s 106ms/step - loss: 0.0840 accuracy: 0.9726 - val_loss: 0.2403 - val_accuracy: 0.8750 Epoch 24/50 accuracy: 0.9708 - val_loss: 0.1125 - val_accuracy: 0.9375

Epoch 25/50 accuracy: 0.9732 - val_loss: 0.3287 - val_accuracy: 0.8125 Epoch 26/50 accuracy: 0.9724 - val_loss: 0.6152 - val_accuracy: 0.7500 Epoch 27/50 122/122 [=================================] - 13s 105ms/step - loss: 0.0809 accuracy: 0.9706 - val_loss: 0.6779 - val_accuracy: 0.6875 Epoch 28/50 accuracy: 0.9698 - val_loss: 0.5346 - val_accuracy: 0.6250 Epoch 29/50 122/122 [===============] - 13s 106ms/step - loss: 0.0813 accuracy: 0.9723 - val_loss: 0.3399 - val_accuracy: 0.7500 Epoch 30/50 122/122 [======] - 13s 106ms/step - loss: 0.0709 accuracy: 0.9754 - val_loss: 0.4146 - val_accuracy: 0.7500 Epoch 31/50 accuracy: 0.9706 - val_loss: 0.3292 - val_accuracy: 0.7500 Epoch 32/50 accuracy: 0.9730 - val_loss: 0.4310 - val_accuracy: 0.8125 Epoch 33/50 122/122 [==========] - 13s 107ms/step - loss: 0.0709 accuracy: 0.9760 - val_loss: 0.4935 - val_accuracy: 0.7500 Epoch 34/50 122/122 [===============] - 13s 108ms/step - loss: 0.0758 accuracy: 0.9732 - val_loss: 0.3261 - val_accuracy: 0.8750 Epoch 35/50 accuracy: 0.9741 - val_loss: 0.2066 - val_accuracy: 0.9375 Epoch 36/50 accuracy: 0.9756 - val_loss: 0.6529 - val_accuracy: 0.8125 Epoch 37/50 122/122 [======] - 13s 105ms/step - loss: 0.0680 accuracy: 0.9760 - val_loss: 0.2156 - val_accuracy: 0.9375 Epoch 38/50 accuracy: 0.9777 - val_loss: 0.8503 - val_accuracy: 0.7500 Epoch 39/50 122/122 [===============] - 13s 107ms/step - loss: 0.0618 accuracy: 0.9778 - val_loss: 0.0871 - val_accuracy: 1.0000 Epoch 40/50 accuracy: 0.9757 - val_loss: 0.3484 - val_accuracy: 0.7500

Epoch 41/50 accuracy: 0.9785 - val_loss: 0.6102 - val_accuracy: 0.8125 Epoch 42/50 accuracy: 0.9725 - val_loss: 0.0790 - val_accuracy: 1.0000 Epoch 43/50 accuracy: 0.9794 - val_loss: 0.6408 - val_accuracy: 0.7500 Epoch 44/50 accuracy: 0.9777 - val_loss: 0.0591 - val_accuracy: 1.0000 Epoch 45/50 122/122 [===========] - 13s 107ms/step - loss: 0.0588 accuracy: 0.9792 - val_loss: 0.6212 - val_accuracy: 0.8125 Epoch 46/50 122/122 [======] - 13s 107ms/step - loss: 0.0668 accuracy: 0.9761 - val_loss: 0.3373 - val_accuracy: 0.8750 Epoch 47/50 accuracy: 0.9803 - val_loss: 0.5278 - val_accuracy: 0.8125 Epoch 48/50 accuracy: 0.9794 - val_loss: 0.2250 - val_accuracy: 0.8750 Epoch 49/50 122/122 [======] - 13s 106ms/step - loss: 0.0583 accuracy: 0.9779 - val_loss: 0.1534 - val_accuracy: 0.9375 Epoch 50/50 122/122 [===============] - 13s 106ms/step - loss: 0.0573 accuracy: 0.9795 - val_loss: 0.1490 - val_accuracy: 1.0000 [24]: print("Loss of the model is - ", model.evaluate(x_test,y_test)[0]*100, "%") print("Accuracy of the model is - ", model.evaluate(x_test,y_test)[1]*100 ,__ → "%"
) 624/624 [================] - 1s 840us/sample - loss: 0.3202 accuracy: 0.9215 Loss of the model is - 32.02381273492789 % 624/624 [=============] - 0s 655us/sample - loss: 0.3202 accuracy: 0.9215 Accuracy of the model is - 92.14743375778198 % [39]: epochs = [i for i in range(50)] fig , ax = plt.subplots(1,2)

train_acc = history.history['accuracy']
train_loss = history.history['loss']
val_acc = history.history['val_accuracy']

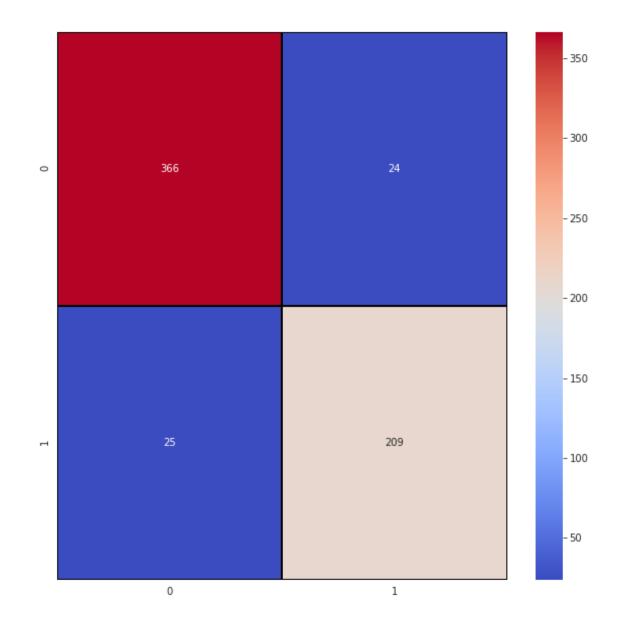
```
val_loss = history.history['val_loss']
fig.set_size_inches(20,10)
ax[0].plot(epochs , train_acc , 'go-' , label = 'Training Accuracy')
ax[0].plot(epochs , val_acc , 'ro-' , label = 'Validation Accuracy')
ax[0].set_title('Training & Validation Accuracy')
ax[0].legend()
ax[0].set_xlabel("Epochs")
ax[0].set_ylabel("Accuracy")
ax[1].plot(epochs , train_loss , 'g-o' , label = 'Training Loss')
ax[1].plot(epochs , val_loss , 'r-o' , label = 'Validation Loss')
ax[1].set_title('Testing Accuracy & Loss')
ax[1].set_xlabel("Epochs")
ax[1].set_xlabel("Epochs")
ax[1].set_ylabel("Training & Validation Loss")
plt.show()
```

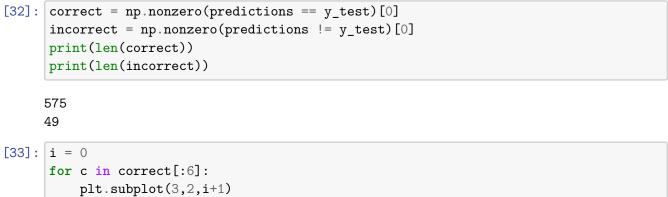


- [27]: predictions = model.predict_classes(x_test)
 predictions = predictions.reshape(1,-1)[0]
 predictions[:15]

precision recall f1-score support

Pneumonia (Class O)	0.94	0.94	0.94	390	
Normal (Class 1)	0.90	0.89	0.90	234	
accuracy			0.92	624	
macro avg	0 92	0 92			
weighted avg					
werghted avg	0.92	0.92	0.92	024	
[29]: cm = confusion_matrix	(y_test,pre	dictions)			
cm					
[29]: array([[366, 24],					
[25, 209]])					
[30]: cm = pd.DataFrame(cm	, index = ['0','1'] ,	columns =	['0','1'])	
[31]: plt.figure(figsize =					
<pre>sns.heatmap(cm,cmap=</pre>	"coolwarm",	linecolor	= 'black'	, linewidth =	1 , annot =
→True, fmt='')					
	3				
[31]: <matplotlib.axessub< td=""><td>piots.AxesS</td><td>ubplot at</td><td>0x718680092</td><td>2650></td><td></td></matplotlib.axessub<>	piots.AxesS	ubplot at	0x718680092	2650>	





```
plt.xticks([])
```

```
plt.yticks([])
plt.imshow(x_test[c].reshape(150,150), cmap="gray", interpolation='none')
plt.title("Predicted Class {},Actual Class {}".format(predictions[c],__

→y_test[c]))
plt.tight_layout()
i += 1
```

Predicted Class 0, Actual Class 0 Predicted Class 0, Actual Class 0





Predicted Class 0, Actual Class 0 Predicted Class 0, Actual Class 0





Predicted Class 0, Actual Class 0 Predicted Class 0, Actual Class 0





```
[34]: i = 0
for c in incorrect[:6]:
    plt.subplot(3,2,i+1)
    plt.xticks([])
    plt.yticks([])
    plt.imshow(x_test[c].reshape(150,150), cmap="gray", interpolation='none')
    plt.title("Predicted Class {},Actual Class {}".format(predictions[c],⊔
    ·y_test[c]))
    plt.tight_layout()
    i += 1
```

Predicted Class 1, Actual Class 0 Predicted Class 1, Actual Class 0



Predicted Class 1, Actual Class 0 Predicted Class 1, Actual Class 0





Predicted Class 1, Actual Class 0 Predicted Class 1, Actual Class 0





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