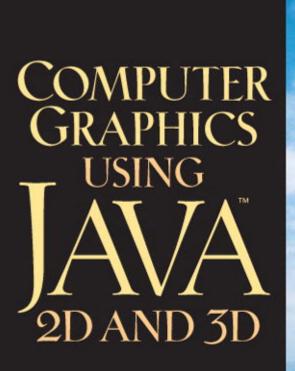
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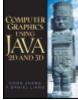


# HONG ZHANG Y. DANIEL LIANG



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Computer Graphics Using Java<sup>™</sup> 2D and 3D by Hong Zhang, Y. Daniel Liang - Armstrong Atlantic State University Publisher: Prentice Hall Pub Date: December 06, 2006 Print ISBN-10: 0-13-035118-0 Print ISBN-13: 978-0-13-035118-0 eText ISBN-10: 0-13-232920-4 eText ISBN-13: 978-0-13-232920-0 Pages: 632

#### Overview

This Java based graphics text introduces advanced graphic features to a student audience mostly trained in the Java language. Its accessible approach and in-depth coverage features the high-level Java 2D and Java 3D APIs–offering an elegant and easy-to-understand presentation of 2D and 3D graphics without compromising the fundamentals of the subject.

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#### Dedication

To My Parents, Xuemei Sun and Zhongyi Zhang

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### Preface

On March 3, 2001, the first Oscar of the new millennium was awarded to three computer scientists, Rob Cook, Loren Carpenter, and Ed Catmull, "for their significant advancements to the field of motion picture rendering as exemplified in Pixar's 'RenderMan.'" This incredible event symbolizes the emergence of computer graphics and its applications, once an esoteric research subject, as an essential part of the digital community. The rapid development of computer hardware, graphical applications, and network technologies has made computer graphics indispensable in mainstream computing.

Modeling and rendering virtual graphics objects with digital computers are the main objectives of computer graphics. The topics involved in this process span a wide range of disciplines from mathematics and computer science to psychology and arts. From the big model of the universe to the small details of rasterizing a graphical primitive, sophisticated and ingenious methods, algorithms, and paradigms have been developed to address the problems of modeling and rendering in computer graphics. A thorough treatment of this subject, therefore, would require a broad and deep coverage of many related areas. A traditional computer graphics course, due to its complexity and mathematical sophistication, is usually beyond the scope of a standard undergraduate computer science curriculum.

However, we believe that the new technological developments and the availability of well-designed and easy-touse graphics programming packages have made an elementary graphics course feasible. This development is analogous to the evolution of programming languages. Programming used to be a very tedious task when only low-level languages such as machine instructions were available. The development of high-level languages freed programmers from the low-level technical details. Programs at the more abstract levels are much more manageable and logical. The performance loss due to the abstraction has become negligible with the improvement of hardware and compiler technologies. Most programmers today may never need to program in machine or assembly languages. Computer graphics programming is going through a similar process. Highlevel, portable systems are rapidly replacing the tedious low-level approaches in many aspects of computer graphics. The rapid development of hardware technologies is also erasing the performance gap.

The primary focus of this book is the fundamental concepts of computer graphics and applications of Java 2D and Java 3D to graphics programming. Rather than studying the technical details of low-level implementations, we will emphasize the techniques of developing practical applications using existing graphics packages. This approach enables us to provide an introductory computer graphics text that is accessible to undergraduate computer science and engineering students and most computer professionals.

Java 2D and Java 3D are the ideal graphics packages for such a purpose. They are high-level comprehensive graphics packages that offer a much-needed layer of abstraction. They are also platform independent and provide state-of-the-art graphics programming capabilities.

Java 2D and Java 3D are parts of the Java platform. Java is a relatively new programming language, yet it has quickly gained popularity because of its unique characteristics and features, such as platform independence, simplicity, and object-oriented programming support. Java 2D and Java 3D provide powerful, natural, and object-oriented interfaces for graphics modeling and rendering.

This book is intended for students and computer professionals who want to learn basic computer graphics concepts and techniques and to get started in programming with Java 2D and Java 3D. However, it is not just another tutorial on Java 2D or Java 3D. Its purpose is to introduce the fundamentals of computer graphics to the readers, and the powerful Java packages serve as useful and convenient tools to achieve the goal.

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The prerequisite of this book is a basic knowledge of programming with Java, including GUI programming (AWT and Swing). Appendix B, "GUI Programming with AWT and Swing," illustrates the differences in programming with AWT and Swing components. Basic mathematical courses in geometry and linear algebra will be helpful but are not required. Appendix A, "Mathematical Background for Computer Graphics," provides a brief review of some relevant mathematical concepts.

### Companion Website

The companion website at www.cs.armstrong.edu/liang/graphics contains the following resources:

- Answers to review questions
- Solutions to even-numbered programming exercises
- Source code for the examples in the book
- Resource links
- Errata

### Instructor Resource Website

The Instructor Resource website accessible from www.prenhall.com/liang or www.cs.armstrong.edu/liang/graphics contains the following resources:

- Microsoft PowerPoint slides with interactive buttons to view full-color, syntax-highlighted source code and to run programs without leaving the slides.
- Sample exams.
- Solutions to all the exercises. Students will have access to the solutions of even-numbered exercises in the book's companion website.

Some readers have requested the materials from the Instructor Resource Website. Please understand that these are for instructors only. Such requests will not be answered.

### Acknowledgments

UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO The computer science department at Armstrong Atlantic State University is a great place to work. We thank Ray Greenlaw and our colleagues at Armstrong Atlantic State University for their support of this book.

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### Chapter 1. Overview of Computer Graphics

(This item omitted from WebBook edition)

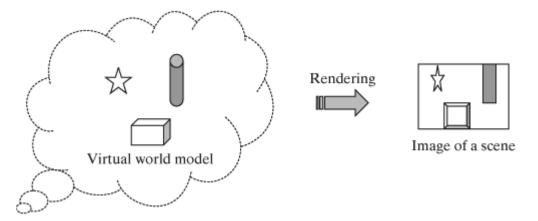
Objectives
• To understand the basic objectives and scope of computer graphics.
To identify computer graphics applications.
<ul> <li>To understand the basic structures of 2D and 3D graphics systems.</li> </ul>
<ul> <li>To understand evolution of graphics programming environments.</li> </ul>
To identify common graphics APIs.
<ul> <li>To understand the roles of Java language and the Java 2D and Java 3D packages.</li> </ul>
<ul> <li>To identify fields related to computer graphics.</li> </ul>

### 1.1. Introduction

Computer graphics studies the theory and techniques of modeling, processing, and rendering of graphical objects in computers. The basic objective of computer graphics is to build a virtual world of graphics objects and to render a scene of the virtual model from a specific view onto a graphic device, as shown in Figure 1.1.

[Page 2]

Figure 1.1. Main tasks of computer graphics: modeling a virtual world and rendering a scene.



A graphics system typically consists of two major components: a modeler and a renderer. The *modeler* is responsible for the construction of the virtual world models and the *renderer* performs the rendering of a scene. A "retained-mode" system maintains a persistent model of graphics objects and the modeler's function is explicit. An "immediate-mode" system renders the objects immediately and the model is more transient. This view of the modeling–rendering paradigm is convenient for studying graphics systems, even if the separation may not be clear in some systems.

Typically the graphics objects to be modeled are in either a 2D or a 3D space. This common space to host all the graphics objects is often called the *world space*. A rendered scene of the world space, the main output of a graphics system, is typically in a 2D form. Consequently the techniques involved in 2D and 3D graphics are considerably different. Because 3D graphics problems are significantly more complex, 2D and 3D graphics are often treated as separate topics.

The graphics objects to be modeled in a world space are usually geometric entities such as lines and surfaces, but they also include other special objects such as lights, texts and images. The graphics objects may possess many characteristics and properties such as color, transparency and texture.

Various mathematical representations are used to model geometric objects. Straight-line segments and simple polygon meshes provide simple and compact representations. Only the vertices of the structures need to be stored and they are easy to implement. More sophisticated representations include spline curves and surfaces. They are versatile and require only the storage of relatively few control points.

Geometric transformations are applied to the objects to achieve the proper placement of the objects in the virtual space. Transformations of this type are called *object transformations*. Transformations are also used for the viewing; these are known as *viewing transformations*. A useful family of the geometric transforms is the *affine transforms*, which include the most common types such as translations, rotations, scalings and reflections. A more general set of transforms, the *projective transformations*, are useful for 3D viewing.

A *view* is used to see the model in the virtual world from a specific perspective. A *2D viewing* process is relatively simple. The viewing transformation is usually indistinguishable from the object transformation. Rendering features such as composition rules and clipping paths may be applied. A *3D view* is much more complicated. Like eyes or cameras, 3D viewing involves a projection process that maps 3D objects to a 2D plane. Many parameters such as the projection, view position, orientation, and field of view could affect the 3D rendering.

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In order to achieve a realistic rendering of the virtual world, numerous rendering issues need to be addressed. Relative locations of the objects need to be correctly reflected in the rendered images. For example, an object may be hidden behind another object, and the hidden portion should not be shown in the image. Light sources of various characteristics should be considered. The properties of the materials of the objects will affect the appearance. Many of the methods for solving the problems have significant computational demands.

The capabilities and characteristics of *hardware devices* have great impact on graphics systems. The most common output devices for displaying the results of the graphics rendering are video monitors and printers. Other output devices include plotters and holographic projectors. For input devices, mice, joysticks and tablets with pens are widely available. There are also more sophisticated input devices and sensors such as six-degree-of-freedom trackers.

*Animation* is also an important part of computer graphics. Instead of still images, animation produces dynamic graphics contents and rendering. In applications such as movie-scene rendering and gaming, animation plays a crucial role. Another dynamic aspect of computer graphics is *interaction*. In response to user inputs, the graphics model may change accordingly. The fundamental principle of GUI (graphical user interface) is based on the user interactions with graphics systems. Another example of extensive application of interaction is video games.

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Computer graphics has a wide range of applications. The popularity of GUI environments has made graphics an

integral part of ordinary user programs. CAD (computer-aided design) and other engineering applications depend heavily on graphics systems. Data visualization and other scientific applications also make extensive use of graphics. With the rapid development of new computer-based instrumentation such CT (computer tomography), PET (positron emission tomography), and MRI (magnetic resonance imaging), medical systems have increasingly employed computer graphics technologies. Computer graphics is also a crucial ingredient in video games and other entertainment applications.

Traditionally computer graphics has to deal with implementation details, using the low-level algorithms to convert primitives such as lines to pixels, to determine the surfaces hidden from the view, to calculate the color values of points on a surface, and so on. These algorithms and methods have made the subject technically difficult and complex. In this book we shall rely on the Java 2D and Java 3D packages to avoid dealing with most of the low-level details directly. This will enable us to focus on the big picture of modeling and rendering problems in graphics, rather than the tedious implementation details.

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### 1.2. Evolution of Computer Graphics Programming

Graphics programming has appeared in almost every level of computer architecture. Generally it is moving from low-level, platform-dependent methods toward abstract, high-level, and portable environments.

Figure 1.2 gives examples of graphics programming environments at various levels of computer architecture. The subsections that follow discuss the characteristics of graphics programming at the different levels.

#### Figure 1.2. Graphics programming at different levels.

Platform independent (Java 2D and Java 3D)

Graphics standard (GKS, PHIGS, OpenGL)

OS (WIN32, X, Mac OS)

Hardware (direct register/video buffer programming)

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#### 1.2.1. Hardware Level

Computer graphics programs depend on output devices with graphical capabilities. The most common display devices for computer graphics are CRT (cathode ray tube) monitors and LCD (liquid crystal display) panels. These are 2D raster devices that provide a display surface consisting of a rectangular array of discrete dots. A display device of this kind is usually driven by a dedicated graphics board with its own processor and memory.

Lower-level graphics applications often program the graphics hardware directly. In the popular environment of personal computers running MS-DOS, for example, most graphics applications directly access the display memory. Even though BIOS and DOS provide certain primitive support for graphics functions, they are considered too slow for graphics-intensive programs. Such programs are typically written in assembly language and manipulate the hardware registers and video buffers in a highly machine-dependent way.

### Listing UNREAGES THE REPORT WERSIONS OF IC HIMICT OF BOTTO ON WERTER PRO

Macro Assembler and can be executed on any IBM PC compatible machine with a VGA graphics card. It draws a circle by directly writing to the memory locations of the video buffer. An ideal circle centered at the origin has the equation:

#### $x^2 + y^2 = R^2$

A computer monitor only displays discrete pixels. Therefore a set of pixels approximating the curve must be computed. Only one-eighth of the circle needs to be calculated; other portions can be obtained through symmetry. As illustrated in Figure 1.3, the algorithm generates a series of pixels close to the curve. Consider the top right arc of the circle. Starting from the top pixel (x = 0, y = R), the algorithm attempts to obtain the next pixel to the right of the current one. There are only two possible directions of movement: "east" or "southeast." Between the two pixels, the one closer to the curve is selected. The two cases can be decided by testing the midpoint (x + 1, y - 0.5). If the midpoint is inside the circle, the "east" pixel should be chosen; if it is outside, the "southeast" pixel is the closer one. The equation of the circle is used to perform the test. By using certain difference variables, the actual operations of the test can be further simplified to only integer additions.

Listing 1.1. Circle.asm

(This item is displayed on pages 4 - 7 in the print version)

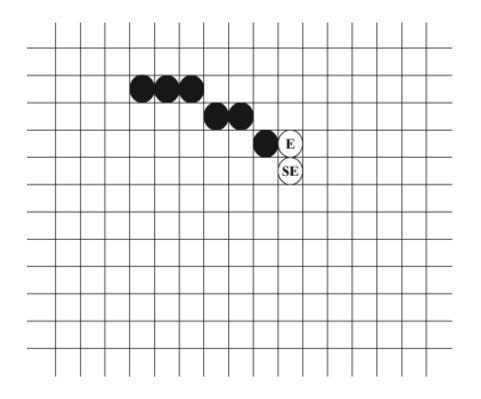


```
4
 5 .data
 6 saveMode BYTE ? ; saved video mode
 7 xc WORD ? ; center x
8 yc WORD ?
                 ; center y
9 x SWORD ?
                 ; x coordinate
10 y SWORD ?
                 ; y coordinate
11 dE SWORD ?
                 ; east delta
12 dse sword ?
                 ; southeast delta
13 w WORD 320
                 ; screen width
14
15 .code
16 main PROC
17 mov ax,@data
18 mov ds,ax
19
20 ;Set Video Mode 320X200
21 mov ah, OFh ; get current video mode
22 int 10h
23 mov saveMode,al
                       ; save mode
24
[Page 5] 25 mov ah,0
                       ; set new video mode
26 mov al,13h ; mode 13h
27 int 10h
28
29 push 0A000h ; video segment address
30 pop es
                 ; ES = A000h (video segment)
31
32 ;Set Background
33 mov dx, 3c8h ; video palette port (3C8h)
34 mov al,0
                 ; set palette index
35 out dx,al
36
37 ;Set screen background color to dark blue
38 mov dx, 3c9h ; port address 3C9h
                 ; red
39 mov al,0
40 out dx,al
41 mov al,0
                 ; green
42 out dx,al
43 mov al,32
              ; blue (32/63)
44 out dx,al
45
46 ; Draw Circle
47 ; Change color at index 1 to yellow (63,63,0)
48
   mov dx,3c8h ; video palette port (3C8h)
   mov al,1
49
                 ; set palette index 1
50
   out dx,al
51
                ; port address 3C9h
52 mov dx,3c9h
53 mov al,63
                ; red
   out dx,al
54
55
   mov al,63
                 ; green
   out dx,al
56
57
    mov al.0
                 ; blue
58
    out dx,al
59
60
   mov xc,160
                 ; center of screen
61
    mov yc,100
62
```

63 ; Calculate coordinates 64 mov x, 0 65 mov y, 50 ; radius 50 mov bx, -49 ; 1-radius 66 mov dE, 3 67 mov dSE, -95 68 69 70 DRAW: 71 call Draw\_Pixels ; Draw 8 pixels 72 73 cmp bx, 0 ; decide E or SE 74 jns MVSE 75 76 add bx, dE ; move east 77 add dE, 2 78 add dSE, 2 79 inc x 80 jmp NXT 81 MVSE: 82 add bx, dSE ; move southeast 83 add dE, 2 84 add dSE, 4 85 inc x [Page 6] 86 dec y 87 NXT: 88 ; continue if x < y mov cx, x 89 cmp cx, y 90 jb DRAW 91 92 ; Restore Video Mode 93 mov ah,10h ; wait for keystroke 94 int 16h 95 mov ah,0 ; reset video mode 96 mov al, saveMode ; to saved mode 97 int 10h 98 UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO 99 100 101 102 ; Draw 8 pixels symmetrical about the center 103 Draw\_Pixels PROC 104 ; Calculate the video buffer offset of the pixel. 105 mov ax, yc 106 add ax, y 107 mul w 108 add ax, xc 109 add ax, x 110 mov di, ax 111 mov BYTE PTR es:[di],1; store color index 112 ; Horizontal symmetrical pixel 113 sub di, x sub di, x 114 115 mov BYTE PTR es:[di],1; store color index 116 ; Vertical symmetrical pixel mov ax, yc 117 sub ax, y 118 119 UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO 120 121 add ax, x

```
122 mov di, ax
123 mov BYTE PTR es:[di],1; store color index
124 ; Horizontal pixel
125 sub di, x
126 sub di, x
127 mov BYTE PTR es:[di],1; store color index
128 ; Switch x, y to get other 4 pixels
129 mov ax, yc
130 add ax, x
131 mul w
132 add ax, xc
133 add ax, y
134 mov di, ax
135 mov BYTE PTR es:[di],1; store color index
136 sub di, y
137 sub di, y
138 mov BYTE PTR es:[di],1; store color index
139 mov ax, yc
140 sub ax, x
141 mul w
142 add ax, xc
143 add ax, y
144 mov di, ax
145 mov BYTE PTR es:[di],1; store color index
[Page 7]146 sub di, y
147 sub di, y
148 mov BYTE PTR es:[di],1; store color index
149
150 ret
151 Draw_Pixels ENDP
152
153 END main
```

Figure 1.3. Determination of the pixels on a circle. From the current pixel, the next pixel will be either to the "east" or to the "southeast."



The program first saves the current video mode and switches to mode 13h by using the BIOS interrupt 10h (line 27). The video mode 13h is an easy-to-use graphics mode with 320 by 200 pixels and 256 colors. Each pixel color is represented by a byte value in the video buffer starting from the segment address A000h. Each byte value is a color index to represent a color given in a color table. Because the aspect ratio of this mode does not match that of a standard monitor, the display may appear to be stretched vertically and the circle may actually appear as an ellipse.

The background color of the screen is set to a dark blue by writing to the register at port address 3c9h (lines 3844). The Reference is the register of the screen is set to a dark blue by writing to the register at port address 3c9h (lines 3844). The Reference is the register of the screen is set to a dark blue by writing to the register at port address 3c9h (lines 3844). The Reference is set to a dark blue by writing to the register at port address 3c9h (lines 3844). The Reference is set to a dark blue by writing to the register at port address 3c9h (lines 3844). The Reference is set to a dark blue by writing to the register at port address 3c9h (lines 3844). The Reference is set to a dark blue by writing to the register at port address 3c9h (lines 3844). The Reference is set to a dark blue by writing to the register at port address 3c9h (lines 3844). The Reference is set to a dark blue by writing to the register at port address 3c9h (lines 3844). The Reference is set to a dark blue by writing to the register at port address 3c9h (lines 3844). The Reference is set to a dark blue by writing to the register at port address 3c9h (lines 3644). The Reference is set to a dark blue by writing to the register at port address 3c9h (lines 3644). The Reference is set to a dark blue by writing to the register at port address 3c9h (lines 3644). The Reference is set to a dark blue by writing to the register at port address 3c9h (lines 3644). The Reference is set to a dark blue by writing to the register at port address 3c9h (lines 3644). The Reference is set to a dark blue by writing to the register at port address 3c9h (lines 3644). The Reference is set to a dark blue by writing to the register at port address 3c9h (lines 3644). The Reference is set to a dark blue by writing to a dark blue by

The circle is centered at the middle of the screen and has a radius 50. The variables (xc, yc) define the center. A loop starting at the label DRAW (line 70) is set to calculate and draw the pixels approximating the circle. The variables (x, y) represent current pixel coordinates. The variables dE and dSE represent differences used for deciding the next move. The loop calls the procedure Draw\_Pixels to draw the current pixel and seven other pixels in the symmetrical positions. It decides the movement for the next pixel and updates the variables. The loop terminates when the calculation of one-eighth of the circle is completed.

The Draw\_Pixels procedure (line 103) draws eight pixels corresponding to the current calculation. It writes a color index to the memory locations corresponding to the pixels. A calculation of the proper offset in the video buffer is necessary because the memory addresses of the pixels are organized linearly:

 $Offset = 320^* x + y$ 

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The video buffer starts from the segment address A000h, which is placed in the register ES. To draw a pixel, the pixel offset is calculated and placed in DI. The color index (the yellow color index 1 in this case) is directly written to the memory address.

UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO After the circle is drawn, the program waits for a keystroke from the user, using an interrupt 16h. Upon receiving the keystroke, it will then restore the video mode and terminate.

#### 1.2.2. Operating-System Level Support

The low-level graphics infrastructures provide basic facilities for programming the displays. However, directly programming video buffers and hardware registers is not an effective approach for general graphics applications. As illustrated in the previous section, programming at the hardware level requires intimate knowledge of the devices. It is tedious even for simple tasks. Programs written at this level are not portable, even for different devices in the same platform.

High-level programming interfaces are needed to ease the burden of graphics programming. Because of the inherent complexities in graphics problems, it is certainly desirable to provide a layer of abstraction for application programming. One natural place to add the abstraction is the operating system.

With the development and widespread application of graphical user interface (*GUI*) in modern computer systems, graphics support in operating systems has become common and extensive. Graphics *APIs* (application programming interfaces) provided at the operating-system level offer a uniform interface for graphics programming within the same platform. Typically hardware differences are accommodated by using device-specific software drivers. A software driver implements a standard interface with the operating system for a particular device. Application programs only need to call standard graphics functions provided by the operating system and do not have to deal with hardware specifics.

*WIN32* is the API for 32-bit Windows operating systems such as Windows 9x/ME/NT/2000/XP. The code example in Listing 1.2 shows a WIN32 program that draws a circle (Figure 1.4). This example is a simple Windows program written in the C language. The program creates a standard window and calls WIN32 API directly to draw a circle in the client area of the main program window. The circle is centered in the window and the size is adjusted automatically if the window is resized.

Listing 1.2. WinCircle.c

(This item is displayed on pages 8 - 10 in the print version)

```
1 #include <windows.h>
  2 #include <string.h>
 3
 4 LRESULT CALLBACK
 5 MainWndProc (HWND hwnd, UINT nMsg, WPARAM wParam, LPARAM lParam) {
                 /* Device context used for drawing */
 6 HDC hdc;
                         /* Paint structure used during drawing */
 7
    PAINTSTRUCT ps;
                         /* Client area rectangle */
    RECT rc;
 8
                         /* Center x-coordinate */
    int cx;
 9
                         /* Center y-coordinate */
    int cy;
 10
 11
    int r;
                         /* Radius of circle */
12
13
      /* Message processing.*/
 14
     switch (nMsg) {
15
[Page 9] 16
           case WM_DESTROY:
17
        /* The window is being destroyed, close the application */
 18
        PostQuitMessage (0);
        return 0;
19
20
 21
      case WM_PAINT:
 22
       /* The window needs to be redrawn. */
 23
        hdc = BeginPaint (hwnd, &ps);
 24
        GetClientRect (hwnd, &rc);
 25
        /* Calculate center and radius */
 26
        cx = (rc.left + rc.right)/2;
 27
        cy = (rc.top + rc.bottom)/2;
 28
        if (rc.bottom - rc.top < rc.right - rc.left)</pre>
```

```
r = (rc.bottom - rc.top) / 2 - 20;
29
30
       else
         r = (rc.right - rc.left) / 2 - 20;
31
32
33
       Ellipse(hdc, cx-r, cy-r, cx+r, cy+r);
34
35
       EndPaint (hwnd, &ps);
       return 0;
36
37
38
    }
39
40
      return DefWindowProc (hwnd, nMsg, wParam, lParam);
41 }
42
43 int WINAPI
44 WinMain (HINSTANCE hInst, HINSTANCE hPrev, LPSTR lpCmd, int nShow) {
                                         /* Main window handle */
45
      HWND hwndMain;
                                         /* Win32 message structure */
46
      MSG msg;
                                         /* Window class structure */
47
      WNDCLASSEX wndclass;
48
      char* szMainWndClass = "WinCircle"; /* The window class name */
49
      /* Create a window class */
50
      /* Initialize the entire structure to zero */
51
      memset (&wndclass, 0, sizeof(WNDCLASSEX));
52
53
54
      /* The class Name */
55
      wndclass.lpszClassName = szMainWndClass;
56
57
      /* The size of the structure. */
58
      wndclass.cbSize = sizeof(WNDCLASSEX);
59
60
      /* All windows of this class redraw when resized. */
      wndclass.style = CS_HREDRAW | CS_VREDRAW;
61
62
63
      /* All windows of this class use the MainWndProc window function. */
      wndclass.lpfnWndProc = MainWndProc;
64
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66
67
      wndclass.hInstance = hInst;
68
69
      /* Use standard application icon and arrow cursor */
      wndclass.hlcon = LoadIcon (NULL, IDI_APPLICATION);
70
     wndclass.hlconSm = LoadIcon (NULL, IDI_APPLICATION);
71
72
     wndclass.hCursor = LoadCursor (NULL, IDC_ARROW);
73
           /* Color the background white */
[Page 10] 74
75
      wndclass.hbrBackground = (HBRUSH) GetStockObject (WHITE_BRUSH);
76
77
      /* Register the window class */
78
     RegisterClassEx (&wndclass);
79
80
      /* Create a window using the window class */
      hwndMain = CreateWindow (
81
82
        szMainWndClass,
                                  /* Class name */
83
        "Circle",
                                  /* Caption */
84
        WS_OVERLAPPEDWINDOW,
                                   /* Style */
    UNREGENETERE
                             DVERSION CECHW/TOPPF CONVERTER PRO
85
86
87
        CW_USEDEFAULT,
                                  /* Initial x size (use default) */
```

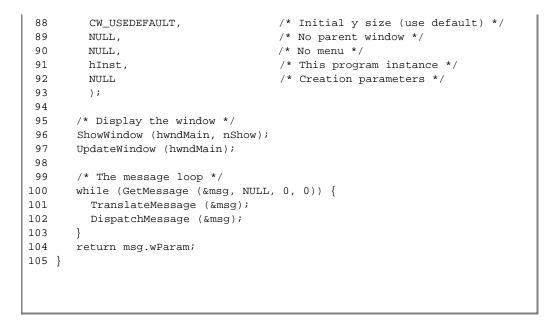
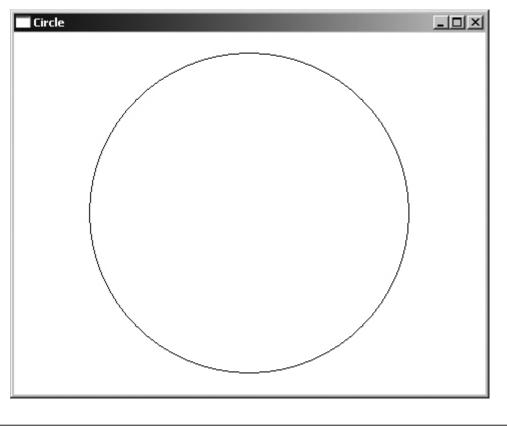


Figure 1.4. A WIN32 program in C displaying a circle.



[Page 11]

This is a typical C program for WIN32 API. The WinMain function (line 44) is the entry point of the program. In

the method a window class named "WinCircle" is created with a set of commonly used options. The window class is then registered with Windows. A window is created based on the registered window class. The window is displayed and updated.

As in most GUI environments, Windows programming follows an event-driven model. Messages are sent to a window and the message handler of the window performs certain actions in response to a message. The loop near the end of WinMain function is a standard message loop which is set up to dispatch the messages received.

The function MainWndProc (line 5) is the window procedure responsible for handling the message events of the window. It is a callback function specified in the definition of the window class. In this example, it handles two types of messages: WM\_DESTROY, which is usually sent when the user tries to close the window, and WM\_PAINT, which is sent when the system attempts to repaint the window. If a WM\_DESTROY message is received, the handler terminates the program by posting a quit message. When a WM\_PAINT message is received, the handler draws a circle in the window. The drawing is done through a device context obtained by a call to the BeginPaint function. The Ellipse function (line 33) draws a circle when the width and the height are the same. The EndPaint function ends the drawing. The center and radius of the circle are calculated based on the size of the window client area, which is obtained by calling the function GetClientRect.

#### 1.2.3. GKS and PHIGS

Graphics programming based on operating-system APIs is a major step forward from hardware-level approaches in terms of device independency and convenience. However, graphics programs that rely on operating-system functions are certainly not portable across platforms. Microsoft Windows and Mac OS, for example, are both operating systems with graphical user interfaces (GUI). However, their APIs are different and incompatible at the level of system calls.

It is easy to see the advantages of a standard interface for graphics programming. A graphics programming standard will provide a layer of abstraction necessary for device and platform independence. In the short history of computer graphics, several graphics standards have risen to the prominence. Graphics Kernel System (*GKS*) is the first international standard for computer graphics. GKS (ISO 7942 1985) is a standard for 2D graphics. It specifies basic graphics functions independent of computer platforms. Several levels are defined to accommodate different capabilities of the hardware systems. A specific implementation of GKS in a programming language will certainly require a syntax definition appropriate for the language. A *language binding* is used to define the specific format of GKS in the programming language. The most common language binding for <u>GKS</u> is <u>FORTRAN</u>. Other language bindings such as <u>Pascal and C are also available</u>.

binding for GKS is FORTRAN. Other language bindings such as Pascal and C are also available. UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO *GKS-3D* (ISO 8805 1988) is an extension of GKS to support 3D graphics. GKS and GKS-3D APIs are designed mainly for drawing individual objects with certain attributes. They are useful for static unstructured graphics primitives, but they do not directly support more complex graphics models.

*PHIGS* (Programmer's Hierarchical Interactive Graphics System, ISO 9592 1991) is a graphics standard similar to GKS. PHIGS and PHIGS+ include the capabilities of GKS, even though they are not strict supersets of GKS. They have additional functionalities for hierarchical organizations of graphics primitives and dynamic editing.

Listing 1.3 demonstrates GKS programming in the FORTRAN binding. The simple FORTRAN program draws a red circle using a GKS polyline primitive (Figure 1.5). The points on the circle are calculated with high-level trigonometric functions provided by FORTRAN.

[Page 12]

 $X = X_0 + 7 \cos \theta$ 

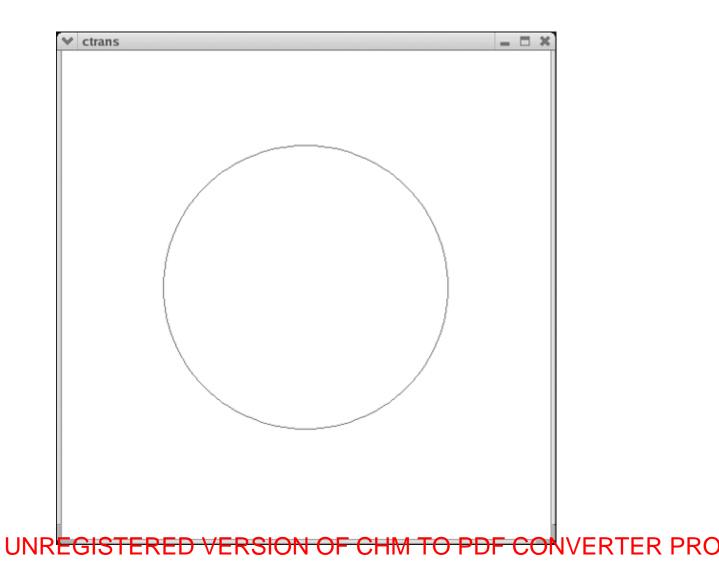
 $y = y_0 + r \sin \theta$ 

Listing 1.3. circle.f UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

```
1
         PROGRAM CIRCLE
 2 C
 3 C Define error file, Fortran unit number, and workstation type,
 4 C and workstation ID.
 5 C
         PARAMETER (IERRF=6, LUNIT=2, IWTYPE=1, IWKID=1)
 6
 7
         PARAMETER (ID=121)
         DIMENSION XP(ID), YP(ID)
8
9 C
10 C Open GKS, open and activate a workstation.
11 C
12
         CALL GOPKS (IERRF, IDUM)
         CALL GOPWK (IWKID,LUNIT,IWTYPE)
13
         CALL GACWK (IWKID)
14
15 C
16 C Define colors.
17 C
18
         CALL GSCR(IWKID,0, 1.0, 1.0, 1.0)
19
         CALL GSCR(IWKID,1, 1.0, 0.0, 0.0)
20 C
21 C Draw a circle.
22 C
23
        X0 = .5
24
        Y0 = .5
25
        R = .3
26
        JL = 120
27
        RADINC = 2.*3.1415926/REAL(JL)
28
        DO 10 J=1,JL+1
29
       X = X0 + R*COS(REAL(J)*RADINC)
30
        Y = Y0 + R*SIN(REAL(J)*RADINC)
31
        XP(J) = X
32
        YP(J) = Y
    10 CONTINUE
33
34
        CALL GSPLI(1)
        CALL GSPLCI(1)
35
         CALL GPL(JL+1,XP,YP)
36
37 C
38 C Deactivate and close the workstation, close GKS.
39 C
40
        CALL GDAWK (IWKID)
        CALL GCLWK (IWKID)
41
        CALL GCLKS
42
43 C
        STOP
44
45
        END
```

[Page 13]

Figure 1.5. A simple GKS program displaying a circle.



The GKS routines usually have a "G" prefix in their names. The calls to GOPKS, GOPWK and GACWK (lines 1214) set up the GKS environment. The GSCR calls define color indices. The circle is defined as a polyline of 120 points, which are calculated directly using COS and SIN functions. An extra point is added to close the curve. The GPL call (line 36) draws the polyline.

The program is compiled under the Linux operating system using the NCAR graphics package.

#### 1.2.4. OpenGL

*OpenGL* is a popular 2D/3D graphics API derived from GL (Graphics Library) of Silicon Graphics Inc. GL is the graphics programming interface used on SGI's successful graphics workstations. OpenGL is designed to be an open and vendor-neutral industry standard. It is available virtually on all computer platforms. In fact, many hardware vendors offer OpenGL interfaces for their graphics cards and devices. With over 200 functions, OpenGL provides a much more powerful graphics API than the earlier standards such as GKS.

OpenGL is a relatively low-level API with a procedural-oriented interface. Different language bindings for OpenGL in a possible, as the comparison of openGL in the C language is still apparent. The C binding is the most popular one. OpenGL consists of two libraries: GL and GLU (OpenGL Utility Library). The GL library contains the core functions for basic graphics features, and the GLU library contains higher-level utility functions built on top of GL functions. OpenGL itself does not have functions for constructing a user interface. A simple portable package called GLUT (OpenGL Utility Toolkit) can be used with OpenGL to construct a complete graphics program.

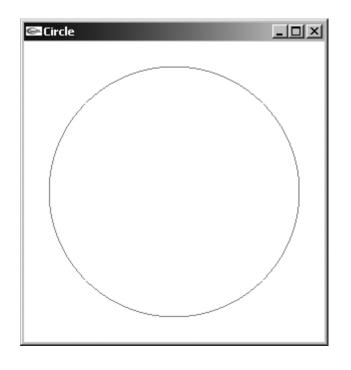
Listing 1.4 is a simple OpenGL example that draws a circle (Figure 1.6). The program uses GLUT to construct the user interface and uses GL and GLU functions to construct the display. The function names from the GL, GLU, and GLUT libraries usually have their library names as prefixes.

[Page 14]

```
1 #include <GL/glut.h>
 2 #include <math.h>
 3
 4 void display(void) {
 5
       int i;
       int n = 80;
 6
       float a = 2*3.1415926535/n;
 7
 8
       float x;
 9
       float y;
10
       glClear(GL_COLOR_BUFFER_BIT);
11
12
       glColor3f(1.0,0,0);
13
       glBegin(GL_LINE_LOOP);
14
       for (i = 0; i < n; i++) {
15
              x = cos(i*a);
16
17
              y = sin(i*a);
18
              glVertex2f(x, y);
19
       }
20
       glEnd();
21
       glFlush();
22 }
23
24 int main(int argc, char** argv) {
25
       glutInit(&argc, argv);
26
       glutCreateWindow("Circle");
27
       glutDisplayFunc(display);
28
       glMatrixMode(GL_PROJECTION);
29
       glLoadIdentity();
30
       gluOrtho2D(-1.2, 1.2, -1.2, 1.2);
31
       glClearColor(1.0, 1.0, 1.0, 0.0);
32
       glutMainLoop();
33 }
```

Listing 1.4. OpenGLCircle.c

Figure 1.6. An OpenGL circle program.



[Page 15]

The main function calls several GLUT functions to set up the display window, the display function, and the message loop. The glutInit function (line 25) initializes GLUT. The glutCreateWindow function creates a window. The glutDisplayFunc function sets the display function, which is a callback function for graphics drawing. The glutMainloop function (line 32) starts the event loop.

The projection matrix of the display is set to a 2D orthogonal projection using several GL functions and the GLU function gluOrtho2D.

The function bip by the first as the display function for this program. Indraws a since by using a TER PRO sequence of vertices in the mode of LINE\_LOOP. The vertices are calculated with a parametric equation for the R PRO circle and set with the function glvertex2f.

Of course OpenGL, as a 3D API, is capable of much more than drawing a circle. Another simple OpenGL example is given in Listing 1.5. It displays a spinning 3D sphere (Figure 1.7).

Listing 1.5. OpenGLSphere.c

```
1 #include <GL/glut.h>
 2
 3 GLUquadricObj* sphere;
 4
 5 void display(void) {
       glClear(GL_COLOR_BUFFER_BIT);
 б
 7
       glMatrixMode(GL_MODELVIEW);
 8
       glRotatef(0.2, 0.0, 0.0, 1.0);
 9
       gluSphere(sphere, 1.8, 24, 24);
10
       glutSwapBuffers();
11 }
12
13 void idle(void) {
14
       glutPostRedisplay();
15 }
16
17 int main(int argc, char** argv) {
18
       glutInit(&argc, argv);
19
       glutInitDisplayMode(GLUT_DOUBLE | GLUT_RGB);
20
       glutCreateWindow("Spinning Sphere");
21
      glutDisplayFunc(display);
22
       glMatrixMode(GL_PROJECTION);
23
       glLoadIdentity();
24
       glOrtho(-2.0, 2.0, -2.0, 2.0, -2.0, 2.0);
25
       glClearColor(1.0, 1.0, 1.0, 0.0);
26
       glColor3f(1.0, 0.5, 0.5);
27
       sphere = gluNewQuadric();
28
       gluQuadricDrawStyle(sphere, GLU_LINE);
29
       glutIdleFunc(idle);
30
       glEnable(GL_CULL_FACE);
31
       glCullFace(GL_BACK);
32
       glMatrixMode(GL_MODELVIEW);
33
       glLoadIdentity();
       gluLookAt(1.0, 1.0, 1.0, 0.0, 0.0, 0.0, 0.0, 1.0, 0.0);
34
35
       glutMainLoop();
36 }
```

[Page 16]

Figure 1.7. An OpenGL program displaying a 3D spinning sphere.



Double buffering is applied in this example through the function glutInitDisplayMode (line 19). The projection matrix of the display is set to an orthogonal projection using GL functions. The function call gluLookAt (line 34) defines the view to have the eye positioned at (1, 1, 1) looking at (0, 0, 0). A sphere object is created with GLU functions.

In this case, in addition to the display callback, an idle callback is also defined to drive the animation. The idle function (line 13) calls glutPostRedisplay to request a call to the display function. In the display function, the model view matrix is rotated by a small angle. The sphere is then redrawn on the hidden buffer. Finally the two buffers are swapped to show the new drawing.

### 1.2.5. JAVA 1.2.5. JAVA

OpenGL provides a standard and efficient rendering interface to graphics hardware. However, with the rapid development of computer hardware and software technology, it can be argued that an even higher level abstraction of graphics programming is now feasible. OpenGL offers a C-like procedural abstraction. It is not designed to directly accommodate the graphics modeling in an object-oriented programming paradigm. A high-level OOP-based graphics API (potentially built on top of OpenGL) may offer great benefits to application programmers.

Java 2D and Java 3D are newer graphics APIs associated with the Java programming language. They are highlevel object-oriented APIs with high portability. Java 2D and Java 3D will be the APIs used in this book. Java 3D is typically implemented on top of other lower-level APIs such as OpenGL. Figure 1.8 shows a typical graphicssystem layout.

Figure 1.8. Graphics-system layers.

Graphics application	
Java APIs	Java 3D
Java VM	OpenGL
OS	
Display driver	
Graphics card	
Display	

An overview of the Java language and its graphics facilities is given in the next three sections.

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Next 🕨

### 1.3. Java Programming Language

Java is a full-featured, general-purpose programming language that is capable of developing robust missioncritical applications. In recent years, Java has gained enormous popularity and has quickly become the programming language of choice for a wide range of applications. Today, it is used not only for Web programming, but also for developing standalone applications across platforms on servers, desktops, and mobile devices.

[Page 17]

A Java program is compiled to a standard, platform-independent format called "byte code." The compiled byte code can be executed without any change on any machine with a *Java Virtual Machine*. This platform independence makes Java the ideal language for delivering applications over the Internet.

Java is designed from the ground up to support object-oriented programming (OOP). A Java program consists entirely of class definitions. Object instantiations and interactions constitute the main actions of a Java program.

The Java language also maintains the simplicity, elegance, and efficiency of its predecessor, the C programming language. At the same time, Java avoids many of the pitfalls and deficiencies of C and C++.

While the language itself is very simple, the Java platform offers a comprehensive set of APIs (application programming interfaces). The Java APIs cover a wide range of tasks and applications: file I/O, graphics, multimedia, database, network, security, and so on.

Java contains two nearly parallel sets of facilities for GUI programming: *AWT* and *Swing*. The early versions of Java offered limited graphics support. Only minimal graphics features were included in JDK 1.x. Graphical user interface (GUI) support and graphics drawing features were provided in the Abstract Window Toolkit (AWT) package. GUI components in AWT are heavyweight—they are mapped to native components of the operating system. Besides a simple set of features to create GUI elements, AWT offers capabilities to control certain rendering attributes such as drawing color and to draw simple graphics primitives such as lines, rectangles, and ovals. There is also some support for images. However, these features are severely limited. For example, there is no way to control the width of drawing lines. Because of the limitations, early Java versions certainly did not provide adequate support for modern computer graphics programming. The Swing package is a completely redesigned on the provide and the provide and the provide and the provide as native components. The graphics support in Java 2 is also greatly enhanced. The Java 2D package provides comprehensive 2D graphics features. Listing 1.6 shows a simple Java GUI program using AWT only. A Swing example will be given in the next section.

The program in Listing 1.6 is a simple Java GUI application using only the drawing facilities provided by AWT without more advanced features from Java 2D. It draws a circle in a frame (Figure 1.9). If the user clicks on the frame, the circle will move to a new location with the center at the mouse pointer. A menu is added to the frame with an item "Exit," which will terminate the program when selected.

Listing 1.6. AWTDemo.java

(This item is displayed on pages 17 - 18 in the print version)

```
1 package chapter1;
 2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5
 6 public class AWTDemo extends Frame implements ActionListener{
 7
    int x = 100;
    int y = 100;
 8
9
10
   public static void main(String[] args) {
11
     Frame frame = new AWTDemo();
12
      frame.setSize(640, 480);
13
      frame.setVisible(true);
14
   }
15
16
    public AWTDemo() {
17
      setTitle("AWT Demo");
18
       // create menu
19
      MenuBar mb = new MenuBar();
[Page 18]20
             setMenuBar(mb);
21
      Menu menu = new Menu("File");
22
      mb.add(menu);
23
      MenuItem mi = new MenuItem("Exit");
24
      mi.addActionListener(this);
25
      menu.add(mi);
26
      // end program when window is closed
27
      WindowListener l = new WindowAdapter() {
28
        public void windowClosing(WindowEvent ev) {
29
           System.exit(0);
30
       }
      };
31
32
      this.addWindowListener(1);
33
       // mouse event handler
      MouseListener mouseListener = new MouseAdapter() {
34
        public void mouseClicked(MouseEvent ev) {
35
36
           x = ev.getX();
37
           y = ev.getY();
38
           repaint();
39
        }
40
      };
41
       addMouseListener(mouseListener);
42
    }
43
    public void paint(Graphics g) {
44
45
     g.drawOval(x-50, y-50, 100, 100);
46
    }
47
48
    public void actionPerformed(ActionEvent ev) {
49
     String command = ev.getActionCommand();
50
       if ("Exit".equals(command)) {
51
         System.exit(0);
52
       }
53
    }
54 }
```

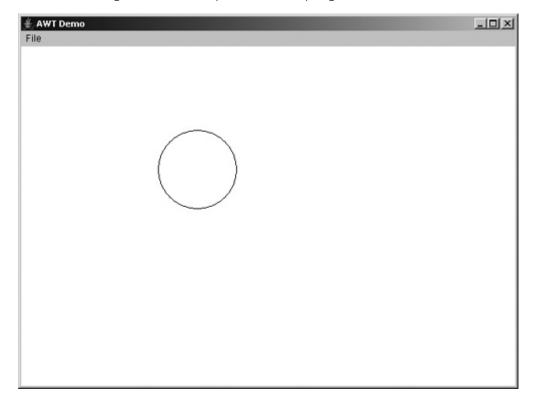


Figure 1.9. A simple Java GUI program with AWT.

[Page 19]

This program is a GUI application using AWT. It has a main window with a menu and a circle. The menu contains only one item, "Exit," which closes the window when selected. The graphical drawing responds to a mouse click by rediation rediation of the response of the selected of the sele

The AWTDemo class is defined to be a subclass of Frame (line 6). It defines the main program window. The menu in the frame is created with objects of the classes MenuBar, Menu, and MenuItem (lines 19–25). The AWTDemo class implements the Action Listener interface to process the ActionEvent generated by menu selections. The actionPerformed method defined in the interface is the handler for the events. When the "Exit" menu item is selected, the program exits by calling the method System. exit(0).

Two other event handlers are defined in the constructor of the AWTDemo class. A WindowListener is defined as an anonymous inner class from WindowAdapter (lines 27–32). It overrides the windowClosing method to terminate the program upon receiving the closing event for the window. The other listener is a MouseListener, derived from the MouseAdapter class (lines 34–41). The mouseClicked method is overridden to handle the mouse-click events. In the mouseClicked method, the mouse location is saved to the variables x and y, and a call to the repaint method is made to refresh the drawing and to move the figure to the new location.

The method paint (line 44) draws a circle of radius 50 with the method drawOval in the Graphics object. The center of the circle is determined by the variables x and y.

The main method creates and displays an instance of AWTDemo. The frame is set to the size 640 by 480.

One grading of Singer Ref D Jave Role of Jave Ref And Anter Singer Control of JSR 231: Java language bindings for OpenGL. JOGL is an implementation of JSR 231: Java language bindings for OpenGL. JOGL provides

the classes GL and GLU to encapsulate the functions in GL and GLU. The two components GLCanvas and GLJPanel provide the drawing surfaces for the OpenGL calls. The GLCanvas is a heavyweight component that will use the hardware acceleration. The GLJPanel is a lightweight component implemented in memory. No hardware acceleration is available to GLJPanel. A typical procedure for programming JOGL is outlined below.

- 1. Create a GLCanvas or GLJPanel object through the GLDrawableFactory class.
- 2. Add a GLEvent listener to the canvas object.
- 3. Implement the listener by implementing the four methods: init, display, reshape, and displayChanged.

Listing 1.7 is the JOGL equivalent of Listing 1.4.

```
Listing 1.7. JOGLDemo.java
```

(This item is displayed on pages 19 - 20 in the print version)

```
1 package chapter1;
 2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5 import javax.swing.*;
 6 import net.java.games.jogl.*;
 7
8 public class JOGLDemo {
9
10
    public static void main(String[] args) {
11
       Frame frame = new Frame("JOGL Demo");
12
       GLCapabilities cap = new GLCapabilities();
              GLCanvas canvas =
[Page 20]13
      GLDrawableFactory.getFactory().createGLCanvas(cap);
14
15
       canvas.setSize(300, 300);
16
      canvas.addGLEventListener(new Renderer());
17
      frame.add(canvas);
18
     frame.pack();
19
      frame.addWindowListener(new WindowAdapter() {
20
         public void windowClosing(WindowEvent e) {
21
           System.exit(0);
22
         }
23
       });
24
       frame.show();
25
     }
26
27
    static class Renderer implements GLEventListener {
28
     private GL gl;
29
      private GLU glu;
30
       private GLDrawable gldrawable;
31
32
      public void init(GLDrawable drawable) {
33
         gl = drawable.getGL();
34
         glu = drawable.getGLU();
35
         this.gldrawable = drawable;
36
         gl.glMatrixMode(GL.GL_PROJECTION);
37
         gl.glLoadIdentity();
38
         glu.gluOrtho2D(-1.2, 1.2, -1.2, 1.2);
39
         gl.glClearColor(1.0f, 1.0f, 1.0f, 0.0f);
```

```
}
40
41
42
       public void display(GLDrawable drawable) {
43
         int i;
44
         int n = 80;
45
         float a = (float)(2*3.1415926535/n);
46
         float x;
47
         float y;
48
          gl.glClear(GL.GL_COLOR_BUFFER_BIT);
49
50
         gl.glColor3f(1.0f,0,0);
51
         gl.glBegin(GL.GL_LINE_LOOP);
52
         for (i = 0; i < n; i++) {
53
           x = (float)Math.cos(i*a);
54
           y = (float)Math.sin(i*a);
55
           gl.glVertex2f(x, y);
56
         }
57
         gl.glEnd();
         gl.glFlush();
58
59
       }
60
       public void reshape(GLDrawable drawable, int x, int y, int width,
61
62
         int height) {}
63
        public void displayChanged(GLDrawable drawable,
64
          boolean modeChanged, boolean deviceChanged) {}
65
    }
66 }
```

JOGL, as a language binding for OpenGL, has the same advantages and shortcomings as OpenGL. It is an efficient renderer, but it does not offer a full-fledged modeler with Java's OOP features.

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#### 1.4. Java 2D

The Java 2 platform brings significant improvements in graphics capabilities with the introduction of Swing and Java 2D and 3D APIs. The well-designed APIs offer comprehensive support for many tasks of computer graphics. Together with the unique advantages of the Java programming language, they have made the combination of Java with Java 2D and Java 3D a very attractive option for graphics programming and learning computer graphics.

The graphics support in early versions of Java is very primitive and limited. Java 2D provides a rather complete set of functionalities to manipulate and render 2D graphics. Specifically the enhancements include:

- A separate class hierarchy for geometric objects is defined in Java 2D.
- The rendering process is much more refined.
- Completely new image-processing features are introduced.
- Color models, fonts, printing, and other graphics-related supports are also greatly improved.

The Graphics2D class, a subclass of the Graphics class, is the rendering engine for Java 2D. It provides methods to render geometric shapes, images, and texts. The rendering process can be controlled by selecting transformation, paint, line properties, composition, clipping path, and other properties.

The *Swing* components and Java 2D included in the Java 2 platform are more advanced than the graphics facilities in earlier Java platforms. The Java 2D examples in this book will use the Swing classes and avoid the old AWT components whenever possible.

Listing 1.8 is a simple demonstration of Java 2D graphics features. It uses certain advanced capabilities of Java 2D such as transparency, gradient paint, transformation, and font glyphs that are not available in AWT. (See Figure 1.10.)

Listing 1.8. Demo2D.java

(This item is displayed on pages 21 - 22 in the print version)

```
1 package chapter1;
 2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5 import javax.swing.*;
 6 import java.awt.font.*;
 7 import java.awt.geom.*;
 8
 9 public class Demo2D extends JApplet {
   public static void main(String s[]) {
10
       JFrame frame = new JFrame();
11
12
       frame.setTitle("Java 2D Demo");
13
       frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
14
       JApplet applet = new Demo2D();
15
       applet.init();
16
       frame.getContentPane().add(applet);
17
       frame.pack();
18
       frame.setVisible(true);
19
     }
20
21
     public void init() {
```

```
22
       JPanel panel = new Panel2D();
23
       getContentPane().add(panel);
24
   }
25 }
26
27 class Panel2D extends JPanel{
[Page 22]28 public Panel2D() {
      setPreferredSize(new Dimension(500, 400));
29
       setBackground(Color.white);
30
31
   }
32
33
    public void paintComponent(Graphics g) {
34
       super.paintComponent(g);
35
       Graphics2D g2 = (Graphics2D)g;
36
      // draw an ellipse
37
       Shape ellipse = new Ellipse2D.Double(150, 100, 200, 200);
38
      GradientPaint paint =
39
      new GradientPaint(100,100, Color.white, 400, 400, Color.gray);
40
       g2.setPaint(paint);
41
      g2.fill(ellipse);
42
      // set transparency
43
      AlphaComposite ac =
      AlphaComposite.getInstance(AlphaComposite.SRC_OVER, 0.4f);
44
45
      g2.setComposite(ac);
46
       g2.setColor(Color.blue);
47
      // draw transparent text
48
       Font font = new Font("Serif", Font.BOLD, 120);
49
       g2.setFont(font);
50
       g2.drawString("Java", 120, 200);
51
      // get outline of text glyph
52
      FontRenderContext frc = g2.getFontRenderContext();
53
       GlyphVector gv = font.createGlyphVector(frc, "2D");
54
       Shape glyph = gv.getOutline(150,300);
55
       // draw rotated glyph
56
       g2.rotate(Math.PI/6, 200, 300);
57
       g2.fill(glyph);
       INREGISTERED VERSION OF CHM T� PDF CONVERTER PRO
58
59 }
```

Figure 1.10. A Java 2D program. The circle is filled with a gradient paint and the text is semitransparent.



The class names of Swing components typically have a prefix "J." The class Panel2D (line 27) extends the JPanel class and overrides the paintComponent method (line 33). The Graphics parameter in the method is cast to Graphics2D to take advantage of the extended functionality in Java 2D. A circle is drawn with a gradient paint that changes its color based on locations. The composite rule is then set to achieve a degree of transparency. The font glyphs for text string "2D" are retrieved and the outlines are used as geometric shapes. The shape for the string "2D" is rotated 30 degrees (p/6). The details of Java 2D programming are introduced in the later chapters.

#### [Page 23]

A Java program can often be written as both an applet and an application. This program is an example of such "dual-purpose" programs. The Demo2D class is a subclass of JApplet (line 9) and can be executed as an applet. However, it also contains a main method (line 10) so it can also be executed as an application. The main method creates an instance of JFrame and adds an instance of Demo2D to the frame. It simulates the execution of the applet by calling the init method. The results from the application and the applet are almost identical. Most examples in this book will use this format.

Java 2D is a standard part of the core Java 2 platform. Any Java 2 Standard Edition (J2SE) Software Development Kit (SDK) or Java Runtime Environment (JRE) installation automatically includes Java 2D. This example can be compiled under such an SDK without additional packages.

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#### 1.5. Java 3D

Java 3D is an optional package of the Java platform. It can be obtained from the site: http://www.javasoft.com/java3d. Java 3D provides an incredibly comprehensive framework for 3D graphics, including such advanced features as animation, 3D interaction, and sophisticated viewing. Yet it still provides a relatively simple and intuitive programming interface.

The Java 3D programming paradigm is very different from that of Java 2D. It closely follows the modeling–rendering paradigm. An abstract model known as the *scene graph* is used to organize and retain the visual objects and behaviors in the virtual scene. The scene graph contains the complete information of the virtual graphics world. The Java 3D rendering engine renders the scene graph automatically.

Java 3D renders a scene on a Canvas3D object. Canvas3D is a heavyweight component that does not work well with the new Swing components. For this reason, the Java 3D examples in this book will use AWT objects.

Note

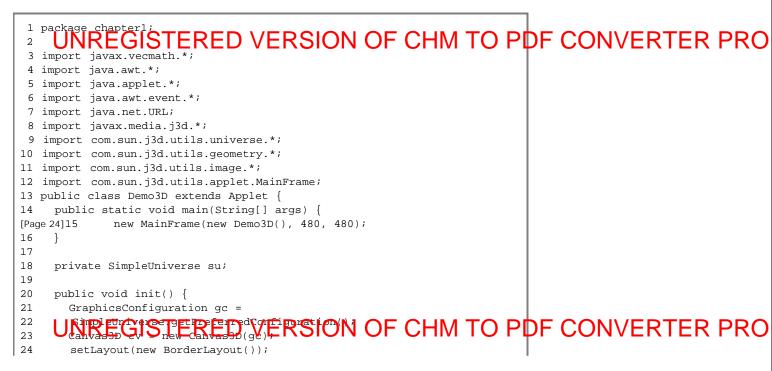


The reason that Java 3D still does not have a lightweight canvas is to take advantage of hardware acceleration. With heavyweight components, the hardware graphics acceleration provided through the native platform support is automatically used. It is possible to mix heavyweight and lightweight components, but care must be taken to avoid some undesirable effects. See Appendix B for more details.

Listing 1.9 is a simple Java 3D application. It displays a rotating globe and a 3D text string "Java 3D" in front of the globe as shown in Figure 1.11.

Listing 1.9. Demo3D.java

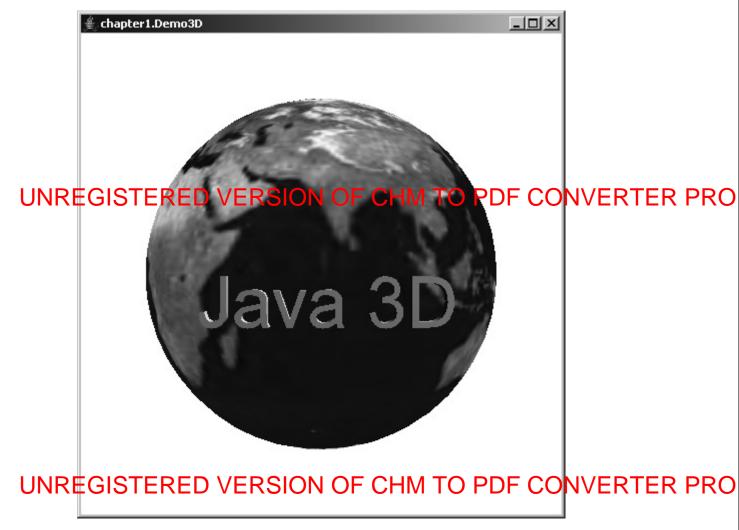
(This item is displayed on pages 23 - 25 in the print version)



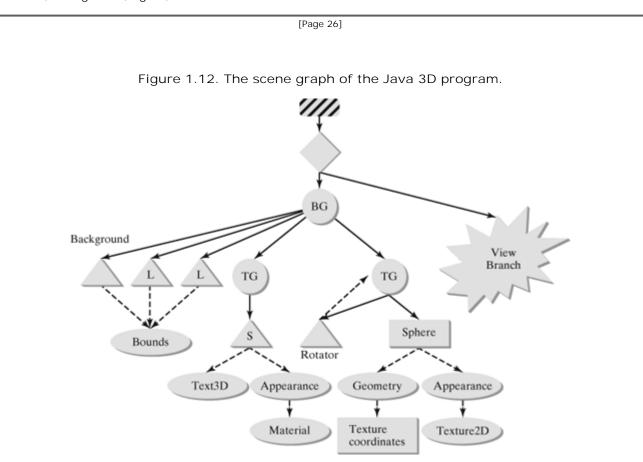
```
25
       add(cv);
26
       BranchGroup bg = createSceneGraph();
27
       bg.compile();
28
       su = new SimpleUniverse(cv);
29
       su.getViewingPlatform().setNominalViewingTransform();
30
       su.addBranchGraph(bg);
31
    }
32
33
    public void destroy() {
34
     su.cleanup();
35
    }
36
    private BranchGroup createSceneGraph() {
37
38
      BranchGroup root = new BranchGroup();
39
       TransformGroup spin = new TransformGroup();
40
       spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
41
      root.addChild(spin);
42
       // 3d text
      Appearance ap = new Appearance();
43
44
       ap.setMaterial(new Material());
      Font3D font = new Font3D(new Font("Helvetica", Font.PLAIN, 1),
45
46
      new FontExtrusion());
       Text3D text = new Text3D(font, "Java 3D");
47
       Shape3D shape = new Shape3D(text, ap);
48
49
      // transform for text
50
       Transform3D tr = new Transform3D();
51
      tr.setScale(0.2);
52
       tr.setTranslation(new Vector3d(-0.35,-0.15,0.75));
53
      TransformGroup tg = new TransformGroup(tr);
54
      root.addChild(tg);
55
      tg.addChild(shape);
56
      // globe
57
      ap = createAppearance();
58
      spin.addChild(new Sphere(0.7f,
59
       Primitive.GENERATE_TEXTURE_COORDS, 50, ap));
60
       // rotation
61
       Alpha alpha = new Alpha(-1, 6000);
62
       RotationInterpolator rotator =
63
       new RotationInterpolator(alpha, spin);
64
      BoundingSphere bounds = new BoundingSphere();
65
      rotator.setSchedulingBounds(bounds);
66
       spin.addChild(rotator);
67
       // background and lights
       Background background = new Background(1.0f, 1.0f, 1.0f);
68
69
      background.setApplicationBounds(bounds);
70
       root.addChild(background);
71
      AmbientLight light =
72
      new AmbientLight(true, new Color3f(Color.red));
73
       light.setInfluencingBounds(bounds);
74
       root.addChild(light);
[Page 25]75
              PointLight ptlight = new PointLight(new Color3f(Color.white),
       new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
76
77
       ptlight.setInfluencingBounds(bounds);
78
       root.addChild(ptlight);
79
      return root;
80
    }
81
82
     private Appearance createAppearance(){
83
     Appearance ap = new Appearance();
```

```
84
       URL filename =
85
       getClass().getClassLoader().getResource("images/earth.jpg");
86
       TextureLoader loader = new TextureLoader(filename, this);
87
       ImageComponent2D image = loader.getImage();
88
       Texture2D texture =
89
       new Texture2D(Texture.BASE_LEVEL, Texture.RGBA,
       image.getWidth(), image.getHeight());
90
91
      texture.setImage(0, image);
92
      texture.setEnable(true);
93
       texture.setMagFilter(Texture.BASE_LEVEL_LINEAR);
94
      texture.setMinFilter(Texture.BASE_LEVEL_LINEAR);
95
      ap.setTexture(texture);
96
      return ap;
97
   }
98 }
```

Figure 1.11. A Java 3D program that displays a rotating globe and a 3D text string.



This is a typical Java 3D application. The main task of the program is centered on the construction of a conceptual data structure called scene graph. The visual effects of the program are achieved by creating a scene graph and placing the appropriate graphics elements into it. The scene graph for the program is shown in Figure 1.12. It is a treelike structure containing objects such as the sphere, the 3D text, appearance, transforms, background, lights, and so on.



The rendering of the scene is done automatically by the Java 3D engine. The results are shown in Figure 1.11. The concepts and techniques of programming Java 3D with scene graphs will be introduced in the later chapters.

The program is also constructed as a dual-purpose applet/application. The class Demo3D is defined as a subclass of Applet. A main method also exists in Demo3D to run the class as an application. The utility class MainFrame (line 16) included in Java 3D provides the necessary functionality to run an applet in a frame.

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## 1.6. Related Fields

Computer graphics, image processing, and computer vision are all computer-related fields that deal with graphical objects. They are different in their objectives and techniques. However, close relationships exist among them, and the lines between them have been increasingly blurred.

*Image processing* is concerned with techniques of processing digital raster images. It typically deals with problems such as image enhancement, noise reduction, image compression, and edge detection. Image processing takes an existing image as input and performs appropriate actions. Computer graphics, on the other hand, generates synthetic images from a virtual world.

Image processing is closely related to computer graphics. The results of graphics rendering are usually images. Raster images are used extensively in computer graphics as graphics primitives. They are also used as textures to enhance graphics rendering. Listing 1.9 shows a globe that is constructed as a sphere with an earth image mapped on its surface. Examples of basic image-processing techniques will be given in Chapter 4.

*Computer vision* attempts to derive an understanding from images of the real world. In a way a computer vision system is the inverse of a computer graphics system. Its main goal is to reconstruct a virtual world from real-world images. Therefore, computer vision and computer graphics are complementary to each other. They provide different perspectives to a common system.

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The theory and practice of computer graphics depend heavily on certain important mathematical concepts. Closely related mathematics areas include analytic geometry and linear algebra. *Analytic geometry* provides a numerical representation for graphical objects. Linear *algebra* studies the operations and transformations of vector spaces, which are important in many fundamental problems of computer graphics. Relevant mathematical topics will be introduced in the chapters associated with the graphics problems. Appendix A provides a summary of graphics-related mathematical background.

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### 1.7. Resources

A classical reference for computer graphics is:

• J. Foley, A. van Dam, S. Feiner, and J. Hughs, *Computer Graphics, Principles and Practices*, 2d ed., Reading, MA: Addison-Wesley, 1990.

Many current computer graphics textbooks use OpenGL:

- E. Angel, *Interactive Computer Graphics, A Top-Down Approach with OpenGL*, 2d ed., Reading, MA: Addison-Wesley, 2000.
- D. Hearn and M. P. Baker, *Computer Graphics with OpenGL*, 3d ed., Upper Saddle River, NJ: Prentice Hall, 2003.
- F. S. Hill, Computer Graphics Using OpenGL, 2d ed., Upper Saddle River, NJ: Prentice Hall, 2001.

GKS and other ISO standards are available at the ISO site:

http://www.iso.ch/

The NCAR Graphics package contains an implementation of GKS and is available at:

http://ngwww.ucar.edu/ng4.4/

The classical OpenGL books include:

- OpenGL Architecture Review Board, *OpenGL Programming Guide*, 4th ed., Reading, MA: Addison-Wesley, 2004.
- OpenGL Architecture Review Board, *OpenGL Reference Manual*, 4th ed., Reading, MA: Addison-Wesley, 2004.

Many websites for OpenGL are available. The official OpenGL site contains useful information and links:

http://opengl.org/

The website for the JOGL project is:

http://jogl.dev.java.net/

You may find tutorials, documentations, software downloads, and other useful information at the official Java developer site:

http://java.sun.com/

A useful reference book on Java 3D is the API specification:

• H. Sowizral, K. Rushforth, and M. Deering, *The Java 3D API Specification*, 2d ed., Reading, MA: Addison-Wesley, 2000.

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Web resources for Java 3D include:

http://java.sun.com/products/java-media/3D/index.jsp

http://j3d.org/

https://java3d.dev.java.net/

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#### [Page 28 (continued)]

## Key Classes and Methods

- javax.swing.JFrame A Swing class for the main window of an application.
- javax.swing.JFrame.setDefaultCloseOperation(int) A method to set the operation in response to the window close event.
- java.lang.System.exit(int) A method to end the program.
- java.awt.Frame An AWT class for the main window of an application.
- javax.swing.JPanel A Swing component that can be used as a container or a base class for a custom drawing canvas.
- javax.awt.Graphics A class for all graphics drawing facilities in AWT.
- javax.awt.event.MouseListener An interface for listening and handling mouse events.
- javax.awt.event.MouseListener.mouseClicked(MouseEvent) The method to implement the handler for mouse clicking.

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# Key Terms modeling

The process of constructing a graphics model.

#### rendering

The process of constructing an image of a scene from a graphics model.

#### virtual world

A graphics model constructed in a computer.

#### API

Application Programmer's Interface. A standardized software interface to specify the usage of functionalities provided by a software package.

#### GKS

Graphics Kernel System. A standard graphics API.

#### PHIGS UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO Programmer's Hierarchical Interactive Graphics System. A graphics API.

OpenGL

A popular graphics API derived from Silicon Graphics' GL (Graphics Library). It has a programming interface typically associated with the C language.

JOGL

A Java language binding for OpenGL.

image processing

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#### computer vision

A computer and engineering field to study the perception and reconstruction of a scene from captured images.

#### AWT

Abstract Window Toolkit. A Java graphics package existing since the early versions of Java API.

#### Swing

A new enhanced Java graphics package.

### OOP

Object-oriented programming. A software engineering paradigm that views a program as a system of interrelated objects.

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### Chapter Summary

• This chapter provides an overview of computer graphics, its basic structures, its applications, its relationships with other fields, and the graphics supports in the Java platform.

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- The fundamental objectives of computer graphics include the construction of a virtual world of graphics objects and the rendering of a scene from the virtual world. Modeling and rendering are the two major topics of computer graphics.
- The characteristics of problems involved in 2D and 3D graphics systems may be quite different. Usually 2D and 3D graphics systems have different structures and they may be implemented as separate packages. This is the case in the Java platform. Java 2D and Java 3D are separate packages with different programming models.
- The graphics programming environment has been evolving from low-level hardware-specific methods to high-level object-oriented paradigms. To reduce platform dependency and to achieve high levels of abstraction, many graphics APIs have been developed. Examples of the standard graphics packages include GKS, PHIGS, OpenGL, Java 2D, and Java 3D.
- Unlike early Java versions, the Java 2 platform offers extensive graphics support. The Java 2D and Java 3D packages are high-level, full-featured graphics systems. This book will use Java 2D and Java 3D as the main tools to introduce graphics programming.
- Computer graphics, as a computer discipline, is different from image processing and computer vision. But it maintains close ties to these fields, which also deal with visual images.

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### **Review** Questions

- 1.1 List three applications that use 2D computer graphics.
- 1.2 Name a nongame application that uses 3D computer graphics.
- 1.3 Search the Internet to assemble a list of movies that have applied computer graphics.
- 1.4 Identify the fields (computer graphics, image processing, and computer vision) that are applicable to the following applications:
  - a. Locate small bright spots in a mammogram image.
  - b. Construct a 3D model of a building from a set of its pictures.
  - c. Display a simulation of the solar system with the sun and nine planets in motion.
  - d. Recognize the brain region in a MRI scan and display a 3D model of the brain.
  - e. Use computers to generate the scene of a car collision.
  - f. Make a computer identification of a person from a photograph.
- 1.5 Search the Internet to find an example program that uses GKS.
- 1.6 Search the Internet to find an example program that uses PHIGS.
- 1.7 Compare OpenGL and Java 3D. List the advantages of each API.
- 1.8 Discuss the advantages and disadvantages of including graphics support in a standard language platform such as Java.
- 1.9 List the major GUI components of AWT and find their approximate equivalents in Swing.
- 1.10 Read the documentation of Java 3D and list the Java packages in Java 3D.

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### **Programming Exercises**

- 1.1 Write a console-based Java program that fills a double array with 100 random values and prints their mean and standard deviation.
- 1.2 Write a Java AWT program that draws a circle in the middle of the window.
- 1.3 Write a Java Swing program that draws a circle in the middle of the window.
- 1.4 Write a Java GUI program that responds to a mouse click by drawing a filled circle at the mouse location.
- 1.5 Edit, compile, and run the Java 2D program in Listing 1.8 on your local machine.
- 1.6 Edit, compile, and run the Java 3D program in Listing 1.9 on your local machine.

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## Chapter 2. 2D Graphics: Basics

(This item omitted from WebBook edition)

Objectives
• To understand the architecture and operations of a 2D graphics system.
To understand 2D coordinate systems and equations of graphs.
• To be able to identify the various coordinate spaces in a rendering pipeline.
• To understand Java 2D program structure and the Graphics2D object.
To graph equations with Java programs.
To use basic 2D geometric primitives.
• To construct custom shapes using the GeneralPath class.
To construct geometric shapes through constructive area geometry.

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## 2.1. Introduction

This chapter introduces basic concepts of 2D computer graphics systems and the Java 2D package. A 2D graphics system models the virtual world with a two-dimensional space. Compared to 3D graphics, 2D graphics is simpler in both modeling and rendering. 2D objects are easier to create and manipulate. The 2D rendering usually does not involve any complicated projections such as those in 3D graphics. Even though a 2D model cannot completely capture the full nature of a 3D space, 2D computer graphics is widely applied because of its simplicity and efficiency. It is an essential ingredient of modern GUI-based programs.

The key concepts related to 2D graphics include the rendering pipeline, the object space, the world space, the device space, coordinate systems, graphics primitives, geometric transformations, colors, clipping, composition rules, and other topics. Java 2D provides comprehensive support for 2D graphics. This chapter covers the basic structures of Java 2D programs and the geometric-object models. Additional topics for 2D graphics and Java 2D programming will be discussed in the next two chapters.

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## 2.2. 2D Rendering Process

In 2D graphics, the virtual world space and the viewing space are both two dimensional. The rendering involves composing various objects through some relatively straightforward transformations. Often the 2D world space is not even needed in order to explicitly model the relationships among the graphics objects. However, to achieve the clarity of system structures and to keep the analogy with 3D graphics, the notion of a virtual world space will be retained.

Conceptually, a graphics object can be defined in its own *object space* and then placed in the 2D *world space* by an object transformation. A 2D rendering takes a snapshot of the world and produces an image representing a particular view in a device space.

Figure 2.1 shows a typical procedure for 2D graphics rendering.

Figure 2.1. A 2D graphics object is processed in a pipeline of transformation and viewing.



The essential components of a 2D graphics system include the 2D object model to be rendered, the geometric transformations applied to the objects, and the rendering engine that creates a particular view of the virtual world on a display device. The basic steps for rendering graphics in a simple 2D graphics program can be outlined as follows:

- 1. Construct the 2D objects.
- 2. Apply REGISTERED EXERSION OF CHM TO PDF CONVERTER PRO
- 4. Render the scene on a graphics device.

The graphics objects in the model are two dimensional. Besides geometric objects constructed from basic primitives such as lines, polygons, and ellipses, the model may also include objects such as texts and images.

The transformations involved in 2D graphics are usually affine transforms. The object transformations change the shapes and locations of the visual objects to which the transforms are applied. The viewing transformations do not change the virtual world model, but they change the views of the entire scene on the world space. For example, in a virtual model with a circle and a triangle, a translation applied to the circle as an object transformation will move only the circle without changing the triangle. A translation as a viewing transformation, on the other hand, will move the entire view.

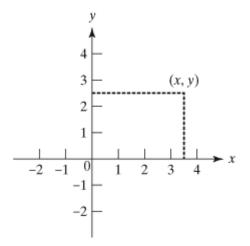
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In addition to the geometry, many other attributes will affect the rendering of a scene. Colors, transparency, textures, and line styles are examples of such attributes. A 2D graphics system will render a scene based on the geometry information, transformation, and a graphics context involving other attributes.

## 2.3. 2D Geometry and Coordinate Systems

The fundamental components of a graphics model are geometric objects. In order to represent geometry precisely and efficiently in computers, *coordinate systems* are employed. The most commonly used 2D coordinate system employs rectangular (Cartesian) coordinates, as illustrated in Figure 2.2.

Figure 2.2. The 2D coordinate system with the *x*-axis and *y*-axis.

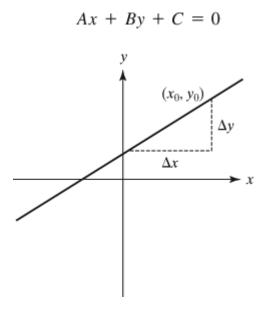


Two perpendicular axes are placed in the plane. Each axis is labeled with the set of real numbers. The horizontal axis is customarily called the x-axis and the vertical axis the y-axis. The intersection of the axes is identified with the number 0 on both axes and is called the origin. Each point on the plane is associated with a pair of real numbers (x, y) known as the x-coordinate and the y-coordinate. The coordinates measure the horizontal and vertical position of the point relative to the axes.

A 2D geometric object is a set of points in the plane. The number of points in the set that constitutes the geometric object is usually infinite. To effectively represent such an object, an equation is used to define the relation that the x- and y-coordinates of a point in the object must satisfy.

For example, a *line* (see Figure 2.3) can be represented by a polynomial equation of degree 1 (a linear equation):

Figure 2.3. A line can be represented by a linear equation.



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A *circle* centered at the origin with radius *R* is represented by the equation:

 $x^2 + y^2 = R^2$ 

More generally, an *ellipse* centered at  $(x_0, y_0)$  has the standard equation:

$$\frac{(x-x_0)^2}{a^2} + \frac{(y-y_0)^2}{b^2} = 1$$

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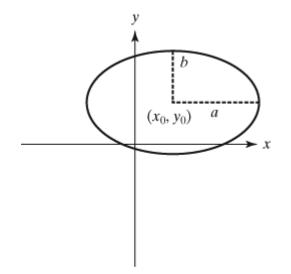
Another common type of equation to represent a curve is the *parametric equation*. Instead of an equation relating x and y, a third variable, t, is introduced. Both x and y are expressed as functions of t.

$$\begin{aligned} x &= f(t) \\ y &= g(t) \end{aligned}$$

An advantage of parametric equations is that they provide explicit functional forms for evaluating the coordinates. The ellipse shown in Figure 2.4 can also be expressed using the parametric equation:

 $x = x_0 + a\cos t$  $y = y_0 + b\sin t$ 

Figure 2.4. An ellipse can be represented by a quadratic equation. UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO



The collection of all points or coordinates is also known as a *space*. Three types of spaces are typically involved in a graphics system: *object space*, *world space*, and *device space*. Each space is usually characterized by its own coordinate system. Geometric objects in one space can be mapped to another by transformations.

An object coordinate system, also known as *local* or *modeling coordinate system*, is associated with the definition of a particular graphics object or primitive. In constructing such an object, it is usually convenient to choose a coordinate system that is natural to the object without concerning its final destination and appearance in the world space. For example, when we define a circle primitive, we may choose to have the origin of the coordinate system at the center of the circle and simply define a unit circle (a circle of radius 1). The circle can later be placed anywhere in the world space through a transformation called *translation*. Its radius can be changed to any value by scaling. It can even be transformed to an ellipse by using a nonuniform scaling.

The *world coordinate system,* or *user coordinate system*, defines a common reference space for all the objects in a graphics model. It represents the virtual world shared by the modeling and rendering subsystems. Geometric objects are placed into this space through object transforms. The rendering system takes a snapshot of the space and produces a rendered image on an output device.

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The *device coordinate system* represents the display space of an output device such as a screen or a printer. Figure 2.5 shows a typical example of such a coordinate system. The origin is located at the upper left corner, and the positive direction of the *y*-axis is pointing downward. The coordinate values are usually integers only. This choice is obviously different from the usual mathematical representation, but it is more natural for most computer display devices.

Figure 2.5. Java 2D's coordinate system originates from origin (0, 0) with the x-axis increasing rightward and the y-axis increasing downward.



By default, Java 2D's world coordinates coincide with the device coordinates. With the available transformation facilities in a graphics system, it is easy to define a different world space that may be more appropriate for a particular application.

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### 2.4. The Graphics2D Class

In Java 2D, the rendering engine is accessed through the class Graphics2D. In early versions of Java, graphics drawings are obtained through the class java.awt.Graphics. The Graphics class contains basic methods for rendering graphics primitives and controlling the rendering modes. Java 2D uses the more extensive Graphics2D class for its graphics rendering. Graphics2D extends the Graphics class to maintain compatibility with the early AWT rendering in GUI components.

Graphics and Graphics2D classes are abstract, because their implementations will necessarily be platform dependent. Consequently, you cannot directly instantiate the Graphics2D class. There are two ways to retrieve a Graphics2D object. It can be obtained as the parameter in the paintComponent method or by calling the getGraphics method. The standard approach to draw graphics in a JComponent object is to override the paintComponent method:

void paintComponent(Graphics g)

The parameter g is declared to be Graphics, but it is also a Graphics2D object. It can be cast to a Graphics2D object. The paintComponent method is called automatically by Java Virtual Machine whenever the display needs to be redrawn, such as when the window is restored after it is minimized. Therefore the drawing made in the method will appear to be persistent.

Java does not explicitly provide a "retained-mode" modeling facility for 2D graphics. The custom code in the paintComponent method may be regarded implicitly as a model for the graphics system.

Another way to obtain a reference to a Graphics2D object is to call the method getGraphics in the class Component.

Graphics getGraphics()

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Again the Graphics object returned from the method can be cast to a Graphics2D, and it can be used to perform graphics rendering. However, usually the drawings obtained this way will not be persistent.

In AWT, the Graphics class provides the methods to control all aspects of rendering. It contains methods to set colors and fonts, to translate the coordinates, to set XOR mode, and to draw primitives such as lines and ovals directly. Some of the methods in Graphics are listed below.

```
void setColor(Color c)
void setFont(Font f)
void setXORMode(Color c)
void setPaintMode()
void translate(int x, int y)
void drawLine(int x1, int y1, int x2, int y2)
void drawRect(int x1, int y1, int width, int height)
void drawOval(int x1, int y1, int width, int height)
void drawArc(int x1, int y1, int width, int height)
void drawRoundRect(int x1, int y1, int width,
    int height, int start, int arc)
void drawRoundRect(int x1, int y1,
    int width, int height, int arcW, int arcH)
void drawPolygon(int[] xPoints, int[] yPoints, int nPoints)
void fillRect(int x1, int y1, int width, int height)
```

void fillOval(int x1, int y1, int width, int height) void fillArc(int x1, int y1, int width, int height, int start, int arc) void fillRoundRect(int x1, int y1, int width, int height, int arcW, int arcH) void fillPolygon(int[] xPoints, int[] yPoints, int nPoints) void drawString(String str, int x, int y)

There is no clear separation between the modeler and the renderer in AWT. For example, a single method drawoval is responsible for both defining (modeling) an ellipse and drawing (rendering) the ellipse.

Java 2D, on the other hand, is required to handle much more sophisticated graphics objects. Therefore, instead of bundling all rendering functions into a single class, the modeling and transformation features are implemented with additional classes separated from the Graphics2D class. Graphics2D provides some generic methods such as draw(Shape) and fill(Shape) to render separately defined objects. The objects to be drawn are implemented as Shape objects. Similarly, the transformations can be constructed with the AffineTransform class. Graphics2D provides the method setTransform(AffineTransform) to set the current transformation to the separately defined transformation object. A partial list of Graphics2D methods is given below.

```
void draw(Shape s)
void fill(Shape s)
void setTransform(AffineTransform Tx)
void transform(AffineTransform Tx)
void setPaint(Paint p)
void setStroke(Stroke s)
void clip(Shape s)
void setComposite(Composite c)
void addRenderingHints(Map hints)
```

The separation of modeling and rendering is more apparent in Graphics2D. For example, to draw an ellipse you will create an instance of Ellipse2D (which implements the Shape interface) and call the draw method to render

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[Page 37]

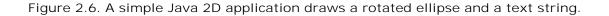
A typical Java 2D graphics program uses the JPanel class as the drawing canvas. By overriding the paintComponent method, custom painting is achieved. The associated Graphics2D object can be configured for proper settings such as colors, paints, strokes, and transformations. A graphical object is constructed as an instance of a class implementing the Shape interface. It can be rendered through the Graphics2D object.

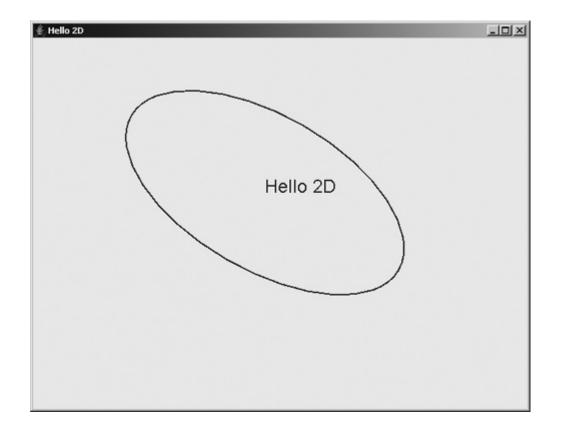
Listing 2.1 shows a simple Java 2D program. It illustrates the basic structure of a Java 2D program and the use of the Graphics2D class. The program displays a transformed circle and a text string with a blue color, as shown in Figure 2.6.

Listing 2.1. Hello2D.java

```
1 package chapter2;
 2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5 import javax.swing.*;
 6 import java.awt.geom.*;
 7
 8 public class Hello2D extends JApplet {
   public static void main(String s[]) {
9
10
       JFrame frame = new JFrame();
11
      frame.setTitle("Hello 2D");
12
       frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
13
      JApplet applet = new Hello2D();
14
      applet.init();
15
       frame.getContentPane().add(applet);
16
       frame.pack();
17
       frame.setVisible(true);
18
    }
19
20
    public void init() {
21
       JPanel panel = new Hello2DPanel();
22
       getContentPane().add(panel);
23
   }
24 }
25
26 class Hello2DPanel extends JPanel {
27
    public Hello2DPanel() {
28
       setPreferredSize(new Dimension(640, 480));
29
    }
30
31
    public void paintComponent(Graphics g) {
32
       super.paintComponent(g);
33
       Graphics2D g2 = (Graphics2D)g;
34
       g2.setColor(Color.blue);
       Ellipse2D e = new Ellipse2D.Double(-100, -50, 200, 100);
35
36
       AffineTransform tr = new AffineTransform();
37
       tr.rotate(Math.PI / 6.0);
       Shape shape = tr.createTransformedShape(e);
38
       g2.translate(300,200);
39
       g2.scale(2,2);
40
41
       g2.draw(shape);
42
       g2.drawString("Hello 2D", 0, 0);
43
   }
44 }
```







The program is written to run as both an applet and an application. The Hello2D class extends JApplet. A main method is also included that creates a JFrame window and adds an instance of Hello2D to the window. The applet contains an instance of the Hello2DPanel. The Hello2DPanel class extends the JPanel class and overrides the paintComponent method to draw the graphics display.

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method of the superclass is invoked first to handle the necessary cleanup operations. The Graphics object g is cast into a Graphics2D object g2 to use the Java 2D features (line 33). The parameter g is declared as Graphics, but it is actually a Graphics2D object in all versions of Java that include Java 2D. The drawing color is then set to blue by calling the method setColor() in the Graphics object. More sophisticated drawing attributes that exist in the Graphics2D class will be introduced later in this chapter.

An ellipse is created using the Ellipse2D.Double class (line 35). A rotation of p/6 is constructed as an AffineTransfrom object. The rotation is an object transformation applied only to the ellipse. The transformed shape is obtained by calling the createTransformedShape method of the AffineTransform object.

The viewing transformation consists of a translation by (300, 200) and a scaling of factor 2. The transformation is achieved by directly calling the methods translate and scale in the Graphics2D object.

Using the draw method the rotated ellipse is drawn to the screen (line 41). A string "Hello 2D" is drawn with the method drawString in the Graphics2D object.

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## 2.5. Graphing Equations

Mathematical equations are important in modeling graphics objects. Conversely, graphical plots offer a useful tool for studying mathematical functions and equations. Plotting an equation is a simple graphics application.

A simple way to graph an equation is to generate a sequence of coordinates satisfying the equation and then plot the points. For a function of the form y = I(x), it is straightforward to choose a set of *x*-coordinates and calculate the corresponding *y*-coordinates. An equation of the implicit form F(x,y) = 0 is more difficult to calculate, because, given a value of the *x*- (or *y*-) coordinate, it would in general require solving an equation to find the other coordinate. Certain equations can be expressed in the parametric form that is convenient for calculations.

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A sample run of the program is shown in Figure 2.7.

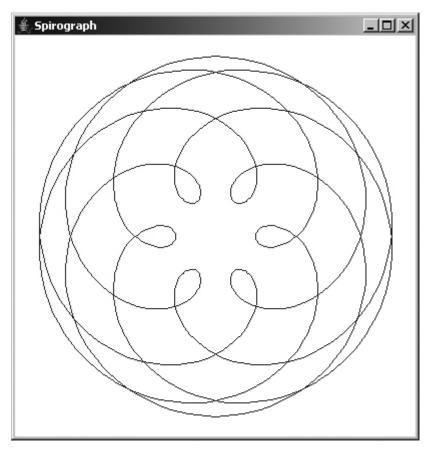


Figure 2.7. A spirograph plot using a parametric equation.

Listing 2.2 plots a spirograph based on a parametric equation. Consider a circle rolling on another circle. The curve formed by a pen attached to the rolling circle is called an *epicycloid* or *spirograph*. Using the angle of rolling as the parameter, a parametric equation can be derived:

 $\begin{aligned} x &= (r_1 + r_2) \cos t - \rho \cos((r_1 + r_2)t/r_2) \\ y &= (r_1 + r_2) \sin t - \rho \sin((r_1 + r_2)t/r_2) \end{aligned}$ 

The radii of the fixed circle and the rolling circle are denoted by r1 and r2. The offset of the pen position relative to the center of the rolling circle is p. A variety of curves can be generated by changing the values of r1, r2, and p.

Listing 2.2. Spirograph.java

(This item is displayed on pages 39 - 40 in the print version)

```
1 package chapter2;
 2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5 import javax.swing.*;
 6 import java.awt.geom.*;
 7
 8 public class Spirograph extends JApplet {
 9
    public static void main(String s[]) {
10
       JFrame frame = new JFrame();
11
       frame.setTitle("Spirograph");
12
       frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
13
       JApplet applet = new Spirograph();
14
       applet.init();
15
       frame.getContentPane().add(applet);
16
       frame.pack();
17
       frame.setVisible(true);
18
    }
19
[Page 40]20
           public void init() {
21
       JPanel panel = new SpiroPanel();
22
       getContentPane().add(panel);
23
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24
  }
25
26 class SpiroPanel extends JPanel{
27
   int nPoints = 1000;
28
    double r1 = 60;
29
    double r2 = 50;
30
    double p = 70;
31
32
    public SpiroPanel() {
33
       setPreferredSize(new Dimension(400, 400));
34
       setBackground(Color.white);
35
    }
36
37
    public void paintComponent(Graphics g) {
38
       super.paintComponent(g);
39
       Graphics2D g2 = (Graphics2D)g;
40
       g2.translate(200,200);
41
      int x1 = (int)(r1 + r2 - p);
42
      int y1 = 0;
43
       int x2;
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          REGIST
44
45
       for (int i = 0; i < nPoints; i++)</pre>
        double t = i * Math.PI / 90;
46
```

```
47  x2 = (int)((r1+r2)*Math.cos(t)-p*Math.cos((r1+r2)*t/r2));
48  y2 = (int)((r1+r2)*Math.sin(t)-p*Math.sin((r1+r2)*t/r2));
49  g2.drawLine(x1, y1, x2, y2);
50  x1 = x2;
51  y1 = y2;
52  }
53  }
54 }
```

The SpiroPanel class is defined as a subclass of JPanel. The plotting is performed inside the paintComponent method (line 37). The variable nPoints defines the number of points to evaluate. The variables for the parametric equation are set to the values:

r1 = 60r2 = 50p = 70

The parameter t is initialized to 0 and incremented by p/90 for each point. The x- and y-coordinates are calculated based on the parametric equation. A line segment is drawn between two adjacent points.

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[Page 40 (continued)]

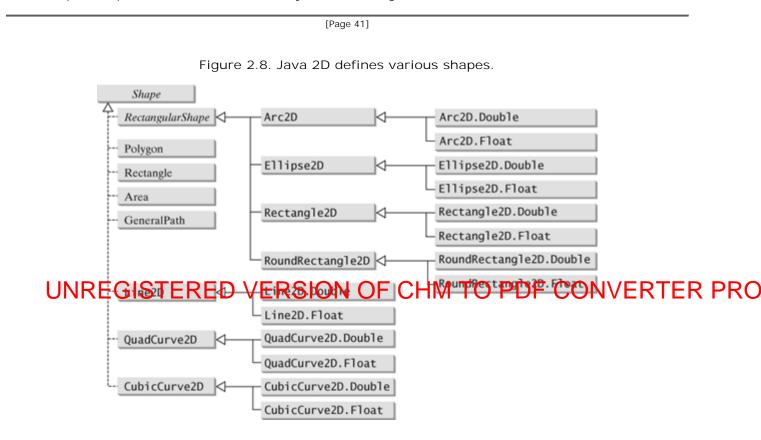
#### Next 🕨

### 2.6. Geometric Models

2D graphics objects that constitute a virtual world model may include geometric shapes, text objects, and images. More detailed discussions on fonts, texts, and images will be presented later in Chapters 3 and 4. This section will focus on the geometric objects.

### 2.6.1. Shapes

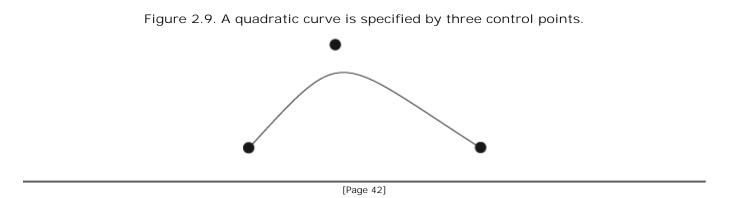
In Java 2D, a geometric object can be rendered by Graphics2D if it implements the Shape interface. Graphics2D contains draw(Shape s) and fill(Shape s) methods that draws the outline of the shape or fills the interior of the shape. Java 2D provides facilities to construct basic shapes and to combine them to form more complex shapes. The Shape class hierarchy is shown in Figure 2.8.



The classes Line2D, QuadCurve2D, CubicCurve2D, Rectangle2D, RoundRectangle2D, Arc2D, and Ellipse2D are abstract classes. Each has two concrete *inner subclasses* named *X.Double* and *X.Float* that represent the coordinates using double or float data types, respectively. For example, Line2D.Double and Line2D.Float are subclasses of Line2D and they are also inner classes of Line2D. The two inner subclasses both represent lines, but they differ in their data types for coordinate representation. To create a Line2D object with double data type, you may use the following constructor:

QuadCurve2D represents a *quadratic curve*, which is mathematically defined as a quadratic polynomial and specified by three control points. The first and last control points are the endpoints of the curve. The middle control point usually is not on the curve but instead defines the trend of the quadratic curve, as shown in Figure 2.9. A QuadCurve2D object may be created using a constructor as shown below. The coordinates of the three control points are specified with the six parameters.

QuadCurve2D quad = new QuadCurve2D.Double(x1, y1, x2, y2, x3, y3);



CubicCurve2D represents a *cubic Bzier curve*, which is defined as a cubic polynomial and specified by four control points. As in the quadratic curves, the first and last control points are the endpoints of the curve. The middle two control points define the shape of the curve but are not necessarily on the curve, as shown in Figure 2.10. An example of constructing a CubicCurve2D object is given below.

CubicCurve2D cubic = **new** CubicCurve2D.Float(x1,y1,x2,y2,x3,y3,x4,y4);

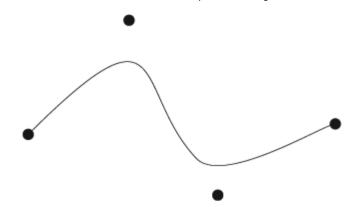


Figure 2.10. A cubic Bzier curve is specified by four control points.

The Rectangle2D class defines *rectangles* with horizontal and vertical sides. The Rectangle class defined in JDK 1.1 has been integrated into Java 2D. Rectangle is now a subclass of Rectangle2D. Rectangle uses integer coordinates. Rectangle2D.Double and Rectangle2D.Float, the other subclasses of Rectangle2D, use double and float, respectively, to represent coordinates. The following code fragment creates three Rectangle2D objects with different data type. The upper left corner of the rectangles is (20, 30) and the dimension is (100, 80).

```
Rectangle2D ri = new Rectangle(20,30,100,80);
Rectangle2D rd = new Rectangle2D.Double(20.0,30.0,100.0,80.0);
Rectangle2D rf = new Rectangle2D.Float(20f,30f,100f,80f);
```

RoundRectangle2D defines rectangles with *round corners*. The constructor for a RoundRectangle2D object may contain two more parameters that specify the width and height of the arch. For example, the arch in the following round rectangle has dimension 5 by 5:

RoundRectangle2D rrect = new RoundRectangle2D.Double(20,30,100,80,5,5);

Ellipse2D represents a full *ellipse*. The parametric equation of the ellipse centered at the origin can be written as

 $X = \partial \cos$ 

y = b sin

The parameter varies from 0 to 2p or 0 to 360 degrees. The location and size of an Ellipse2D object are specified using its bounding rectangle. An Ellipse2D object with float data type can be created with the following constructor. The upper left corner of the bounding rectangle is (20, 30) and the dimension is (100, 80).

Ellipse2D ellipse = new Ellipse2D.Float(20f, 30f, 100f, 80f);

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Arc2D defines an elliptic *arc*. The underlying ellipse is defined in the same way as Ellipse2D and can be represented with the same parametric equation. The portion of the arc is specified by a range on the parameter . Arc2D defines three ways to close an arc: OPEN, CHORD, and PIE. For example, the following code constructs an arc with the parameter ranging from = 30 degrees to = 75 degrees, and the arc is closed with a pie shape.

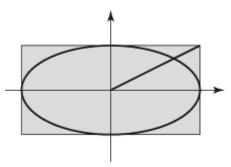
## Arc2D UNREGISTERED VERSION OF GHM2TOPPDF CONVERTER PRO

Note



The angle is specified in degrees instead of radians. The parameter in general does not correspond to the radial angle of a given point. For example, when = 45 degrees, the line from the center to the point on the ellipse corresponds to the diagonal of the bounding rectangle, as shown in Figure 2.11. Clearly the angle of the line is not 45 degrees, unless the ellipse is a circle.

Figure 2.11. The geometric angle of the radial line for a point on the ellipse is not necessarily equal to the parameter value.



The classes Rectangle2D, RoundRectangle2D, Ellipse2D, and Arc2D provide only for the construction of objects that have their bounding rectangles parallel to the x- and y- axes. However, this is not a severe limitation, because the general "rotated" versions of these objects can be obtained easily with proper transformations. A detailed discussion of transformations will be given in the next chapter.

The Polygon class, similar to the Rectangle class, comes from the old AWT, and it supports only integer coordinates. To construct a Polygon object you may use the following constructor:

Polygon(int[] xcoords, int[] ycoords, int npoints);

The two integer arrays define the vertices of the polygon. The first point and last point are joined to form a closed path.

#### 2.6.2. Example

Listing 2.3 is an interactive drawing program. It allows a user to draw various geometric shapes in Java 2D, including rectangles, round rectangles, ellipses, arcs, lines, quadratic curves, cubic curves, and polygons (Figure 2.12). A menu is used to select drawing shapes, and the user draws a particular shape on the screen by dragging the mouse. The drawings are persistentthat is, they will not disappear when the window is repainted.

[Page 44]

Listing 2.3. DrawShapes.java

(This item is displayed on pages 44 - 48 in the print version)

```
1 package chapter2;
2
 3 import java.awt.*;
 4 import java.awt.geom.*;
 5 import java.awt.event.*;
 6 import java.util.*;
 7 import javax.swing.*;
8
 9 public class DrawShapes extends JApplet implements ActionListener {
     public static void main(String s[]) {
10
11
       JFrame frame = new JFrame();
12
       frame.setTitle("Drawing Geometric Shapes");
13
        frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
14
       JApplet applet = new DrawShapes();
15
       applet.init();
16
       frame.getContentPane().add(applet);
17
       frame.pack();
```

```
18
        frame.setVisible(true);
     }
19
20
21
      JavaDraw2DPanel panel = null;
22
23
     public void init() {
24
       JMenuBar mb = new JMenuBar();
25
        setJMenuBar(mb);
26
       JMenu menu = new JMenu("Objects");
27
       mb.add(menu);
28
       JMenuItem mi = new JMenuItem("Rectangle");
29
       mi.addActionListener(this);
30
       menu.add(mi);
31
       mi = new JMenuItem("RoundRectangle");
32
       mi.addActionListener(this);
33
       menu.add(mi);
34
       mi = new JMenuItem("Ellipse");
35
       mi.addActionListener(this);
36
       menu.add(mi);
37
       mi = new JMenuItem("Arc");
38
       mi.addActionListener(this);
39
       menu.add(mi);
 40
       mi = new JMenuItem("Line");
       mi.addActionListener(this);
 41
 42
       menu.add(mi);
 43
       mi = new JMenuItem("QuadCurve");
 44
       mi.addActionListener(this);
 45
       menu.add(mi);
 46
       mi = new JMenuItem("CubicCurve");
 47
       mi.addActionListener(this);
 48
       menu.add(mi);
 49
       mi = new JMenuItem("Polygon");
50
       mi.addActionListener(this);
51
       menu.add(mi);
52
       panel = new JavaDraw2DPanel();
53
        getContentPane().add(panel);
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54
55
56
      public void actionPerformed(ActionEvent ev) {
57
        String command = ev.getActionCommand();
58
        if ("Rectangle".equals(command)) {
59
          panel.shapeType = panel.RECTANGLE;
              } else if ("RoundRectangle".equals(command)) {
[Page 45] 60
          panel.shapeType = panel.ROUNDRECTANGLE2D;
61
        } else if ("Ellipse".equals(command)) {
 62
63
          panel.shapeType = panel.ELLIPSE2D;
 64
        } else if ("Arc".equals(command)) {
 65
          panel.shapeType = panel.ARC2D;
 66
        } else if ("Line".equals(command)) {
 67
          panel.shapeType = panel.LINE2D;
 68
        } else if ("QuadCurve".equals(command)) {
 69
          panel.shapeType = panel.QUADCURVE2D;
        } else if ("CubicCurve".equals(command)) {
 70
 71
          panel.shapeType = panel.CUBICCURVE2D;
 72
        } else if ("Polygon".equals(command)) {
 73
          panel.shapeType = panel.POLYGON;
 74
         REGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 75
 76 }
```

```
77
 78 class JavaDraw2DPanel extends JPanel
 79
      implements MouseListener, MouseMotionListener {
 80
     private Vector shapes = new Vector();
 81
     static final int RECTANGLE = 0;
    static final int ROUNDRECTANGLE2D = 1;
 82
 83
    static final int ELLIPSE2D = 2i
    static final int ARC2D = 3;
 84
    static final int LINE2D = 4i
 85
 86 static final int OUADCURVE2D = 5;
 87
    static final int CUBICCURVE2D = 6;
 88
    static final int POLYGON = 7;
 89
    static final int GENERAL = 8;
 90
    static final int AREA = 9;
 91
 92
    int shapeType = RECTANGLE;
 93
    // vector of input points
 94
    Vector points = new Vector();
 95
    int pointIndex = 0;
 96
    Shape partialShape = null;
 97
    Point p = null;
 98
 99
    public JavaDraw2DPanel() {
100
      super();
101
       setBackground(Color.white);
102
       setPreferredSize(new Dimension(640, 480));
103
       addMouseListener(this);
104
        addMouseMotionListener(this);
105
    }
106
107
    public void paintComponent(Graphics g) {
108
       super.paintComponent(g);
109
        Graphics2D g2 = (Graphics2D)g;
110
        for (int i = 0; i < shapes.size(); i++) {</pre>
111
          Shape s = (Shape)shapes.get(i);
112
          g2.draw(s);
113
       }
114
    }
115
    public void mouseClicked(MouseEvent ev) {
116
    }
117
118
    public void mouseEntered(MouseEvent ev) {
119
     }
120
[Page 46]121
           public void mouseExited(MouseEvent ev) {
122 }
123
124
     public void mousePressed(MouseEvent ev) {
125
       points.add(ev.getPoint());
126
       pointIndex++;
       p = null;
127
128
      }
129
130
     public void mouseReleased(MouseEvent ev) {
131
       Graphics g = getGraphics();
132
       Point p1 = (Point)(points.get(pointIndex-1));
133
       p = ev.getPoint();
134
       Shape s = null;
135
       switch (shapeType) {
```

```
136
          case RECTANGLE:
137
            s = new Rectangle(p1.x, p1.y, p.x-p1.x, p.y-p1.y);
138
           break;
139
          case ROUNDRECTANGLE2D:
140
            s = new RoundRectangle2D.Float(p1.x, p1.y,
141
           p.x-pl.x, p.y-pl.y, 10, 10);
142
           break;
143
          case ELLIPSE2D:
144
            s = new Ellipse2D.Float(p1.x, p1.y, p.x-p1.x, p.y-p1.y);
145
           break;
146
         case ARC2D:
            s = new Arc2D.Float(pl.x, pl.y, p.x-pl.x,
147
148
           p.y-p1.y, 30, 120, Arc2D.OPEN);
149
           break;
150
         case LINE2D:
151
           s = new Line2D.Float(p1.x, p1.y, p.x, p.y);
152
           break;
153
         case QUADCURVE2D:
154
           if (pointIndex > 1) {
155
              Point p2 = (Point)points.get(0);
156
              s = new QuadCurve2D.Float(p2.x, p2.y, p1.x, p1.y, p.x, p.y);
157
           }
158
           break;
         case CUBICCURVE2D:
159
160
           if (pointIndex > 2) {
              Point p2 = (Point)points.get(pointIndex-2);
161
162
              Point p3 = (Point)points.get(pointIndex-3);
163
              s = new CubicCurve2D.Float(p3.x, p3.y, p2.x, p2.y,
164
             pl.x, pl.y, p.x, p.y);
165
           }
166
           break;
167
          case POLYGON:
168
           if (ev.isShiftDown()) {
169
             s = new Polygon();
170
              for (int i = 0; i < pointIndex; i++)</pre>
                ((Polygon)s).addPoint(((Point)points.get(i)).x,
171
              GISTEREDEVERSION OF CHM TO PDF CONVERTER PRO
172
173
174
           }
175
176
        }
177
       if (s != null) {
178
         shapes.add(s);
179
         points.clear();
180
         pointIndex = 0;
[Page 47]181
               p = null;
         repaint();
182
183
       }
184
     }
185
186
     public void mouseMoved(MouseEvent ev) {
187
     }
188
189
      public void mouseDragged(MouseEvent ev) {
190
        Graphics2D g = (Graphics2D)getGraphics();
191
        g.setXORMode(Color.white);
       Point pl (Point points g
192
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193
194
         case RECTANGLE:
```

```
195
            if (p != null) g.drawRect(p1.x, p1.y, p.x-p1.x, p.y-p1.y);
196
            p = ev.getPoint();
197
            g.drawRect(pl.x, pl.y, p.x-pl.x, p.y-pl.y);
198
            break;
199
          case ROUNDRECTANGLE2D:
200
            if (p != null) g.drawRoundRect(p1.x, p1.y,
201
            p.x-pl.x, p.y-pl.y,10,10);
202
            p = ev.getPoint();
203
            g.drawRoundRect(pl.x, pl.y, p.x-pl.x, p.y-pl.y,10,10);
204
            break;
205
          case ELLIPSE2D:
            if (p != null) g.drawOval(p1.x, p1.y, p.x-p1.x, p.y-p1.y);
206
207
            p = ev.getPoint();
208
            g.drawOval(p1.x, p1.y, p.x-p1.x, p.y-p1.y);
209
            break;
210
          case ARC2D:
211
            if (p != null) g.drawArc(pl.x, pl.y, p.x-pl.x, p.y-pl.y, 30, 120);
212
            p = ev.getPoint();
            g.drawArc(pl.x, pl.y, p.x-pl.x, p.y-pl.y, 30, 120);
213
214
            break;
215
          case LINE2D:
216
          case POLYGON:
217
            if (p != null) g.drawLine(p1.x, p1.y, p.x, p.y);
218
            p = ev.getPoint();
219
            g.drawLine(pl.x, pl.y, p.x, p.y);
220
            break;
221
          case QUADCURVE2D:
222
            if (pointIndex == 1) {
223
              if (p != null) g.drawLine(p1.x, p1.y, p.x, p.y);
224
              p = ev.getPoint();
225
              g.drawLine(pl.x, pl.y, p.x, p.y);
226
            } else {
227
              Point p2 = (Point)points.get(pointIndex-2);
228
              if (p != null) g.draw(partialShape);
229
              p = ev.getPoint();
230
              partialShape = new QuadCurve2D.Float(p2.x, p2.y,
231
              pl.x, pl.y, p.x, p.y);
232
              g.draw(partialShape);
233
234
            break;
          case CUBICCURVE2D:
235
236
            if (pointIndex == 1) {
237
               if (p != null) g.drawLine(p1.x, p1.y, p.x, p.y);
238
              p = ev.getPoint();
239
               g.drawLine(pl.x, pl.y, p.x, p.y);
240
            } else if (pointIndex == 2) {
[Page 48]241
                      Point p2 = (Point)points.get(pointIndex-2);
242
              if (p != null) g.draw(partialShape);
243
              p = ev.getPoint();
244
               partialShape = new QuadCurve2D.Float(p2.x, p2.y,
245
              pl.x, pl.y, p.x, p.y);
246
              g.draw(partialShape);
247
            } else {
248
               Point p2 = (Point)points.get(pointIndex-2);
249
               Point p3 = (Point)points.get(pointIndex-3);
250
              if (p != null) g.draw(partialShape);
251
              p = ev.getPoint();
252
              partialShape = new CubicCurve2D.Float(p3.x, p3.y,
253
              p2.x, p2.y, p1.x, p1.y, p.x, p.y);
```

254	g.draw(partialShape);
255	}
256	break;
257 }	
258 }	
259 }	
	8

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Figure 2.12. Drawing basic shapes defined in Java 2D.

This is a simple drawing program that does not have all the supporting features, such as file I/O, but does have the essential functionality of a typical drawing package. It allows users to draw an arbitrary number of basic shapes with the mouse operations.

The DrawShapes class defines an applet with a menu. The type of shape to be drawn is selected from the menu. The JavaDraw2DPanel, a subclass of JPanel, implements the actual drawing logic. The variable panel holds an instance of the JavaDraw2DPanel (line 52). The menu selection is handled in the DrawShapes class. The action event handler sets the selected shape to the shapeType variable in panel.



drawing of a particular figure is completed, it is added to the vector. Because the Vector class defines a dynamic data structure, the number of shapes is virtually unlimited. The paintComponent method is surprisingly simple. It traverses the vector and calls the draw method on each shape regardless of the types of shapes (lines 110112). This elegant approach is made possible by the powerful polymorphism support of Java and the Graphics2D class.

The JavaDraw2DPanel class handles the mouse events to implement the drawing functions. The details of drawing a shape depend on the type of the shape. Rectangles, rounded rectangles, ellipses, arcs, and lines are defined by their bounding rectangles. They are drawn by dragging the mouse from one corner of the bounding rectangle to the opposite. Quadratic curves are defined by three control points, and they are drawn by dragging the mouse twice to define two line segments. Cubic curves are defined by four control points and are constructed with three mouse drags. The polygons may have arbitrary numbers of points and are constructed by dragging the mouse repeatedly and terminating with a double click.

During the construction of a shape, "rubber-banding" is implemented to provide a visual clue. As the user drags the mouse, the shape corresponding to the current mouse location is displayed and updated continuously. This is done inside the mouse event handlers and through the use of XOR drawing mode. When the mouse button is pressed, the current mouse location is saved to the vector points (line 125). When the mouse is dragged, a Graphics2D object is retrieved (line 190) and its XOR mode is set by calling the setXORMode method (line 191). A temporary shape is drawn based on the shape type and current points. This temporary shape is erased by subsequent calls and replaced with new a temporary shape, thus creating a dynamic "rubber-banding" effect. In the XOR mode, drawing the same figure a second time will erase the first drawing. When the mouse is released (line 130), a new point is created. If enough points are present for the current shape type, a new complete shape is constructed and added to the shapes vector. If the number of points is not enough for the shape, a partial shape is defined.

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### 2.7. Constructive Area Geometry

One way to create more complex shapes is to combine several existing shapes. This is known as constructive area geometry. The class Area is designed to perform constructive area geometry. Four operations are supported: union, intersection, difference, and symmetric difference. These set-theoretic operations are performed on the regions of two areas, resulting in a new area. The union of two sets consists of all points that belong to either set. The intersection of two sets consists of points that belong to both sets. The difference of two sets consists of points that belong to the first set but not the second set. The symmetric difference of two sets consists of the points that belong to exactly one of the two sets. An Area object can be constructed from any Shape object using the following constructor:

Area(Shape s)

The four operations can be performed using the following methods of an Area object:

```
void add(Area a)
void intersect(Area a)
void subtract(Area a)
void exclusiveOr(Area a)
```

The results of the operations are placed in the current Area object. The second Area object passed as a parameter to the methods will not be altered by the operations.

Listing 2.4 shows a program demonstrating the effects of four operations of constructive area geometry. Two shapes are combined using the four operations to obtain four new shapes (Figure 2.13).

[Page 50]

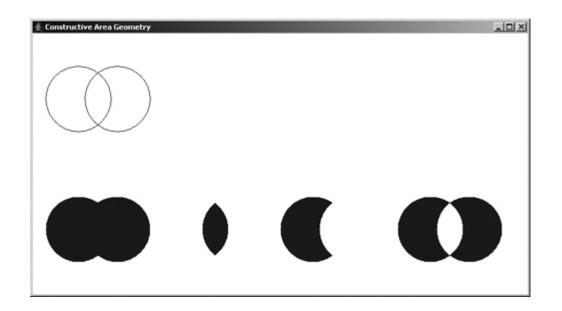
#### Listing 2.4. AreaGeometry.java INREGISTERED VERSION OF CHM TO PDF CONVERTER PRO 1 package chapter2; 2 3 import java.awt.\*; 4 import java.awt.event.\*; 5 import javax.swing.\*; 6 import java.awt.geom.\*; 7 8 public class AreaGeometry extends JApplet { 9 public static void main(String s[]) { 10 JFrame frame = new JFrame(); 11 frame.setTitle("Constructive Area Geometry"); 12 frame.setDefaultCloseOperation(JFrame.EXIT\_ON\_CLOSE); 13 JApplet applet = new AreaGeometry(); 14 applet.init(); 15 frame.getContentPane().add(applet); 16 frame.pack(); 17 frame.setVisible(true); 18 } 19 NREGISTERED VERSION OF CHM TO PDF CONVERTER PRO 20 21 22 getContentPane().add(panel);

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```
23
   }
24 }
25
26 class AreaPanel extends JPanel {
27
   public AreaPanel() {
28
     setPreferredSize(new Dimension(760, 400));
29
   }
30
31
   public void paintComponent(Graphics g) {
      Graphics2D g2 = (Graphics2D)g;
32
       Shape s1 = new Ellipse2D.Double(0, 0, 100, 100);
33
      Shape s2 = new Ellipse2D.Double(60, 0, 100, 100);
34
35
     Area al;
36
      Area a2 = new Area(s2);
37
      g2.translate(20, 50);
      g2.draw(s1);
38
39
      g2.draw(s2);
40
      g2.translate(0,200);
41
      al = new Area(s1);
42
      al.add(a2);
43
      g2.fill(a1);
44
      g2.translate(180,0);
45
      al = new Area(s1);
46
      al.intersect(a2);
47
      g2.fill(a1);
48
      g2.translate(180,0);
49
      al = new Area(s1);
50
      al.subtract(a2);
51
     g2.fill(a1);
52
     g2.translate(180,0);
53
     al = new Area(sl);
     al.exclusiveOr(a2);
54
55
       g2.fill(a1);
56
   }
57 }
```

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Figure 2.13. Top row: Two shape objects. Bottom row: The results of four area operations: add, intersect, subtract, exclusiveOr.



Two overlapping circles s1 and s2 are used as the original shapes, and they are drawn on the top of the screen. Area objects a1 and a2 are created from the shapes (lines 35–36). Each of the four operations is applied to a1 and a2 by calling the methods add, intersect, subtract, and exclusiveOr. The resulting areas are displayed as filled shapes in the bottom row (lines 42–55). Because the Area class implements the Shape interface, the Area objects can be passed directly to the fill method of the Graphics2D object.

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### 2.8. General Path

The Graphics2D engine internally uses five basic types of curve segments or operations to render the borders of any shape. The Shape interface provides methods to retrieve a PathIterator that is an interface describing the path of the shape border using the five types of segments. PathIterator defines the five segment constants:

SEG\_MOVETO SEG\_LINETO SEG\_QUADTO SEG\_CUBICTO SEG\_CLOSE

A powerful way to construct custom shapes is to use the GeneralPath class, which directly supports the path construction with the five basic curve segments known to Graphics2D. The following methods in the GeneralPath class perform the segment constructions corresponding to the five segment types:

```
void moveTo(float x, float y);
void lineTo(float x, float y);
void quadTo(float x1, float y1, float x2, float y2);
void curveTo(float x1, float y1, float x2,
float y2, float x3, float y3);
void closePath();
```

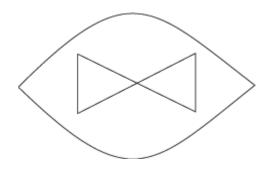
The process of the path construction can be viewed as drawing with a "pen." At any moment, the pen has a "current location." The moveTo method moves the pen to the new location (x, y) without drawing anything. The lineTo method draws a line from the current location to the point (x, y), and the pen takes the new point as its current location. The quadTo method draws a quadratic curve from the current location to  $(x_2, y_2)$  using  $(x_1, y_1)$  as the middle control point. The curveTo method draws a cubic curve from the current point to  $(x_2, y_2)$  using  $(x_1, y_1)$  and  $(x_2, y_2)$  as its two middle control points. The closePath method draws a line back to the point defined by the last moveTo method.

#### [Page 52]

For example, the following code segment constructs the shape shown in Figure 2.14.

```
GeneralPath path = new GeneralPath();
path.moveTo(-2f, 0f);
path.quadTo(0f, 2f, 2f, 0f);
path.quadTo(0f, -2f, -2f, 0f);
path.moveTo(-1f, 0.5f);
path.lineTo(1f, -0.5f);
path.lineTo(1f, -0.5f);
path.lineTo(1f, -0.5f);
path.closePath();
```

Figure 2.14. A shape defined by a GeneralPath object.



The path defines the boundary or outline of a shape. To completely define the shape, however, we must specify what constitutes the interior or the exterior of the shape. This information is needed, for example, in drawing a filled figure of the shape. Because multiple regions with complicated relationships may be formed from the path, the interior region problem is not always trivial. The *winding rules* define the conditions in which a region is considered inside the shape. Two winding rules are defined by PathIterator:

WIND\_EVEN\_ODD WIND\_NON\_ZERO

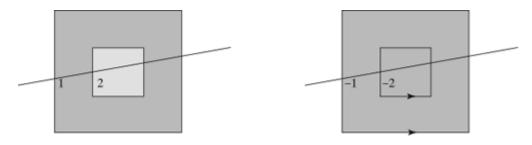
To determine whether a particular region formed by the path is in the interior, draw a line through the region and consider the number of crossings with the path from the outside to reach the region. With the *even-odd rule*, the region is in the interior if the number of crossings is odd and exterior if the number is even. Essentially the path is considered as the boundary separating the interior from the exterior, and consequently the designation of interior and exterior alternates every time the line crosses the path.

With the *nonzero rule*, the direction of the path crossing is taken into consideration, and the crossing number can be positive or negative. If the line crosses the path from left to right as you view it in the direction of the path, the crossing number is increased by 1, otherwise it is decreased by 1. The region is interior if the signed crossing number is not zero. The nonzero rule essentially defines the left side of the path, when you move along the path, as the interior and the right side as the exterior.

For example, Figure 2.55 shows a path that consists of two squares. With the even odd-rule, the inner square region of the object of the objec

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Figure 2.15. Even–odd rule and nonzero rule for interior definition.

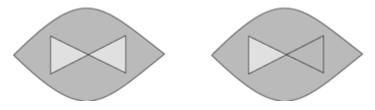


## Another example GISETIERED VERSION OF LOOP OF LIE CONTRACTOR IN THE REGISTIER PRO

be in the exterior. They are holes in the curved region. With the nonzero rule, however, only one triangle is

considered a hole. The triangle on the right is considered to be inside, because the orientation of its path is in the same direction as the outer path and the crossing numbers do not cancel out as a line goes through them.

Figure 2.16. Left: Even–odd rule. Right: Nonzero rule.



The program in Listing 2.5 shows the construction of shapes using the GeneralPath and the effects of the winding rules. Two shapes are created, and they are displayed in three different styles: path only, even-odd rule, and nonzero rule (Figure 2.17).

#### Listing 2.5. CustomPath.java

(This item is displayed on pages 53 - 54 in the print version)

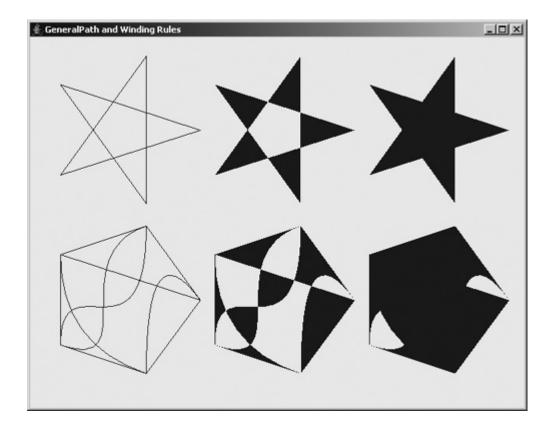
```
1 package chapter2;
 2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5 import javax.swing.*;
 6 import java.awt.geom.*;
 7
 8 public class CustomPath extends JApplet {
 9
    public static void main(String s[]) {
10
       JFrame frame = new JFrame();
11
       frame.setTitle("GeneralPath and Winding Rules");
12
        frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
13
       JApplet applet = new CustomPath();
14
       applet.init();
15
       frame.getContentPane().add(applet);
16
       frame.pack();
17
       frame.setVisible(true);
18
    }
19
20
    public void init() {
21
       JPanel panel = new PathPanel();
22
       getContentPane().add(panel);
23
     }
24 }
25
[Page 54]26 class PathPanel extends JPanel {
27
     public PathPanel() {
28
       setPreferredSize(new Dimension(640, 480));
29
     }
30
    public void paintComponent(Graphics g) {
31
32
       super.paintComponent(g);
33
       Graphics2D g2 = (Graphics2D)g;
34
       GeneralPath path = new GeneralPath(GeneralPath.WIND_EVEN_ODD);
35
       float x0 = 1.0f;
```



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Figure 2.17. General paths and regions formed with the even–odd rule and the nonzero rule.



Two shapes are constructed with the GeneralPath class. The star is formed entirely by line segments. The vertices of the star are calculated by dividing a circle into five equally spaced parts (lines 35–44). The method reset clears the path in a GeneralPath object (line 62). The other shape is a pentagon with several segments of lines, quadratic curves, and cubic curves. Three versions of each shape are displayed in three columns. First the draw method is called to draw the outline path of the shape (lines 55, 78). Then the winding rule of the shape is set to even–odd and the fill method is called to display the shape with filled interior (lines 57, 81). Finally the winding rule is changed to nonzero and the shape is displayed with a filled interior again in the third column (lines 60, 84). It is clear that the nonzero winding rule will often yield more interior regions than the even–odd rule.

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#### [Page 55 (continued)]

### Key Classes and Methods

- javax.swing.JComponent.paintComponent(Graphics) A method usually overridden to perform custom painting for the component.
- java.awt.Graphics2D A class providing an interface to the Java 2D rendering engine.
- java.awt.Graphics2D.draw(Shape) A method to draw the outlines of a shape.
- java.awt.Graphics2D.fill(Shape) A method to fill the interiors of a shape.
- java.awt.Shape An interface for 2D geometric shapes.
- java.awt.geom.GeneralPath A class to define a general 2D contour using all segment types in the Shape interface.
- java.awt.geom.Area A class for constructive area geometry.

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### Key Terms coordinate system

A method to associate geometric points with algebraic quantities of ordered tuples of numbers.

### parametric equation

A set of equations that express coordinate variables as functions of parameters.

#### world space

A common reference coordinate space for a graphics model.

#### object space

A local coordinate space associated with an individual object.

#### device space

A coordinate space used by a specific output device.

#### constructive area geometry

A method to create new geometric shapes by using set operations such as union and intersection on the areas of existing shapes.

### winding rule

A rule to determine the interior regions with given contours.

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### Chapter Summary

- In this chapter we discuss the basic principles of 2D graphics systems and Java 2D programming. A typical 2D graphics rendering pipeline involves three different coordinate spaces. In an object space, various visual objects are defined in a local coordinate system convenient for object modeling. Through object transformations the object spaces are mapped into a world space that is a common reference coordinate system for all objects. The graphics scene modeled in the world space is mapped to a device space for display. This transformation from the world space to the device space is known as the *viewing transformation*.
- A 2D curve can often be represented as an equation. Parametric equations are convenient for graphics applications.
- The geometric model of a visual object is constructed from primitive elements and constructive operations. Java 2D provides a rich family of graphics primitives, including line, rectangle, rounded rectangle, ellipse, arc, quadratic curve, and cubic curve. The shape interface provides a general framework for the geometric descriptions.
- Constructive area geometry is a technique to create new shapes based on operations on existing areas. Java 2D supports four set-theoretical operations for constructive area geometry.
- Five basic operations are recognized in the Shape interface to define a path with different segments. The GeneralPath class provides direct access to the five segment types. Two winding rules are available to determine the interior of a region.

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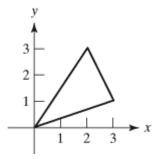
### **Review** Questions

- 2.1 What are the differences between object transformations and viewing transformations?
- 2.2 Plot the following points in a 2D coordinate system:

(1, 3), (-2,1.5), (0, -2), (0, 0)

2.3 Find the coordinates of the vertices of the triangle in Figure 2.18.

Figure 2.18. A triangle for Question 2.3. (This item is displayed on page 57 in the print version)

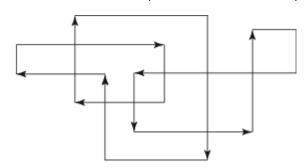


- 2.4 Write the Java code to construct an ellipse of width 80 and height 100 centered at (100, 300).
- 2.5 Find the actual angle spanned by the following arc: new Arc2D.Float(0, 0, 100, 200, 0, 45);

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- 2.6 Use the GeneralPath class to construct a shape of regular octagon.
- 2.7 Determine the interior of the shape in Figure 2.19 using the even–odd rule.

Figure 2.19. Define shape interior from the path.



2.8 Determine the interior of the shape in Figure 2.19 using the nonzero rule.

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### **Programming Exercises**

- 2.1 Write a Java program to plot the following parametric equation:
  - $\begin{array}{rcl} \mathcal{X} &= & \mathcal{t}^2 \\ \mathcal{Y} &= & \mathcal{t}^3 \end{array}$
- 2.2 Write a Java program to plot the following parametric equation:
  - $x = 20t\cos t$
  - $y = 20t \sin t$
  - $0 \leq t \leq 8p$
- 2.3 Write a Java program to display a square centered at the origin and rotated by 45°.
- 2.4 Write a Java program to draw an 8 x 8 chessboard.
- 2.5 Write a Java program to display the accompanying filled shape (Figure 2.20) using constructive area geometry.

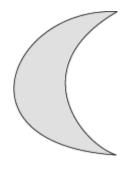


Figure 2.20. A moon shape.

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- 2.6 Write a program to display the figure shown in the preceding problem using a general path.
- 2.7 Write a Java program to draw a Ying-Yang symbol as shown in Figure 2.21. (*Hint*: Use constructive area geometry.)

Figure 2.21. A Ying-Yang symbol.

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## Chapter 3. 2D Graphics: Rendering Details

(This item omitted from WebBook edition)

Objectives
To understand color spaces.
• To use the Java Color class.
<ul> <li>To be able to use different types of paints in drawing visual objects.</li> </ul>
To apply stroke types.
• To construct affine transforms including translation, rotation, scaling, shearing, and reflection.
<ul> <li>To understand object transformations and viewing transformations.</li> </ul>
<ul> <li>To combine basic transformations to form more complex ones.</li> </ul>
To identify the compositing rules.
To use clipping path.
To apply fonts and font metrics.
<ul> <li>To understand glyph, ligature, and derived font.</li> </ul>

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## 3.1. Introduction

This chapter introduces several important attributes associated with 2D graphics rendering and their implementation in Java 2D. Besides the geometry that defines the structure of the graphics objects, many other attributes and operations contribute significantly to the appearance of rendered images. Colors, stroke types, transformations, compositing rules, clipping paths, and rendering hints are some of the factors affecting the outcome of rendering.

Colors and paints are highly visible attributes. Colors are usually represented in numerical forms called color spaces. Java defines the class Color to represents colors as objects. A generalization of color is the concept of paint that can represent complex color patterns. Java 2D uses the Paint interface to unify different paints. The classes Color, GradientPaint, and TexturePaint all implement the Paint interface and can be used by a Graphics2D object.

*Strokes* define the details of painting pens such as the width, end style, join style, and dash type. Similar to Paint, Graphics2D allows the selection of a Stroke object as one of its rendering attributes. The concrete class BasicStroke implements the Stroke interface and provides common stroke settings.

*Transformations* are crucial parts of computer graphics. Transformations can be used to modify geometric objects and to change the views. Affine transforms are the common family of transformations in computer graphics. Transforms such as translation, rotation, scaling, reflection, and shearing are all examples of affine transforms.

Related to colors, transparency and more general compositing rules for overlapping objects are interesting rendering attributes. A general set of compositing rules known as *Porter–Duff rules* are often applied in 2D graphics. The recent versions of Java 2D fully support Porter–Duff rules.

*Clip path* is another rendering attribute. It defines a region in which the rendered objects will actually be visible.

*Texts* are special graphics objects that have very compact representations. The actual geometric shapes of texts are predefined by fonts. Java 2D provides extensive support for fonts. In addition to the standard application of drawing texts with various settings of fonts, advanced features such as retrieving the outline of a character are also available.

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## 3.2. Colors and Paints

### 3.2.1. Color Space

Colors are important attributes in graphics systems. The color of light is associated with the wavelength or frequency of the light. Usually light has a spectrum of frequencies whose exact description will be complex. In practical terms, only colors visible and distinguishable to human eyes need to be defined in graphics systems. A system called *color space* is often used to define visible colors with numerical values. Several different color spaces exist to specify colors in a precise and quantitative way. The general approach is to select a small number of fixed primary colors such as (red, green, blue) and represent an arbitrary color as a combination of the primary colors:

### $C = r \cdot p_r + g \cdot p_g + b \cdot p_b$

The coefficients (r, g, b) represent the components of the color c in red, green, and blue. They provide a convenient numerical specification for colors.

The *CIEXYZ* is a color standard that uses three primary colors, X, Y, and Z, instead of red, green, and blue. Any visible color can be represented as a positive combination of X, Y, and Z. However, it is usually difficult to directly implement CIEXYZ in physical devices.

Most monitors use *RGB* (red, green, blue) color spaces and printers typically use *CMYK* (cyan, magenta, yellow, black) spaces. The combinations of the primary colors are used to represent different colors. These systems are natural to the devices, but they are usually device dependent and they cannot represent all visible colors with positive coefficients.

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*sRGB* (standard RGB) is an absolute device-independent color space. It uses the same type of red, green, and blue components as other RGB systems, but it standardizes the color definitions so that they are independent of any specific device.

### 3.2.2. Color

When the geometry of a shape is constructed, it can be rendered with the fill(Shape) or draw(Shape) methods in Graphics2D. To set the color for rendering the object, the following method of the Graphics class may be used:

void setColor(Color c)

A Color object defines a color. The Color class by default uses the sRGB color space, a proposed standard color space. A color contains Red, Green, Blue and Alpha components. The Alpha component defines the transparency of the color. The Color class defines the following constant color values:

black blue cyan darkGray gray green lightGray magenta orange pink red white yellow

Note



These names do not follow the Java naming convention, which specifies that constants should be in all capital letters. Since JDK 1.4, you can also use the new constants: BLACK, BLUE, CYAN, DARK\_GRAY, GREEN, LIGHT\_GRAY, MAGENTA, ORANGE, PINK, RED, WHITE, and YELLOW.

Other colors can be easily constructed using one of many constructors of the Color class. You may directly specify the RGB values using the following constructors:

Color(int r, int g, int b); Color(int rgb); Color(float r, float g, float b);

The first version specifies the three-color components using int values in the range 0–255. The second version is similar, but the three values are packed into a single int value. The third version uses float values in the range 0.0–1.0 to define the color components.

Besides RGB values, an alpha value related to the transparency of the color can be specified. The following constructors allow alpha value specification:

Color(int r, int g, int b, int a); Color(int rgba, boolean hasAlpha); Color(float r, float g, float b, float a);

Another constructor of the Color class allows the specification of a color space. UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO Color(Colorspace colorspace, float[] components, float alpha);

The following code fragment draws three squares of different colors:

```
public void paintComponent(Graphics g) {
  g.setColor(Color.red);
[Page 62] g.draw(new Rectangle(0, 0, 100, 100));
  g.setColor(new Color(0, 255, 128));
  g.draw(new Rectangle(100, 0, 100, 100));
  g.setColor(new Color(0.5f, 0.0f, 1.0f));
  g.draw(new Rectangle(200, 0, 100, 100));
}
```

Listing 3.1 illustrates the combinations of primary colors and the usage of colors in Java 2D rendering. The program displays three overlapping circles representing red, green, and blue. Seven different regions represent various combinations of the three primary components. Three sliders on the right of the window control the values of the red, green, and blue components (Figure 3.1).

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Listing 3.1. TestColors.java

(This item is displayed on pages 62 - 64 in the print version)

```
1 package chapter3;
 2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5 import javax.swing.*;
 6 import javax.swing.event.*;
 7 import java.awt.geom.*;
 8
 9 public class TestColors extends JApplet {
10 public static void main(String s[]) {
11
       JFrame frame = new JFrame();
12
        frame.setTitle("Colors");
13
        frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
14
       JApplet applet = new TestColors();
15
       applet.init();
16
        frame.getContentPane().add(applet);
17
       frame.pack();
18
       frame.setVisible(true);
19
    }
20
 21
    ColorPanel panel;
 22 public void init() {
 23
       panel = new ColorPanel();
 24
       Container cp = getContentPane();
 25
       cp.setLayout(new BorderLayout());
 26
        cp.add(panel, BorderLayout.CENTER);
27
       JPanel p = new JPanel();
28
       cp.add(p,BorderLayout.EAST);
29
        p.setLayout(new GridLayout(1,3,30,10));
30
       JSlider slider = new JSlider(JSlider.VERTICAL,0,255,100);
31
       p.add(slider);
32
       slider.addChangeListener(new ChangeListener() {
33
        public void stateChanged(ChangeEvent ev) {
34
            panel.red = ((JSlider)(ev.getSource())).getValue();
35
            panel.repaint();
36
        }
37
       });
        slider = new JSlider(JSlider.VERTICAL,0,255,100);
 38
39
        p.add(slider);
 40
        slider.addChangeListener(new ChangeListener() {
41
        public void stateChanged(ChangeEvent ev) {
42
            panel.green = ((JSlider)(ev.getSource())).getValue();
43
            panel.repaint();
44
         }
45
       });
               slider = new JSlider(JSlider.VERTICAL,0,255,100);
[Page 63] 46
       p.add(slider);
47
48
        slider.addChangeListener(new ChangeListener() {
49
         public void stateChanged(ChangeEvent ev) {
50
            panel.blue = ((JSlider)(ev.getSource())).getValue();
51
            panel.repaint();
52
          }
53
       });
54
     }
55 }
56
 57 class ColorPanel extends JPanel{
58 int red = 100;
```

```
59
      int green = 100;
     int blue = 100;
 60
 61
 62
      public ColorPanel() {
 63
        setPreferredSize(new Dimension(500, 500));
        setBackground(Color.white);
 64
      }
 65
 66
 67
      public void paintComponent(Graphics g) {
 68
        super.paintComponent(g);
        Graphics2D g2 = (Graphics2D)g;
 69
 70
        Shape rc = new Ellipse2D.Double(100, 113, 200, 200);
 71
        Shape gc = new Ellipse2D.Double(50, 200, 200, 200);
 72
        Shape bc = new Ellipse2D.Double(150, 200, 200, 200);
 73
        Area ra = new Area(rc);
 74
        Area ga = new Area(gc);
 75
        Area ba = new Area(bc);
 76
        Area rga = new Area(rc);
 77
        rga.intersect(ga);
 78
        Area gba = new Area(gc);
 79
        gba.intersect(ba);
 80
        Area bra = new Area(bc);
 81
        bra.intersect(ra);
 82
        Area rgba = new Area(rga);
 83
        rgba.intersect(ba);
 84
        ra.subtract(rga);
 85
        ra.subtract(bra);
 86
        ga.subtract(rga);
 87
        ga.subtract(gba);
 88
        ba.subtract(bra);
 89
        ba.subtract(gba);
 90
        // fill the color regions
 91
        g2.setColor(new Color(red,0,0));
 92
        g2.fill(ra);
 93
        g2.setColor(new Color(0,green,0));
 94
        g2.fill(ga);
    UNRECISTERED, ₩ERSION OF CHM TO PDF CONVERTER PRO
 95
 96
 97
        g2.setColor(new Color(red,green,0));
 98
        g2.fill(rga);
 99
        g2.setColor(new Color(0,green,blue));
100
        g2.fill(gba);
101
        g2.setColor(new Color(red,0,blue));
102
        g2.fill(bra);
103
        g2.setColor(new Color(red,green,blue));
104
        g2.fill(rgba);
105
        // draw three circles
[Page 64]106
               g2.setColor(Color.black);
107
        g2.draw(rc);
108
        g2.draw(gc);
109
        g2.draw(bc);
110
     }
111 }
```

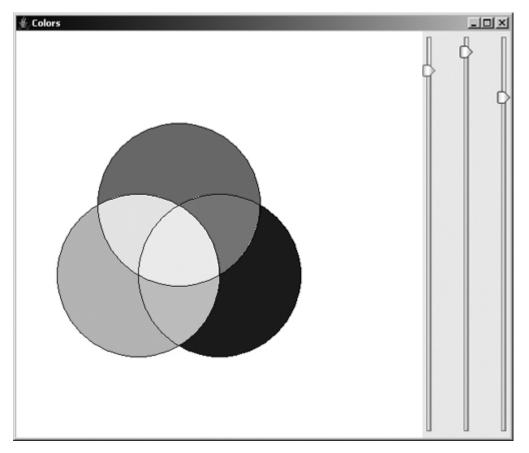


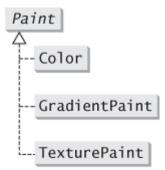
Figure 3.1. Colors formed by combinations of red, green, and blue.

The ColorPanel class has three int fields red, green, and blue to represent the primary color components. In the paintComponent method (line 67), the seven regions of the picture are formed from three circles using constructive area geometry. Each region is filled with a combination of primary colors covering the region. For example, the region covered by the red circle is filled with the red components. The region covered by the red and blue circles is filled with the color composed of red and blue components. The center region covered by all three circles is colored with all three components. The three circles are drawn in black.

Three vertical JSlider objects are placed on the right side of the window. They are used to control the values of the fields red, green, and blue in the ColorPanel. The values of the slides have the range 0 to 255. When a slider is changed, the corresponding ChangeListener implementation will change the color variable and repaint the panel (lines 30–53).

### 3.2.3. Paint

The setColor(Color c) method belongs to the older Graphics class. It sets only a solid color for rendering. The Graphics2D class of Java 2D contains a much more powerful setPaint(Paint p) method to control the rendering colors. Paint is a generalization of color. The Paint interface is implemented by the Color class and also implemented by other classes (see Figure 3.2) that can represent more attributes than simple solid colors. Figure 3.2. Paint class hierarchy.



The GradientPaint class defines a type of paint with varying colors. A *gradient paint* is specified by two points and two colors. As the location moves from the first point to the second, the paint color changes gradually from the first color to the second. A gradient paint can be cyclic or acyclic. A cyclic gradient paint repeats the same pattern periodically. To create an acyclic gradient paint, the following constructors can be used:

GradientPaint(float x1, float y1, Color c1, float x2, float y2, Color c2); GradientPaint(Point2D p1, Color c1, Point2D p2, Color c2);

In either version, two points are specified with their associated colors. The colors for points between the two given points will change gradually from one specified color to the other color. Cyclic gradient paints can be created with the following constructors.

GradientPaint(float x1, float y1, Color c1, float x2, float y2, Color c2, boolean cycl); GradientPaint(Point2D p1, Color c1, Point2D p2, Color c2, boolean cycl);

Setting the last parameter to true will construct a cyclic gradient paint. UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRC The TexturePaint class allows an object to be filled with a *texture pattern*. An image and an anchor rectangle

are used to define a texture paint. When painting with the texture, the image is repeatedly applied to the tiled rectangular regions. A TexturePaint object is created with the following constructor:

TexturePaint(BufferImage image, Rectangle2D anchor);

The image defines the texture for painting. The anchor rectangle specifies the positioning of the image in the user space.

Listing 3.2 demonstrates the effects of graphics drawing with gradient and texture paints. A sample run of the program is shown in Figure 3.3.

Listing 3.2. TestPaints.java

(This item is displayed on pages 65 - 66 in the print version)



```
7 import java.awt.font.*;
 8 import java.awt.geom.*;
 9 import java.io.*;
10 import java.net.URL;
11 import javax.imageio.*;
12
13 public class TestPaints extends JApplet {
   public static void main(String s[]) {
14
15
      JFrame frame = new JFrame();
[Page 66]16
            frame.setTitle("Gradient and Texture Paints");
17
       frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
18
       JApplet applet = new TestPaints();
19
       applet.init();
20
      frame.getContentPane().add(applet);
21
     frame.pack();
22
       frame.setVisible(true);
23
   }
24
   public void init() {
25
26
     JPanel panel = new PaintPanel();
27
       getContentPane().add(panel);
28
   }
29 }
30
31 class PaintPanel extends JPanel{
32 private BufferedImage image;
33
34
   public PaintPanel() {
35
     setPreferredSize(new Dimension(500, 500));
36
       setBackground(Color.white);
37
      URL url = getClass().getClassLoader().getResource
38
         ("images/earth.jpg");
39
       try {
         image = ImageIO.read(url);
40
41
       } catch (IOException ex) {
42
         ex.printStackTrace();
43
      }
44
    }
45
46
    public void paintComponent(Graphics g) {
47
      super.paintComponent(g);
48
       Graphics2D g2 = (Graphics2D)g;
49
       GradientPaint gp = new GradientPaint(100,50,
50
         Color.white, 150, 50, Color.gray, true);
51
       g2.setPaint(gp);
52
       g2.fillRect(100, 40, 300, 20);
53
       TexturePaint tp = new TexturePaint(image,
54
         new Rectangle2D.Double(100, 100, image.getWidth(),
55
           image.getHeight()));
56
       g2.setPaint(tp);
57
       Shape ellipse = new Ellipse2D.Double(100, 100, 300, 200);
58
       g2.fill(ellipse);
       GradientPaint paint = new GradientPaint(100, 300, Color.white,
59
60
         400, 400, Color.black);
       g2.setPaint(paint);
61
62
       Font font = new Font("Serif", Font.BOLD, 144);
63
       g2.setFont(font);
64
       g2.drawString("Java", 100, 400);
65
     }
```



Figure 3.3. Shapes drawn with cyclic gradient paint, texture paint, and acyclic gradient paint. (This item is displayed on page 67 in the print version)

This program draws three visual objects in the paintComponent method (line 46). Three different types of paints are used to draw the figures. The top rectangle is drawn with a cyclic gradient paint created by the following constructor:

new GradientPaint(100,50, Color.white, 150, 50, Color.gray, true);

The grading pair specifies a part of charge spontomine with an the complete 50 one one provide the point (150, 50). The pattern is cyclically repeated, because the two points have the same proordinates, you will see a vertical pattern.

The ellipse is filled with a texture paint defined by an image.

```
new TexturePaint(image, new Rectangle2D.Double(100, 100, image.getWidth(),
image.getHeight()));
```

The image is a BufferedImage object loaded from a file using the read method of the ImageIO class.

The text string is drawn with an acyclic gradient paint:

new GradientPaint(100,300, Color.white, 400, 400, Color.black);

The gradient paint changes the color from white to black as the location moves from (100, 300) to (400, 400). The paint is acyclic, and the color pattern does not repeat.

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[Page 67 (continued)]

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### 3.3. Strokes

A line rendered in computer graphics is not an ideal line with zero width. To be practically realizable, lines must have specific shapes. The attributes that define the fine details of such shapes are called *strokes*. A stroke may include attributes such as the width of lines, the dash style of lines, the cap shape at the ends of lines, and the style at the joins of lines.

Java 2D includes the interface Stroke to represent strokes. A concrete implementation of the Stroke interface is the class BasicStroke. BasicStroke provides settings for width, end style, join style, and dash. The constructors of BasicStroke are listed below.

```
BasicStroke()
BasicStroke(float width)
BasicStroke(float width, int cap, int join)
BasicStroke(float width, int cap, int join, float miterlimit)
BasicStroke(float width, int cap, int join, float miterlimit,
    float[] dash, float dashphase)
```

[Page 68]

The parameter width defines the width of the drawing pen. The parameter cap sets the end cap style and can take values:

CAP\_BUTT CAP\_ROUND CAP\_SQUARE

The parameter join defines the join style with values:

```
JOIN_BEVEL
JOIN_MITTER
JOIN_REGISTERED VERSION OF CHM TO PDF CONVERTER PRO
```

The miterlimit sets a limit for JOIN\_MITER to prevent a very long join when the angle between the two lines is small.

The dash array defines a dash pattern by specifying the lengths of the ON/OFF segments. The dashphase defines the starting point in the dash pattern.

Graphics2D has the following method to set the current stroke:

void setStroke(Stroke s)

Listing 3.3 demonstrates the effects of graphics drawing with different stroke settings. Three end styles, three join styles, and a dash array with two different dash phase values are illustrated. A sample run of the program is shown in Figure 3.4.

Listing 3.3. TestStrokes.java

	UNREGISTERED VERSION OF CHM	
1		LŲ PDF CONVERTER PRO
l	1 package chapter3;	

```
2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5 import javax.swing.*;
 6 import java.awt.geom.*;
 7
 8 public class TestStrokes extends JApplet {
    public static void main(String s[]) {
 9
       JFrame frame = new JFrame();
10
11
       frame.setTitle("Different Strokes");
12
       frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
13
       JApplet applet = new TestStrokes();
14
      applet.init();
15
       frame.getContentPane().add(applet);
16
     frame.pack();
17
       frame.setVisible(true);
18
    }
19
   public void init() {
20
21
     JPanel panel = new StrokePanel();
22
       getContentPane().add(panel);
23
   }
24 }
25
26 class StrokePanel extends JPanel {
27
   public StrokePanel() {
28
       setPreferredSize(new Dimension(700, 400));
[Page 69]29
              setBackground(Color.white);
30
    }
31
32
    public void paintComponent(Graphics g) {
33
     super.paintComponent(g);
34
       Graphics2D g2 = (Graphics2D)g;
35
       GeneralPath path = new GeneralPath(GeneralPath.WIND_EVEN_ODD);
36
      path.moveTo(0,120);
37
      path.lineTo(80,0);
38
      path.lineTo(160,120);
39
       Stroke stroke = new BasicStroke(20, BasicStroke.CAP_BUTT,
40
        BasicStroke.JOIN_BEVEL);
41
      g2.setStroke(stroke);
42
       g2.translate(50,50);
43
       g2.draw(path);
       g2.drawString("JOIN_BEVEL",100,0);
44
45
       g2.drawString("CAP_BUTT", 40, 120);
46
       stroke = new BasicStroke(20, BasicStroke.CAP_ROUND,
47
         BasicStroke.JOIN_MITER);
48
       g2.setStroke(stroke);
49
       g2.translate(200,0);
50
       g2.draw(path);
       g2.drawString("JOIN_MITER",100,0);
51
52
       g2.drawString("CAP_ROUND", 40, 120);
       stroke = new BasicStroke(20, BasicStroke.CAP_SQUARE,
53
        BasicStroke.JOIN_ROUND);
54
55
       g2.setStroke(stroke);
56
       g2.translate(200,0);
57
       g2.draw(path);
58
       g2.drawString("JOIN_ROUND",100,0);
59
       g2.drawString("CAP_SQUARE", 40, 120);
60
       float[] dashArray = \{60, 20, 20, 40\};
```

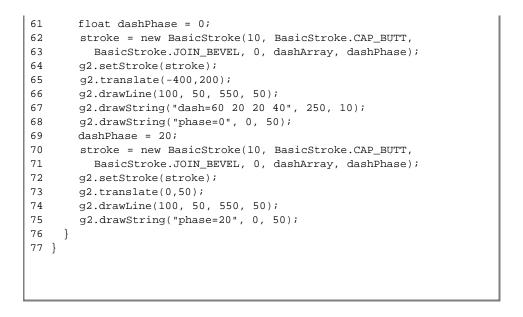
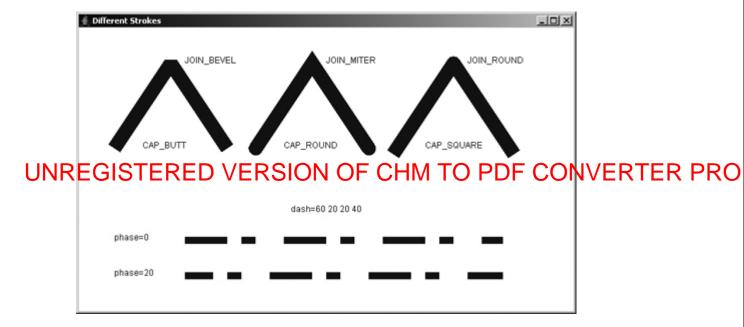


Figure 3.4. Examples of strokes with different end style, join style, and dash settings. (This item is displayed on page 70 in the print version)



A GeneralPath is constructed with two joining line segments (lines 34–37). The path is drawn three times on the top row. Three BasicStroke instances with different end styles and join styles are applied to the drawings. The width is set to 20 in order to show the details of stroke styles.

The bottom two rows display dashed lines. The dash array is defined to be {60, 20, 20, 40} (line 59), and the width is 10 for both strokes, but the dash phase values are 0 and 20, respectively. The shifting of the dash pattern due to nonzero dash phase is clearly visible **UNREGISTERED VERSION OF CHM TO PDF CONVERTER I** 

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### 3.4. Affine Transformation

Geometric objects go through a transformation stage before being rendered. A general family of geometric transforms commonly used in computer graphics is called *affine transforms*. An affine transform preserves the parallel lines. The affine transforms that also preserve distances are called *isometries, Euclidean motions*, or *rigid motions*. The common affine transforms include:

- Translation
- Rotation
- Reflection
- Scaling
- Shearing

A *translation* moves all points of the object by a fixed amount (see Figure 3.5). It is specified by the amounts of movements in the x- and y-directions. A translation is an isometry, since it does not change lengths and angles. Figure 3.5 shows a translation of (3, -1). The object is moved 3 units to the right and 1 unit up.

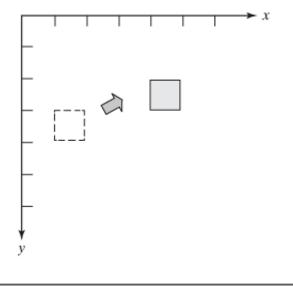
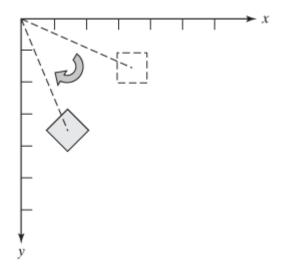


Figure 3.5. A translation of (3, -1).

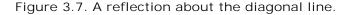
[Page 71]

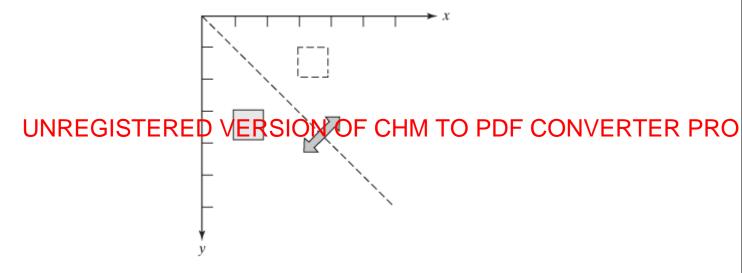
A *rotation* rotates the object about a point by an angle (see Figure 3.6). It is determined by the point and the angle. A rotation is also an isometry, though it changes the orientation of the shape. Figure 3.6 shows a rotation of 45 degrees about the origin.

Figure 3.6. A rotation about the origin.



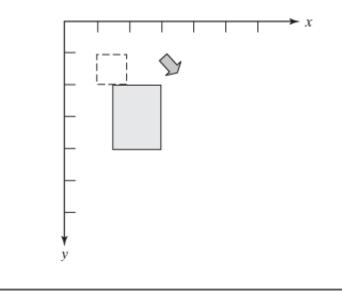
A *reflection* maps the object to its mirror image about a line (see Figure 3.7). It is determined by the line. A reflection is an isometry, though it changes the orientation of an angle. Figure 3.7 shows a reflection about the 45 degree line between the x- and y-axes.





A *scaling* resizes the object by certain fixed factors in the x- and y-directions (see Figure 3.8). A scaling is not an isometry, because it will change distances and angles. However, it preserves parallelism. Figure 3.8 shows a scaling by the factors (1.5, 2).

Figure 3.8. A scaling by factors (1.5, 2).



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A *shearing* about a line shifts a point by an amount proportional to the signed distance to the line (see Figure 3.9). The movements of the points are parallel to the line. Points on the line are not moved. Points on the opposite sides of the line are moved in the opposite directions. A shearing is not an isometry, but it still preserves parallelism. Figure 3.9 shows a shearing by the factor 1.0 along the horizontal line  $\gamma = 2$ .

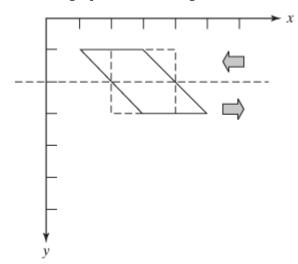


Figure 3.9. A shearing by factor 1 along the dashed horizontal line.

Mathematically a 2D affine transformation can be represented as a 3 x 3 *matrix*. An affine transform requires a 3 x 3 instead of a 2 x 2 matrix, because transforms such as translations are not linear in a 2D space. Using the concept of homogeneous coordinates, it is possible to treat all affine transforms in a linear framework by adding one dimension to the vector representation of the points. A more detailed discussion on matrices and homogeneous coordinates can be found in Appendix A.

For basic transforms, it is usually easy to find the transformation matrices directly. A rotation of an angle about the origin is represented as the matrix:

$\cos \theta$	$\sin \theta$	0
$-\sin\theta$	$\cos \theta$	0
0	0	1

A translation by the amount (a, b) has the matrix:

1	0	a
1 0 0	1	a b 1
0	0	1

A scaling by the factors (a, ) has the matrix representation:

Γα	0	0
$\begin{array}{c} \alpha \\ 0 \\ 0 \end{array}$	$\beta$	0
0	0	1

A reflection about the line y = kx is represented by the matrix:



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A shear along the x-axis by the factor s is given by the matrix:

[1	S	0
0	1	0
0_	0	1

Java 2019 REGISTEREDAYER

named transforms,

```
void setToIdentity()
void setToRotation(double theta)
void setToRotation(double theta, double x, double y)
void setToScale(double sx, double sy)
void setToShear(double shx, double shy)
void setToTranslation(double tx, double ty)
```

One transform missing from this list of methods is the reflection. However, you may define a reflection by setting its matrix. The following matrix defines a reflection about the  $\gamma$ -axis:

```
\begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}
```

The AffineTransform class has constructors and methods to directly set the first two rows of the transformation matrix.

```
AffineTransform(double m00, double m10, double m01,
    double m11, double m02, double m12)
AffineTransform(float m00, float m10,
    float m01, float m11, float m02, float m12)
AffineTransform(double[] flatmatrix)
AffineTransform(float[] flatmatrix)
void setTransform(double m00, double m10, double m01,
    double m11, double m02, double m12)
```

Because the last row of an affine transformation matrix is always (0 0 1), it is omitted in the parameter list. The reflection matrix defined above may be set by the following method:

```
transform.setTransform(-1, 0, 0, 1, 0, 0);
```

Because the AffineTransform class allows a scaling with negative factors, the reflection can also be defined as a special kind of scaling:

```
transform.setToScale(-1, 1);
```

An AffineTransform object can be used for both *object transformations* and viewing transformations. The following methods of the AffineTransform class apply the transform to geometric objects:

```
Shape createTransformedShape(Shape shape)
void transform(double[] src, int srcOff, double[] dst,
    int dstOff, int numPts)
void transform(double[] src, int srcOff, float[] dst,
    int dstOff, int numPts)
void transform(float[] src, int srcOff, double[] dst,
```

```
int dstOff, int numPts)
void transform(float[] src, int srcOff, float[] dst,
    int dstOff, int numPts)
Point2D transform(Point2D src, Point2D dst)
[Page 74]Point2D transform(Point2D[] src, int srcOff, Point2D[] dst,
    int dstOff, int numPts)
void deltaTransform(double[] src, int srcOff, double[] dst,
    int dstOff, int numPts)
Point2D deltaTransform(Point2D src, Point2D dst)
```

The createTransformedShape method transforms an entire shape. The transform methods perform the transformation on a set of points. The deltaTransform methods perform the transformation on a set of vectors.

A viewing transformation can be realized with the transformation in the Graphics2D object. The Graphics2D class has the following methods to manipulate its transformation:

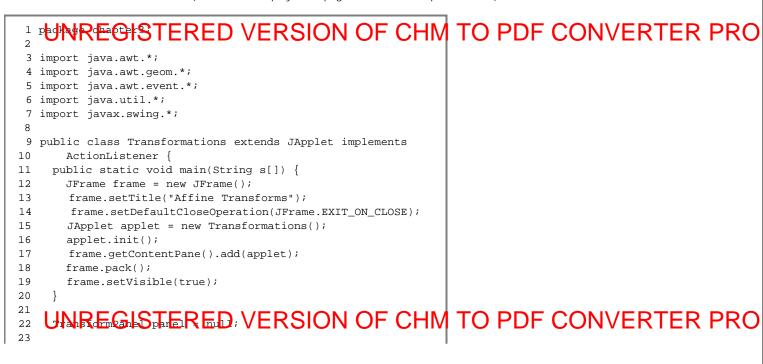
```
void setTransform(AffineTransform tx)
void transform(AffineTransform tx)
```

The method setTransform replaces the current transformation with the given AffineTransform object. The method transform concatenates the current transformation with the given AffineTransform object on the right.

Listing 3.4 illustrates the effects of affine transforms through an interactive approach. A user is allowed to perform the transformations on a graphics object using the mouse. The affine transforms are selected with a menu that includes translation, rotation, scaling, shearing, and reflection. A sample run of the program is shown in Figure 3.10.

```
Listing 3.4. Transformations.java
```

(This item is displayed on pages 74 - 77 in the print version)

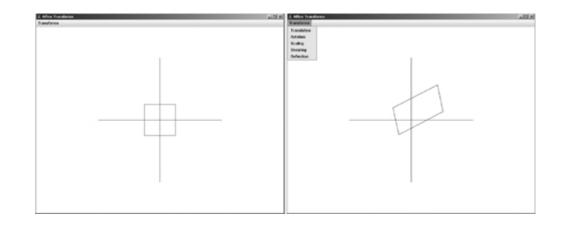


```
24
    public void init() {
 25
       JMenuBar mb = new JMenuBar();
 26
       setJMenuBar(mb);
 27
       JMenu menu = new JMenu("Transforms");
 28
       mb.add(menu);
       JMenuItem mi = new JMenuItem("Translation");
 29
 30
       mi.addActionListener(this);
 31
       menu add(mi);
 32
       mi = new JMenuItem("Rotation");
33
       mi.addActionListener(this);
34
        menu.add(mi);
[Page 75] 35
           mi = new JMenuItem("Scaling");
 36
       mi.addActionListener(this);
 37
        menu.add(mi);
 38
        mi = new JMenuItem("Shearing");
 39
       mi.addActionListener(this);
 40
       menu.add(mi);
 41
        mi = new JMenuItem("Reflection");
       mi.addActionListener(this);
 42
 43
       menu.add(mi);
 44
 45
       panel = new TransformPanel();
 46
       getContentPane().add(panel);
 47
    }
 48
 49
    public void actionPerformed(ActionEvent ev) {
 50
       String command = ev.getActionCommand();
 51
        if ("Translation".equals(command)) {
 52
        panel.transformType = panel.TRANSLATION;
 53
       } else if ("Rotation".equals(command)) {
 54
         panel.transformType = panel.ROTATION;
 55
       } else if ("Scaling".equals(command)) {
 56
        panel.transformType = panel.SCALING;
 57
        } else if ("Shearing".equals(command)) {
 58
        panel.transformType = panel.SHEARING;
 59
        } else if ("Reflection".equals(command)) {
 60
          panel.transformType = panel.REFLECTION;
 61
        }
 62
    }
 63 }
 64
 65 class TransformPanel extends Jpanel
 66
        implements MouseListener, MouseMotionListener {
 67
      static final int NONE = 0;
    static final int TRANSLATION = 1;
 68
    static final int ROTATION = 2;
 69
 70
    static final int SCALING = 3;
 71
     static final int SHEARING = 4;
 72
     static final int REFLECTION = 5;
 73
 74
    int transformType = NONE;
 75
     Shape drawShape = null;
 76
     Shape tempShape = null;
 77
     Point p = null;
 78
     int x0 = 400;
 79
     int y0 = 300;
 80
 81
     public TransformPanel() {
 82
      super();
```

```
83
        setPreferredSize(new Dimension(800, 600));
 84
        setBackground(Color.white);
        drawShape = new Rectangle(-50, -50, 100, 100);
 85
 86
        addMouseListener(this);
 87
        addMouseMotionListener(this);
     }
 88
 89
 90
     public void paintComponent(Graphics g) {
        super.paintComponent(g);
 91
 92
       Graphics2D g2 = (Graphics2D)g;
 93
        g2.translate(x0, y0);
 94
       g2.drawLine(-200, 0, 200, 0);
[Page 76] 95
              g2.drawLine(0, -200, 0, 200);
 96
       g2.draw(drawShape);
 97
     }
98
99
     public void mouseClicked(MouseEvent ev) {
100
     }
101
102
     public void mouseEntered(MouseEvent ev) {
103
     }
104
     public void mouseExited(MouseEvent ev) {
105
106
     }
107
108
     public void mousePressed(MouseEvent ev) {
109
       p = ev.getPoint();
110
     }
111
112
     public void mouseReleased(MouseEvent ev) {
113
       Graphics g = getGraphics();
114
       Point p1 = ev.getPoint();
115
       AffineTransform tr = new AffineTransform();
       switch (transformType) {
116
117
          case TRANSLATION:
            tr.setToTranslation(p1.x-p.x, p1.y-p.y);
118
        NRECISTERED VERSION OF CHM TO PDF CONVERTER PRO
119
120
            double a = Math.atan2(p1.y-y0, p1.x-x0) - Math.atan2
121
122
             (p.y-y0, p.x-x0);
123
           tr.setToRotation(a);
124
           break;
         case SCALING:
125
126
            double sx = Math.abs((double)(p1.x-x0)/(p.x-x0));
127
            double sy = Math.abs((double)(p1.y-y0)/(p.y-y0));
           tr.setToScale(sx, sy);
128
129
           break;
130
         case SHEARING:
131
            double shx = ((double)(p1.x-x0)/(p.x-x0))-1;
132
            double shy = ((double)(p1.y-y0)/(p.y-y0))-1;
           tr.setToShear(shx, shy);
133
134
           break;
135
         case REFLECTION:
136
           tr.setTransform(-1, 0, 0, 1, 0, 0);
137
           break;
138
       }
139
    UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
140
141
     }
```

```
142
143
      public void mouseMoved(MouseEvent ev) {
144
      }
145
146
     public void mouseDragged(MouseEvent ev) {
147
       Point p1 = ev.getPoint();
148
        AffineTransform tr = new AffineTransform();
       switch (transformType) {
149
150
          case TRANSLATION:
151
            tr.setToTranslation(pl.x-p.x, pl.y-p.y);
152
           break;
153
          case ROTATION:
154
            double a = Math.atan2(p1.y-y0, p1.x-x0) - Math.atan2
155
              (p.y-y0, p.x-x0);
[Page 77]156
                   tr.setToRotation(a);
157
            break;
158
          case SCALING:
            double sx = Math.abs((double)(p1.x-x0)/(p.x-x0));
159
            double sy = Math.abs((double)(p1.y-y0)/(p.y-y0));
160
161
            tr.setToScale(sx, sy);
162
           break;
163
          case SHEARING:
164
            double shx = ((double)(p1.x-x0)/(p.x-x0))-1;
165
            double shy = ((double)(p1.y-y0)/(p.y-y0))-1;
166
           tr.setToShear(shx, shy);
167
           break;
168
          case REFLECTION:
169
            tr.setTransform(-1, 0, 0, 1, 0, 0);
170
            break;
171
        }
172
       Graphics2D g = (Graphics2D)getGraphics();
173
        g.setXORMode(Color.white);
174
        g.translate(x0, y0);
175
        if (tempShape != null)
176
          g.draw(tempShape);
177
        tempShape = tr.createTransformedShape(drawShape);
178
        g.draw(tempShape);
179
     }
180 }
```

Figure 3.10. Affine transforms applied to a rectangle.



The program initially displays a set of axes for the coordinate system and a rectangle. A menu is defined to select an affine transformation from a list including translation, rotation, scaling, shearing, and reflection (lines 2543). To perform a selected transformation, drag the mouse in the desired direction. The amount of mouse movement is used to determine the corresponding transformation on the object.

Two classes are defined in this program, Transformations and TransformPanel. The Transformations class is a subclass of JApplet and contains the menu for selecting the current affine transform. The class is also the action event handler to handle the menu selection actions and to set the appropriate values for the transformType variable in TransformPanel.

The TransformPanel class is a subclass of JPanel and it handles the mouse events. When a transform is requested, an AffineTransform object is set to the value determined by the selected transform type and the mouse movements. The transform is then applied to the shape as an object transformation using the method createTransformedShape (line 139). The shape is initially a rectangle, but the transformations on the shape are accumulative, and the newly transformed shape becomes the current shape. The transformations do not affect other objects such as the axes, because they are object transformations applied locally to the shape only.

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method is the same as that in Listing 2.3. The XOR drawing mode is applied to draw and erase the temporary shapes.

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### 3.5. Compositions of Transformations

Transformations can be combined to form new transformations. For example, you may apply a translation followed by a rotation and followed by another translation. Any *composition* of affine transforms is still an affine transform. Any composition of rigid motions is still a rigid motion. Conversely, a transform may be decomposed into a series of (usually simpler) transforms.

The transformation matrix of a composite transform is the product of matrices of the individual transforms. For example, if  $M_1$ ,  $M_2$ ,  $M_3$  are the matrices for the affine transforms  $\overline{7}_1$ ,  $\overline{7}_2$ ,  $\overline{7}_3$ , respectively, then the matrix for the composition  $\overline{7}_1 \circ \overline{7}_2 \circ \overline{7}_3$  is  $M_1 M_2 M_3$ . Note that the operation of transformation composition is *noncommutative*, so the order of applying the transforms is significant. In our notation, the transforms in a composite transform are applied from right to left. For example, when the composite transform  $\overline{7}_1 \circ \overline{7}_2 \circ \overline{7}_3$  is applied to a point  $\rho$ , the order of the transforms is  $\overline{7}_3$ ,  $\overline{7}_2$ ,  $\overline{7}_1$ :

$$(\mathcal{F}_1 \circ \mathcal{F}_2 \circ \mathcal{F}_3)(\rho) = \mathcal{F}_1(\mathcal{F}_2(\mathcal{F}_3(\rho)))$$

Composite transforms are useful in constructing complex transforms from simpler ones. If you need a rotation about the point (3, 4) by 30 degrees, you may first perform a translation to move the point (3, 4) to the origin. Then you may perform a 30-degree rotation about the origin. Finally you can translate the origin back to the point (3, 4). Combining the three transforms, you will obtain the required transform. In the matrix form, the translation that moves (3, 4) to the origin is given by:

1	0	-3
0	1	-4
0_	0	1

The rotation of 30 degrees about the origin is

$\int \sqrt{3}/2$	-1/2	0
1/2	$\sqrt{3}/2$	0
0	0	1

The second translation is

1	0	3
0	1	4
0	0	1

Combing three transforms, the final rotation has the transformation matrix:

Γ	1	0	3	$\int \sqrt{3/2}$	-1/2	0	[1	0	-3]
	0	1	4	1/2	$\sqrt{3/2}$	0	0	1	- 4
L	0	0	1_	0	0	1	0	0	1

In Java 2D, the AffineTransform class provides the following methods to support composite transforms:

void rotate(double theta) void rotate(double theta, double x, double y) [Page 79]void scale(double sx, double sy) void shear(double shx, double shy) void translate(double tx, double ty)

Unlike the setTo\* methods introduced in the previous section, these methods do not clear the existing transforms in the current objects, but combine the current transforms with the newly specified transforms. The new transforms are appended to the right of the current ones. Instead of the simple transformations listed above, it is also possible to combine the current transform with another AffineTransform object:

void concatenate(AffineTransform tx)
void preConcatenate(AffineTransform tx)

The first method concatenates the other transform to the right of the current. The second concatenates the other transform to the left of the current.

Note that the order of transform composition is from left to right, and the methods above (except for preConcatenate) concatenate the transform from the right. If you create a composite transform by calling the above methods, the transforms are applied in the opposite order of your calling sequence. For example, consider the following code:

AffingTransform Charge The Converter PRO transform.rotate(Math.PF73), AffingTransform() OF CHM TO PDF CONVERTER PRO transform.scale(2, 0.3); transform.translate(100, 200);

The first transform to be applied is the translation and the last transform is the rotation.

Listing 3.5 illustrates the use of transform composition. To rotate an ellipse about its center that is not located at the origin, you may first translate the object to the origin. Then rotate around the origin. Finally, translate the center of the rotated ellipse to its original point. (See Figure 3.11.)

Listing 3.5. Composition.java (This item is displayed on pages 79 - 80 in the print version)

```
1 package chapter3;
 2
 3 import javax.swing.*;
 4 import java.awt.*;
 5 import java.awt.geom.*;
 6
7 public class Composition extends JApplet {
    public static void main(String s[]) {
 8
9
       JFrame frame = new JFrame();
10
       frame.setTitle("Transformation Composition");
11
       frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
12
       JApplet applet = new Composition();
13
      applet.init();
14
       frame.getContentPane().add(applet);
15
      frame.pack();
16
       frame.setVisible(true);
17
   }
18
   public void init() {
19
       JPanel panel = new CompositionPanel();
20
21
       getContentPane().add(panel);
22
   }
23 }
24
25 class CompositionPanel extends JPanel {
    public CompositionPanel() {
26
[Page 80]27
              setPreferredSize(new Dimension(640, 480));
28
       this.setBackground(Color.white);
29
    }
30
31
   public void paintComponent(Graphics g) {
32
       super.paintComponent(g);
33
       Graphics2D g2 = (Graphics2D)g;
34
       g2.translate(100,100);
       Shape e = new Ellipse2D.Double(300, 200, 200, 100);
35
       g2.setColor(new Color(160,160,160));
36
37
       g2.fill(e);
       AffineTransform transform = new AffineTransform();
38
39
       transform.translate(-400,-250);
40
       e = transform.createTransformedShape(e);
41
       g2.setColor(new Color(220,220,220));
42
       g2.fill(e);
43
       g2.setColor(Color.black);
44
       g2.drawLine(0, 0, 150, 0);
45
       g2.drawLine(0, 0, 0, 150);
46
       transform.setToRotation(Math.PI / 6.0);
47
       e = transform.createTransformedShape(e);
48
       g2.setColor(new Color(100,100,100));
49
       g2.draw(e);
50
       transform.setToTranslation(400, 250);
51
       e = transform.createTransformedShape(e);
52
       g2.setColor(new Color(0,0,0));
53
       g2.draw(e);
54
    }
55 }
```

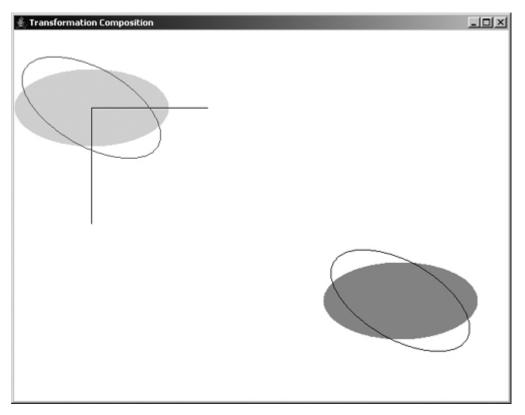


Figure 3.11. Composition of a translation, a rotation, and another translation.

The program shows a shape at different stages of a composite transformation. The shape is an ellipse originally construct Rteaps of Rteaps and Rteaps of Rteaps and the center (400, 250). To achieve this transformation, a composition of three transformations is used. First a translation of (-400, -250) will move the ellipse so that it is centered at the origin. Then a rotation of 30 degrees about the origin is applied. The ellipse is rotated and still centered at the origin. Finally a translation of (400, 250) moves the ellipse back so that its center is again at (400, 250). The composition of the three transforms is the desired transformation.

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To show all parts of the figures, a viewing transformation is used to move the origin of the world space from the upper left corner of the screen to (100, 100) (line 34). The x- and y-axes are drawn to show the new origin. The ellipse at each stage of the transformation is displayed with different gray levels. The rotated ellipses are not filled.

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### 3.6. Transparency and Compositing Rules

*Compositing rules* determine the results of rendering overlapped objects. Various visual effects such as different degrees of transparency can be obtained by choosing compositing rules.

To establish the compositing rules, the concept of an a-channel is needed. The a-channel can be viewed as a part of color properties that specifies the transparency. An a-channel is a number between 0.0 and 1.0, with 0.0 representing complete transparency and 1.0 complete opaqueness.

Given the source and destination pixel color and a-values, the *Porter–Duff* rules define the resulting color and a-values as linear combinations of the source and destination values:

$$\begin{aligned} \mathbf{a} \cdot &= F_{\mathcal{S}} \cdot \mathbf{a}_{\mathcal{S}} \cdot C_{\mathcal{S}} + F_{\mathcal{A}} \cdot \mathbf{a}_{\mathsf{d}} \cdot C_{\mathcal{A}} \\ C \end{aligned}$$
$$\mathbf{a} &= F_{\mathcal{S}} \cdot \mathbf{a}_{\mathcal{S}} + F_{\mathcal{A}} \cdot \mathbf{a}_{\mathsf{d}} \end{aligned}$$

Often the color components may have their a-values premultiplied to speed up the computation. The different choices of the two coefficients  $F_s$  and  $F_d$  in the equation define the different compositing rules. There are twelve Porter–Duff rules, having the coefficients shown in Table 3.1.

Porter–Duff Rule	$F_{S}$	$F_{d}$
Clear	0	0
SrcOver	1	1 - a <sub>s</sub>
DstOver	1 - a <sub>đ</sub>	1
SrcIn	a <sub>d</sub>	0
DstIn	0	as
SrcOut	1 - a <sub>ď</sub>	0
DstOut	0	1 - a <sub>s</sub>
Src	1	0
Dst	0	1
SrcAtop	ad	1 - a <sub>s</sub>
DstAtop	1 - a <sub>ď</sub>	as
Xor	1 - a <sub>ď</sub>	1 - a <sub>s</sub>

Table 3.1. (This item is displayed on page 82 in the print version)

The Porter–Duff rules can be derived systematically from a *probabilistic model*. The a-value of a color can be interpreted as the probability that the color will be shown, or more concretely as the portion of the pixel area covered by the specified color. To combine the source and destination colors with their respective a-values, four different cases need to be considered: source color occurs only, destination color occurs only, both colors occur, and neither color occurs. Figure 3.12 illustrates the four events, which occur with probabilities  $a_s(1 - a_d)$ ,  $a_d(1 - a_s)$ ,  $a_s a_{d_1}$  and  $(1 - a_s)$   $(1 - a_d)$ , respectively. A compositing rule simply decides whether to retain a color when

the color occurs. In the source-color-only event, a rule can choose to retain the source color or to omit it. In the destination-color-only event, the destination color can be selected or omitted. In the both-colors event, a rule can choose the source color, the destination color, or no color. In the neither-color event, a rule can only select no color. Therefore, the total number of rules based on this model is  $2 \times 2 \times 3 \times 1 = 12$ .

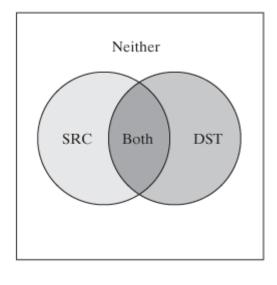


Figure 3.12. Four different events of color occurrence in the probabilistic model of compositing.

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For example, the SrcOver rule chooses the source color in the event of source color only and the event of both colors. It chooses the destination color in the destination-color-only event. It must choose no color in the neither-color event. Consequently the probability of source color occurring in the combined color is  $a_s(1 - a_a) + a_s a_{a'} = a_{s'}$  and the probability of destination color is  $a_a(1 - a_s)$ . This leads to the selection of the coefficients  $F_s = 1$ ,  $F_{a'} = (1 - a_s)$  as shown in Table 3.1.

**UNREGISTERED VERSION OF CHM TO PDF CONVERTER PR** Early versions of Java 2D supports the first eight rules in Table 3.1. Starting with J2SDK 1.4, all twelve rules are supported. The AlphaComposite class encapsulates the rules. An instance of AlphaComposite for a rule can be obtained by a static field of AlphaComposite with the name shown in Table 3.1. To apply a compositing rule to a Graphics2D object, simply call the setComposite method. For example, the following statement sets the compositing rule to SrcIn:

Graphics2D g2 = (Graphics2D)g; g2.setComposite(AlphaComposite.SrcIn);

Listing 3.6 illustrates the application of the AlphaComposite class to implement Porter–Duff rules. This example shows several visual objects rendered with the twelve different Porter–Duff compositing rules. The rules are selected by clicking the mouse on the display panel. A sample run of the program is shown in Figure 3.13.

Listing 3.6. Compositing.java

(This item is displayed on pages 82 - 84 in the print version)



```
6 import javax.swing.*;
 7 import java.awt.font.*;
 8 import java.awt.geom.*;
 9 import java.io.*;
10 import java.net.URL;
[Page 83]11 import javax.imageio.*;
12
13 public class Compositing extends JApplet {
   public static void main(String s[]) {
14
15
       JFrame frame = new JFrame();
16
       frame.setTitle("Compositing Rules");
17
       frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
18
      JApplet applet = new Compositing();
19
      applet.init();
20
       frame.getContentPane().add(applet);
21
     frame.pack();
22
       frame.setVisible(true);
23
    }
24
25
   public void init() {
       JPanel panel = new CompositePanel();
26
27
       getContentPane().add(panel);
28
   }
29 }
30
31 class CompositePanel extends JPanel implements MouseListener {
32
   BufferedImage image;
33
     int[] rules = {AlphaComposite.CLEAR, AlphaComposite.SRC_OVER,
34
       AlphaComposite.DST_OVER, AlphaComposite.SRC_IN,
35
       AlphaComposite.DST_IN, AlphaComposite.SRC_OUT,
36
       AlphaComposite.DST_OUT, AlphaComposite.SRC,
37
       AlphaComposite.DST, AlphaComposite.SRC_ATOP,
38
       AlphaComposite.DST_ATOP, AlphaComposite.XOR};
39
     int ruleIndex = 0;
40
41
    public CompositePanel() {
      setPreferredSize(new Dimension(500, 400));
42
43
       setBackground(Color.white);
44
       URL url =
45
          getClass().getClassLoader().getResource("images/earth.jpg");
46
       try {
47
         image = ImageIO.read(url);
48
       } catch (IOException ex) {
49
         ex.printStackTrace();
50
       }
51
       addMouseListener(this);
52
    }
53
54
    public void paintComponent(Graphics g) {
55
       super.paintComponent(g);
56
       Graphics2D g2 = (Graphics2D)g;
57
       g2.drawImage(image, 100, 100, this);
58
       AlphaComposite ac =
59
         AlphaComposite.getInstance(rules[ruleIndex], 0.4f);
60
       g2.setComposite(ac);
61
       Shape ellipse = new Ellipse2D.Double(50, 50, 120, 120);
62
       g2.setColor(Color.red);
63
       g2.fill(ellipse);
64
       g2.setColor(Color.orange);
```

```
65
       Font font = new Font("Serif", Font.BOLD, 144);
66
      g2.setFont(font);
       g2.drawString("Java", 90, 240);
67
68
   }
69
70
    public void mouseClicked(MouseEvent e) {
[Page 84]71
            ruleIndex++;
      ruleIndex %= 12;
72
73
      repaint();
74
   }
75
   public void mousePressed(MouseEvent e) {
   }
76
77
   public void mouseReleased(MouseEvent e) {
78
   }
79
   public void mouseEntered(MouseEvent e) {
80
   }
81
   public void mouseExited(MouseEvent e) {
82
   }
83 }
```

Figure 3.13. Overlapping objects rendered with the **src\_over** rule, one of the twelve compositing rules demonstrated in this example.



This program demonstrates the twelve Porter-Duff compositing rules. The class Compositing extends the JPanel class and implements the MouseListener interface.

The list of compositing rules is placed in an int array using the constants defined in the AlphaComposite class (line 33). The variable ruleIndex points to the current compositing rule. The mouseClicked method rotates the compositing rules by incrementing the ruleIndex modulo 12 (lines 71–72). A repaint method is called to refresh the display with the new compositing rule. Therefore, every time the panel is clicked, the panel switches to a different compositing rule.

In the constructor of CompositePanel an image is loaded from a disk file (line 41). In the paintComponent method (line 54), the image is drawn first. The composite rule is then set to the current compositing rule with an a-value of 0.4, using the static method getInstance of the AlphaComposite class. A red circle is drawn, and the string "Java" is also drawn with a white color.

The on-screen drawing surface does not maintain an itself, and the a-value of any pixel is always implicitly assumed to be 1.0. Consequently, as soon as an object is painted to the screen, the destination a becomes 1.0. Because of this behavior, some of the compositing rules do not produce interesting results. For example, the rules DstOver, DstOut, DstATop, and Xor will always ignore the source, since the destination a is 1. One way to show more interesting effects is to draw on an off-screen image with an a-channel.

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## 3.7. Clipping

A clipping path defines a region in which the objects will actually be visible. Graphics2D maintains a current clipping region. When an object is drawn, it is clipped against the clipping path. Portions of the object falling outside the clipping path will not be drawn. Any Shape object can be used for clipping. The following code segment sets an ellipse as the clipping shape and draws an image. Only the portion of the image which lies inside the ellipse will be visible.

```
Graphics2D g2 = (Graphics2D)g;
Shape ellipse = new Ellipse2D.Double(0, 0, 300,200);
g2.setClip(ellipse);
g2.drawImage(image, 0, 0, this);
```

Another method of Graphics2D that can change the clip region is:

void clip(Shape path)

This method will clip the current clipping region further with the specified shape.

Listing 3.7 demonstrates the use of clipping path. Another example will be given in the next section. In this simple example, a special shape is created and used as the clip path for a Graphics2D object. The subsequent drawings are clipped by the shape. A sample run of the program is shown in Figure 3.14.

Listing 3.7. TestClip.java

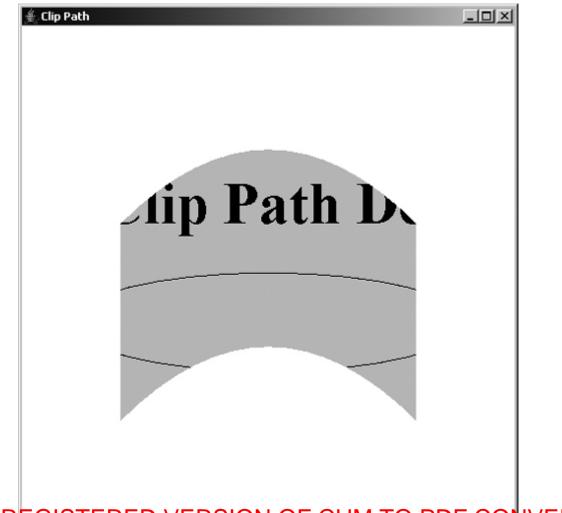
(This item is displayed on pages 85 - 86 in the print version)

```
1 package chapter3;
 2
 3 import java.awt.*;
 4
  import
         javax.swing
                        RED VERSION OF CHM TØ PDF CONVERTER PRO
  import java.awt.goom.
 5
 6
 7
  public class TestClip extends JApplet {
 8
    public static void main(String s[])
 9
      JFrame frame = new JFrame();
10
      frame.setTitle("Clip Path");
11
       frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
12
      JApplet applet = new TestClip();
13
      applet.init();
14
      frame.getContentPane().add(applet);
15
      frame.pack();
16
      frame.setVisible(true);
17
    }
18
19
    public void init() {
      JPanel panel = new ClipPanel();
20
21
      getContentPane().add(panel);
22
    }
23
  }
24
25
           EGISTERED VERSION OF CHM TO PDF CONVERTER PRO
  clas
26
27
       setPreferredSize(new Dimension(500, 500));
```

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```
[Page 86]28
              setBackground(Color.white);
29
    }
30
31
    public void paintComponent(Graphics g) {
32
       super.paintComponent(g);
33
     Graphics2D g2 = (Graphics2D)g;
34
      GeneralPath path = new GeneralPath(GeneralPath.WIND_EVEN_ODD);
35
     path.moveTo(100,200);
      path.quadTo(250, 50, 400, 200);
36
37
      path.lineTo(400,400);
      path.quadTo(250,250,100,400);
38
39
      path.closePath();
40
      g2.clip(path);
41
      g2.setColor(new Color(200,200,200));
42
     g2.fill(path);
43
      g2.setColor(Color.black);
44
      g2.setFont(new Font("Serif", Font.BOLD, 60));
45
     g2.drawString("Clip Path Demo",80,200);
46
       g2.drawOval(50, 250, 400, 100);
47
   }
48 }
```

Figure 3.14. The gray area is enclosed by the clip path. Graphical drawings are clipped by the clip path.



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The program has a structure similar to that in the previous examples. An applet with a main method is created to form an application as well as an applet. The ClipPanel class extends JPanel to form the drawing canvas of the program.

In the paintComponent method (line 31), a GeneralPath object with two line segments and two quad curves is constructed. The closed path is set as the current clip path of the Graphics2D object by calling the method clip. The path is used again with the fill method to show the clip area in a light gray shade. Two graphics objects are drawn: a text string "Clip Path Demo" and an ellipse. The effect of clipping is obvious. Only the portions of the objects lying inside the clip path are visible.

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[Page 87 (continued)]

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## 3.8. Text and Font

In computer graphics, text represents a special type of geometric objects. A text string can be compactly represented by a sequence of characters with standard coding schemes, such as ASCII and Unicode. The actual rendering shapes of the characters are determined by predefined fonts. The geometry describing the shape of a character is known as a *glyph*. A font is a collection of glyphs for an entire alphabet.

#### Note



The relation between characters and glyphs is not always one to one. Sometimes one glyph may correspond to several characters, as in the case of a *ligature*. A ligature occurs in some fonts when certain two-character sequences are rendered in a combined fashion. A common ligature is "fi" in some fonts, as shown in Figure 3.15.

Figure 3.15. A common ligature.



Java 2D offers a rich set of font and text-manipulation features. The most common high-level usages of texts involve creating a Font object and calling the methods setFont and drawString in Graphics2D.

A Font object can be created with the following constructor:

Font(String name, int style, int size)

The name parameter specifies the font face name or the logical name of a font. A font is identified by the font face name (also called font name), such as "Times New Roman." The fonts available in an environment are platform dependent. Java also supports *logical fonts* to improve portability. A logical font is mapped to a physical font on a particular system. For example, the logical font "SansSerif" is mapped to "Arial" in a Windows system. Five logical font families are always supported in Java.

Serif SansSerif Monospaced Dialog DialogInput

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The style parameter is a mask to select *font styles*. Three bit masks are defined in Font, and they may be combined with the bitwise OR "|" operator:

PLAIN ITALIC BOLD

The size parameter specifies the point size of the font.

A Font object can be selected in a Graphics2D object with the method:

void setFont(Font font)

The font will take effect for subsequent calls to methods for drawing texts:

```
void drawString(String s, int x, int y)
void drawString(String s, float x, float y)
```

In addition to applying existing fonts in the system, it is also possible to derive new fonts from existing ones by modifying certain attributes. The following methods in the Font class generate *derived fonts*.

```
Font deriveFont(int style)
Font deriveFont(float size)
Font deriveFont(int style, float size)
Font deriveFont(AffineTransform tx)
Font deriveFont(int style, AffineTransform tx)
Font deriveFont(Map attributes)
```

The point size of a font provides only a crude indication of the size of the text drawn. The actual size of the rendered text usually depends on the characters in the string. In tasks such as centering the text, it may be useful to know the actual geometric size of the text. *Font metrics* are measurements of rendered texts with a specific text. Font metrics are measurements of rendered texts with a specific text. Font metrics are measurements of rendered texts with a specific text. Font metrics are measurements of rendered texts with a specific text.

Rectangle2D getStringBounds(String str, FontRenderContext frc) LineMetrics getLineMetrics(String str, FontRenderContext frc)

Because the precise metrics also depend on the options of rendering, the above methods use a FontRenderContext object to obtain the additional information. The FontRender-Context object can be obtained through a method in Graphics2D:

FontRenderContext getFontRenderContext()

The getStringBounds method returns a bounding rectangle for the string. The getLineMetrics method returns a LineMetrics object that contains more detailed line metric data. The *baseline* is the reference line of a font. The *ascent* is the amount that the font extends above the baseline. The *descent* is the amount extending below the baseline. The *leading* is the extra space between the two lines. The following methods of LineMetrics retrieve the metrics:

float getAscent() float getAscentGISTERED VERSION OF CHM TO PDF CONVERTER PRO float getLeading() Listing 3.8 demonstrates font-related features. The derived fonts and font metrics are demonstrated in this example. Three lines of text are displayed. The first line is drawn with a derived font that is slanted to the left. The second line shows the bounding rectangle together with the text. The third line displays the baseline, ascent, descent, and leading for the text. A sample run of the program is shown in Figure 3.16.

```
[Page 89]
```

#### Listing 3.8. FontFun.java

(This item is displayed on pages 89 - 90 in the print version)

```
1 package chapter3;
 2
 3 import java.awt.*;
 4 import javax.swing.*;
 5 import java.awt.geom.*;
 6 import java.awt.font.*;
 8 public class FontFun extends JApplet {
 9
    public static void main(String s[]) {
10
       JFrame frame = new JFrame();
11
       frame.setTitle("Fonts");
        frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
12
13
       JApplet applet = new FontFun();
14
       applet.init();
15
       frame.getContentPane().add(applet);
16
       frame.pack();
17
       frame.setVisible(true);
18
    }
19
20
    public void init() {
21
       JPanel panel = new FontPanel();
22
       getContentPane().add(panel);
23
    }
24 }
25
26 class FontPanel extends JPanel {
27
   public FontPanel() {
28
       setPreferredSize(new Dimension(640, 480));
29
       setBackground(Color.white);
30
    }
31
32
     public void paintComponent(Graphics g) {
33
       super.paintComponent(g);
34
       Graphics2D g2 = (Graphics2D)g;
35
       Font font = new Font("Serif", Font.BOLD, 36);
36
       AffineTransform tx = new AffineTransform();
37
       tx.shear(0.5, 0);
38
       g2.setFont(font.deriveFont(tx));
39
       g2.drawString("Derived font", 100, 100);
40
41
       g2.setFont(font);
42
       FontRenderContext frc = g2.getFontRenderContext();
43
       String str = "String bounds";
44
       Rectangle2D bounds = font.getStringBounds(str, frc);
45
       g2.translate(100, 200);
46
       g2.draw(bounds);
```

47 48	g2.drawString(str, 0, 0);
49	<pre>str = "Baseline, ascent, descent, leading";</pre>
50	g2.translate(0,100);
51	<pre>int w = (int)font.getStringBounds(str, frc).getWidth();</pre>
52	<pre>LineMetrics lm = font.getLineMetrics(str, frc);</pre>
53	g2.drawLine(0, 0, w, 0);
54	<pre>int y = -(int)lm.getAscent();</pre>
55	g2.drawLine(0, y, w, y);
	<pre>y = (int)lm.getDescent();</pre>
57	g2.drawLine(0, y, w, y);
58	<pre>y = (int)(lm.getDescent()+lm.getLeading());</pre>
[Page 90]	59 g2.drawLine(0, y, w, y);
60	
61	g2.drawString(str,0,0);
62 }	
63 }	

Figure 3.16. The first line shows the text drawn with a derived font. The second line draws the bounding rectangle. The third line shows the baseline and the amounts of ascent, descent, and leading.

🛓 Fonts	×
Derived font	
UNREGISTERED VERSION OF CHM TO PDF CO String bounds	ONVERTER PRO
Baseline, ascent, descent, leading	

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Three lines of text are drawn in the paintComponent method of the FontPanel class (line 32). An

AffineTransform object is created to perform a horizontal shear. A new font is derived from a 36-point bold Serif font with the transformation. The derived font is slanted to the left because of the shear transform. The text string "Derived font" is drawn using the derived font.

A FontRenderContext object is obtained from the Graphics2D object (line 42). It is used in the method getStringBounds of the Font object to retrieve the bounding rectangle for the string "String bounds." The string is drawn together with the bounding rectangle.

The third line of text is the string "Baseline, ascent, descent, leading." The baseline of the text is drawn based on the width of the text. The LineMetrics object for the string is retrieved through the method getLineMetrics (line 52). The values for ascent, descent, and leading are obtained from the object, and the lines corresponding to the values are drawn relative to the baseline.

Java 2D also provides advanced functions for font-related operations. In particular, *glyphs* of characters in a font can be retrieved as Shape objects. This enables sophisticated processing and application of the glyphs to achieve varieties of visual effects. The class Font represents a font. The class GlyphVector encapsulates the geometric description of a sequence of glyphs. To obtain a GlyphVector object for a string corresponding to a font, use the following method of Font:

[Page 91] GlyphVector createGlyphVector(FontRenderContext frc, String str)

The FontRenderContext object defines certain measurements necessary to render a font. It can be obtained from a Graphics2D object by calling the method getFontRender-Context. Once the GlyphVector object is created, the Shape object corresponding to the glyphs can be obtained by the following methods of GlyphVector:

Shape getOutline()
Shape getOutline(float x, float y)

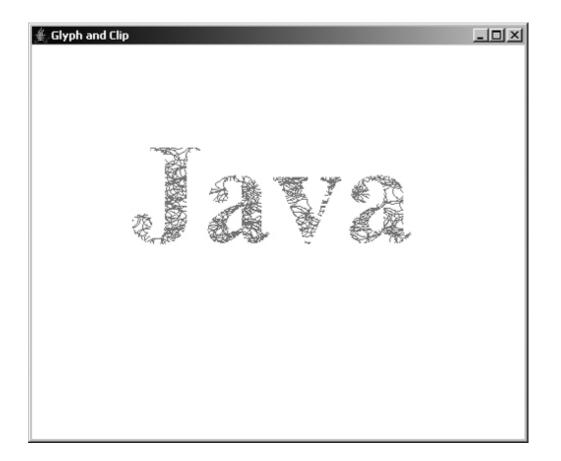
The *x*- and *y*-parameters specify the starting location for rendering the glyphs. The returned Shape object corresponding to the glyphs can be processed and rendered like other Shape objects. Listing 3.9 illustrates the use of glyphs as a clipping shape. The program shows the technique of retrieving the glyphs of a text string as a Shape and use it as a clip path. A sample run of the program is shown in Figure 3.17.

Listing 3.9. GlyphClip.java

(This item is displayed on pages 91 - 92 in the print version)

```
1 package chapter3;
 2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5 import javax.swing.*;
 6 import java.awt.font.*;
 7 import java.awt.geom.*;
 8
 9 public class GlyphClip extends JApplet {
    public static void main(String s[]) {
10
11
       JFrame frame = new JFrame();
12
       frame.setTitle("Glyph and Clip");
13
       frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
14
       JApplet applet = new GlyphClip();
15
       applet.init();
16
       frame.getContentPane().add(applet);
17
       frame.pack();
18
       frame.setVisible(true);
19
    }
20
    public void init() {
21
22
       JPanel panel = new GlyphPanel();
23
       getContentPane().add(panel);
24
   }
25 }
26
27 class GlyphPanel extends JPanel {
28
    public GlyphPanel() {
29
       setPreferredSize(new Dimension(500, 400));
30
       setBackground(Color.white);
31
   }
32
    public void paintComponent(Graphics g) {
33
       super.paintComponent(g);
34
       Graphics2D g2 = (Graphics2D)g;
35
       Font font = new Font("Serif", Font.BOLD, 144);
     UNREGISTERED: VERSION, OF CHM TO PDF CONVERTER PRO
36
37
38
       Shape glyph = gv.getOutline(100,200);
39
       g2.setClip(glyph);
[Page 92]40
             g2.setColor(Color.red);
41
       for (int i = 0; i < 2000; i++) {
42
         Shape shape = new Ellipse2D.Double(Math.random()*500,
          Math.random()*400, 30, 20);
43
44
         g2.draw(shape);
45
       }
46
    }
47 }
```

Figure 3.17. Two thousand random ellipses drawn on a clipping shape defined by the glyphs of the string "Java."



The program displays the special figure in a subclass of JPanel. The paintComponent method is overridden to perform the drawing. A bold, 144-point "Serif" font object is created. A FontRenderContext object is obtained through the Graphics2D object.

The glyphs from the string "Java" are obtained from the font and font render context and they are kept in a GlyphVector variable (line 37). The glyph vector is converted to a Shape object through the getOutline methods (line 38). The shape is then set to the clipping path of the rendering by calling the method setClip of the Graphics2D object.

Two thousand ellipses with random locations are drawn on the panel (lines 41–44). Only the portions inside the glyphs are visible. The text string is never explicitly drawn, but the drawing inside the clipping region clearly highlights the outline of the glyphs.

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[Page 92 (continued)]

### Key Classes and Methods

- java.awt.Color A class encapsulating colors.
- java.awt.Paint An interface for Color, GradientPaint, and TexturePaint classes.
- java.awt.GradientPaint A class for gradient paint.
- java.awt.TexturePaint A class for texture paint.
- java.awt.Stroke An interface for stroke definitions.
- java.awt.BasicStroke An implementation of common strokes.
- java.awt.geom.AffineTransform A class encapsulating 2D affine transformations.
- javax.awt.AlphaComposite A class for alpha compositing rules.

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- java.awt.Graphics2D.setClip(Shape) A method to set the current clipping path.
- java.awt.Graphics2D.setComposite(AlphaComposite) A method to set the current compositing rule.
- java.awt.Font A class encapsulating a font.
- java.awt.font.LineMetrics A class for font metrics.
- java.awt.font.GlyphVector A class encapsulating a series of glyphs for a text string.

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### Key Terms

color space

A system to specify colors with numerical values.

#### affine transformation

A transform that preserves parallelism.

#### transform composition

A combining of two or more transforms to form a new one.

#### Porter–Duff rules

A method to create new geometric shapes by using set operations such as union and intersection on the areas of existing shapes.

#### clip path

A shape defining a region to constrain rendering.

#### font

A design of the shapes for a set of characters.

#### font metrics

Measurements of the rendered text such as ascent, descent, and leading.

#### glyph

A geometric description of a text string in a specific font.

#### ligature

A special combination of multiple characters forming one glyph.

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[Page 93 (continued)]

## Chapter Summary

- In this chapter we discuss several important aspects of 2D graphics rendering and their implementations in Java 2D. Main topics covered include colors, strokes, transformations, clip paths, compositing rules, and fonts.
- Colors and, more generally, paints are attributes that can be applied to visual objects when they are rendered. Java 2D provides three types of paints using the classes Color, GradientPaint, and TexturePaint.
- Strokes define the details of line styles. Java 2D contains the Stroke interface for general stroke definitions and a specific implementation BasicStroke for commonly used stroke attributes such as line width, end cap style, and join style.
- Affine transformations are a large set of transformations commonly used for object transformations and viewing transformations. An affine transform preserves parallelism. Basic affine transforms include translation, rotation, scaling, shearing, and reflection. Java 2D provides comprehensive supports for affine transformation. The class AffineTransform defines an affine transform and contains many constructors and methods to specify the transform. The method createTransformedShape provides a way to perform the object transformations. An AffineTransform object can also be used by a Graphics2D object to set the viewing transformation. Transformations can be combined to form more complex ones.
- The Porter–Duff rules define the compositing operations with an The twelve compositing rules specify various ways that colors from the source and the destination may be combined. Interesting visual effects such as transparency can be achieved by using appropriate compositing rules.

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- Clipping is a rendering facility that can produce complex visual effects. In Java 2D, a clipping path for a Graphics2D object can be set to any Shape object.
- Text strings are useful visual objects. A font defines the glyphs of all the characters. Besides the usual rendering of texts with the drawString method, glyphs for a text string can be retrieved as a Shape object that can be directly manipulated as other Shape objects.

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### **Review** Questions

- 3.1 What is the wavelength range of visible color?
- 3.2 In an RGB system, if each of the red, green, and blue components is represented by a byte, how many different colors can be formed?
- 3.3 Construct a Color object equivalent to the following using float parameters: **new** Color(255, 0, 128);
- 3.4 Construct a Color object equivalent to the following using int parameters: **new** Color(Of, 0.5f, 0.125f);
- 3.5 Construct a cyclic gradient paint that varies from the color red at the point (0, 0) to the color blue at the point (100, 100).
- 3.6 Construct an acyclic gradient paint that varies from the color yellow at the point (100, 0) to the color green at the point (800, 600).
- 3.7 What is the transformation matrix of the rotation of 45 degrees about the origin?
- 3.8 Construct an AffineTransform object for a general reflection about a line through the origin.
- 3.9 Is it possible to transform an ellipse to a circle using affine transformations? Rigid motions?
- 3.10 Is it possible to transform a trapezoid to a square using affine transformations? Rigid motions?

- 3.12 Find an affine transform that maps x-axis to y-axis and y-axis to x-axis.
- 3.13 Find the transformation matrix for the rotation ? of angle about the point (a, b).
- 3.14 Find the transformation matrix for the reflection about the line y = 2x.
- 3.15 Find the transformation matrix for the reflection about the line y = 2x 1.
- 3.16 Find the transformation matrix for the shear along the  $\gamma$ -axis with the factor 0.5.
- 3.17 Find the transformation matrix for the composition of a rotation of p/3 about the origin and a reflection about the line y = 2x.
- 3.18 If the RGB and a-values of a source pixel are 0.5, 0.0, 0.8, and 0.4, and the values for the destination pixel are 0.2, 1.0, 0.5, and 0.6, find the RGB and of the composite using the SrcOver rule.

		Repeat the												
<b>J</b> .	<b>JN</b> 20	Repeat the	previous	D V probler	ERS	ON ne Src	OF rule.	CHM	ТО	PDF	CON	/ERT	ER	PRO

- 3.21 Repeat the previous problem using the Dst rule.
- 3.22 Repeat the previous problem using the SrcOut rule.
- 3.23 Repeat the previous problem using the DstOut rule.

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- 3.24 If the destination color has an a-values 1.0, which compositing rules will not be affected by the source color?
- 3.25 Write a code segment that draws the outline of a text string in the paintComponent method.

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## Programming Exercises

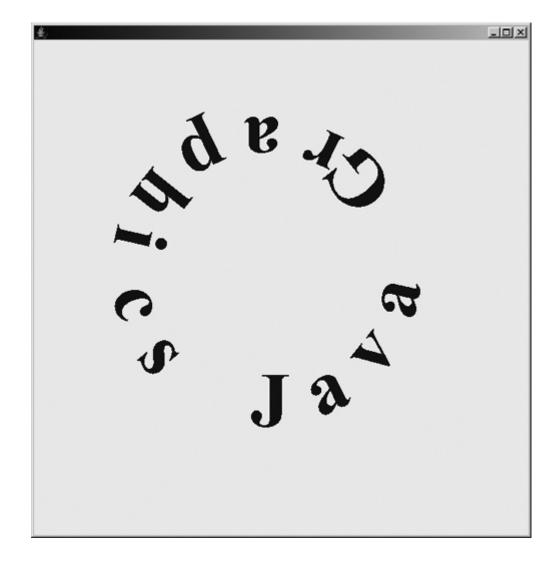
- 3.1 Write a Java program to draw a series of rectangles filled with colors defined by the constants in the Color class.
- 3.2 Write a Java program to draw the shape in Figure 3.18 filled with green color.

Figure 3.18. A filled shape.



- 3.3 Write a Java program to display the shape in Figure 3.18 using a gradient paint with colors varying vertically from black to white.
- 3.4 Write a Java program to display the shape in Figure 3.18 using a texture paint.
- 3.5 Swing contains the class JColorChooser that allows interactive color selections through a dialog box. Modify the program in Exercise 3.2 to allow the selection of drawing colors using the JColorChooser class.
- 3.6 Draw a pentagon with a stroke of width 20 and a round join style.
- 3NREGISTIERED VERSION200 CHIMITETAST POP SOUTHING TER PRO the origin and rotated by 45 degrees. Display the shape.
- 3.8 Write a Java program to display the mirror image of the string "Hello 2D." (*Hint*: Use a reflection.)
- 3.9 Write a Java program that performs a reflection about the line y = 2x. Draw an original rectangle of size 100 by 50 at (0, 100). Apply the reflection to the rectangle and draw the transformed shape in a different color.
- 3.10 Write a Java program to draw a circular text around the point (300, 300) as shown in Figure 3.19. (*Hint*: Use the drawstring method for each character and apply a rotation repeatedly.)

Figure 3.19. A circular text. (This item is displayed on page 96 in the print version)



- 3.11 Write a Java program that performs a scaling of factor 3 along the line y = x. Draw an original square of size 100 centered at (0, 0). Apply the scaling to the square and draw the transformed shape in a different color. (*Hint*: Decompose the transform into a standard scaling and two rotations.)
- 3.12 Use the shape in Figure 3.18 as the clip path and draw the text string "Java 2D" with a large font.

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- 3.13 Write a program to load an image and display only an elliptic region of the image. Use a clipping path to achieve this effect.
- 3.14 Derive a font by a rotation of 45 degrees and draw a string with the font.
- 3.15 Use the glyph shapes and area geometry to display the outline of the superimposed glyphs of the characters "N" and "Y."

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## Chapter 4. 2D Graphics: Advanced Topics (Optional)

(This item omitted from WebBook edition)

Objectives	
• To understand B-spline curves.	
To construct custom shape primitives.	
To apply basic image-processing techniques.	
To create fractal images.	
To create 2D animation.	
To perform graphics printing.	
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## 4.1. Introduction

In the preceding chapters we discussed basic concepts and techniques of 2D computer graphics systems and the Java 2D package. In this chapter we discuss more advanced topics of 2D graphics and several features not directly available in Java 2D.

### Spline curves are important modeling tools for computer graphics. A Baspline curve bas smooth curve curve fined ER PRO by a sequence of control points. Java 2D does not offer direct support for drawing spline curves. However, a Bspline curve can be converted to a series of Bézier curves. This technique is introduced in this chapter.

Java 2D offers a set of common graphics primitives through a class hierarchy implementing the Shape interface. You may also implement your own primitives. This chapter will introduce a technique to implement a custom Shape class so it can be passed to a Graphics2D object for rendering just like the built-in classes.

Even though image processing is a separate subject, it is closely related to computer graphics. Images are useful objects in computer graphics, as you have seen from the example of texture paints. The image-handling features of Java 2D will be introduced in this chapter. Java 2D offers an image model much improved over the previous AWT model. Images can be conveniently loaded, processed, and saved through the support of Java APIs. It is also possible to create an image from scratch. Fractal images will be used to illustrate image creation in Java.

Animation creates an images series of a dynamic scene. It adds a new dimension of time to the graphics system. Java's multithreading capability provides crucial support for implementing animation in a Java 2D program. Several examples of animation including cellular automata will be introduced.

Printing is a part of many graphics applications. Java 2D offers convenient printing support that is highly consistent with the maximum of the maximum of the constant of the support that is highly and the consistent with the maximum of the constant of th

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### 4.2. Spline Curves

A *spline curve* consists of a sequence of smoothly joined polynomial curves. A type of spline curves widely used in CAD and other computer graphics applications is the *B-spline curves*. In particular, the *cubic B-spline curves* are the most commonly used B-spline curves in computer graphics.

The mathematical definitions of Bézier curves can be given in parametric equations. A *general Bézier curve* of degree n with control points  $p_0$ ,  $p_1$ , ...,  $p_n$  is given by

$$s(t) = \sum_{i=0}^{n} p_i B_{n,i}(t)$$

where  $B_{n,k}(t)$  is known as the Bernstein polynomials or *Bernstein basis*.

$$B_{n,i}(t) = \binom{n}{i} t^i (1-t)^{n-i}$$

The quadratic curves and cubic curves supported in Java 2D are special cases of Bézier curves with degrees n = 2 and n = 3, respectively. Their equations may be expressed as follows:

 $s_{2}(\hbar) = (1 - \hbar)^{2}\rho_{0} + 2t(1 - \hbar)\rho_{1} + t^{2}\rho_{2}$  $s_{3}(\hbar) = (1 - \hbar)^{3}\rho_{0} + 3t(1 - \hbar)^{2}\rho_{1} + 3t^{2}(1 - \hbar)\rho_{2} + t^{3}\rho_{3}$ 

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A *B-spline curve* is defined by a sequence of control points. Like a Bézier curve, the B-spline curve follows the general directions of the control points, but it need not always interpolate the points. A general B-spline curve of degree *k* is defined by n + 1 control points  $\rho_0$ ,  $\rho_1$ , ...,  $\rho_n$  and a sequence of n + k + 2 parameter values known as the knots:  $t_0 \leq t_1 \leq t_{n+k+1}$ . The parametric equation of the B-spline curve can be expressed as:

$$p(t) = \sum_{i=0}^{n} p_i N_{k,i}(t)$$

The curve is defined only over the interval  $[t_3, t_{n+k-2})$ . The functions  $N_{k,k}(t)$  are called the *normalized B-spline blending functions* and may be defined recursively:

$$N_{0,i}(t) = \begin{cases} 1, & t \in [t_i, t_{i+1}) \\ 0, & \text{otherwise} \end{cases}$$
$$N_{k,i}(t) = \frac{t - t_i}{t_{i+k} - t_i} N_{k-1,i}(t) + \frac{t_{i+k+1} - t}{t_{i+k+1} - t_{i+1}} N_{k-1,i+1}(t)$$

The B-spline curves are versatile modeling tools. The smoothness and continuity of a curve can be controlled by the knots. When the differences between adjacent knot values are a constant:  $t_{A-1} - t_i = c_i$ , the curve is called a *uniform B-spline*. In general, the curve is a nonuniform B-spline. The B-spline formulation can also be applied to homogeneous coordinates with the same blending functions for the *w* components. When the control points are represented in homogeneous coordinates, the curve is known as a *rational B-spline curve*. The most general family of B-spline curves is therefore called the NURBS (nonuniform rational B-spline).

In this section, we consider only a special type of cubic B-spline curves that are direct extensions of cubic Bézier curves. The knots are chosen to be uniformly distributed, except that the first four and the last four knots are set to be equal:

 $t_0 = t_1 = t_2 = t_3$  $t_{A+1} - t_7 = 1, \ f = 3, 4, \dots, \ f$  $t_{n+1} = t_{n+2} = t_{n+3} = t_{n+4}$ 

The duplicated knots will cause the first and the last control points to be interpolated by the curve, similar to a Bézier curve. In fact, if n = 3, a cubic B-spline of this type is exactly a regular cubic Bézier curve:

$$\mathcal{N}_{0,0}(\hbar) = \mathcal{N}_{0,1}(\hbar) = \mathcal{N}_{0,2}(\hbar) = 0, \ \mathcal{N}_{0,3}(\hbar) = \mathcal{X}_{0,1}, \ \mathcal{N}_{0,4}(\hbar) = \mathcal{N}_{0,5}(\hbar) = \mathcal{N}_{0,6}(\hbar) = 0$$

$$\mathcal{N}_{1,0}(\hbar) = \mathcal{N}_{1,1}(\hbar) = 0, \ \mathcal{N}_{1,2}(\hbar) = (1 - \hbar)\mathcal{X}_{0,1}, \ \mathcal{N}_{1,3}(\hbar) = \mathcal{X}_{0,1}, \ \mathcal{N}_{1,4}(\hbar) = \mathcal{N}_{1,5}(\hbar) = 0$$

$$\mathcal{N}_{2,0}(\hbar) = 0 \ \mathcal{N}_{2,1}(\hbar) = (1 - \hbar)^2 \mathcal{X}_{0,1}, \ \mathcal{N}_{2,2}(\hbar) = 2 \mathcal{X}_{1}(1 - \hbar) \mathcal{X}_{0,1}, \ \mathcal{N}_{2,3}(\hbar) = \mathcal{X}_{0,1}, \ \mathcal{N}_{2,4}(\hbar) = 0$$

$$\mathcal{N}_{3,0}(\hbar) = (1 - \hbar)^3 \mathcal{X}_{0,1}, \ \mathcal{N}_{3,1}(\hbar) = 3 \mathcal{X}_{1}(1 - \hbar)^2 \mathcal{X}_{0,1} \ \mathcal{N}_{3,2}(\hbar) = 3 \mathcal{X}_{1}(1 - \hbar) \mathcal{X}_{0,1}, \ \mathcal{N}_{3,3}(\hbar) = \mathcal{X}_{0,1}$$

[Page 100]

 $\mathcal{X}_{0,1}$  denotes the characteristic function of the interval [0,1). The parametric equation of the B-spline is:

$$\rho(\hbar) = (1 - \hbar)^3 \rho_0 + 3\hbar(1 - \hbar)^2 \rho_1 + 3\hbar^2(1 - \hbar)\rho_2 + \hbar^3 \rho_3 \quad t [0, 1)$$

This is exactly the equation for a cubic Bézier curve. When n > 3, the B-spline has more than one polynomial segment and more control points than a Bézier curve.

Java 2D does not directly support B-spline curves. However, a cubic B-spline curve may be converted to a series of cubic Bézier curves that can be rendered with the cubic Bézier curve support of Java 2D. Let  $\rho_0$ ,  $\rho_1$ , ...,  $\rho_n$  be the control points of a B-spline. Each segment of the B-spline can be converted to a cubic Bézier curve. Let the control points of a Bézier curve be  $\rho_0$ ,  $\rho_1$ ,  $\rho_2$ ,  $\rho_3$ . Then, except for the first and the last segment, the conversion is given by the following formula:

 $(p_{\neq 1} + 2p)/3$  $b_{-1} =$  $(2\rho_{i} + \rho_{i+1})/3$  $b_1$ =  $(b_{-1} + b_1)/2$  $b_0$ =  $(p_{/} + 2p_{/+1})/3$  $b_2$ =  $(2\rho_{+1} + \rho_{+2})/3$  $b_4$ =  $(b_2 + b_4)/2$ *b*<sub>3</sub> =

The first and the last segments are handled differently, because the first and last control points are the endpoints of the curve. The conversion of the first segment is given by the following formula:

 $b_{0} = p_{0}$   $b_{1} = p_{1}$   $b_{2} = (p_{1} + p_{2})/2$   $b_{4} = (2b_{2} + p_{3})/3$   $b_{3} = (b_{2} + b_{4})/2$ 

The last segment uses the following formula:

 $b_{-1} = (2\rho_{7-2} + \rho_{7-3})/3$   $b_1 = (\rho_{7-1} + \rho_{7-2})/2$   $b_0 = (b_{-1} + b_1)/2$   $b_2 = \rho_{7-1}$   $b_3 = \rho_{7-1}$ 

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Listing 4.1 illustrates the conversion and rendering of a B-spline curve. In this example a B-spline curve is converted to a series of cubic Bzier curves which is represented with a GeneralPath. A simple drawing program is implemented to allow the user to input control points with a mouse. The B-spline and its control points are displayed. A sample run of the program is shown in Figure 4.1.

[Page 101]

Listing 4.1. BSpline.java

(This item is displayed on pages 101 - 103 in the print version)



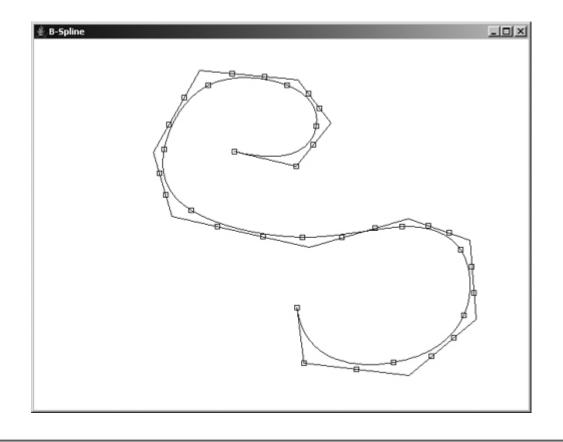
```
11
        JFrame frame = new JFrame();
12
        frame.setTitle("B-Spline");
        frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
13
14
        JApplet applet = new BSpline();
15
       applet.init();
16
        frame.getContentPane().add(applet);
17
       frame.pack();
18
       frame.setVisible(true);
19
    }
20
21
    public void init() {
22
       JPanel panel = new BSplinePanel();
23
        getContentPane().add(panel);
24
    }
25 }
26
27 class BSplinePanel extends Jpanel
28
      implements MouseListener, MouseMotionListener {
29
    Vector points = null;
30 boolean completed = true;
31
32 public BSplinePanel() {
33
      setPreferredSize(new Dimension(640, 480));
34
        setBackground(Color.white);
35
       addMouseListener(this);
36
       addMouseMotionListener(this);
37
       points = new Vector();
38
    }
39
40
    public void paintComponent(Graphics g) {
41
      super.paintComponent(g);
42
        Graphics2D g2 = (Graphics2D)g;
43
       Point p0 = null;
44
       Point p1 = null;
45
       Point p2 = null;
46
       Point p3 = null;
47
       float x1, y1, x2, y2, x3, y3, x4, y4;
48
        Iterator it = points.iterator();
49
        if (it.hasNext()) {
50
        p1 = (Point)(it.next());
51
       }
52
       while (it.hasNext()) {
53
        p2 = (Point)(it.next());
54
         g2.drawLine(p1.x, p1.y, p2.x, p2.y);
55
        p1 = p2;
56
       }
57
58
        GeneralPath spline = new GeneralPath();
[Page 102] 59
              int n = points.size();
       if (n == 0) return;
60
61
        pl = (Point)points.get(0);
62
       spline.moveTo(pl.x, pl.y);
       g2.drawRect(p1.x-3, p1.y-3, 6, 6);
63
64
       p1 = (Point)points.get(1);
65
       p2 = (Point)points.get(2);
66
       p3 = (Point)points.get(3);
67
       x1 = p1.x;
68
       y1 = p1.y;
69
       x2 = (p1.x + p2.x)/2.0f;
```

```
70
       y2 = (p1.y + p2.y)/2.0f;
 71
       x4 = (2.0f*p2.x+p3.x)/3.0f;
 72
       y4 = (2.0f*p2.y+p3.y)/3.0f;
 73
       x3 = (x2+x4)/2.0f;
 74
       y3 = (y2+y4)/2.0f;
 75
        spline.curveTo(x1, y1, x2, y2, x3, y3);
 76
        g2.drawRect((int)x1-3, (int)y1-3, 6, 6);
        g2.drawRect((int)x2-3, (int)y2-3, 6, 6);
 77
 78
        g2.drawRect((int)x3-3, (int)y3-3, 6, 6);
 79
       for (int i = 2; i < n - 4; i++) {
         p1 = p2;
 80
         p2 = p3;
 81
         p3 = (Point)points.get(i+2);
 82
 83
         x1 = x4;
 84
         y1 = y4;
 85
         x2 = (p1.x+2.0f*p2.x)/3.0f;
 86
          y2 = (p1.y+2.0f*p2.y)/3.0f;
 87
          x4 = (2.0f*p2.x+p3.x)/3.0f;
 88
          y4 = (2.0f*p2.y+p3.y)/3.0f;
 89
         x3 = (x2+x4)/2.0f;
 90
         y3 = (y2+y4)/2.0f;
 91
          spline.curveTo(x1,y1,x2,y2,x3,y3);
 92
          g2.drawRect((int)x1-3, (int)y1-3, 6, 6);
          g2.drawRect((int)x2-3, (int)y2-3, 6, 6);
 93
 94
          g2.drawRect((int)x3-3, (int)y3-3, 6, 6);
 95
       }
 96
       p1 = p2;
 97
       p2 = p3;
 98
       p3 = (Point)points.get(n-2);
 99
       x1 = x4;
100
       y1 = y4;
101
       x2 = (p1.x+2.0f*p2.x)/3.0f;
102
       y2 = (p1.y+2.0f*p2.y)/3.0f;
103
       x4 = (p2.x+p3.x)/2.0f;
104
       y4 = (p2.y+p3.y)/2.0f;
105
       x3 = (x2+x4)/2.0f;
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106
107
        g2.drawRect((int)x1-3, (int)y1-3, 6, 6);
108
109
        g2.drawRect((int)x2-3, (int)y2-3, 6, 6);
110
        g2.drawRect((int)x3-3, (int)y3-3, 6, 6);
111
       p2 = p3;
112
       p3 = (Point)points.get(n-1);
113
       x1 = x4;
114
       y1 = y4;
115
       x2 = p2.x;
116
       y2 = p2.y;
117
       x3 = p3.x;
118
       y3 = p3.y;
[Page 103]119
               spline.curveTo(x1,y1,x2,y2,x3,y3);
120
        g2.drawRect((int)x1-3, (int)y1-3, 6, 6);
121
        g2.drawRect((int)x2-3, (int)y2-3, 6, 6);
122
        g2.drawRect((int)x3-3, (int)y3-3, 6, 6);
123
        g2.draw(spline);
124
     }
125
     public void mouseClicked(MouseEvent ev) {
126
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127
128
      public void mouseEntered(MouseEvent ev) {
```

```
129
      }
130
131
      public void mouseExited(MouseEvent ev) {
132
      }
133
134
      public void mousePressed(MouseEvent ev) {
135
        Graphics g = getGraphics();
136
        if (completed) {
137
          points.clear();
          completed = false;
138
139
        }
        if (ev.getClickCount() == 1) {
140
141
          Point p =ev.getPoint();
142
          points.add(p);
143
          g.fillOval(p.x-3, p.y-3, 6, 6);
144
        }
145
      }
146
147
      public void mouseReleased(MouseEvent ev) {
148
        if (ev.getClickCount() > 1) {
149
          completed = true;
150
          repaint();
151
        }
152
      }
153
154
      public void mouseMoved(MouseEvent ev) {
155
      }
156
157
      public void mouseDragged(MouseEvent ev) {
158
      }
159 }
```

Figure 4.1. A B-spline curve rendered with a series of Bézier curves. The polygon represents the control points of the B-spline curve, and the small squares indicate the locations of control points of the Bézier curves.

(This item is displayed on page 104 in the print version)



[Page 103]

Note

The B-spline curve conversion shown above is only for the simple type of B-spline discussed in this section. More general types of B-splines with nonuniform *knots* can also be converted to Bézier curves. UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

The class BSplinePanel extends the JPanel class and provides a panel for drawing a B-spline curve. A vector points (line 29) is defined to hold the input control points of the B-spline curve. Mouse events are processed to enter the control points. A single mouse click defines one control point, and the point is shown as a small filled circle. A double click defines the last control point of the curve and completes the control-point entry. For simplicity only one B-spline curve is defined at any moment. After all control points are entered, the B-spline curve is drawn by the paintComponent method.

The conversion from the B-spline curve to Bézier curves is performed in the paintComponent method. The conversion uses the formulas introduced in this section. A GeneralPath object is used to hold the converted sequence of Bézier curves (line 58). The path is drawn after all curve segments are converted. The control polygon formed by the control points is shown as a series of line segments (line 54). The small squares in the display show the Bézier control points after the conversion.

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### 4.3. Custom Primitives

As seen from the previous chapters, geometric primitives defined as classes in the Shape family can be transformed and rendered in a uniform fashion. It is also possible to define your own primitives that behave just like the built-in classes. The key is the Shape interface that has ten abstract methods.

```
public boolean contains(Rectangle2D rect)
public boolean contains(Point2D point)
public boolean contains(double x, double y)
public boolean contains(double x, double y, double w, double h)
public Rectangle getBounds()
public Rectangle2D getBounds2D()
public PathIterator getPathIterator(AffineTransform at)
public PathIterator getPathIterator(AffineTransform at, double flatness)
public boolean intersects(Rectangle2D rect)
public boolean intersects(double x, double y, double w, double h)
```

The contains methods test whether the given point or rectangle is entirely contained in the shape. The intersects methods test for intersections. The getBounds and getBounds2D methods return the bounding rectangle of the shape. The getPathIterator method returns a PathIterator object that describes the path using the basic drawing segments.

Extending the class GeneralPath may appear to be an easy way to implement a custom primitive, because GeneralPath provides an implementation for all the Shape methods and it allows all the basic drawing functions for a path. Unfortunately, this approach is not possible, because GeneralPath is declared as a final class, so further extension is not allowed. You may still take advantage of the GeneralPath implementation by wrapping it in your class. The required methods declared in the Shape interface can be implemented simply by invoking the corresponding methods in GeneralPath. Listing 4.2 illustrates this approach. This example shows the construction of a custom Shape by wrapping a GeneralPath object. A heart shape is constructed with two cubic curves (Figure 4.2).

Listing 4.2. Heart.java

[Page 105]

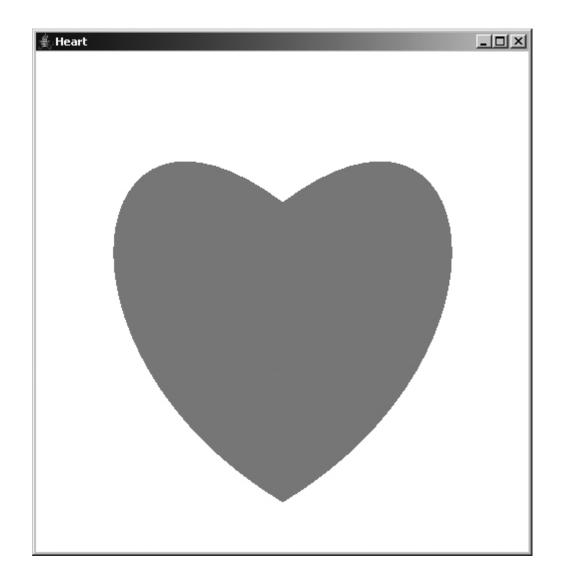
(This item is displayed on pages 105 - 106 in the print version)

```
1 package chapter4;
 2
 3 import java.awt.*;
 4 import java.awt.geom.*;
 5 import javax.swing.*;
 6
 7 public class Heart implements Shape {
 8
     GeneralPath path;
 9
10
    public Heart(float x, float y, float w, float h) {
11
       path = new GeneralPath();
12
      float x0 = x + 0.5f*w;
      float y0 = y + 0.3f*h;
13
14
      float x1 = x + 0.1f*w;
15
      float y1 = y + 0f * h;
16
      float x^2 = x + 0f * w;
17
       float y^2 = y + 0.6f * h;
       float x3 = x + 0.5f * w;
18
```

```
float y3 = y + 0.9f * h;
19
      float x4 = x + 1f * w;
20
      float y4 = y + 0.6f * h;
21
      float x5 = x + 0.9f * w;
22
      float y5 = y + 0f * h;
23
24
       path.moveTo(x0, y0);
25
       path.curveTo(x1, y1, x2, y2, x3, y3);
       path.curveTo(x4, y4, x5, y5, x0, y0);
26
27
    }
28
29
     public boolean contains(Rectangle2D rect) {
30
      return path.contains(rect);
31
     }
32
33
    public boolean contains(Point2D point) {
34
     return path.contains(point);
35
     }
36
37
    public boolean contains(double x, double y) {
38
      return path.contains(x, y);
39
     }
40
    public boolean contains(double x, double y, double w, double h) {
41
42
      return path.contains(x, y, w, h);
43
44
45
     public Rectangle getBounds() {
46
     return path.getBounds();
47
48
49
     public Rectangle2D getBounds2D() {
50
     return path.getBounds2D();
51
     }
[Page 106]52
53
     public PathIterator getPathIterator(AffineTransform at) {
       return path.getPathIterator(at);
54
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55
56
57
     public PathIterator getPathIterator(AffineTransform at,
58
     double flatness) {
59
       return path.getPathIterator(at, flatness);
60
     }
61
    public boolean intersects(Rectangle2D rect) {
62
63
     return path.intersects(rect);
64
     }
65
     public boolean intersects(double x, double y, double w, double h) {
66
67
       return path.intersects(x, y, w, h);
68
     }
69 }
```

Figure 4.2. A heart-shape primitive constructed with a General Path object using two symmetric cubic

curves.



The class Heart implements the Shape interface so it can be used like other geometric primitives in the Shape family. A GeneralPath object is created and stored in the variable path (line 8). The ten required methods in Shape are implemented by calling the corresponding methods in path.

The Heart class defines a constructor that specifies a bounding rectangle for the shape. In the constructor (line 10), the GeneralPath object is constructed and the path of the heart shape is defined. Two symmetric cubic curves define the left and right sides of the heart. The control points are calculated and the curves are constructed with the curveTo method of the GeneralPath class. The closed path forms a region that can be filled.

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In Listing 4.3, an applet TestHeart with a main method is included to test the Heart primitive. An anonymous subclass of JPanel is created and added to the applet. The panel overrides the paintComponent method to paint a Heart object filled with the color red.

Listing 4.3. TestHeart.java

```
1 package chapter4;
 2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5 import javax.swing.*;
 6 import java.awt.geom.*;
 7
 8 public class TestHeart extends JApplet {
 9
    public static void main(String s[]) {
10
        JFrame frame = new JFrame();
11
        frame.setTitle("Heart");
12
        frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
13
        JApplet applet = new TestHeart();
14
        applet.init();
15
        frame.getContentPane().add(applet);
16
        frame.pack();
17
        frame.setVisible(true);
18
    }
19
20
    public void init() {
21
      JPanel panel = new JPanel() {
22
         public void paintComponent(Graphics g) {
23
           super.paintComponent(g);
24
           Heart h = new Heart(0, 0, 500, 500);
25
           g.setColor(Color.red);
26
           ((Graphics2D)g).fill(h);
27
        }
       };
28
29
       panel.setBackground(Color.white);
30
       panel.setPreferredSize(new Dimension(500,500));
31
       getContentPane().add(panel);
32
    }
33 }
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```

### 4.4. I mage Processing

A digital image is a raster representation of a 2D picture and is defined by an array of point values called *pixels*. Each pixel value represents the color, gray level, and other attributes of the corresponding point. Even though image processing is a separate specialized subject, it does have a close connection with computer graphics. Images are useful objects in graphics rendering. The output of graphics rendering is typically an image. Java 2D offers powerful image-processing facilities.

In AWT, an image is represented by the Image class. AWT uses a "*push*" *mode*/for images. The data for the image is not necessarily available when the Image is created. An object implementing the ImageProducer interface is a producer, and an object implementing the ImageConsumer is a consumer. A producer acts as the source of the image, and a consumer receives the data from a producer. Between a producer and a consumer, there can also be a chain of filters that implement both ImageProducer and ImageConsumer. A producer pushes the data to the consumer in an asynchronous fashion. The consumer cannot request data. The data transfer process can be monitored by an instance of ImageObserver. This model is designed with the idea of loading images over a network. However, the "push" model is not very convenient for image processing.

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Java 2D introduces a new "*immediate*" *model*. The new image class BufferedImage is used to represent an image with an immediately available data store. A BufferedImage contains a Raster and a ColorModel. A Raster represents pixel values in numerical forms and a ColorModel specifies the mapping between the numerical values in the Raster and the actual colors.

Note



Java Advanced Image (JAI) is an optional package that offers even more advanced and comprehensive image-processing capabilities. JAI is not covered in this book.

A typical image-processing cycle is illustrated in Figure 4.3.

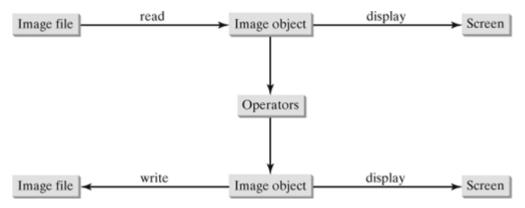


Figure 4.3. An image-processing system.

The source image is usually given as a file in one of many image-file formats. An image object is created in the

Java program to represent an image. The external image file needs to be read into the image object. The image may be displayed in a device such as a screen or a printer. The next step is to process the image through one or more image-processing operators. The result is another image object. The processed image can be displayed and written to an external image file.

A Java 2D image processing program usually uses BufferedImage to represent images. A BufferedImage object can be created using one of its constructors. For example, the following statement creates a blank buffered image:

```
BufferedImage bi = new BufferedImage(300, 400, BufferedImage.
TYPE_INT_RGB);
```

To draw on a BufferedImage, we need to obtain a Graphics2D object:

```
Graphics2D g2 = (Graphics2D)(bi.createGraphics());
```

With the Graphics2D object g2 you may perform all types of graphics renderings on the BufferedImage, just like drawing to the screen.

In J2SDK versions prior to 1.4, standard Java 2D does not directly support loading a BufferedImage from external files or network sources. To load an image from a file to an Image object, we can use the old AWT facilities, as follows:

```
Image image = Toolkit.getDefaultToolkit().getImage(imageFileName);
```

In an applet, instead of using the Toolkit object, an image can be loaded from a network URL using the getImage(url) method of the Applet class.

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In the push model, the images are loaded asynchronously. The above call will return immediately without waiting for the image loading to complete. If we want to be sure that the image is fully loaded, we may use a

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```
MediaTracker tracker = new MediaTracker(new Component() {});
tracker.addImage(image, 0);
try {
   tracker.waitForID(0);
} catch (InterruptedException ex) {
}
```

The constructor of MediaTracker requires a parameter of class Component. Because Component is an abstract class, it is not possible to create a generic instance of Component. Instead, the above code uses an instance of an anonymous subclass new Component() {} as the parameter.

The above procedure only reads an external image to an Image object image. To convert the externally loaded Image to a BufferedImage, you may use the Graphics2D object g2 associated with the BufferedImage object bi. The drawImage method of g2 allows the drawing of the image into bi.

g2.drawImage(image, 0, 0, new Component() {});



the class Component implements the ImageObserver interface, the anonymous subclass can be used as a generic parameter. You may also use null for the image observer. If this code is in a GUI application, then a GUI component such a JPanel object is usually used as the image observer. The purpose of the ImageObserver object is to support asynchronous loading of images in the original AWT push model. The default implementation for ImageObserver in Component is to repaint the component so that the image can be drawn incrementally as the image data arrives.

J2SDK 1.4 includes the new ImageIO API that offers support for direct reading and writing of BufferedImage. To read an image from a file, you can simply call the following static method:

```
BufferedImage bi = ImageIO.read(file);
```

Once we have a BufferedImage object properly set up, we may apply image-processing operations to it. Java 2D contains a set of classes for image operations. These classes implement the BufferedImageOp interface, as shown in Figure 4.4.

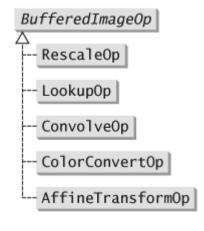


Figure 4.4. BufferedImageOp is a common interface for buffered image operations.

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RescaleOp performs pixel-by-pixel rescaling of the pixel values by a linear function. A pixel value is multiplied by a scaling factor and then an offset is added. If f(x, y) and g(x, y) represent the pixel values of the images before and after the processing, then the rescale operation can be written as

g(x, y) = af(x, y) + b

ColorConvertOp performs pixel-by-pixel conversions of colors. The operation can be specified with color spaces.

LookupOp performs pixel-by-pixel conversions of pixel values based on lookup tables. The operator can be expressed as

 $\mathcal{G}(X, \mathcal{Y}) = \mathcal{T}(\mathcal{I}(X, \mathcal{Y}))$ 

AffineTransformOp performs affine transforms on the image. The operator does not change the value of a pixel, but it moves the pixel to a different location. The AffineTransform object is used to set the transform. The formula for affine transform operator is

 $\mathcal{G}(X, \mathcal{Y}) = f(\mathcal{A}(X, \mathcal{Y}))$ 

ConvolveOp defines convolution operators. A convolution is a linear transformation. If an image is represented mathematically by a function f(x, y), the convolution can be expressed as

$$g(x, y) = \iint K(x - u, y - v)f(u, v) \, du \, dv$$

where *K* is a fixed function known as the *kernel*. The property of the convolution is determined by the kernel. By choosing appropriate kernels, you may achieve various effects on the images, such as smoothing, sharpening, and edge detection.

For digital images, the integrals become summations.

$$g(x, y) = \sum_{i} \sum_{j} K(x - i, y - j) f(i, j)$$

The indices i from through the entire image. To improve the efficiency, the kernel is often chosen to have a finite support; that is, k is 0 except for a neighborhood of the origin. For example, k(i, j) may have only nine nonzero values when  $-1 \leq i$ ,  $j \leq 1$ . In this case, the above convolution formula becomes

$$g(x, y) = \sum_{i=x-1}^{x+1} \sum_{j=y-1}^{y+1} K(x - i, y - j) f(i, j)$$

At each point, only the nine pixels around the point need to be considered for the calculation.

In Java UNREG ISSTEERED BVE ERSIGN MORE IGHEIMLET OUTBORT HORDER PRO

```
dst = op.filter(src, null);
```

A BufferedImage can be displayed using the drawImage method of the Graphics object. For example,

```
public void paintComponent(Graphics g) {
    super.paintComponent(g);
    g.drawImage(bi, 0, 0, this);
}
```

This code segment may be inside a component such as JPanel. The drawImage call paints the BufferedImage starting at the location (0, 0).

Prior to J2SDK 1.4, Java 2D does not contain direct support for exporting a BufferedImage to an external file or encoding the image in a standard image file format. The new ImageIO class offers the static write method to store the image to an external file:

```
Image IU WIRE GISTERED VERSION OF CHM TO PDF CONVERTER PRO
```

[Page 111]

The first parameter is the BufferedImage object to be saved. The second parameter is a string specifying the file format. The third object is a File object representing the external file to write.

Listing 4.4 shows a complete image-processing program with I/O, processing, and display. A user may load an image from a disk file, perform several common image-processing operations, and save the processed image to a disk file. A sample run of the program is shown in Figure 4.5.

#### Listing 4.4. ImageProcessing.java

(This item is displayed on pages 111 - 114 in the print version)

```
1 package chapter4;
 2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5 import java.awt.image.*;
 6 import java.awt.color.*;
7 import java.awt.geom.*;
8 import java.io.*;
9 import javax.swing.*;
10 import javax.imageio.*;
11
12 public class ImageProcessing extends JFrame implements
13 ActionListener {
14
    public static void main(String[] args) {
15
       JFrame frame = new ImageProcessing();
16
       frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
17
       frame.pack();
18
       frame.setVisible(true);
19
     }
20
21
     ImagePanel imageSrc, imageDst;
22
     JFileChooser fc = new JFileChooser();
23
24
    public ImageProcessing() {
25
       JMenuBar mb = new JMenuBar();
       setJMenuBar(mb);
26
27
28
       JMenu menu = new JMenu("File");
29
       JMenuItem mi = new JMenuItem("Open image");
30
       mi.addActionListener(this);
31
       menu.add(mi);
32
       mi = new JMenuItem("Open image (awt)");
33
       mi.addActionListener(this);
34
       menu.add(mi);
35
       mi = new JMenuItem("Save image");
36
       mi.addActionListener(this);
37
       menu.add(mi);
38
       menu.addSeparator();
39
       mi = new JMenuItem("Exit");
40
       mi.addActionListener(this);
41
       menu.add(mi);
42
       mb.add(menu);
43
44
       menu = new JMenu("Process");
45
       mi = new JMenuItem("Copy");
46
       mi.addActionListener(this);
47
       menu.add(mi);
```

```
48
        mi = new JMenuItem("Smooth");
 49
        mi.addActionListener(this);
 50
        menu.add(mi);
 51
        mi = new JMenuItem("Sharpen");
 52
        mi.addActionListener(this);
 53
        menu.add(mi);
[Page 112] 54
              mi = new JMenuItem("Edge");
 55
        mi.addActionListener(this);
 56
        menu.add(mi);
 57
        mi = new JMenuItem("Rescale");
 58
        mi.addActionListener(this);
 59
        menu.add(mi);
        mi = new JMenuItem("Rotate");
 60
 61
        mi.addActionListener(this);
 62
        menu.add(mi);
 63
        mi = new JMenuItem("Gray scale");
 64
        mi.addActionListener(this);
 65
        menu.add(mi);
 66
       mb.add(menu);
 67
 68
        Container cp = this.getContentPane();
        cp.setLayout(new FlowLayout());
 69
 70
        imageSrc = new ImagePanel();
        imageDst = new ImagePanel();
 71
 72
        cp.add(imageSrc);
 73
        cp.add(imageDst);
 74
     }
 75
 76
     public void actionPerformed(ActionEvent ev) {
 77
        String cmd = ev.getActionCommand();
 78
        if ("Open image".equals(cmd)) {
 79
          int retval = fc.showOpenDialog(this);
 80
          if (retval == JFileChooser.APPROVE_OPTION) {
 81
           try {
 82
              BufferedImage bi = ImageIO.read(fc.getSelectedFile());
 83
              imageSrc.setImage(bi);
                                    ERSION OF CHM TO PDF CONVERTER PRO
             Catch (IOException ex)
 84
 85
              ex.printStackTrace();
 86
 87
           }
 88
          }
 89
        } else if ("Open image (awt)".equals(cmd)) {
          int retval = fc.showOpenDialog(this);
 90
 91
          if (retval == JFileChooser.APPROVE_OPTION) {
 92
            Toolkit tk = Toolkit.getDefaultToolkit();
 93
            Image img = tk.getImage(fc.getSelectedFile().getPath());
            MediaTracker tracker = new MediaTracker(new Component() {});
 94
           tracker.addImage(img, 0);
 95
 96
           try {
 97
              tracker.waitForID(0);
 98
            } catch (InterruptedException ex) {}
 99
            BufferedImage bi = new BufferedImage(img.getWidth(this),
100
            img.getHeight(this), BufferedImage.TYPE_INT_RGB);
101
            bi.getGraphics().drawImage(img, 0, 0, this);
102
            imageSrc.setImage(bi);
103
          }
          REGISTERED VERSION OF CHM TO PDF CONVERTER PRO
104
105
106
          if (retval == JFileChooser.APPROVE_OPTION) {
```

```
107
            try{
108
               ImageIO.write(imageDst.getImage(), "png",
109
                fc.getSelectedFile());
110
            } catch (IOException ex) {
111
               ex.printStackTrace();
112
            }
113
          }
[Page 113]114
                } else if ("Exit".equals(cmd)) {
          System.exit(0);
115
        } else if ("Copy".equals(cmd)) {
116
117
          imageSrc.setImage(imageDst.getImage());
118
        } else {
119
          process(cmd);
120
        }
121
      }
122
123
      void process(String opName) {
124
        BufferedImageOp op = null;
        if (opName.equals("Smooth")) {
125
126
          float[] data = new float[9];
127
          for (int i = 0; i < 9; i++) data[i] = 1.0f/9.0f;</pre>
128
          Kernel ker = new Kernel(3,3,data);
129
          op = new ConvolveOp(ker);
130
        } else if (opName.equals("Sharpen")) {
131
          float[] data = {0f, -1f, 0f, -1f, 5f, -1f, 0f, -1f, 0f};
132
          Kernel ker = new Kernel(3,3,data);
133
          op = new ConvolveOp(ker);
134
        } else if (opName.equals("Edge")) {
135
          float[] data = {0f, -1f, 0f, -1f, 4f, -1f, 0f, -1f, 0f};
136
          Kernel ker = new Kernel(3,3,data);
137
          op = new ConvolveOp(ker);
138
        } else if (opName.equals("Rescale")) {
139
          op = new RescaleOp(1.5f, 0.0f, null);
140
        } else if (opName.equals("Gray scale")) {
141
          op = new ColorConvertOp(ColorSpace.getInstance
142
          (ColorSpace.CS_GRAY), null);
143
        } else if (opName.equals("Rotate")) {
144
          AffineTransform xform = new AffineTransform();
145
           xform.setToRotation(Math.PI/6);
146
           op = new AffineTransformOp(xform, AffineTransformOp.
147
            TYPE_BILINEAR);
148
        }
149
        BufferedImage bi = op.filter(imageSrc.getImage(), null);
150
        imageDst.setImage(bi);
151
        pack();
152
      }
153 }
154
155 class ImagePanel extends JPanel {
156
      BufferedImage image = null;
157
158
      public ImagePanel() {
159
        image = null;
160
        setPreferredSize(new Dimension(256, 256));
161
      }
162
163
      public ImagePanel(BufferedImage bi) {
164
        image = bi;
165
      }
```

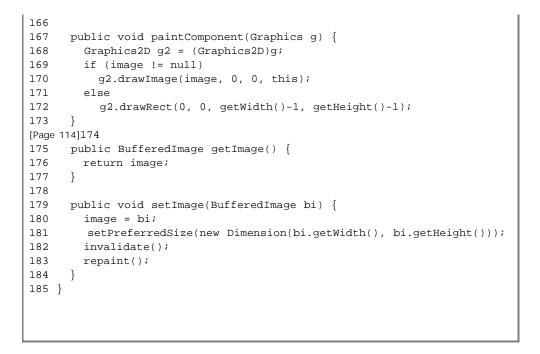


Figure 4.5. I mage sharpening is one of the operations supported by this image-processing example program.



This program is an example of image-processing systems. It provides basic functions of image I/O, operations, and displays. The main frame of the program contains two menus. The "File" menu has items to open an image file using AWT facilities, to save an image to a file, and to exit the program. The "Process" menu to hai premetric splice to splice the content pare of the content pare of the content pare of the content pare of the source image on the left and the processed image on the right.

The ImagePanel class extends the JPanel class and it displays a BufferedImage. An image can be passed to the ImagePanel by a constructor or by the method setImage.

The program implements two different ways to load image files. One method uses the static method read of the ImageIO class to load an image file directly to a BufferedImage object (line 82). The other uses AWT image loading and a BufferedImage is obtained by drawing the image (lines 92–101). A JFileChooser object is used to allow the user to select an image file to open.

Several operations are implemented to perform common image-processing tasks including: smooth, sharpen, edge detection, rescale, rotation, and grayscale. The smooth operator is a convolution defined by the following 3 x 3 kernel:

[ 1/9	1/9	1/9
1/9 1/9 1/9	1/9	1/9
_ 1/9	1/9	1/9

[Page 115]

The sharpen operator is defined with the kernel

0	-1	$0 \\ -1$
-1	5	-1
0	-1	0_

The edge-detection operator has the kernel

0	-1	0
$\begin{vmatrix} 0\\ -1\\ 0 \end{vmatrix}$	4	-1
0	-1	0

The rescale operation uses the RescaleOp class. It is designed to brighten the image.

The rotation operation uses the AffineTransformOp class. A rotation of p/6 is defined by an AffineTransform object and applied to the AffineTransformOp object.

The grayscale operation uses the ColorConvertOp class to convert the source image to a grayscale image.

The copy operation simply copies the processed image back to the source image so that additional processing can be applied.

The processed image can be saved to a disk file in PNG format. A JFileChooser is used to select a file to write. The ImageIO static method save is used to save an image.

◀ Previous

Next 🕨

### 4.5. Creating Fractal I mages

In the last section, we discussed how to create, load, save, process, and display a BufferedImage. It is also possible to perform low-level operations and directly manipulate the pixels in a BufferedImage.

The Raster class encapsulates the pixel data of the BufferedImage. The WritableRaster is a subclass of Raster that is writable. To obtain a WritableRaster object from a BufferedImage, you may use the getRaster method:

```
BufferedImage bi = new BufferedImage(640, 480, BufferedImage.TYPE_ARGB);
WritableRaster raster = bi.getRaster();
```

The Raster class provides a number of methods to get pixel data, and WritableRaster adds methods to set pixel data.

```
int[] getPixel(int x, int y, int[] data);
float[] getPixel(int x, int y, float[] data);
double[] getPixel(int x, int y, double[] data);
int[] getPixels(int x, int y, int w, int h, int[] data);
float[] getPixels(int x, int y, int w, int h, float[] data);
double[] getPixels(int x, int y, int w, int h, double[] data);
void setPixel(int x, int y, int[] data);
void setPixel(int x, int y, float[] data);
void setPixel(int x, int y, float[] data);
void setPixel(int x, int y, int w, int h, int[] data);
void setPixels(int x, int y, int w, int h, int[] data);
void setPixels(int x, int y, int w, int h, float[] data);
void setPixels(int x, int y, int w, int h, float[] data);
```

The parameters *x*, *y* specify the location of the pixel and *w* / define the dimension of a rectangle of pixels. The *data* and whole the base data in Dize/dt the analythe points on the two of the mage. For example, in Rei ER PR BufferedImage is TYPE\_INT\_RGB, then the data array for each pixel has three elements containing the RGB values.

[Page 116]

Through the WritableRaster object, the contents of an image can be created at the pixel level. This method of pixel-by-pixel image generation may be illustrated by the example of building a fractal image. A fractal is a self-similar geometric structure. Fractals often exhibit a great deal of complexity, even though they might be generated by some rather simple procedures. The *Mandelbrot set* is a well-known example of fractals. It is defined on the complex plane. A complex number has the form

x + iy

where x and y are real numbers and /satisfies the equation  $\lambda^2 = -1$ . The addition and multiplication of two complex numbers  $z_1 = x_1 + iy_1$  and  $z_2 = x_2 + iy_2$  are defined as:

 $Z_1 + Z_2 = (X_1 + X_2) + (Y_1 + Y_2)$ 

The absolute value of a complex number is  $|x + iy| = \sqrt{x^2 + y^2}$ . A complex number can be interpreted as a point on a 2D plane by identifying the (x, y) values as the coordinates of the point. The absolute value of the complex number corresponds to the distance of the point to the origin.

To define the Mandelbrot set, we consider the iteration on the complex plane:

$$z_{n+1} = z_n^2 + c$$

*c* is a complex number, and the starting point of iteration is  $z_0 = 0$ . For a given *c* the iteration will produce a sequence of complex numbers:  $z_0, z_1, ..., z_n$  .... It can be shown that the sequence either tends to infinity or stays bounded. The Mandelbrot set is defined to be the set of points *c* such that the iteration sequence is bounded. The Mandelbrot set is surprisingly complex. It contains recursively self-similar substructures. It is known that the Mandelbrot set is contained in the circle of radius 2 centered at the origin, and if at any step of the iteration the point goes outside the circle, the sequence will escape to infinity and the corresponding *c* does not belong to the Mandelbrot set.

Listing 4.5 illustrates a way to build an image based on the Mandelbrot set. This example creates an image approximating the Mandelbrot set. The iteration process is carried out for each pixel and the number of iterations is color coded to create the image. A sample run of the program is shown in Figure 4.6

```
Listing 4.5. Mandelbrot.java
```

(This item is displayed on pages 116 - 117 in the print version)

```
1 package chapter4;
 2
 3 import javax.swing.*;
 4 import java.awt.*;
 5 import java.awt.image.*;
 6
 7 public class Mandelbrot extends JApplet {
 8 public static void main(String s[]) {
 9
      JFrame frame = new JFrame();
10
      frame.setTitle("Mandelbrot set");
11
       frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
12
       JApplet applet = new Mandelbrot();
13
       applet.init();
14
       frame.getContentPane().add(applet);
       frame.pack();
15
[Page 117]16
             frame.setVisible(true);
17
    }
18
19
    public void init() {
20
       JPanel panel = new MandelbrotPanel();
21
       getContentPane().add(panel);
22
    }
23 }
24
25 class MandelbrotPanel extends JPanel{
26 BufferedImage bi;
27
28
   public MandelbrotPanel() {
29
     int w = 500;
30
       int h = 500;
31
      setPreferredSize(new Dimension(w, h));
32
       setBackground(Color.white);
```

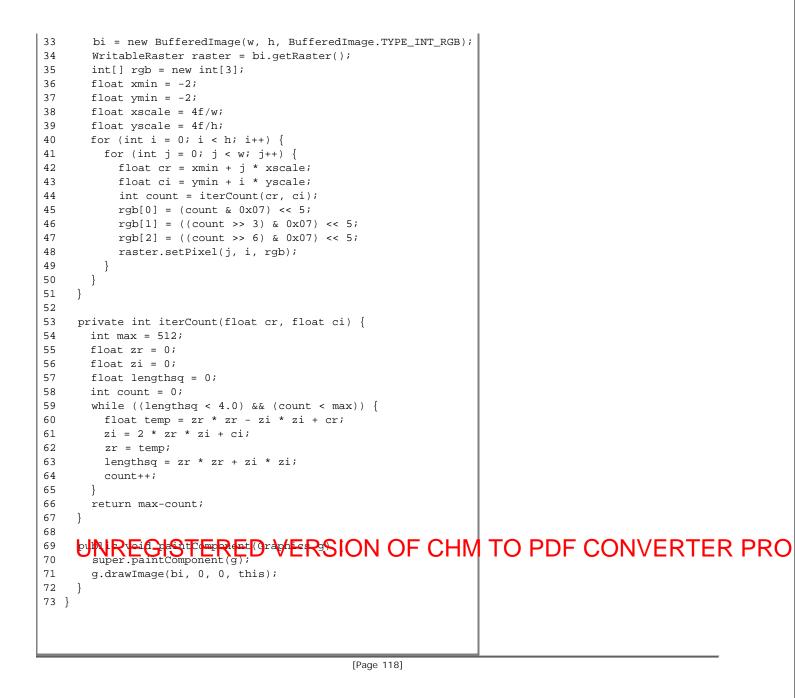
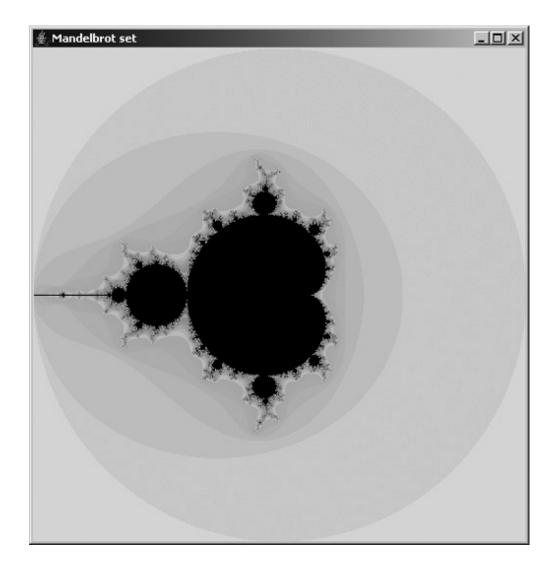


Figure 4.6. The Mandelbrot set colored with the number of iterations.



This program creates an image depicting the Mandelbrot set in the complex plane over the square:

## $_{-2} \leq _{X, Y} \leq _{2}$

A BufferedImage is created with the size 500 x 500 and with the integer RGB pixel type. A WritableRaster object is obtained from the image (line 34). The pixels of the image are set through the raster. The pixel indices are mapped to the coordinates on the complex plane by linear functions.

The iterations are carried out by the method iterCount. A complex number is represented by two float

variables. The iteration terminates if the value goes outside the circle  $Z_r > 2$  (or, equivalently,  $Z_r ^2 > 4$ ). The maximum number of iterations for each pixel is limited to 512, so the iteration count is in the range [1, 512]. The complement of the counter *max-count* is used to color a pixel. It has the range [0, 511]. The 9-bit counter value is divided into three 3-bit RGB components.

The paintComponent method draws the completed image to MandelbrotPanel, a subclass of JPanel. Because of the large number of calculations required in generating the Mandelbrot image, it may take a while for the image to appear in the window.

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[Page 118 (continued)]

### 4.6. Animation

Animation introduces dynamic changes to graphics contents and often creates a visual effect of motion. An animation produces a series of rendered images (frames) that depicts the changes in a scene. When the frames are displayed consecutively at certain rate (for example, 60 frames per second), we may perceive continuous motion in the scene rather than discrete images. Animation adds a dimension of time to the graphics model. Each rendered frame at a specific time instance is essentially a regular still image. However, the content of the frames may change over time. Higher *frame rates* represent smoother animations, but the frame rate of an animation is limited by the capability of the rendering system.

Implementing animation in Java usually requires additional threads to handle the time-related changes. Because an animation typically runs indefinitely, placing all animation code in the event dispatch thread will make the GUI program not responsive. However, when using Swing components to display graphics animation, you need to avoid direct manipulation of the Swing components from the thread other than the event dispatch thread, because Swing components are not *thread safe*. For example, in the animation thread, you should not call getGraphics() method and use the Graphics object to do graphics painting. There are several methods of Swing components that are safe to call from other threads:

[Page 119]

```
public void repaint()
public void revalidate()
```

Therefore, a proper way to create an animation on Swing components is to separate the rendering from the model changes. The rendering code is placed in the paintComponent method of the Swing component only. The animation logic is placed in the separate thread without actual rendering. When the data for a frame is ready, the method repaint() is called to trigger the rendering. An outline of a typical multithread animation is shown below.

The paintComponent method contains all the rendering code to generate a frame. The run method of the Runnable interface or the Thread class is overridden to perform the animation. It typically contains an infinite loop to continuously generate the frames. A frame is rendered by calling the repaint method. Between two frames, the thread typically goes to sleep for a specific period of time. The sleep method of Thread specifies a sleep time in milliseconds.

Listing 4.6 creates a simple scene of simulated rain. Numerous vertical line segments are moving downward. The locations and the lengths of the lines are random. A sample run of the program is shown in Figure 4.7.

Listing 4.6. Rain.java

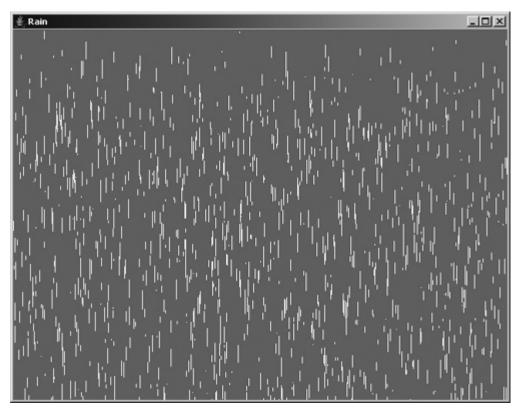
(This item is displayed on pages 119 - 120 in the print version)

```
1 package chapter4;
 2
 3 import java.awt.*;
 4 import java.awt.geom.*;
 5 import java.awt.event.*;
 6 import java.util.*;
 7 import javax.swing.*;
 8
 9 public class Rain extends JApplet {
10
    public static void main(String s[]) {
11
       JFrame frame = new JFrame();
12
       frame.setTitle("Rain");
13
       frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
[Page 120]14
              JApplet applet = new Rain();
15
       applet.init();
16
       frame.getContentPane().add(applet);
17
       frame.pack();
18
       frame.setVisible(true);
19
    }
20
21
    public void init() {
22
       JPanel panel = new RainPanel();
23
       getContentPane().add(panel);
24
    }
25 }
26
27 class RainPanel extends JPanel implements Runnable{
    Point2D.Double[] pts = new Point2D.Double[1200];
28
29
30
    public RainPanel() {
31
      setPreferredSize(new Dimension(640, 480));
32
       setBackground(Color.gray);
       for (int i = 0; i < pts.length; i++) {
33
         pts[i] = new Point2D.Double(Math.random(), Math.random());
34
35
       }
36
                  STERED VERSION OF CHM TO PDF CONVERTER PRO
37
38
    }
39
40
    public void paintComponent(Graphics g) {
41
       super.paintComponent(g);
42
       g.setColor(Color.white);
43
       for (int i = 0; i < pts.length; i++) {</pre>
44
         int x = (int)(640*pts[i].x);
         int y = (int)(480*pts[i].y);
45
         int h = (int)(25*Math.random());
46
47
         g.drawLine(x, y, x, y+h);
48
      }
49
    }
50
    public void run() {
51
52
      while(true) {
53
         for (int i = 0; i < pts.length; i++) {
54
           double x = pts[i].getX();
55
           double y = pts[i].getY();
56
           y += 0.1*Math.random();
         REGISTERED VERSION OF CHM TO PDF CONVERTER PRO
57
58
59
            x = Math.random();
```

```
60
            }
61
            pts[i].setLocation(x, y);
62
         }
63
         repaint();
64
         try {
65
            Thread.sleep(100);
66
          } catch (InterruptedException ex) {}
67
68
     }
69 }
```

[Page 121]





The class RainPanel extends JPanel and implements Runnable interface. An array pts of Point2D.Double is used to store the locations of the lines (line 28). They are initialized to random values.

The paintComponent method draws the vertical lines based on the values in the pts array (scaled to component size) and random lengths.

A new thread is created in the constructor of Rain to execute the code provided by the run method in the same class. The run method (line 51) contains an infinite loop that updates line locations in the pts array. Each point is increased by a random amount in the  $\mu$ -coordinate, so the line drops down. When a line reaches the bottom,

the point is reset to a random location in the top region. After the array is updated, the repaint method is called to redraw the panel. The thread then goes to sleep for 100 milliseconds.

An instance of RainPanel is placed in the applet Rain. A standard main method is included to run the animation as an application.

An alternative to creating your own thread is to use the Timer class provided by Swing. A Timer object periodically generates an action event at a predefined rate. The events will trigger the listeners, which may perform the rendering of a frame. To set up a Timer object, you may specify its period and listeners in its constructor and call its start() method:

```
Timer timer = new Timer(period, listener);
timer.start();
```

The ActionListener object should implement the rendering in its actionPerformed method:

```
public void actionPerformed(ActionEvent event) {
    <* do frame rendering *>
}
```

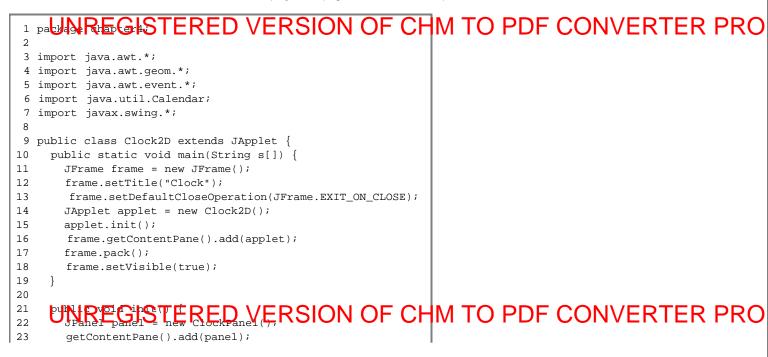
The Timer class provides a more convenient approach for animation than explicit creation of threads. Because the actionPerformed method is invoked in the event dispatch thread, it is safe to perform rendering on Swing components in the method.

[Page 122]

Listing 4.7 demonstrates the application of the Timer class. A real-time analog clock is displayed as shown in Figure 4.8. The time of the clock is from the system time. The clock is updated continuously to achieve the visual effect of clock movements.

Listing 4.7. Clock2D.java

(This item is displayed on pages 122 - 123 in the print version)



```
24
    }
25 }
26
27 class ClockPanel extends JPanel implements ActionListener{
28
    AffineTransform rotH = new AffineTransform();
     AffineTransform rotM = new AffineTransform();
29
30
    AffineTransform rotS = new AffineTransform();
31
    public ClockPanel() {
32
33
      setPreferredSize(new Dimension(640, 480));
34
       setBackground(Color.white);
35
       Timer timer = new Timer(500, this);
36
       timer.start();
37
    }
38
     public void paintComponent(Graphics g) {
39
40
       super.paintComponent(g);
41
       Graphics2D g2 = (Graphics2D)g;
42
       g2.translate(320,240);
43
       // clock face
      Paint paint = new GradientPaint
44
       (-150,-150,Color.white,150,150,Color.gray);
45
46
       g2.setPaint(paint);
47
       g2.fillOval(-190, -190, 380, 380);
48
       g2.setColor(Color.gray);
49
       g2.drawString("Java 2D", -20, 80);
50
       Stroke stroke = new BasicStroke(3);
51
       g2.setStroke(stroke);
52
       g2.drawOval(-190, -190, 380, 380);
53
       for (int i = 0; i < 12; i++) {
         g2.rotate(2*Math.PI/12);
54
[Page 123]55
                 g2.fill3DRect(-3, -180, 6, 30, true);
56
      }
57
       // clock hands
58
       Shape hour = new Line2D.Double(0, 0, 0, -80);
59
       hour = rotH.createTransformedShape(hour);
60
       Shape minute = new Line2D.Double(0, 0, 0, -120);
61
       minute = rotM.createTransformedShape(minute);
62
       Shape second = new Line2D.Double(0, 0, 0, -120);
63
       second = rotS.createTransformedShape(second);
64
       g2.setColor(Color.black);
       g2.setStroke(new BasicStroke(5,
65
66
       BasicStroke.CAP_ROUND, BasicStroke.JOIN_ROUND));
67
       g2.draw(hour);
68
       g2.draw(minute);
69
       g2.setStroke(new BasicStroke(2));
70
       g2.draw(second);
71
    }
72
73
    public void actionPerformed(ActionEvent e) {
74
      int hour = Calendar.getInstance().get(Calendar.HOUR);
75
       int min = Calendar.getInstance().get(Calendar.MINUTE);
       int sec = Calendar.getInstance().get(Calendar.SECOND);
76
77
       rotH.setToRotation(Math.PI * (hour+min/60.0)/6.0);
78
       rotM.setToRotation(Math.PI * min /30.0);
79
       rotS.setToRotation(Math.PI * sec /30.0);
80
       repaint();
81
    }
82 }
```



Figure 4.8. A real-time analog clock.

# UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

The class ClockPanel extends JPanel and implements ActionListener interface. Three AffineTransform fields define the rotations for the hour, minute, and second hands (lines 28–30).

[Page 124]

The paintComponent method paints the clock face and the three hands. The face consists of a circle filled with a gradient paint and drawn with a gray color, twelve tick marks created with filled 3D rectangles, and a text string "Java 2D." The hour, minute, and second hands are drawn as lines. Their positions are determined by the rotation fields that specify the correct angles for the current time. The rotations are applied to the corresponding hands that start from the 12 o'clock position.

A Timer object is created and started in the constructor of ClockPanel. It uses the ClockPanel object as the listener and sets a period of 500 ms (line 35). Responding to the action events generated by the Timer, the actionPerformed method (line 73) implements the animation functions. It uses the Calendar class to get the current system time and sets appropriate angles for the three rotations. After the rotations are updated, a repaint method call is made to update the display.

A cellular automator is a simple iterative system on a grid that evolves based on a fixed set of rules. Many cellular automata generate supersingly compressibilities. App cellular automator is defined on a fixed set of rules. Many cellular automator is a simple iterative system on a grid that evolves based on a fixed set of rules. Many cellular automator is a simple iterative system on a grid that evolves based on a fixed set of rules. Many cellular automator is a simple iterative system on a grid that evolves based on a fixed set of rules. Many cellular automator is a simple iterative system on a grid that evolves based on a fixed set of rules. Many cellular automator is a simple set of rules are cellular automator in the set of rules are cellular automator is a simple set of rules. Many cellular automator is a simple set of rules are cellular automator is a simple set of rules. Many cellular automator is a simple set of rules are cellular automator is a simple set of rules. Many cellular automator is a simple set of rules are cellular automator is a simple set of rules. Many cellular automator is a simple set of rules are cellular automator is a simple set of rules are cellular automator is a simple set of rules. Many cellular automator is a simple set of rules are cellular automator is a simple set of rules. The set of rules are cellular automator is a simple set of rules are cellular automator is a simple set of rules. The set of rules are cellular automator is a simple set of rules are cellular automator is a simple set of rules. The set of rules are cellular automator is a simple set of rules are cellular automator is a simple set of rules. The set of rules are cellular automator is a simple set of rules are cellular automator is a simple set of rules. The set of rules are cellular automator is a simple set of rules are cellular automator is a simple set of rules are cellular automator is a simple set of rules are cellular automator is a simple set of rules are cellular automator and are cellular automato

only four neighbors are considered. The iteration of the system proceeds by assigning the next state of each cell based on the previous configuration. Each cell follows the same set of rules, and the new state depends only upon the current states of the same cell and its neighbors. For example, Figure 4.9 shows one iteration step with the rule: "A cell is black if exactly one of its neighbors in the current configuration is black."

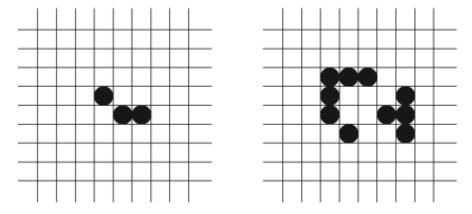
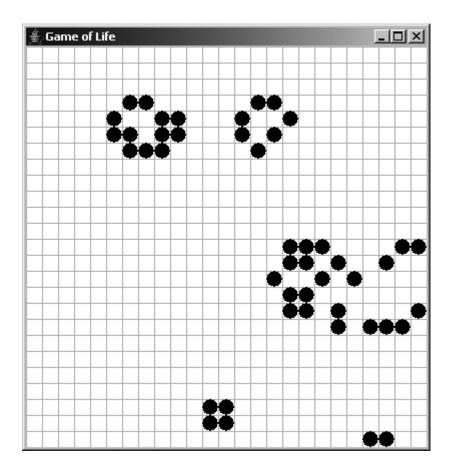


Figure 4.9. One step in the evolution of a cellular automaton.

A well-known example of cellular automata is Conway's *Game of Life*, as illustrated in Listing 4.8. A sample run of the program is shown in Figure 4.10.

Figure 4.10. Game of Life. (This item is displayed on page 126 in the print version)

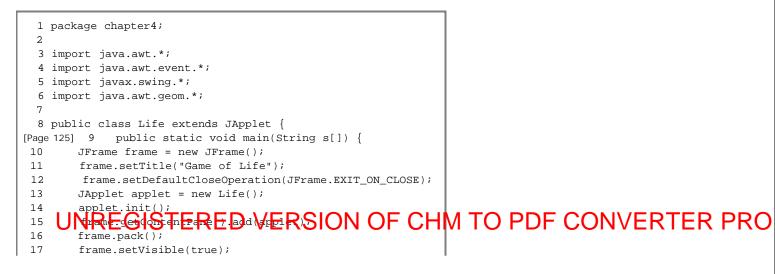


The Game of Life is a 2D cellular automaton. The rules are quite simple:

- 1. (birth) A dead call becomes live if it has exactly three live peighbors 2. (UMMA) EAG Sell tenas is use viewer SubOM redive beighbors. TO PDF CONVERTER PRO
- 3. (death). Otherwise, a cell dies.

Listing 4.8. Life.java

(This item is displayed on pages 124 - 126 in the print version)



```
18
    }
19
20
    public void init() {
      JPanel panel = new LifePanel();
21
2.2
        getContentPane().add(panel);
23
    }
24 }
25
26 class LifePanel extends JPanel implements ActionListener{
27
    int n = 30;
28
    boolean[][] cells1;
    boolean[][] cells2;
29
30
31
    public LifePanel() {
32
       setPreferredSize(new Dimension(400, 400));
33
       setBackground(Color.white);
34
       cells1 = new boolean[n][n];
35
       cells2 = new boolean[n][n];
       for (int i = 0; i < n; i++) {
36
37
         for (int j = 0; j < n; j++) {
            cells1[i][j] = Math.random() < 0.1;</pre>
38
39
            cells2[i][j] = false;
40
         }
41
       }
42
       Timer timer = new Timer(1000, this);
43
       timer.start();
44
    }
45
46
     public void paintComponent(Graphics g) {
47
       super.paintComponent(g);
48
        Graphics2D g2 = (Graphics2D)g;
49
       g2.setColor(Color.lightGray);
50
51
       int p = 0;
52
       int c = 16;
53
       int len = c*n;
54
       for (int i = 0; i <= n; i++) {
55
        g2.drawLine(0, p, len, p);
56
        g2.drawLine(p, 0, p, len);
57
        p += c;
58
      }
       g2.setColor(Color.black);
59
       for (int i = 0; i < n; i++) {
60
        for (int j = 0; j < n; j++) {
61
62
           if (cells1[i][j]) {
63
            int x = i*c;
64
             int y = j*c;
65
              g2.fillOval(x, y, c, c);
66
            }
67
          }
68
        }
[Page 126] 69
             }
70
71
     public void actionPerformed(ActionEvent e) {
72
       boolean[][] cells = cells1;
       for (int i = 0; i < n; i++) {
73
74
         for (int j = 0; j < n; j++) {</pre>
75
            cells2[i][j] = cells[i][j];
76
            int nb = neighbors(cells, i, j);
```

77			if (nb == 3)
78			cells2[i][j] = true;
79			if (nb < 2    nb > 3)
80			cells2[i][j] = false;
81			}
82			}
83			
84			cells1 = cells2;
85			cells2 = cells;
86			repaint();
87		}	
88			
89		р	rivate int neighbors(boolean[][] cells, int x, int y) {
90			int x1 = (x>0)?x-1:x;
91			int x2 = (x <n-1)?x+1:x;< td=""></n-1)?x+1:x;<>
92			int y1 = (y>0)?y-1:y;
93			int y2 = (y <n-1)?y+1:y;< td=""></n-1)?y+1:y;<>
94			int count = 0;
95			for (int i = x1; i <= x2; i++) {
96			for (int j = y1; j <= y2; j++) {
97			<pre>count += (cells[i][j])?1:0;</pre>
98			}
99			}
100			if (cells[x][y]) count;
101			return count;
102		}	
103	}		

[Page 127]

The program creates an *n*-by-*n* board to display the game. A 2D array of boolean is used to hold the states of the cells. The initial configuration is set randomly, with the probability of live cells being 0.1.

# A timer of 1000 milliseconds is used to animate the progress of the game (line 12) The Life pane) object is the R PRO action listener for the timer Every line the even listed, one step to the game is performed in the Every line the even listed, one step to the game is performed in the Every line the even listed one step to the game (lines 28–29). cells1

repeated creation of arrays, only two arrays for the cell configurations are used (lines 28–29). cells1 references the array for the currently displayed cells. cells2 is for the next configuration. After the computation for a board update is completed, the two arrays are swapped.

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### 4.7. Printing

Printing is a common task in computer applications. The rendering problems involved in printing graphics are essentially the same as those in drawing on the screen. However, printing does present some special problems such as pagination. Java API provides convenient facilities for printing.

The PrinterJob class can be used to manage a printing process. The following static method returns an instance of PrinterJob:

```
static PrinterJob getPrinterJob();
```

At the beginning of a print job the user is usually presented with a printer selection dialog box. You may do that by simply invoking the method of PrinterJob:

boolean printDialog();

The method returns true if the user chooses to proceed with the printing. You may initiate the printing by calling the following method:

```
void print() throws PrinterException;
```

The actual graphics contents of printing are defined using the Printable interface. An object implementing Printable is selected to a PrinterJob through the method:

```
void setPrintable(Printable painter);
```

The Printable interface provides a callback structure to define the custom drawing of the printing job. The interface contains the following method for custom implementation:

int print(Graphics g, PageFormat pf, int pageIndex);

The implementation of this method is very similar to that of paintComponent. The code can often be shared between the two methods. The Graphics parameter, which can be cast to a Graphics2D object, provides access to the 2D rendering engine. All the drawing, transformation, and other features are available to printing.

The pageIndex parameter provides the page number of the page currently being rendered. It starts with 0. The implementation of the method should return either the value NO\_SUCH\_PAGE if the page should not be printed or the value PAGE\_EXISTS if the page is rendered.

The PageFormat object contains information about the printer's page settings. The following are some of the methods in PageFormat:

```
int getOrientation();
double getWidth();
double getHeight();
double getImageableX();
[Page 128]double getImageableY();
double getImageableWidth();
double getImageableHeight();
```

The last four methods retrieve the rectangle of the printable area of the page.

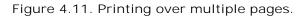
Listing 4.9 demonstrates the usage of these classes in implementing printing functionalities in Java applications. The program displays a window containing a panel with the text "Welcome!" and a button labeled "Print." If the button is clicked, a printer selection dialog box is displayed. When a printer is chosen, the same text string will be printed on two pages, as shown in Figure 4.11. The rendered image is cut against the printable area, but the fragments are properly aligned across the pages.

```
Listing 4.9. Printing.java
```

(This item is displayed on pages 128 - 129 in the print version)

```
1 package chapter4;
 2
 3 import java.awt.*;
 4 import java.awt.geom.*;
 5 import java.awt.event.*;
 6 import java.awt.print.*;
 7 import javax.swing.*;
 8
 9 public class PrintGraphics extends JFrame implements ActionListener {
10
    public static void main(String[] args) {
11
       JFrame frame = new PrintGraphics();
12
       frame.setTitle("Printing");
13
       frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
14
       frame.pack();
       frame.setVisible(true);
15
16
    }
17
18
     PrinterJob pj;
19
     PrintPanel painter;
20
21
     public void actionPerformed(ActionEvent e) {
22
       if (pj.printDialog()) {
23
         REGISTERED VERSION OF CHM TO PDF CONVERTER PRO
24
25
         } catch (PrinterException ex) {
26
           ex.printStackTrace();
27
         }
28
       }
    }
29
30
31
     public PrintGraphics() {
32
       Container cp = this.getContentPane();
33
       cp.setLayout(new BorderLayout());
34
       JButton button = new JButton("Print");
35
       cp.add(button, BorderLayout.SOUTH);
36
       button.addActionListener(this);
37
       painter = new PrintPanel();
38
       cp.add(painter, BorderLayout.CENTER);
39
       pj = PrinterJob.getPrinterJob();
40
       pj.setPrintable(painter);
41
    }
42 }
43
[Page 12
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                45
46
       setPreferredSize(new Dimension(800, 400));
```

```
47
       setBackground(Color.white);
48
    }
49
50
    public int print(Graphics g, PageFormat pf, int pageIndex) {
51
     switch (pageIndex) {
52
       case 0:
          draw(g);
53
54
          break;
55
        case 1:
56
          g.translate(-(int)pf.getImageableWidth(), 0);
57
          draw(g);
58
          break;
59
        default:
60
          return NO_SUCH_PAGE;
61
     }
62
      return PAGE_EXISTS;
63
    }
64
65
    public void paintComponent(Graphics g) {
66
     super.paintComponent(g);
67
     draw(g);
68
   }
69
70
   private void draw(Graphics g) {
71
      g.setFont(new Font("Serif", Font.BOLD, 144));
       g.drawString("Welcome!", 200, 300);
72
73
   }
74 }
```





The class PrintPanel extends JPanel and implements the Printable interface. An instance of PrintPanel is added to the main frame of the program. It is also used for printing. The panel paints the string "Welcome!" using a 144-point font. A private method draw is defined to perform the drawing (line 70). Both paintComponent and print methods call the draw method.

The print method has additional logic to handle the page split. The first page (pageIndex = 0) is printed without change. In the second page, a translation is performed to move the page so that it covers the area to the right of the first page. To determine the precise offset, we use the PageFormat object to retrieve the width of the printable area (line 56).

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#### [Page 130 (continued)]

### Key Classes and Methods

- javax.awt.geom.GeneralPath.curveTo(...) A method to construct a cubic curve segment.
- javax.awt.image.BufferedImage A class encapsulating an image.
- javax.awt.image.BufferedImageOp An interface for image-processing operators.
- java.swing.Timer A class generating action events in a periodic fashion.
- java.lang.Runnable An interface to define code executable as a separate thread.
- java.lang.Thread A class encapsulating a thread of execution of a program.
- java.lang.Thread.sleep(long ms) A method to place the thread to sleep for a specified time period.
- **java.util.Calendar** A class encapsulating a calendar for date and time.
- java.awt.image.Raster A class encapsulating image data.
- java.awt.image.WritableRaster A class encapsulating writable image data.
- java.awt.print.PrinterJob A class for printing management.
- java.awt.print.Printable An interface to define print contents.

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#### [Page 130 (continued)]

### Key Terms

B-spline curve

A curve defined as a parametric equation of piecewise polynomials blending with a sequence of control points.

#### Bézier curve

A curve defined as a parametric equation of polynomials blending with control points.

#### NURBS

Nonuniform rational B-spline.

#### image processing

Computer manipulation of digital images to enhance or extract information.

convolution

A type of linear operations often used in signal and image processing.

#### Kernel UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO A function to define a convolution.

complex numbers

An extension of real numbers.

complex plane

The set of complex numbers interpreted as points on a plane.

frame rate

The speed of an animation measured in frames per second (fps).

#### thread

A line of execution in a running program. In a multithreading environment a single program may have several threads running simultaneously.

#### cellular automata

A dynamic system on a grid of cells, evolving based a simple set of rules that specify the next state of a cell using the previous states of itself and its neighbors.

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[Page 130 (continued)]

### Chapter Summary

- In this chapter we present several advanced techniques in 2D computer graphics.
- B-spline curves are important tools in modeling 2D geometry. A B-spline curve can be converted to a sequence of Bézier curves, which may then be rendered directly by the Graphics2D object. The control points of each Bézier curve are linear combinations of the control points of the B-spline curve.

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- Java 2D provides a basic set of graphics primitives. We discussed how to build custom primitives by implementing the Shape interface. Even though it is not possible to extend the GeneralPath class, you may still include it in your own class to take advantage of its implementation.
- A brief introduction to image processing is given in this chapter. Java 2D provides supports for image reading, writing, rendering, and processing. The BufferedImage class is the main representation for images in Java 2D. Image-processing operators implementing the BufferedImageOp interface provides convenient ways to process BufferedImage objects.
- Images can also be created and manipulated in a program at the pixel level. Raster and WritableRaster classes offer access to the pixel data in a BufferedImage. An example in constructing an image for the Mandelbrot set is given.
- Animation is an important part of computer graphics. Implementing a 2D animation in Java usually requires multiple threads to separate the continuous rendering from the regular user interface handling. The Thread class and the Runnable interface provide essential multithreading support. The Timer class of the Swing package provides a convenient utility to trigger the periodic frame rendering.
- Printing in Java fits the general rendering scheme of Java 2D quite well. The same Graphics2D class provides the rendering engine. The Printable interface allows for the necessary callback structure for defining the graphics output. The PrinterJob class facilitates the special tasks in printing.

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## **Review** Questions

- 4.1 Given a cubic B-spline curve as defined in this chapter with *n* control points, how many Bézier curves will be generated from the conversion?
- 4.2 Another kind of B-spline curve does not impose special restrictions of the endpoints of the curves. The first and the last segments are treated in the same way as other segments. It uses the same formula for the conversion to Bézier curves on every segment. Consequently, the first and the last control points are not necessarily interpolated by the curve. Find the conversion formula for this type of B-spline curve.
- 4.3 If you apply a smoothing operator to an image followed by a sharpening operator, will you recover the original image?
- 4.4 Perform five iterations in the Mandelbrot set definition for c = 1/2
- 4.5 Perform five iterations in the Mandelbrot set definition for c = 1.
- 4.6 If it takes 0.01 second to complete a frame rendering, and the thread sleeps for 50 milliseconds for each frame, calculate the frame rate.
- 4.7 How many different rules are there for cellular automata with four neighbors?

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[Page 131 (continued)]

## Programming Exercises

- 4.1 Implement the type of B-spline curve defined in Review Question 4.2.
- 4.2 Add the Heart primitive to the program in Listing 2.3 so it can be selected and drawn like other shapes.

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- 4.3 Write a Triangle class that implements the Shape interface. Provide a constructor to define the three vertices of the triangle.
- 4.4 Implement a regular *n*-gon primitive. Define the class to implement the Shape interface and provide a constructor to specify the number of sides *n*.
- 4.5 Add an invert operation to the program in Listing 4.4. The color of every pixel is turned to its opposite color; that is, a color with components *r*, *g*, *b* is changed to 1 *r*, 1 *g*, 1 *b*.
- 4.6 Write a Java program with a text field, a button, and a text area as shown in Figure 4.12. A user may enter a string in the text field. When the button "Print" is clicked, the text area will display the pattern of the string formed with the character '\*'.

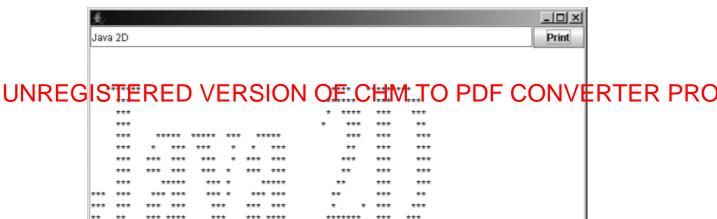
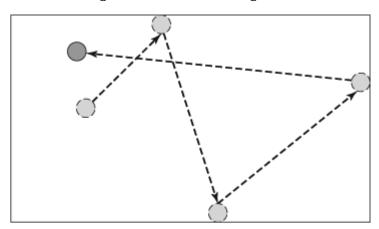


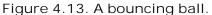
Figure 4.12. ASCII art.

4 N REPERCING IS TREATED IS IN EAR SHOW OF FRACE AND UNTREPORT OF THE COMPANY ERTER PRO

- 4.8 The Julia set uses the same type of iterations as in the Mandelbrot set. The constant c is always fixed. The starting point of the iteration is not necessarily 0. A point is in the Julia set if the sequence generated by the iteration starting at the point is bounded. Write a Java program to display the Julia set when c = -0.672 + 0.435 *i*.
- 4.9 Modify the program in Listing 3.6 so that the drawing with compositing rules is done on an offscreen image that supports the a-channel. The image is drawn to the screen after the drawing is completed.
- 4.10 Write a program to display a running fan with four blades.
- 4.11 Write a Java 2D program that animates a ball bouncing inside a rectangle, as illustrated in Figure 4.13. The ball initially moves on a randomly chosen line. When the ball hits a side of the rectangle, it bounces back in another random direction.



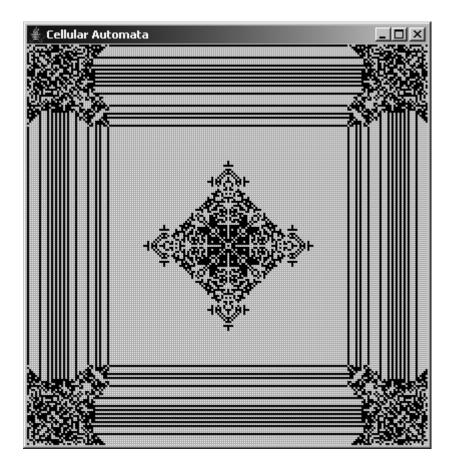




- 4.12 Write a Java program simulating an analog stopwatch. Use mouse clicking to operate the stopwatch which cycles through three states: Start–Stop–Reset.
- 4.13 Implement a cellular automaton with the following rules based on the four-neighbors of a cell:
  - 1. A white cell becomes black if the number of its black neighbors is not 1;
  - 2. A black cell stays black if the number of its black neighbors is either 1 or 3;
  - 3. Otherwise, the cell becomes white.

Starting from a single black cell at the center of the board, the amazing pattern shown in Figure 4.14 will emerge. Use a Timer object to animate the process, and allow the user to stop the animation by a mouse click.

Figure 4.14. A pattern generated by a simple cellular automaton.



4.14 Write a Java program to print an analog clock showing the current time.

4.15 Add a "Print" menu item to the drawing program in Listing 2.3. When selected, it will initiate a UNRECISTERED AND A CHARACTER PRO

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## Chapter 5. Basic 3D Graphics

(This item omitted from WebBook edition)

Objectives
• To describe the 3D rendering process.
To present an overview of Java 3D programs.
• To define the Java 3D scene graph.
To classify components of a scene graph.
To apply background nodes.
To understand and apply bounds.
To make changes in live scene graphs.

## 5.1. Introduction

Our perception of the physical world is clearly three dimensional. However, the visual images that we see through our eyes are two dimensional. A special type of mapping called *perspective projections* is the underlying mechanism to capture a 3D scene to a 2D image. The basic objective of 3D computer graphics is to simulate this process in computers.

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3D computer graphics studies the modeling and rendering of a 3D world. The geometric objects in the 3D space may have dimension 0 (points), dimension 1 (curves), dimension 2 (surfaces), or dimension 3 (solids). The objects may have different kinds of material properties. There may exist light sources of various characteristics illuminating the scene in the virtual space. The virtual cameras that capture the scenes of the virtual world may be placed at different locations in the space and have different characteristics. A 3D computer graphics system needs to address many problems in representing the graphics objects and their properties, facilitating transformations, organizing all the components, and rendering the scene.

Java 3D is an object-oriented API for 3D computer graphics. The entire graphics model of a Java 3D program is organized in a structure called the *scene graph*. Each node of the scene graph is an object of a class representing one of many graphics entities. The scene graph provides a systematic model for the Java 3D rendering engine to automatically render a scene constructed by a Java 3D program.

In this chapter, we will introduce the basic concepts of a 3D graphics system. In particular you will learn the overall architecture of Java 3D, the concept of a Java 3D scene graph, and an overview of different categories of scene-graph components. You will be able to construct Java 3D scene graphs and write simple Java 3D programs.

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## 5.2. 3D Rendering Process

Rendering a 3D scene to produce an image (typically 2D) is an inherently complex process. Unlike 2D graphics, a rendered image of a 3D object is significantly different from its original 3D version. To directly model the object based on its rendered image would not be feasible. Therefore, a 3D graphics system invariably involves the construction of a virtual world in which various graphics objects and light sources are defined. Rather than constructing the scene "on the fly," as often seen in the 2D cases, a persistent "retained" model of the virtual world separated from the rendering engine is often needed. The scene is then viewed in a structured way within the virtual world, and the rendering engine produces the image of the view. A simple illustration of 3D graphics concepts is shown in Figure 5.1.

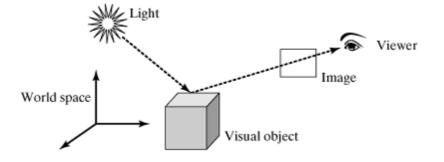


Figure 5.1. 3D graphics model and view.

The rendering process of a static graphics scene is similar to that of a real camera taking a picture. The virtual world contains visual objects that reflect light from various light sources. The camera is located at a specific point in the virtual world and projects the visible portions of the virtual world along a specific direction onto a 2D plane. The graphics objects as well as the views may be dynamic. Consequently, the scene and the rendered images may continuously change over time. There may be interactions between the virtual world and the real physical world. User and sensor inputs may affect the virtual models.

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In order to implement or use such a 3D graphics system, we have to consider many problems related to the modeling of the virtual world and the rendering of a scene—for example,

- Geometry of the graphics objects.
- Location and position of the objects.
- Geometric transformations applied to objects and views.
- Material properties and texture of the objects.
- Lights and their characteristics.
- Type of projections in a view.
- View position, field of view, and other properties.

- Illumination and shading models.
- Dynamic behaviors of various components.
- Reactions to the user inputs

Geometric descriptions of the graphics objects are the most fundamental aspect of building a virtual world in a 3D graphics system. Basic building blocks for 3D graphics objects include points, lines, surfaces, and solids. Simple polygon meshes are commonly used to approximate complex objects. A 3D graphics system usually offers convenient facilities to generate certain high-level geometries such 3D texts and geometric primitives (for example, spheres, cones, and boxes). More advanced modeling tools include spline curves and surfaces.

Transformation is an important tool in a graphics system. Geometric transforms are used to place the geometric objects in the virtual world space and to change their shapes, sizes, and positions when necessary. *3D affine transforms* are the commonly used family of transforms in the virtual world space. Another family known as *projective transforms* is more general. Projective transforms are important parts of a 3D viewing process.

Besides its geometry, a graphics object also has appearance properties that determine how the object is rendered. These properties may include colors, textures, and material properties for more sophisticated shading. The lighting, illumination, or shading policy controls the way that colors and light intensities on objects are calculated. The choice of illumination model also influences the outcome of rendering. Certain geometric information such as the surface normals is closely related to the appearance in some illumination models. The *normal at a point of the surface* is the direction perpendicular (vertical) to the tangent plane at the point. In the Phong illumination model that considers specular reflection, for example, the light intensity at the point is associated with the angle between the direction of the view and the direction of the light reflection. The reflection vector is determined by the direction of the light and the surface normal. The details of illumination and shading models will be introduced in Chapter 9.

The 3D viewing process typically involves a projective transformation that maps a 3D scene to a 2D plane. A view can have many parameters to control its characteristics. The projection may be parallel or perspective. For a particular view, the visible volume of the virtual world is usually finite, and this volume is known as the *view frustum*. Simply applying a mathematical transformation of projection may not be enough for the rendering. For example, the relative positions among the objects may also be important to the rendering process. A portion of an object may be hidden by another object. These problems need to be properly addressed to achieve acceptable visual results.

Of coulseNR Ercice in Figure Init is a change designed internally in the virtual world. The dynamic effects of the rendering process may include animation and interaction. *Interaction* is an alteration of the scene resulting from user feedbacks. *Animation* is a change designed internally in the virtual world. The distinction between the two types of dynamics is often blurred. The dynamic behaviors may be originated from the changes in the graphics objects in the virtual world or from the changes of the viewer. The viewers (cameras or eyes) may themselves be objects located in the virtual world and may dynamically change their positions, directions, and other properties.

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Java 3D API provides a comprehensive implementation of the basic graphics algorithms, enabling us to concentrate on the main concepts and problems in graphics instead of tedious details of lower-level implementations. This book uses the Java 3D package as the tool to study and implement 3D graphics systems and applications.

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Java 3D provides a high-level API for modeling and rendering 3D graphics scenes. The Java 3D rendering engine automatically renders a scene with all the structures and properties specified by the programmer. Programming with Java 3D API, therefore, will require only the specifications of the desired graphics scene and the associated properties, and will not need to implement the highly complex and tedious low-level rendering process.

Java 3D takes advantage of the object-oriented programming features of the Java programming language. Almost all elements involved in the graphics rendering (such as geometry, transformation, light, and animation) are implemented as Java classes. Such objects are created simply by instantiating the corresponding classes.

In order to organize all the objects involved in rendering a scene, Java 3D uses a special structure called a *scene graph*. This, with its superstructure objects, node objects, and node components, defines the entire virtual graphics world to be rendered. The Java 3D rendering engine will traverse the scene graph to continuously perform the actual rendering. The scene graph defines geometries, appearances, transformations, lights, and views in a 3D scene. It may also include animations, interactions, and sounds.

## 5.3.1. A Simple Example

Listing 5.1 shows a simple Java 3D applet and application. It demonstrates the basic structure of a Java 3D program. The program displays a solid 3D text "Hello 3D" illuminated by a point light (Figure 5.2).

Listing 5.1. Hello3D.java

(This item is displayed on pages 138 - 139 in the print version)

```
1 package chapter5;
 2
 3 import java.awt.*;
 4 import java.applet.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import javax.vecmath.*;
 8 import com.sun.j3d.utils.universe.*;
 9 import com.sun.j3d.utils.geometry.*;
10 import com.sun.j3d.utils.applet.MainFrame;
11
12 public class Hello3D extends Applet {
13
     public static void main(String s[]) {
14
       new MainFrame(new Hello3D(), 640, 480);
15
     }
16
17
     public void init() {
18
       GraphicsConfiguration gc =
19
        SimpleUniverse.getPreferredConfiguration();
20
       Canvas3D cv = new Canvas3D(gc);
21
       setLayout(new BorderLayout());
22
       add(cv, BorderLayout.CENTER);
23
       BranchGroup bg = createSceneGraph();
[Page 139]24
               bg.compile();
25
       SimpleUniverse su = new SimpleUniverse(cv);
26
        su.getViewingPlatform().setNominalViewingTransform();
27
        su.addBranchGraph(bg);
28
     }
29
```

```
30
     private BranchGroup createSceneGraph() {
31
      BranchGroup root = new BranchGroup();
32
       // object
33
       Appearance ap = new Appearance();
34
       ap.setMaterial(new Material());
35
       Font3D font = new Font3D(new Font("SansSerif", Font.PLAIN, 1),
36
                                new FontExtrusion());
37
       Text3D text = new Text3D(font, "Hello 3D");
38
       Shape3D shape = new Shape3D(text, ap);
39
       // transformation
40
      Transform3D tr = new Transform3D();
41
      tr.setScale(0.5);
42
      tr.setTranslation(new Vector3f(-0.95f, -0.2f, 0f));
43
      TransformGroup tg = new TransformGroup(tr);
44
      root.addChild(tg);
45
      tg.addChild(shape);
46
       // light
47
       PointLight light = new PointLight(new Color3f(Color.white),
48
                                         new Point3f(1f,1f,1f),
49
                                         new Point3f(1f,0.1f,0f));
50
       BoundingSphere bounds = new BoundingSphere();
51
      light.setInfluencingBounds(bounds);
52
      root.addChild(light);
53
       return root;
54
   }
55 }
```

Figure 5.2. A simple Java 3D program displays a 3D text string.

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This example is a complete Java 3D program. It shows a frame containing a 3D text string "Hello 3D." You can see the depths of the characters and the illumination of the characters originated from a light. The background of the scene is black.

Besides the AWT packages, the program imports the following packages from Java 3D API:

javax.media.j3d
javax.vecmath
com.sun.j3d.utils.universe
com.sun.j3d.utils.geometry

javax.media.j3d is the main package of Java 3D. javax.vecmath contains classes for vectors, matrices, and other mathematical objects that are useful for Java 3D. The other two packages contain many convenient utility classes for building primitives, views, and other objects in Java 3D, even though the com.sun.j3d.\* packages are not considered in the core of Java 3D.

The visual components used in the program Hello3D are the old-style AWT components instead of the Swing components. For example, an Applet object is used instead of JApplet. This is because the GUI component Canvas3D used for Java 3D rendering is a heavyweight component. Even though it is possible to place heavyweight components into a Swing component JFrame, doing so may cause some irregularities in the display. For example, the menu may not be shown properly.

An applet derived from the Applet class can be implemented as an application as well by adding the applet to a Frame instance in a main method, similar to the Swing implementation. Because the Frame class does not have the setDefaultCloseOperation method, the window-closing operation for the frame needs to be implemented by handling the WindowEvent. The class com.sun.j3d.utils.applet.MainFrame provides an implementation

for running an applet as an application (line 14). Hello3D and most subsequent examples will use this convenient utility class to create the dual-purpose program.

A Canvas3D object is created to display the 3D rendering (line 20). Canvas3D is a subclass of the AWT component Canvas and therefore the Canvas3D object can be added to this Frame. The method createSceneGraph defines the scene graph for the application. It returns a BranchGroup object that can be attached to a SimpleUniverse object. The utility class SimpleUniverse provides a basic framework for Java 3D rendering. Once the scene graph branch is attached to the SimpleUniverse object, the rendering will begin.

In the createSceneGraph method (line 30), first a BranchGroup object is created to act as the root. The visual object to be displayed is a 3D text string represented by a Text3D object. It is constructed with a 3D font and an appearance. A transformation is then defined with the Transform3D class. It performs a scaling and a translation. The transformation is applied to the Text3D object. A light is constructed and placed in the scene. The influence of the light is limited to a region defined by a BoundingSphere object.

To fully understand the Java 3D program, it is necessary first to understand Java 3D scene graphs. The details of Java 3D scene graphs will be introduced in the next sections, and the complete analysis of the scene graph contained in this example will be given later in the chapter.

#### 5.3.2. Install Java 3D

To compile and execute a Java 3D program, you need a Java software development environment and the Java 3D package. Java 3D is an optional package of the Java 2 platform. A standard Java installation does not automatically include it. You may download the Java 3D package at the site:

#### http://java.sun.com/products/java-media/3D/

Java 3D is available for various platforms including Solaris, Windows, Linux, and Mac OS. After installing the Java 3D package on top of a Java 2 software development kit, you will be able to compile and run a Java 3D program such as the one in Listing 5.1.

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A Java 3D distribution includes native code and Java libraries. The Java classes are packaged in four jar files:

j3dcor**UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO** j3dutils.jar j3daudio.jar vecmath.jar

In a Windows installation, the jar files are typically placed in the directory:

<j2sdk directory>/jre/lib/ext

The native code is implemented in three dynamic link libraries: J3D.dll, j3daudio.dll, and J3DUtils.dll under the directory:

```
<j2sdk directory>/jre/bin
```

You may also build Java 3D programs in IDEs such as JBuilder and Netbeans. Additional configurations may be required to use the Java 3D packages. In JBuilder, you need to create a new library to include the four jar files above, using the Tools menu item Configure Libraries. After the library is created, you may set the Project proper light Reference of the Configure Libraries of the Java 3D package is installed to the J2SDK associated with the Netbeans installation. However, to take advantage of the context-sensitive code-completion feature of the IDE, you may need to update the parser database for the jar files. This can be done by mounting the four jar files and selecting "Update Parser Database" on each. This step is not necessary for newer versions of Netbeans.

A Java 3D application can be executed in a Java Runtime Environment (JRE) with the Java 3D package installed. A Java 3D program may also be built as an applet. To view a Java 3D applet in a browser, you need to install a Java plug-in associated with a JRE for Java 2 environment and install the Java 3D package on top of the JRE.

Java 3D is usually built on top of other low-level graphics API such as OpenGL. For example, there are two Java 3D distributions for the Windows environment: one for OpenGL and the other DirectX. Rendering 3D graphics is usually a computationally intensive task. To achieve better performance, Java 3D will attempt to take advantage of the acceleration features offered by the graphics hardware. Because of the large variety of different graphics boards, software drivers, and vendors, you may encounter some compatibility problems when using Java 3D on certain platforms. The following suggestions may help you resolve some of the problems:

- Update your video driver to the latest stable version.
- Use the most recent release of Java 3D.
- Set the depth buffer in the OpenGL options of your graphics card to 24 bits or higher.
- Turn off hardware acceleration of the graphics card.
- Join the Java 3D interest group: java3d-interest@java.sun.com

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## 5.4. Java 3D Scene Graphs

In order to organize various elements in the 3D rendering effectively, Java 3D uses the concept of scene graph to build a virtual universe that includes everything relevant to a 3D rendering. A scene graph is an abstract mathematical model for the organization of a scene. It is not a picture or an image of the scene. The scene graph can be conceptually drawn as a diagram, but its actual implementation is done in the program through object instantiation and method invocation. The scene graph enables programmers to specify complex graphics structures and actions in a uniform manner. It also enables the Java 3D rendering engine to process the scene systematically and efficiently.

#### [Page 142]

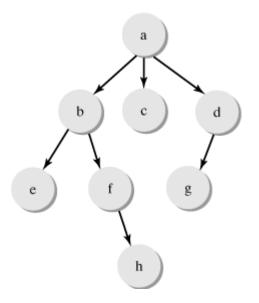
A scene graph is a treelike data structure known as *DAG* (*directed acyclic graph*). A directed graph consists of a set of vertices (or nodes) connected with directed edges (or links). Figure 5.3 shows a directed graph with 6 vertices and 8 edges. A (directed) path in a directed graph is a vertex-edge sequence that moves along the edges of the graph. For example, in Figure 5.3, b-c-f-e is a path. A cycle in a directed graph is a closed path—that is, a path having the same initial and terminal vertex. For example, in Figure 5.3, a-c-f-e-a is a cycle. A DAG is a directed graph without any cycles. Therefore Figure 5.3 is not a DAG. However, if the edge e-a is removed, then it becomes a DAG.

Figure 5.3. A directed graph.

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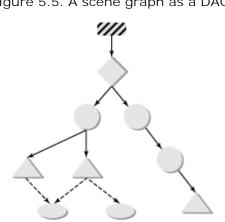
A (directed) *tree* is a special type of DAG. A tree is constructed starting from one vertex known as the *root* of the tree. There can be a number of edges originated from the root leading to other distinct vertices called the *children* of the root. Each child can then have a number of edges leading to its children in the same fashion. This process can iterate an arbitrary number of steps to produce a tree. Figure 5.4 shows an example of a tree. The vertex a is the root of the tree. In a tree, a vertex may have any number of children (including 0), but it cannot have more than one parent. A vertex that has no child is called a *leaf*. A nonleaf vertex is called an *internal node*. In Figure 5.4, the nodes e, h, c, g are leaves and the nodes a, b, d, f are internal nodes.

Figure 5.4. A directed tree.



The nodes of a scene graph represent objects of the various classes related to graphics functions. The links between nodes represent the logical relationships between them. In an actual Java 3D program, the nodes are created by instantiation of the classes defined in the Java 3D API, or the classes derived from the API classes and interfaces. The links are created by calling the appropriate methods or constructor in the classes. Figure 5.5 shows a very simple Java 3D scene graph.

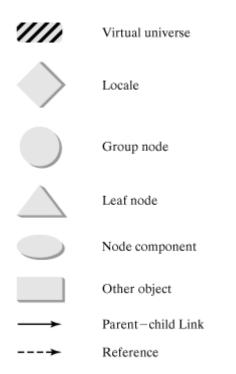
```
[Page 143]
```





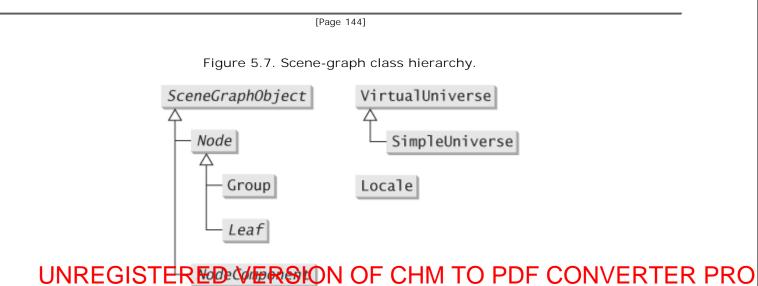
Different types of nodes and links are represented by different symbols in the diagram drawing of a scene graph. Figure 5.6 shows the symbols conventionally used for scene graph nodes and edges.

Figure 5.6. Legend of scene graphs.



A scene graph has three major parts. On the top is the superstructure, which consists of objects from VirtualUniverse and Locale classes. The main body of the scene graph is a tree of objects belonging to the Node class. The third part is a set of NodeComponent objects. The leaf nodes in the tree structure can reference the node component objects. One NodeComponent object may be referenced by several Leaf objects. Therefore, the overall structure of a scene graph is not a tree but only a DAG.

The main class hierarchy for the scene graph elements is shown in Figure 5.7. The VirtualUniverse and Locale are classes for the superstructure and they are not derived from the SceneGraphObject abstract class. The trae nodes in a scene-graph are defined by the subclasses of the abstract class Node. The Node Components abstract class serves as the base class for various node components. IN TO PDF. CONVERTER PRO



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## 5.5. The Superstructure

The VirtualUniverse and Locale objects are the superstructure objects of scene graphs. A Java 3D program typically has only one VirtualUniverse object. The VirtualUniverse is designed to potentially represent the entire space that is of interest to any Java 3D program. In order to accommodate the size and precision of a "universe," VirtualUniverse uses three high-resolution 256-bit fixed-point numbers to represent its coordinates. A high-resolution fixed-point number has its binary point at the middle of the 256 bits, so it has 128 bits for the integer part and 128 bits for the fractional part. The number 1.0 represents the unit of 1 meter. Numbers of this type can provide a distance measure as high as 2<sup>127</sup> meters with a resolution of 2<sup>-128</sup> meters. This should be adequate to measure any real objects in the universe. For example, the distance from the Earth to the Sun is only about 2<sup>37</sup> meters and the radius of a proton is believed to be about 2<sup>-50</sup> meters.

The class HiResCoord is defined to represent such a high-resolution coordinate. It contains three 256-bit high-resolution fixed-point numbers to represent the x-, y-, z-coordinates of a location.

While the VirtualUniverse is capable of modeling essentially the entire universe known to us through the HiResCoord numbers, it is clearly very inefficient to represent all coordinates using HiResCoord objects. Therefore, Java 3D uses the Locale class to represent smaller local spaces and to achieve much greater efficiency. A Locale object defines a local coordinate system anchored at a specific location specified by HiResCoord in the virtual universe. Within a specific locale, the coordinates of the points are represented by usual floating-point numbers. A VirtualUniverse contains one or more Locale objects. A Locale may have branch graphs attached to it. When a branch graph is attached to a Locale, the Java 3D rendering engine will start to render the branch, and the graph becomes live. A Locale object is always attached to one VirtualUniverse object. This association is established with constructors of Locale.

Locale(VirtualUniverse vu) Locale(VirtualUniverse vu, HiResCoord location) Locale(VirtualUniverse vu, int[] x, int[] y, int[] z)

The location of a Locale object in the universe can be specified using a HiResCoord object or three int arrays specifying the high resolution numbers. The default location is (0, 0, 0). The following statements will create a superstruction for a scene branched VERSION OF CHM TO PDF CONVERTER PRO

VirtualUniverse universe = new VirtualUniverse();
Locale locale = new Locale(universe);

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Branches of a scene graph rooted at BranchGroup objects can be attached to a Locale object by using the following method in Locale:

void addBranchGraph(BranchGroup branch)

The branches can be edited with the following methods:

void replaceBranchGraph(BranchGroup oldBranch, BranchGroup newBranch)
void removeBranchGraph(BranchGroup branch)

The following methods seture the number of branches and all the branches ind LPDF CONVERTER PRO int numBranchGraphs() The class SimpleUniverse is a utility class derived from VirtualUniverse. It includes a Locale object and a set of objects to define a standard view. A SimpleUniverse object can be combined with the visual content branch to quickly form a complete scene graph. The world coordinate system in Java 3D is a right-handed rectangular system. The default view position is located on the z-axis looking toward the negative z-axis. From the viewer's perspective, the x-axis is pointing to the right and the y-axis up.

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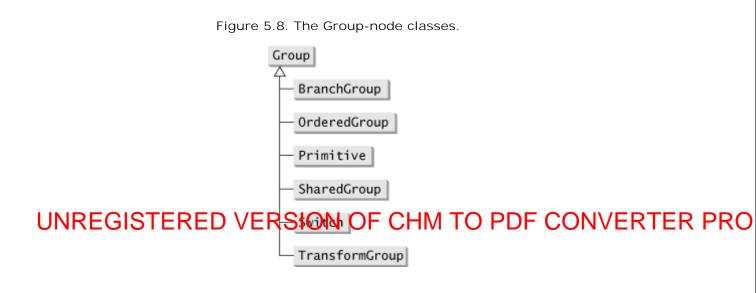
[Page 145 (continued)]

## 5.6. The Nodes

The Node objects are the nodes in the main tree structure of a scene graph. There are two main categories of nodes: the Group nodes and the Leaf nodes. The Group nodes are internal nodes of the tree representing certain relations and operations for the child nodes. The Leaf nodes are leaves of the tree representing certain graphics entities. The leaf nodes in a scene graph usually reference some NodeComponent object to define its attributes and properties. The node components may be shared among different leaf nodes.

## 5.6.1. The Group Nodes

Group nodes are the internal nodes in a scene graph. The main group-node class hierarchy is given in Figure 5.8. Group nodes are the main building blocks of the scene-graph tree structures. They may have children. A child of a group node can be a leaf node or another group node. Because of the tree structure imposed on the Node objects in a scene graph, two group nodes cannot share the same child-node object. A child node has only one parent, and there is a unique path from the root to a leaf node.



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A Group node maintains a list of children. To add a child node to a Group node, you may call the following methods:

void addChild(Node child)
void insertChild(Node child, int index)

A child can be accessed through an index.

Node getChild(int index) void setChild(Node child, int index)

The methods to retrieve information about children include OF CHM TO PDF CONVERTER PRO

```
int numChildren()
int indexOfChild(Node child)
```

Other methods related to children of a Group node include

```
Enumeration getAllChildren()
void removeChild(Node child)
void removeChild(int index)
void removeAllChildren()
```

A BranchGroup node is the root of a branch of a scene graph. It is the only type of node that can be attached to a Locale object. Therefore, there must be at least one BranchGroup node in a scene graph. A BranchGroup node does not perform any special operations other than bringing its children together.

An OrderedGroup node specifies an order of rendering on its children. The Java 3D rendering engine renders a scene by traversing the scene graph from the root to all the leaf nodes. Normally at a particular node the order of visiting the children is not specified. Java 3D may choose to render the children in any order. The OrderedGroup node provides a way to enforce a specific ordering on traversing the children. The children of an OrderedGroup node are guaranteed to be rendered in the order of their indices. For example, the following code constructs a portion of a scene graph in which the three shapes will be guaranteed to render in the order shape1, shape2, shape3. The corresponding scene graph is shown in Figure 5.9.

```
Shape3D shape1 = new Shape3D();
Shape3D shape2 = new Shape3D();
Shape3D shape3 = new Shape3D();
OrderedGroup group = new OrderedGroup();
group.addChild(shape1);
group.addChild(shape2);
group.addChild(shape3);
```

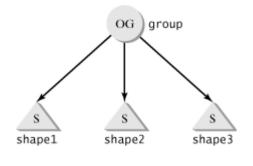


Figure 5.9. An **OrderedGroup** node and its children.

```
[Page 147]
```

A Primitive node represents a complete geometric primitive such as a sphere. It is a utility class in the package com.sun.j3d.utils.geometry. Primitives will be discussed in Chapter 6, "Graphics Contents."

A SharedGroup node is the root of a branch graph that can be shared by several Link leaf nodes. It is not uncommon that certain branches of a scene graph are identical. But the common branch cannot be shared among group nodes, because of the requirement of tree structure. In this case, you may define the common branch using a SharedGroup object as the root. This branch can then be shared by several Link leaf nodes

through references, instead of the parent-child relations. Consider the simple example in Figure 5.10. In the scene graph on the left, two branches have the same structure and attributes. To share the common branch, a SharedGroup node is added as the root of the shared branch. Two Link nodes referencing the shared branch are introduced to replace the original common branches. The result is the scene graph on the right. Note that this structure does not violate the requirement for a tree, because the SharedGroup node is not a child of the Link nodes.

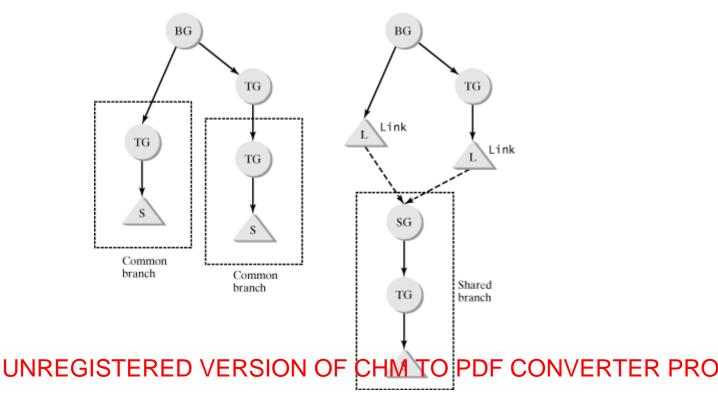


Figure 5.10. I dentical branches may be shared through a sharedGroup node and Link leaf nodes.

A Switch node acts as a switch to select a particular set of children of the node for rendering. In the list children of a Switch node, you may turn on the rendering of a specific child, none of the children, all of the children, or a set of children using the following method:

void setWhichChild(int whichChild)

The parameter whichChild may be a nonnegative integer specifying the index of a child, or one of the predefined constants: CHILD\_NONE, CHILD\_ALL, CHILD\_MASK. If the constant CHILD\_MASK is used, then the set of selected children is defined by a mask. The mask may be set with the following method:

void setChildMask(BitSet mask)

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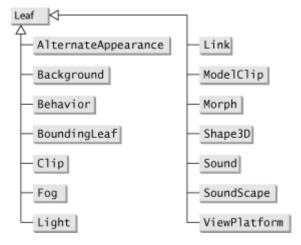
Shape3D shape1 = new Shape3D();

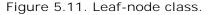
```
Shape3D shape2 = new Shape3D();
Shape3D shape3 = new Shape3D();
Switch group = new Switch();
group.addChild(shape1);
group.addChild(shape2);
group.addChild(shape3);
BitSet mask = new BitSet();
mask.set(0);
mask.set(2);
group.setChildMask(mask);
group.setWhichChild(Switch.CHILD_MASK);
```

A TransformGroup node represents a geometric transform that applies to all of its children. A TransformGroup node uses a Transform3D object for the specification of a transform. Transformations will be covered in Chapter 7, "Geometric Transformation."

#### 5.6.2. The Leaf Nodes

The Leaf class is an abstract subclass of Node. Leaf nodes generally represent various geometric objects, sounds, and other graphics objects in a scene graph. They have no child node, but they usually do contain references to node component objects. The class hierarchy of leaf nodes is given in Figure 5.11.





A Shape3D leaf node represents a graphics object to be rendered. It holds the references to node components that describe the geometry and appearance of the object. The details about the Shape3D and its subclasses can be found in Chapter 6.

The Behavior class encapsulates the actions that can be defined in a scene graph to achieve dynamic effects. It is the foundation for animation and interaction. The details of animation and interaction are covered in Chapters 10 and 11.

A Morph node is similar to Shape3D, but it facilitates the blending of multiple geometries. A Morph node can be used with a Behavior object to achieve morphing effects on an object.

A Light leaf node defines a light that illuminates the scene when lighting is enabled. Lighting models are discussed in Chapter 9, "Lighting and Texturing."

The Fog node provides a special rendering effect of blending object colors with another color. The degree of blending is related to the distance to the viewer. This creates an effect of fading or fog. The details about Fog class will be presented in Chapter 9.

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A ViewPlatform node represents the positioning of a view in the scene graphs. It is a part of the sophisticated Java 3D viewing system and is associated with a View object. Views are discussed in Chapter 8, "Views."

The Background node defines a background for a scene. The usage of Background is discussed later in this chapter.

The BoundingLeaf node defines a bound that limits the influences of certain nodes such as backgrounds, lights, and behaviors. The concept of bounds will be covered later in this chapter.

Clip and ModelClip nodes define planes that clip the view. A Clip node specifies the far clip plane. Anything beyond the plane is clipped and excluded from rendering. A ModelClip node specifies six planes to clip the view.

The Link node is used to reference a SharedGroup node of a shared branch in a scene graph, as introduced before.

An AlternateAppearance node overrides the appearance of visual objects. Shape3D and Morph nodes will have their appearance overridden by an AlternateAppearance node if they are in the influence bound of the node and they allow the appearance to be overridden.

Sound and SoundScape nodes represent audio objects. Java 3D allows incorporation of sounds in a scene graph. This is a useful feature for applications such as video games.

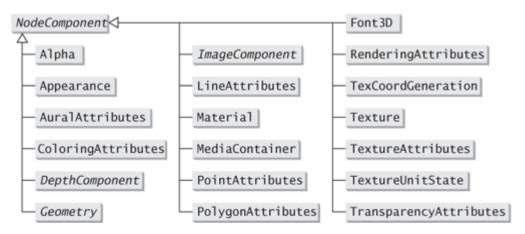
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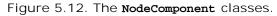
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## 5.7. The Node Components

Group nodes and leaf nodes define the structure of a scene, but usually the attributes of the nodes are defined separately by other objects. Most of the attribute objects belong to the NodeComponent class. The NodeComponent objects define certain attributes such as geometries, colors, textures, and materials. The NodeComponent objects themselves are not nodes in the main tree structure of a scene graph, but they are usually referenced by leaf nodes in the scene graph. The class hierarchy of NodeComponent is shown in Figure 5.12.





The Geometry class (and its subclasses) defines the geometry of a graphics object. A Shape3D leaf node depends on Geometry objects to define its geometric attributes.

The Appearance class controls the appearances of the rendered objects by holding references to other attribute objects. An Appearance object defines the complete rendering states of a Shape3D node. It holds other attribute objects including ColoringAttributes, TransparencyAttributes, Material, PointAttributes, LineAttributes, PolygonAttributes, RenderingAttributes, Texture, TextureAttributes, and TexCoordGeneration. Geometry and Appearance are discussed in Chapter 6.

The ColoringAttributes class defines the color and shading model for rendering a visual object.

The TransparencyAttributes class sets the transparency properties including transparency mode, blend function, and blend value.

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The Material class defines more sophisticated material properties than does ColoringAttributes. Material objects are used in lighting and illumination models. Detailed discussions of material attributes and their effects can be found in Chapter 9.

RenderingAttributes specify certain rendering-related parameters such as depth buffer and alpha test.

PointAttributes, LineAttributes, and PolygonAttributes objects define attributes related to the rendering of points, lines, and polygons. The point attributes include the point size and antialiasing setting. The line

attributes include line width, line pattern, and antialiasing. The polygon attributes include polygon rendering related property settings such as polygon drawing mode, culling, backface normal flip, and offset.

The classes Texture, TextureAttributes, TextureUnitState are related to a rendering technique known as texture mapping. Texture mapping allows images to be used in rendering details of visual objects. The ImageComponent class encapsulates the images for the mapping. An ImageComponent object can also be used to set the background of a scene. The TexCoordGeneration class facilitates automatic generations of texture coordinates that are important parts of texture mapping. The details of texture mapping are presented in Chapters 9 and 12.

The AuralAttributes class defines certain parameters related to audio rendering. The MediaContainer class is used to define sound data. Examples of using sounds in Java 3D can be found in Chapter 12.

An Alpha object converts time values to floating-point numbers between 0 and 1 (alpha-values). It acts as a signal or waveform generator that can trigger certain actions. Alpha objects are useful in animations. Animations are covered in Chapter 11, "Animation."

The DepthComponent class encapsulates the concept of a depth buffer (also known as a z-buffer)—that is, a 2D array to store the depth values (z-values).

The Font3D class defines a solid 3D font. A Font3D object is based on an AWT Font object that defines the 2D glyphs of the font and a FontExtrusion object that defines the extrusion path in the third dimension.

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## 5.8. The Structure of a Java 3D Program

In a simplistic view, to write a Java 3D program is essentially to assemble a scene graph. Of course it is necessary to create the usual user interface elements and other features relevant to an application, but the 3D modeling and rendering of the graphics program mainly consists of the construction of the scene graph. The scene graph is a complete specification of all the graphics objects and their attributes in the system and it is also linked to AWT components for displaying rendered images.

A Java 3D program needs to create a Canvas3D object. Canvas3D is a subclass of java.awt.Canvas, so its instances can be placed in AWT containers in the same way as any other AWT components. A Canvas3D object serves as the panel to display a rendered scene of the virtual world.

The Java 3D program should build a complete and correct scene graph using the objects of the classes provided or derived from the API. A VirtualUniverse object and a Locale object are needed for the superstructure of the scene graph.

A viewing branch of the scene graph is needed to set up a view of the scene. Typically it contains objects of BranchGroup, TransformGroup, ViewPlatform, View, PhysicalBody, and PhysicalEnvironment. The viewing branch is attached to the Locale and is linked to the Canvas3D object to deliver the rendered view.

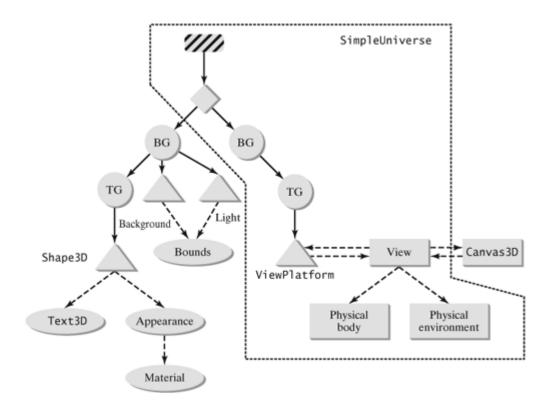
At least one other branch of the scene graph should be constructed for the graphics contents of the virtual world. This content branch should have a BranchGroup node as its root, so that it can be attached to the Locale. Other nodes can be added to build the virtual world. Shape3D, Light, and other nodes can be used to create graphics objects. A Shape3D node can establish its geometry and appearance by referencing appropriate Geometry and Appearance objects. TransformGroup nodes can be used to apply necessary transformations to the child nodes.

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To simplify the process of scene graph creation, Java 3D provides a convenient utility class SimpleUniverse. SimpleUniverse creates a VirtualUniverse, a Locale, and objects for a standard view. The SimpleUniverse is adequate for setting up the superstructures and views in most Java 3D applications using an ordinary video monitor display.

With a basic understanding of Java 3D scene graphs, we can now examine the structure of the program in Listing 5.1. The scene graph corresponding to the Java 3D application in Listing 5.1 is shown in Figure 5.13.

Figure 5.13. The scene graph for Listing 5.1.



The SimpleUniverse object contains objects of classes VirtualUniverse, Locale, BranchGroup, TransformGroup, ViewPlatform, View, PhysicalBody, and PhysicalEnvironment. The branch outside SimpleUniverse is a content branch that defines graphics objects in the virtual world. To attach the branch graph to the Locale object, use the method attachBranchGraph() in SimpleUniverse.

The View object inside SimpleUniverse is associated with a Canvas3D object that is an AWT component. The Canvas3D object in the SimpleUniverse defines a set of default parameters. A partial list of the parameters is ER PRC given below.

Projection policy	PERSPECTIVE_PROJECTION
Field of view	p/4
Front clip distance	0.1
Back clip distance	10.0

The PhysicalBody and PhysicalEnvironment objects are also created with default values appropriate for the normal screen views. The viewing branch of the scene graph inside SimpleUniverse consists of a BranchGroup node, a TransformGroup node, and a ViewPlatform leaf. The BG object is the required node to attach the viewing branch the Locale. The TG node defines a transform for the ViewPlatform. The default view has the view plane pass through the origin. This is not convenient if some objects in the scene are also near the origin. One way to avoid the problem is to move the view back along the z-axis by changing the view transform. This procedure is done by the setNominalViewingTransform method in ViewingPlatform class. The following line from Listing 5 1 retrieves the ViewingPlatform from the SimpleUniverse and calls this method to move the view inew.

#### [Page 152]

su.getViewingPlatform().setNominalViewingTransform();

The content branch in this program contains a BranchGroup node BG as the root. The left child of BG is a TransformGroup node TG that performs an affine transform on its children. The transform is a scaling of 0.5 and a translation by (-0.95, -0.2, 0). There is one leaf node, a Shape3D object, under the TG node. The Shape3D object references a geometry that is a Text3D object. The Text3D node component is set to represent text "Hello 3D." The appearance is set to reference a Material object with default parameters. With the Material object set, the lighting mode is enabled. The 3D text is illuminated by a light defined in the scene.

A light leaf node is another child of the BG node. The light is defined as a point light of white color located at (3, 3, 3) with an attenuation of (1, 0, 0). For computational efficiency, we may limit the range of the light. There is only one Shape3D object in the program, so it is reasonable to limit the influence of the light to a local region enough to cover the 3D text.

The branch graph can be compiled to improve the performance. Once it is attached to the Locale, it becomes "live." A *live scene graph* will be rendered by the Java 3D rendering engine automatically. The objects in a live scene graph can no longer be edited unless specific permissions are given.

Listing 5.2 illustrates the construction of the entire scene-graph with scene-graph objects without using the utility class SimpleUniverse. This example is functionally equivalent to Listing 5.1. However, instead of using the SimpleUniverse utility class, it builds a complete scene graph from the basic objects of node, node component, and other related classes.

Listing 5.2. Hello3DfullGraph.java

(This item is displayed on pages 152 - 153 in the print version)

```
1 package chapter5;
 2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5 import javax.media.j3d.*;
 6 import javax.vecmath.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
 9 import java.applet.*;
10 import com.sun.j3d.utils.applet.MainFrame;
11
12 public class Hello3DFullGraph extends Applet {
    public static void main(String[] args) {
13
14
       new MainFrame(new Hello3DFullGraph(), 640, 480);
15
     }
16
17
    public void init() {
18
      // create canvas
19
       GraphicsConfiguration gc =
20
       SimpleUniverse.getPreferredConfiguration();
21
       Canvas3D cv = new Canvas3D(gc);
22
       setLayout(new BorderLayout());
23
       add(cv, BorderLayout.CENTER);
24
25
       // create superstructure
26
       VirtualUniverse vu = new VirtualUniverse();
27
       Locale loc = new Locale(vu);
[Page 153]28
29
       // create view branch
30
       BranchGroup bgView = createViewBranch(cv);
```

```
31
       bgView.compile();
       loc.addBranchGraph(bgView);
32
33
       // create content branch
34
35
       BranchGroup bg = createContentBranch();
36
       bg.compile();
37
       loc.addBranchGraph(bg);
38
    }
39
40
    private BranchGroup createViewBranch(Canvas3D cv) {
      View view = new View();
41
42
       view.setProjectionPolicy(View.PERSPECTIVE_PROJECTION);
43
       ViewPlatform vp = new ViewPlatform();
44
       view.addCanvas3D(cv);
45
       view.attachViewPlatform(vp);
46
       view.setPhysicalBody(new PhysicalBody());
47
       view.setPhysicalEnvironment(new PhysicalEnvironment());
48
       Transform3D trans = new Transform3D();
49
      Point3d eye = new Point3d(0, 0, 1/Math.tan(Math.PI/8));
50
     Point3d center = new Point3d(0, 0, 0);
51
      Vector3d vup = new Vector3d(0, 1, 0);
52
      trans.lookAt(eye, center, vup);
53
      trans.invert();
      TransformGroup tg = new TransformGroup(trans);
54
55
      tg.addChild(vp);
      BranchGroup bgView = new BranchGroup();
56
57
      bgView.addChild(tg);
58
      return bgView;
59
    }
60
61
    private BranchGroup createContentBranch() {
62
      BranchGroup root = new BranchGroup();
63
       // object
64
       Appearance ap = new Appearance();
65
       ap.setMaterial(new Material());
      Font 3D font = new Font 3D (new Font ("SansSerif", Font.PLAIN, 1),

JNREGISTEREDev Font ("SansSerif", Font.PLAIN, 1),

Text 3D text = new Text 3D (font, "Hello 3D");

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66
67
68
       Shape3D shape = new Shape3D(text, ap);
69
70
       // transformation
71
       Transform3D tr = new Transform3D();
72
      tr.setScale(0.5);
73
      tr.setTranslation(new Vector3f(-0.95f, -0.2f, 0f));
74
      TransformGroup tg = new TransformGroup(tr);
75
      root.addChild(tg);
76
      tg.addChild(shape);
77
       // light
78
       PointLight light = new PointLight(new Color3f(Color.white),
79
                                          new Point3f(1f,1f,1f),
80
                                           new Point3f(1f,0.1f,0f));
81
       BoundingSphere bounds = new BoundingSphere();
82
       light.setInfluencingBounds(bounds);
83
       root.addChild(light);
84
       return root;
85
     }
86 }
    UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
```

#### [Page 154]

This example is essentially equivalent to Listing 5.1. Its scene graph is the same as that of Listing 5.1, as shown in Figure 5.13. The difference is that the superstructure and view branch are created explicitly without using the SimpleUniverse class.

The superstructure objects of VirtualUniverse and Locale are created with default settings (lines 26–27). The Locale object is anchored at the default location (0, 0, 0). The content branch is identical to that in Listing 5.1. The view branch is new, and its construction is done in the method createViewBranch (line 40). As shown in Figure 5.13, the view branch consists of objects of BranchGroup, TransformGroup, View, ViewPlatform, PhysicalBody, and PhysicalEnvironment.

The TransformGroup uses a Transform3D object to represent the transform. The transform is constructed using the methods lookAt and invert (lines 52–53). lookAt sets up a transform based on the eye position, view direction and view up direction. The inverse of this transform is used for setting the view transform group. The transformation settings used in this example are the same as those in SimpleUniverse with the setNominalViewingTransform call. Consequently the display of this example is identical to that of Listing 5.1, as shown in Figure 5.2.

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## 5.9. Backgrounds and Bounds

The default background in a scene is black. If you do not place any visual object or light in the scene graph, you will see a black canvas. The background can be changed by using the Background leaf nodes. A Background leaf may define a solid background color or a background image. It may even define a background geometry. A background will be rendered behind all other visual objects. The constructors of Background are listed below.

```
Background()
Background(Color3f color)
Background(float r, float g, float b)
Background(ImageComponent2D image)
Background(BranchGroup geometry)
```

Listing 5.3 shows an application using a Background node. This program is similar to Listing 5.1. Instead of the default black color, the background color of the rendered scene is white.

Listing 5.3. Hello3Dbackground.java

(This item is displayed on pages 154 - 155 in the print version)

```
1 package chapter5;
 2
 3 import java.awt.*;
 4 import java.applet.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import javax.vecmath.*;
 8 import com.sun.j3d.utils.universe.*;
 9 import com.sun.j3d.utils.geometry.*;
10 import com.sun.j3d.utils.applet.MainFrame;
11
12 public class Hello3DBackground extends Applet
      new MainFrame(new Hello3DBackground(), 640, 480);
    13
14
15
    }
16
17
    public void init() {
18
      GraphicsConfiguration gc =
19
       SimpleUniverse.getPreferredConfiguration();
20
      Canvas3D cv = new Canvas3D(qc);
21
      setLayout(new BorderLayout());
22
      add(cv, BorderLayout.CENTER);
[Page 155]23
             BranchGroup bg = createSceneGraph();
24
      bg.compile();
25
      SimpleUniverse su = new SimpleUniverse(cv);
26
       su.getViewingPlatform().setNominalViewingTransform();
27
       su.addBranchGraph(bg);
28
    }
29
30
    private BranchGroup createSceneGraph() {
31
      BranchGroup root = new BranchGroup();
32
      // object
33
              LISTERED VERSION OF CHM TO PDF CONVERTER PRO
34
         CA + Ma
      Font3D font = new Font3D(new Font("SansSerif", Font.PLAIN, 1)
35
```

```
36
       new FontExtrusion());
37
       Text3D text = new Text3D(font, "Hello 3D");
38
       Shape3D shape = new Shape3D(text, ap);
39
       // transformation
40
       Transform3D tr = new Transform3D();
41
       tr.setScale(0.5);
42
       tr.setTranslation(new Vector3f(-0.95f, -0.2f, 0f));
43
       TransformGroup tg = new TransformGroup(tr);
44
       root.addChild(tg);
45
       tg.addChild(shape);
46
       // light
       PointLight light = new PointLight(new Color3f(Color.white),
47
48
       new Point3f(1f,1f,1f),
49
       new Point3f(1f,0.1f,0f));
50
       BoundingSphere bounds = new BoundingSphere();
51
       light.setInfluencingBounds(bounds);
52
       root.addChild(light);
53
       // background
54
       Background background = new Background(1.0f, 1.0f, 1.0f);
55
       background.setApplicationBounds(bounds);
56
       root.addChild(background);
57
       return root;
58
    }
59 }
```

This example is similar to Listing 5.1. The visible difference is that the background of the scene is changed to white, as shown in Figure 5.14.

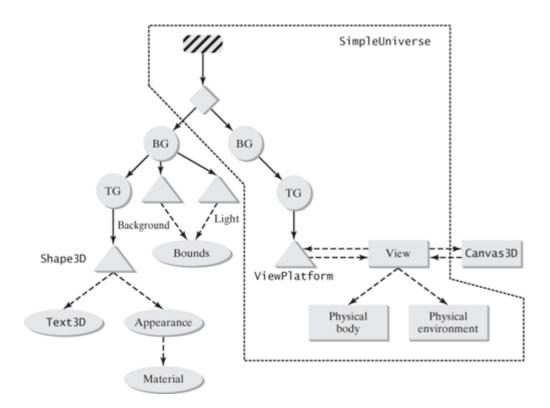
Figure 5.14. A simple Java 3D program with a white background. (This item is displayed on page 156 in the print version)



The new scene graph is given in Figure 5.15. A Background leaf node is added to the content branch of the scene graph (lines 54–56). The background is created with a constructor that specifies color RGB values:

Background background = new Background(1.0f, 1.0f, 1.0f); background.setApplicationBounds(bounds); root.ad Report RED VERSION OF CHM TO PDF CONVERTER PRO

Figure 5.15. The scene graph for Listing 5.3. (This item is displayed on page 156 in the print version)



The application bound of the background is a BoundingSphere object shared with the light.

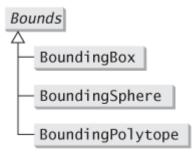
Environmental nodes such as Background and Light may potentially influence the entire universe. To achieve a reasonable rendering efficiency it is necessary to limit the influence. The *bounds* for environmental nodes can be set in two different ways: through the Bounds objects or the BoundingLeaf leaf nodes. Bounds objects are node components and BoundingLeaf objects are leaf nodes of a scene graph. The main difference between the two approaches is the coordinates of the bounds. A node that sets a bound by directly referencing a Bounds object will have the bound positioned relative to the node. A BoundingLeaf node has its own position defined for the bound. A node referencing the BoundingLeaf will acquire a bound positioned according to the BoundingLeaf.

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The Bounds classes are shown in Figure 5.16. The abstract class Bounds has three subclasses BoundingBox, BoundingSphere, and BoundingPolytope to represent different types of bounding volumes.

[Page 157]

Figure 5.16. The Bounds class hierarchy.



The BoundingBox class defines a bound as a rectangular box with edges parallel to the axes. The BoundingSphere class defines a sphere as the bounding volume. The Bound-ingPolytope class defines a bounding volume of a general polytope.

The following statements create three bounds of different types:

A BoundingLeaf object is leaf node in the tree of a scene graph and has a specific location in the locale of the scene. A BoundingLeaf object uses a Bounds object to define its bounding region. This bounding region is positioned according to the position of the BoundingLeaf node. If several nodes located at different places in the virtual world need to reference a common bounding region, it is easier to use a BoundingLeaf node.

Consider an example of setting the influence bound of a light. The two different approaches are illustrated below.

## // setUNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

BoundingSphere bounds = new BoundingSphere(); // a bounding sphere
light.setInfluencingBounds(bounds);
// set bounds by referencing a BoundingLeaf
BoundingSphere bounds = new BoundingSphere(); // a bounding sphere
BoundingLeaf leaf = new BoundingLeaf(bounds);
root.addChild(leaf); // add to scene graph
light.setInfluencingBoundingLeaf(leaf);

In the first case, a unit BoundingSphere is created and the influencing bound of a light is set directly to the bound. The sphere will be centered at the origin in the coordinate space of the light.

In the second case, a similar BoundingSphere is created, but it is referenced by a BoundingLeaf node. The influencing bound of the light is set to the BoundingLeaf node. The bounding sphere will be centered at the origin in the local coordinate system of the leaf node, which may be different from the local coordinate system of the leaf node, which may be different from the local coordinate system of the light. The distinction between Bounds and BoundingLeaf will be more apparent if several lights under different transformation paths in the scene graph reference the same Bounds or BoundingLeaf objects. With direct Bounds references, their actual influencing bounds defined by the object are different. With a BoundLeaf, the actual of the same BOUNDERCERPRO

Listing 5.4 demonstrates the effects of Bounds objects on a light. A scene with an image background, three

spheres and a light is created and rendered as shown in Figure 5.17. The spheres are lit by the light when they are within the influencing bounds of the light. When a user clicks the mouse on the panel, the influencing bound of the light is changed to the next of the three bounds. The first click will reduce the bounds, avoiding the left sphere. The second click reduces the bounds further to include only the right sphere. The third click will return to the original bounds.

```
[Page 158]
```

#### Listing 5.4. TestBounds.java

(This item is displayed on pages 158 - 159 in the print version)

```
1 package chapter5;
 2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5 import javax.media.j3d.*;
 6 import javax.vecmath.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
 9 import java.awt.image.*;
10 import java.io.*;
11 import java.net.URL;
12 import javax.imageio.*;
13 import java.applet.*;
14 import com.sun.j3d.utils.applet.MainFrame;
15
16 public class TestBounds extends Applet {
17
    public static void main(String[] args) {
18
       new MainFrame(new TestBounds(), 640, 480);
19
    }
20
21
    Light light = null;
22
     Bounds[] bounds = new Bounds[3];
    int bIndex = 0;
23
24
25
    public void init() {
26
      // create canvas
27
       GraphicsConfiguration gc =
28
       SimpleUniverse.getPreferredConfiguration();
29
       Canvas3D cv = new Canvas3D(gc);
30
       setLayout(new BorderLayout());
31
       add(cv, BorderLayout.CENTER);
32
       cv.addMouseListener(new MouseAdapter() {
33
         // change background color and image on mouse click
34
         public void mouseClicked(MouseEvent ev) {
35
           bIndex = (bIndex+1) % 3;
36
           System.out.println(bIndex);
37
            light.setInfluencingBounds(bounds[bIndex]);
38
         }
39
       });
40
       BranchGroup bg = createSceneGraph();
41
       bg.compile();
42
       SimpleUniverse su = new SimpleUniverse(cv);
43
        su.getViewingPlatform().setNominalViewingTransform();
44
        su.addBranchGraph(bg);
45
     }
46
47
     private BranchGroup createSceneGraph() {
```

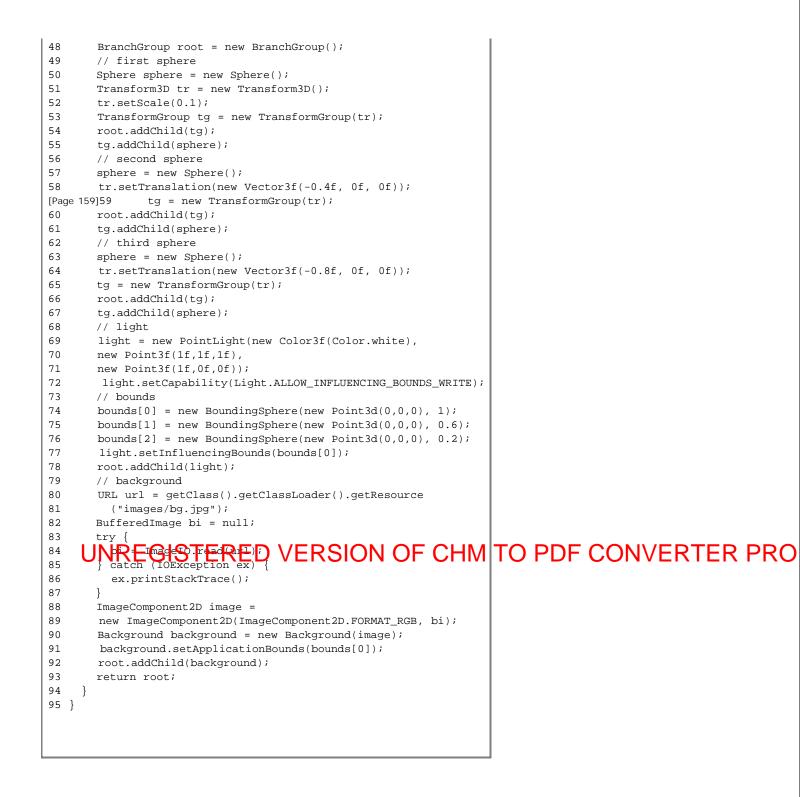
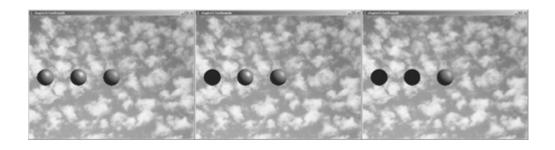


Figure 5.17. The effects of influencing bounds. Left: The light has influencing bounds including all three spheres. Center: The light has influencing bounds including only two spheres. Right: The UNREGISTERED TO ERTSTONING CHM CONFERENCE PORTER PRO



The abbreviated scene graph is shown in Figure 5.18. Three Sphere objects are added to the scene graph. Each sphere is attached to a TransformGroup node to scale it down in size and to translate the sphere to a different location. The amounts of translations for the three spheres are different so they do not overlap (lines 49–67).

[Page 160]

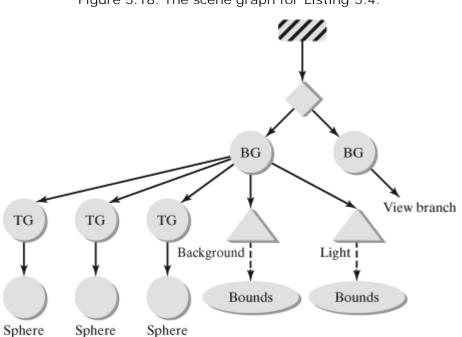


Figure 5.18. The scene graph for Listing 5.4.

A light is placed at (1, 1, 1) to illuminate the spheres. The light has influencing bounds that determines whether an object is lit by the light. Three different BoundingSphere objects of radii 1, 0.6, and 0.2 are created and stored in the bounds array (lines 74–76). An integer field bIndex is an index to keep track of the current bounds. Initially bounds[0] is used by the light, and it is large enough to include all three spheres.

A MouseListener is added to the Canvas3D object to handle the mouse events. In an event of a mouse click, the current bounds index is changed:

bIndex = (bIndex + 1) % 3; light.setInfluencingBounds(bounds[bIndex]); Therefore, the elements in the bounds array are selected in a cyclic way in response to mouse clicks. When bounds[1] is selected, the left sphere is outside the influencing bounds of the light, and it becomes black. When bounds[2] is selected, only the right sphere remains in the bounds, and the other two spheres are black.

The background is defined using a Background leaf node. The background is set to an image loaded from an image file. The Background node also needs a Bounds object to limit its application. In this example the BoundingSphere object in bounds[0] is also used by the background node for its application bounds:

background.setApplicationBounds(bounds[0]);

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# 5.10. Compiling Scene Graphs and Capability Bits

A scene graph rooted at a BranchGroup node can be compiled before it is attached to a Locale and becomes live. The BranchGroup class contains a method compile for *compiling* the scene graph. Compiling a scene graph converts it to an internal representation that will be more efficient for the Java 3D rendering engine to use in rendering the scene. Compiling the scene graph also gives Java 3D an opportunity to perform certain optimizations that can speed up the rendering. The optimizations are not defined by the Java 3D specification and may be implementation dependent.

You may change a scene graph after it is live, but to do so you have to explicitly get permission for every operation attempted on a live scene-graph object. The permissions are expressed in the form of *capability bits* that exist in the node and node-component objects. Each individual operation in an individual object has an independent capability bit. By default, all capability bits are turned off to improve the rendering performance. In order to make a dynamic change on any aspect of a live scene graph, you need to turn on the corresponding capability bit in advance. The capability bits must be set before the scene graph is compiled with the method call compile. If an operation is performed without the appropriate capability bit being set, a runtime exception will be thrown.

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The capability bits can be set with the following method of the SceneGraphObject class,

public final void setCapability(int bit);

The capability bits are defined as constants in individual classes. If multiple capability bits need to be set, you have to make several calls to the setCapability method. Each call can set only one bit. It is not allowed to combine multiple capability bits into one and to make only one call. For example, to allow the change of color in a ColoringAttributes object, you need to set the corresponding capability bit:

coloring.setCapability(ColorAttributes.ALLOW\_COLOR\_WRITE);

To read the color when the scene graph is live, you need to give the read permission:

coloring.setCapability(ColorAttributes.ALLOW\_COLOR\_READ);

To be able to read and write the color, you need to set the two bits:

coloring.setCapability(ColorAttributes.ALLOW\_COLOR\_READ); coloring.setCapability(ColorAttributes.ALLOW\_COLOR\_WRITE);

If you need to modify the geometry of a Shape3D node, you must set the capability bit:

shape.setCapability(Shape3D.ALLOW\_GEOMETRY\_WRITE);

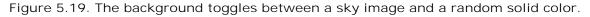
Listing 5.5 shows the use of capability bits and the modification of the background in a live scene graph. This program demonstrates the process of changing the attributes of a live scene graph. The background image and color in the scene are changed in response to mouse clicks. (See Figure 5.19.)

Listing 5.5. ChangeBackground.java

(This item is displayed on pages 161 - 163 in the print version)

```
1 package chapter5;
 2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5 import javax.media.j3d.*;
 6 import javax.vecmath.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
 9 import java.awt.image.*;
10 import java.io.*;
11 import java.net.URL;
12 import javax.imageio.*;
13 import java.applet.*;
14 import com.sun.j3d.utils.applet.MainFrame;
15
16 public class ChangeBackground extends Applet {
    public static void main(String[] args) {
17
       new MainFrame(new ChangeBackground(), 640, 480);
18
19
    }
20
21
     Background background = null;
            ImageComponent2D image = null;
[Page 162]22
23
24
    public void init() {
25
       GraphicsConfiguration gc =
26
       SimpleUniverse.getPreferredConfiguration();
       Canvas3D cv = new Canvas3D(gc);
27
28
       setLayout(new BorderLayout());
29
       add(cv, BorderLayout.CENTER);
       cv.addMouseListener(new MouseAdapter() {
30
31
         // change background color and image on mouse click
         public void mouseClicked(MouseEvent ev) {
32
33
           if (background.getImage() == null)
34
             background.setImage(image);
35
           else {
        NREGISTERED WERSION OF CHM TO PDF CONVERTER PRO
36
37
38
             float g = (float)Math.random();
             float b = (float)Math.random();
39
40
             background.setColor(r, g, b);
41
           }
42
        }
43
       });
44
       BranchGroup bg = createSceneGraph();
45
       bg.compile();
46
       SimpleUniverse su = new SimpleUniverse(cv);
47
        su.getViewingPlatform().setNominalViewingTransform();
48
       su.addBranchGraph(bg);
49
    }
50
51
     private BranchGroup createSceneGraph() {
52
       BranchGroup root = new BranchGroup();
53
       // object
54
       Appearance ap = new Appearance();
55
       ap.setMaterial(new Material());
       Font3D font = new Font3D(new Font("SansSerif", Font.PLAIN, 1),
56
57
                                      RSION OF CHM TO PDF CONVERTER PRO
          rext 3D-text 2 new Text 5D font
58
59
       Shape3D shape = new Shape3D(text, ap);
```

```
60
       // transformation
       Transform3D tr = new Transform3D();
61
62
       tr.setScale(0.5);
63
       tr.setTranslation(new Vector3f(-0.95f, -0.2f, 0f));
64
       TransformGroup tg = new TransformGroup(tr);
65
       root.addChild(tg);
66
       tg.addChild(shape);
67
       // light
68
       PointLight light = new PointLight(new Color3f(Color.white),
69
       new Point3f(1f,1f,1f),
70
       new Point3f(1f,0.1f,0f));
71
       BoundingSphere bounds = new BoundingSphere();
72
       light.setInfluencingBounds(bounds);
73
       root.addChild(light);
74
       // background
75
       background = new Background(1.0f, 1.0f, 1.0f);
76
       background.setApplicationBounds(bounds);
77
       // load image
78
       URL url = getClass().getClassLoader().
       getResource("images/bg.jpg");
79
80
       BufferedImage bi = null;
[Page 163]81
               try {
         bi = ImageIO.read(url);
82
83
       } catch (IOException ex) {
84
         ex.printStackTrace();
85
       }
86
       image = new ImageComponent2D(ImageComponent2D.FORMAT_RGB, bi);
87
       // set capability bit to allow color and image change
88
        background.setCapability(Background.ALLOW_COLOR_WRITE);
89
       background.setCapability(Background.ALLOW_IMAGE_READ);
90
        background.setCapability(Background.ALLOW_IMAGE_WRITE);
91
       root.addChild(background);
92
       return root;
93
    }
94 }
```





This example is similar to Listing 5.2. They have the identical scene graph. Two kinds of backgrounds are applied in this example: an image and a solid color.

An image is read from a file "bg.jpg" to a BufferedImage object and is then passed to an ImageComponent2D object (lines 77–84). The Background node has the following capability bits set to allow live changes of its color and image and to read its image (lines 88–90):

ALLOW\_COLOR\_WRITE ALLOW\_IMAGE\_READ ALLOW\_IMAGE\_WRITE

In the constructor, the Canvas3D object is set to listen to mouse events. In the mouse-click handler, mouseClicked, the background is checked for the existence of a background image. If there is no image in the background, the loaded image is assigned to the background. If there is already an image in the background, the image of the background is set to null and the color of the background is changed to a random color. Therefore, successive clicking of the canvas will toggle the background between the image and a random solid color.

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# Key Classes and Methods

- com.sun.j3d.util.applet.MainFrame A utility class to display an applet in a frame.
- javax.media.j3d.VirtualUniverse A class encapsulating a coordinate space of the entire virtual universe.

[Page 164]

- javax.media.j3d.Locale A class defining a coordinate space with float data type anchored in the virtual universe.
- javax.media.j3d.HiResCoord A fixed-point data type to represent high-resolution coordinates of the virtual universe.
- **com.sun.j3d.util.universe.SimpleUniverse** A convenience class with a default implementation of the virtual universe, a locale, and a view branch of the scene graph.
- javax.media.j3d.SceneGraphObject An abstract class served as the root class for all scene-graph elements.
- javax.media.j3d.Node A class for nodes in a scene graph.
- javax.media.j3d.NodeComponent A class for node components in a scene graph.
- javax.media.j3d.Group A class for group nodes in a scene graph.
- javax.media.j3d.Leaf A class for leaf nodes in a scene graph.
- javax.media.j3d.SceneGraphObject.setCapability(int) A method to allow certain manipulations of the object in a live scene graph.
- javax.media.j3d.Group.addChild(Node) A method to add child nodes in a scene graph.
- javax.media.j3d.BranchGroup A special type of group nodes that can be attached to a locale.
- javax.media.j3d.BranchGroup.compile() A method to compile the scene graph to improve the performance.
- javax.media.j3d.Background A leaf node defining the background color, image, and geometry of a scene.
- **javax.media.j3d.Bounds** A node-component class encapsulating a spatial volume that is used by environmental nodes to limit their scope of activation.
- **javax.media.j3d.BoundingLeaf** A leaf class encapsulating a spatial volume that is used by environmental nodes to limit their scope of activation.
- javax.media.j3d.BoundingBox A class encapsulating box-shaped bounds.
- javax.media.j3d.BoundingSphere A class encapsulating spherical bounds.
- javax.media.j3d.BoundingPolytope A class encapsulating polytope bounds.

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## Key Terms geometry

A structural definition of a visual object.

#### appearance

A collection of rendering attributes of a visual object.

## DAG

(directed acyclic graph) A directed graph with no directed cycles.

## scene graph

A DAG specifying the graph scene to be rendered.

## tree

A graph formed by recursively adding distinct child nodes.

## leaf node

A node in a tree that has no children.

## internal node

A node in a tree that has children.

#### primitive

A basic visual object that may be used to build a model.

## capability bit

A flag in SceneGraphObject that gives permission to performing a specific operation in a live scene graph.

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[Page 164 (continued)]

# Chapter Summary

- In this chapter, we discuss the fundamental concepts of 3D computer graphics and the basic architecture of the Java 3D system.
- In a 3D graphics system, a virtual world is built to model a 3D graphics scene. The model is viewed from a particular perspective to produce a rendering of the scene.

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- The Java 3D API is built on the key concept of scene graphs. A scene graph incorporates all the graphics descriptions and attributes of a scene to be rendered into a single data structure.
- The rules for constructing the scene graphs and their building blocks are introduced. A scene graph is a DAG, with nodes being objects from classes of superstructures, nodes, and node components.
- The overall structure of a Java 3D program is presented. By using a scene graph and its related objects, we can build a 3D graphics model and let Java 3D render the scene automatically.
- The background of a scene can be changed using the Background leaf node. Environmental nodes such as Light and Background need to set bounds to limit their influence in rendering. Bounds and BoundingLeaf objects are two ways of setting bounds.
- A branch graph can be compiled to improve rendering efficiency. A component of a live scene graph can be modified only if appropriate capability bits are set.

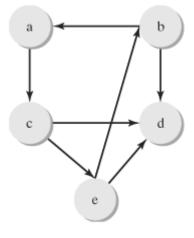
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# **Review** Questions

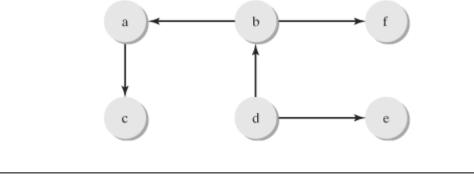
- 5.1 If a tree has 15 nodes, how many links does it have?
- 5.2 Is the following graph (Figure 5.20) a tree? Is it a DAG? If it is a tree, identify its root, leaves, and internal nodes.

Figure 5.20. A graph for Problem 5.2.

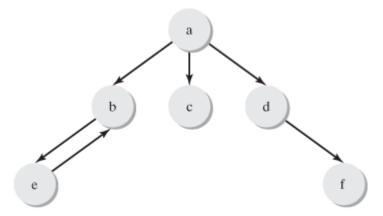


5.3 Is the following graph (Figure 5.21) a tree? Is it a DAG? If it is a tree, identify its root, leaves, and internal nodes.

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- [Page 166]
- 5.4 Is the following graph (Figure 5.22) a tree? Is it a DAG? If it is a tree, identify its root, leaves, and internal nodes.



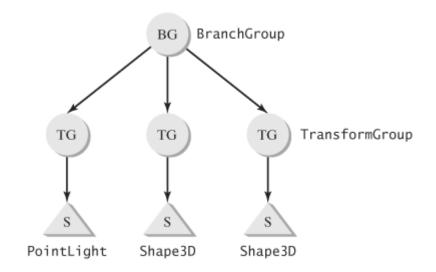
5.5 Draw a scene graph corresponding to the following Java 3D code segment: BranchGroup root = new BranchGroup(); TransformGroup trans = new TransformGroup(); root.addChild(trans); Shape3D shape1 = new Shape3D(); Shape3D shape2 = new Shape3D(); Shape3D shape3 = new Shape3D(); trans.addChild(shape1); trans.addChild(shape2);

```
root.addChild(shape3);
```

```
5.6 Draw a scene graph corresponding to the following Java 3D code segment:
     BranchGroup root = new BranchGroup();
     TransformGroup trans1 = new TransformGroup();
     TransformGroup trans2 = new TransformGroup();
     root.addChild(trans1);
     root.addChild(trans2);
     Light light = new PointLight();
     trans1.addChild(light);
     Switch switch = new Switch();
     Trans2.addChild(switch);
     Shape3D shape1 = new Shape3D();
     Shape3D shape2 = new Shape3D();
     switch.addChild(shape1);
     switch.addChild(shape2);
     Appearance appear = new Appearance();
     shape1.setAppearance(appear);
     shape2.setAppearance(appear);
```

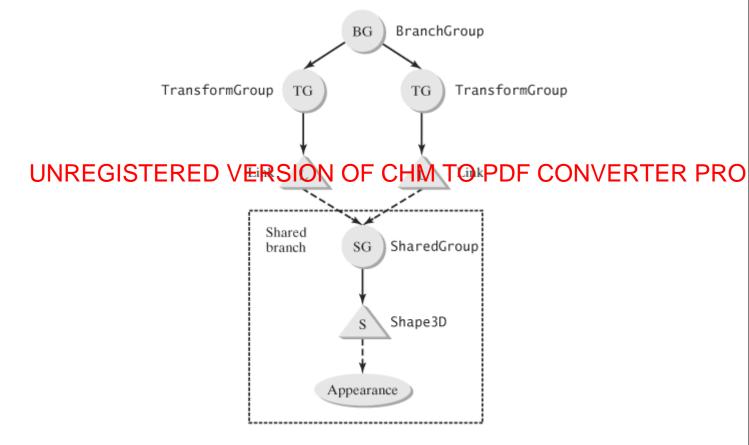
5.7 Write a Java 3D code segment corresponding to the scene graph branch shown in Figure 5.23. [Page 167]

Figure 5.23. Scene graph for Problem 5.7.



5.8 Write a Java 3D code segment corresponding to the scene graph branch shown in Figure 5.24.





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[Page 167 (continued)]

# Programming Exercises

- 5.1 The ColorCube class is a subclass of Shape3D and can be used as a leaf node to represent a cube with colored faces. Write a Java 3D application that displays a ColorCube object using the SimpleUniverse class.
- 5.2 Write a Java 3D program to display a ColorCube as in Exercise 5.1 without using the SimpleUniverse class. Draw a complete scene-graph diagram for the program.

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- 5.3 Add a blue background to the program in Exercise 5.1 using a Background leaf node. Set the application bounds of the background directly with a bounding sphere.
- 5.4 Write a Java 3D program similar to Exercise 5.3, but use a BoundingLeaf node to set the application bounds to a bounding box.
- 5.5 Write a Java 3D program similar to Listing 5.4, but use a BoundingLeaf node for the influencing bounds of the light.

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# Chapter 6. Graphics Contents

(This item omitted from WebBook edition)

Objectives
• To understand geometry and appearance, the basic attributes of visual objects.
To describe the representations of points and vectors.
• To apply the GeometryArray family of classes for constructing geometry.
• To apply the GeometryInfo class for constructing geometry.
To use geometric primitives.
To use texts and fonts as geometric objects.
To use the Appearance class and the associated node-component classes.

# 6.1. Introduction

The fundamental capecing pocks in a rendered scene. A shape object is defined by its geometry and its appearance. The geometry provides a mathematical description of the object's shape, size, and other structural properties. The appearance defines the object's color, texture, material properties, and other attributes.

The geometry of a visual object may be constructed from a set of simple objects such as triangles. More complex but useful objects such as cubes and spheres may be prebuilt as reusable objects known as *primitives*. Primitives provide a level of abstraction that will simplify the construction of many complex objects. Text objects based on fonts provide another source of geometry objects. Both 2D and 3D text objects are useful elements of a 3D graphics scene.

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Java 3D provides the leaf node class Shape3D to represent shape objects. The geometry and appearance of a Shape3D node are defined by referencing the Geometry and Appearance objects. The Geometry class has a number of subclasses to help define various types of geometries in different ways. The Appearance class holds references to various other attribute objects to define different aspects of the appearance. Commonly used primitives such as boxes, spheres, cylinders, and cones are also provided by Java 3D. Java 3D offers supports to use 2D and 3D texts as geometric objects.

In this chapter, we will introduce the construction of visual objects using geometry and appearance specifications. Java 3D's facilities for the low-level construction of geometries are examined. The high-level constructs of primitives and text objects are also presented. We will discuss the basic structure and usage of ER PRC Java 3D appearance by induces in this chapter. The attributes that are related to more advanced mendering TER PRC options such as lighting and texturing will be covered in greater detail in later chapters.

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# 6.2. Points and Vectors

The modeling of geometry begins with the modeling of a *point*. To precisely represent points in computers, the algebraic concept of *vectors* and *vector spaces* is commonly used. An *n*-dimensional vector is an *n*-tuple of numbers:

 $(x_1, x_2, ..., x_n)$ 

The collection of all the *n*-dimensional vectors forms an *n*-dimensional space  $\mathcal{R}^n$ . In a 3D space, a point can be represented by a 3D vector (x, y, z). Using *homogeneous coordinates*, a point is associated with a 4D vector (x, y, z, w).

There is also a geometric concept of vectors that represents quantities with directions. Examples of such vectors include the direction of a line, force, velocity, and acceleration. A geometric vector is also represented as an *n*-tuple. Algebraically there is no distinction between a geometric point and a geometric vector. The difference exists only in the interpretations of general mathematical quantities.

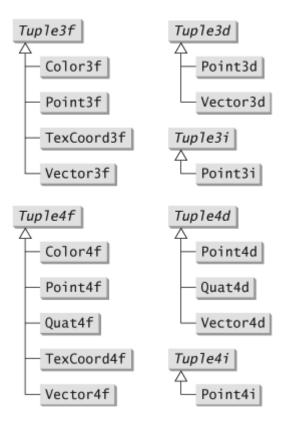
In 3D graphics, geometry construction and transformation depend heavily on the mathematical notion of vectors. Java provides an extensive set of classes for representing points, vectors, and matrices in the package javax.vecmath. Java 3D classes frequently use the vector math classes, and the javax.vecmath package is included in the distribution of Java 3D.

The package javax.vecmath contains many variations of vector and matrix classes. A partial list of the vector classes is given below in Figure 6.1.

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Figure 6.1. Vector math classes.

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The suffixes in the class names indicate the dimensions and the data types of the components. The data type suffixes are listed below:

- f: float
- d: double
- i: int
- b: byte

For example, "4d" represents a four-dimensional tuple of double values. The stems of the class names indicate the categories of their usage.

- Tuple\* classes: the abstract base classes for the tuples.
- Color\* classes: color representations.
- Point\* classes: geometric points.
- Vector\* classes: geometric vectors.
- TexCoord\* classes: texture-mapping coordinates.
- Quat\* classes: quaternions.

Besides the data representation, the vector classes contain methods for standard operations related to their categories. For example, the Tuple4f class includes methods:

- **void** add(Tuple4f t1)— Add another tuple.
- **void** sub(Tuple4f t1)— Subtract another tuple.
- **void** scale(**float** k)— Scale the tuple.
- **void** negate() Negate all components of the tuple.

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Point 3d class adds distance-related methods:

- **void** distance(Point3d p1)— Find the distance to another point.
- **void** distanceL1(Point3d p1)— Find the  $L^1$  distance to another point.
- **void** distanceLinf(Point3d p1)— Find the Z distance to another point.

Vector3d class includes methods for vector operations:

- **double** dot(Vector3d v1)— Find the dot product with another vector.
- double cross(Vector3d v1, Vector3d v2)— Calculate the cross product of the two vectors.
- **double** length() Find the length of the vector.
- **double** angle(Vector3d v1)— Find the angle with another vector.

The vector math objects are easy to create and manipulate. The following example creates two Point3d objects and finds the distance between them:

Point 3d pl REG ST3E RED 3, ERSION OF CHM TO PDF CONVERTER PRO double dist = pl.distance(p2);

To find the angle between two vectors, you can call the angle method:

```
Vector3f v1 = new Vector3f(1.0, 2.3, 0.0);
Vector3f v2 = new Vector3f(0.0, -0.5, 1.2);
double angle = v1.angle(v2);
```

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# 6.3. Geometry

The basic geometric shapes of 3D objects are typically modeled as points, lines, and surfaces. Points and lines (including curves) are relatively simple to define because they are usually straightforward extensions of the corresponding 2D models. The surface models present some real challenges. 3D solid objects can usually be modeled as surfaces. Mathematically a surface can often be represented by an *implicit equation* on the coordinates:

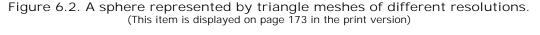
## $F(X, y, \vec{z}) = 0$

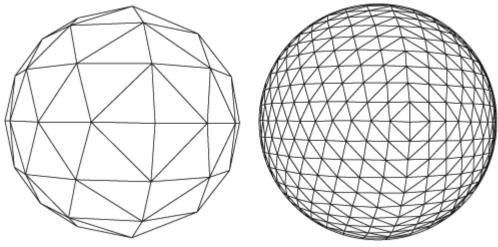
Alternatively, a *parametric equation* with two parameters is usually more convenient for graphics applications:

- X = f(U, V)
- $\mathcal{Y} = \mathcal{G}(\mathcal{U}, \mathcal{V})$

Z = h(U, V)

Because of the obvious complexity involved in representing an arbitrary 3D surface, it is often necessary to use a collection of simpler surfaces as an approximation. A commonly used representation is a mesh of simple polygons, such as triangles and quadrilaterals. Another versatile and powerful representation tool for surfaces is the polynomial and spline surfaces. Figure 6.2 shows an example of *polygon meshes* representing a surface.

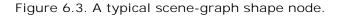


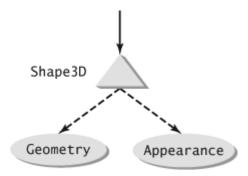


Java 3D offers direct support for arrays of points, lines, and triangles or quadrilaterals as the basic tools for geometry construction. It also offers support for high-level geometries such as primitives and 3D text.

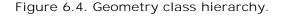
In a Java 3D scene graph, a visual object is usually represented by a Shape3D leaf node. The Shape3D object references a Geometry object that defines the shape and other geometric characteristics of the visual object. The Shape3D node also references Appearance objects to define its appearance in rendering. A typical scene-graph Shape3D node configuration is shown in Figure 6.3.

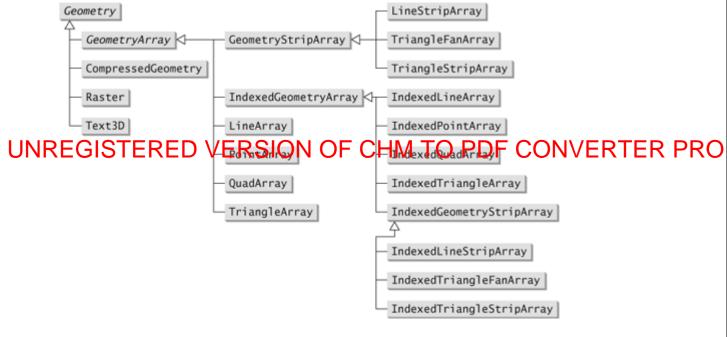
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The Geometry class is an abstract class with a large number of descendants. Figure 6.4 shows the class hierarchy of the Geometry classes.





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## 6.3.1. GeometryArray

The GeometryArray family of classes provides facilities to directly construct geometries with arrays of simple polygons, lines, or points. A GeometryArray defines the vertices and specifies the structural relationships among the vertices **REGISTERED VERSION OF CHM TO PDF CONVERTER PRO** 

In a GeometryArray object, the definitions for vertices always include their coordinates, but they may also

include other types of data components such as surface normals and colors. The presence of a particular type of vertex data component is indicated by a corresponding bit mask.

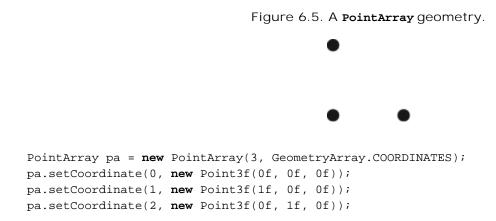
COORDINATES – the coordinates of vertices. NORMALS – the surface normals of vertices. COLOR\_3 – the colors of vertices without COLOR\_4 – the colors of vertices with TEXTURE\_COORDINATE\_2 – the 2D texture coordinates. TEXTURE\_COORDINATE\_3 – the 3D texture coordinates. TEXTURE\_COORDINATE\_4 – the 4D texture coordinates.

These masks can be combined using bitwise OR operator "|". The masks can be set in the constructors of GeometryArray classes. The data components, if present, are assigned to each vertex. Color specifications at the vertices may be used to determine the colors of the visual objects under given shading models. The surface normals are necessary to calculate light reflections in illuminated models. Texture coordinates define the coordinates in texture space. Lighting models and texture mapping are discussed in Chapter 9.

Typically an object in the GeometryArray family is created by calling an appropriate constructor with the specified data components and the array sizes. Then the vertex data are set through method calls. GeometryArray provides a variety of different methods to set the coordinates and other data. For example, a coordinate can be set individually or an array of coordinates can be set in one method:

```
void setCoordinate(int index, Point3f coord)
void setCoordinates(int startIndex, Point3f[] coords)
```

The PointArray class defines a geometry consisting of a set of points. Each vertex specification corresponds to a point in the geometry. For example, the following code fragment defines a PointArray geometry with three points. The geometry is shown in Figure 6.5.



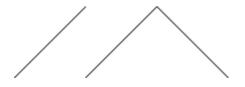
The LineArray class defines a geometry of line segments. Every two vertices specified sequentially correspond to a line segment in the geometry:

[Page 175]LineArray la = new LineArray(6, GeometryArray.COORDINATES);

```
Point3f[] coords = new Point3f[6];
coords[0] = new Point3f(0f, 0f, 0f);
coords[1] = new Point3f(1f, 1f, 0f);
coords[2] = new Point3f(1f, 0f, 0f);
coords[3] = new Point3f(2f, 1f, 0f);
coords[4] = new Point3f(2f, 1f, 0f);
coords[5] = new Point3f(3f, 0f, 0f);
la.setCoordinates(0, coords);
```

The line geometry defined above is illustrated in Figure 6.6.

#### Figure 6.6. A LineArray geometry.

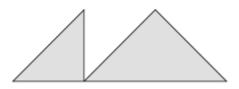


The TriangleArray class defines a surface consisting of triangle patches. Every three vertices define a triangle. The following code fragment defines a geometry object of two triangles:

```
TriangleArray ta = new TriangleArray(6, GeometryArray.COORDINATES);
Point3f[] coords = new Point3f[6];
coords[0] = new Point3f(0f, 0f, 0f);
coords[1] = new Point3f(1f, 1f, 0f);
coords[2] = new Point3f(1f, 0f, 0f);
coords[3] = new Point3f(1f, 0f, 0f);
coords[4] = new Point3f(2f, 1f, 0f);
coords[4] = new Point3f(2f, 1f, 0f);
ta.setCoordinates(0, coords);
```

The geometry defined in the TriangleArray is shown in Figure 6.7.

Figure 6.7. A TriangleArray geometry.



The geometry of a cone may be defined as a series of triangles using a TriangleArray:

int nUNR/EGISTEREDeVERSION OF CHM TO PDF CONVERTER PRO TriangleArray ta = new TriangleArray(3\*n, GeometryArray.COORDINATES);

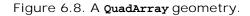
```
Point3f apex = new Point3f(0, 0, 1);
Point3f p1 = new Point3f(1, 0, 0);
int count = 0;
for (int ii = 1; ii <= n; ii++) {
  float x = (float)Math.cos(ii*2*Math.PI/n);
  float y = (float)Math.sin(ii*2*Math.PI/n);
  Point3f p2 = new Point3f(x, y, 0);
  ta.setCoordinate(count++, apex);
  ta.setCoordinate(count++, p1);
  ta.setCoordinate(count++, p2);
  p1 = p2;
}
```

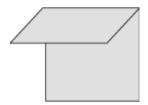
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The circular base of the cone is divided into n segments. The two points of each segment and the apex form a triangle. Because the TriangleArray requires explicit specification of each vertex in each triangle, we need to define 3n coordinates, even though there are only n + 1 distinct points.

The QuadArray class defines a surface of quadrilateral patches. Every four sequential vertices define a quadrilateral. The four vertices are required to be on a plane. The following QuadArray object consists of two squares not on the same plane, but the vertices of each square are on the same plane. (See Figure 6.8.)

```
QuadArray qa = new QuadArray(8, GeometryArray.COORDINATES);
Point3f[] coords = new Point3f[8];
coords[0] = new Point3f(0f, 0f, 0f);
coords[1] = new Point3f(1f, 0f, 0f);
coords[2] = new Point3f(1f, 1f, 0f);
coords[3] = new Point3f(0f, 1f, 0f);
coords[4] = new Point3f(0f, 1f, 0f);
coords[5] = new Point3f(0f, 1f, 0f);
coords[6] = new Point3f(0f, 1f, 1f);
coords[7] = new Point3f(1f, 1f, 1f);
qa.setCoordinates(0, coords);
```





Note that even though there are only six distinct points in this geometry, we still need to define eight vertices for the QuadArray object, because it is necessary to specify each quadrangle with four vertices.

Besides coordinates, other attributes of the vertices such as normals and colors may be set in a similar fashion. For example, the following TriangleArray object contains color definitions for vertices as well as coordinates:

TriangleArray ta = **new** TriangleArray(6,

```
GeometryArray.COORDINATES | GeometryArray.COLOR_3);
Point3f[] coords = new Point3f[6];
coords[0] = new Point3f(0f, 0f, 0f);
coords[1] = new Point3f(1f, 1f, 0f);
coords[2] = new Point3f(1f, 0f, 0f);
coords[3] = new Point3f(1f, 0f, 0f);
coords[4] = new Point3f(2f, 1f, 0f);
coords[5] = new Point3f(3f, 0f, 0f);
ta.setCoordinates(0, coords);
Color3f[] colors = new Color3f[6];
colors[0] = new Color3f(1f, 0f, 0f);
colors[1] = new Color3f(0f, 1f, 0f);
colors[2] = new Color3f(0f, 0f, 1f);
colors[3] = new Color3f(1f, 1f, 0f);
colors[4] = new Color3f(0f, 1f, 1f);
colors[5] = new Color3f(1f, 0f, 1f);
ta.setColors(0, colors);
```

[Page 177]

Surface normals can also be specified for the vertices in a geometry array. The following QuadArray object contains normal specifications:

```
QuadArray qa = new QuadArray(8,
  GeometryArray.COORDINATES | GeometryArray.NORMALS);
Point3f[] coords = new Point3f[8];
coords[0] = new Point3f(0f, 0f, 0f);
coords[1] = new Point3f(1f, 0f, 0f);
coords[2] = new Point3f(1f, 1f, 0f);
coords[3] = new Point3f(0f, 1f, 0f);
coords[4] = new Point3f(1f, 1f, 0f);
coords[5] = new Point3f(0f, 1f, 0f);
coordal NREGISTERED WERSION OF CHM TO PDF CONVERTER PRO
coords[6]
qa.setCoordinates(0, coords);
Vector3f[] normals = new Vector3f[8];
normals[0] = new Vector3f(0f, 0f, 1f);
normals[1] = new Vector3f(0f, 0f, 1f);
normals[2] = new Vector3f(0f, 0f, 1f);
normals[3] = new Vector3f(0f, 0f, 1f);
normals[4] = new Vector3f(0f, 1f, 0f);
normals[5] = new Vector3f(0f, 1f, 0f);
normals[6] = new Vector3f(0f, 1f, 0f);
normals[7] = new Vector3f(0f, 1f, 0f);
qa.setNormals(0, normals);
```

#### 6.3.2. GeometryStripArray

Often a vertex in an array is shared by several different polygons. Using TriangleArray or QuadArray would add the shared vectors multiple times. Who approaches can improve the efficiency. Die Geometrayer barray ER PRO class uses the idea of strips to allow the sharing of adjacent vertices. To define separate strips, the number of vertices in each strip can be specified with an array of integers:

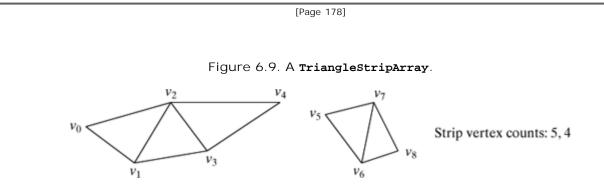
```
void setStripVertexCounts(int[] stripVertexCounts);
```

The length of the array is the number of strips. The number in each array entry represents the number of vertices in a strip.

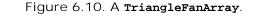
GeometryStripArray has three subclasses. The LineStripArray defines a strip as a polyline. A sequence of points is used to specify the strip without duplicating the internal points. For example, the following code defines the same geometry as shown in Figure 6.6 with a LineStripArray object:

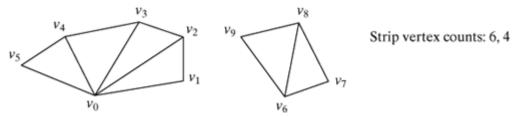
```
int[] stripVertexCounts = {2, 3};
LineStripArray lsa = new LineStripArray(5, GeometryArray.COORDINATES,
stripVertexCounts);
Point3f[] coords = new Point3f[5];
coords[0] = new Point3f(0f, 0f, 0f);
coords[1] = new Point3f(1f, 1f, 0f);
coords[2] = new Point3f(1f, 0f, 0f);
coords[3] = new Point3f(2f, 1f, 0f);
coords[4] = new Point3f(3f, 0f, 0f);
lsa.setCoordinates(0, coords);
```

The TriangleStripArray class defines strips of triangles. In each strip every three consecutive vertices define a triangle. Figure 6.9 illustrates the geometry constructed from a TriangleStripArray object.



The TriangleFanArray class offers an alternative way to define strips of triangles. In each strip the first vertex with every two consecutive vertices form a triangle. Figure 6.10 illustrates this approach.





The geometry of a cone may be defined very naturally as a TriangleFanArray:

```
int n = 60; // number of triangle patches
int[] stripVertexCounts = {n+2}; // 1 strip
TriangleFanArray tfa = new TriangleFanArray
  (n+2, GeometryArray.COORDINATES, stripVertexCounts);
Point3f apex = new Point3f(0, 0, 1);
tfa.setCoordinate(0, apex);
for (int ii = 0; ii <= n; ii++) {
  float x = (float)Math.cos(ii*2*Math.PI/n);
  float y = (float)Math.sin(ii*2*Math.PI/n);
  Point3f p = new Point3f(x, y, 0);
  ta.setCoordinate(ii+1, p);
}
```

The *n* triangle patches are defined by only n + 2 points in a single strip.

#### 6.3.3. IndexedGeometryArray

Another approach to avoid duplicated vertices is to use IndexedGeometryArray. Instead of defining a polygon by specifying the vertices directly, an IndexedGeometryArray object specifies the indices of the vertices in an array of points. Consequently a vertex needs to be defined only once, but it may be referenced several times through its index. For example, the following IndexedQuadArray object defines a geometry of two squares, as shown in Figure 6.8. It uses only six vertices instead of eight as needed by the GeometryArray. Each quadrangle is specified with four indices corresponding to the corner vertices.

```
IndexedQuadArray iqa = new IndexedQuadArray
  (6, GeometryArray.COORDINATES, 8);
Point3f[] coords = new Point3f[6];
coords[0] = new Point3f(0f, 0f, 0f);
coords[2] = new Point3f(1f, 1f, 0f);
coords[2] = new Point3f(0f, 1f, 0f);
coords[3] = new Point3f(0f, 1f, 0f);
coords[4] = new Point3f(0f, 1f, 1f);
coords[5] = new Point3f(1f, 1f, 1f);
[Page 179]iqa.setCoordinates(0, coords);
int[] indices = {0, 1, 2, 3, 2, 3, 4, 5};
iga.setCoordinateIndices(0, indices);
```

Other attributes such as normals and colors can be indexed in a similar way.

There is also an IndexedGeometryStripArray class with its subclasses Indexed LineStripArray, IndexedTriangleStripArray, and IndexedTriangleFanArray. These classes add indices to the strip arrays and combine the features of strip arrays and indexed arrays. To define separate strips, a stripIndexCounts array can be specified in the constructor or with the following method:

void setStripIndexCounts(int[] stripIndexCounts)

The folling a Glasta a Bar of the store of t

```
int[] stripIndexCounts = {4, 4};
IndexedTriangleStripArray itsa = new IndexedTriangleStripArray(7,
GeometryArray.COORDINATES, 8, stripIndexCounts);
Point3f[] coords = new Point3f[7];
coords[0] = new Point3f(0f, 0f, 0f);
coords[1] = new Point3f(0f, 1f, 0f);
coords[2] = new Point3f(1f, 1f, 0f);
coords[3] = new Point3f(2f, 1f, 0f);
coords[4] = new Point3f(-1f, 0f, 0f);
coords[5] = new Point3f(-1f, -1f, 0f);
coords[6] = new Point3f(-2f, -1f, 0f);
itsa.setCoordinates(0, coords);
int[] indices = {0, 1, 2, 3, 0, 4, 5, 6};
itsa.setCoordinateIndices(0, indices);
```

The resulting geometry is shown in Figure 6.11.

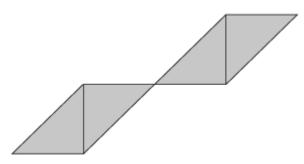


Figure 6.11. An IndexedTriangleStripArray geometry.

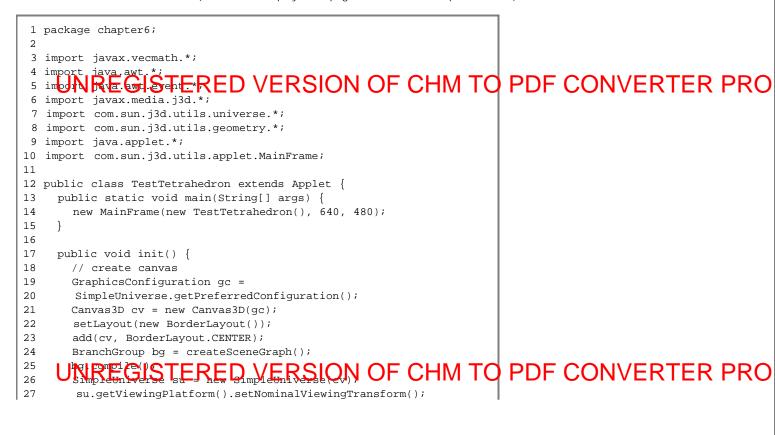
Listing 6.1 constructs a regular tetrahedron using the IndexedTriangleArray class. The tetrahedron is one of the five regular polyhedrons known as the *Platonic solids*. This example defines a tetrahedron as a subclass of IndexedTriangleArray. A tetrahedron is a solid consisting of four faces of congruent equilateral triangles. A test program in Listing 6.2 displays an instance of the tetrahedron rotating in space to view it from different angles.

Listing 6.1. Tetrahedron.java

(This item is displayed on pages 179 - 180 in the print version)

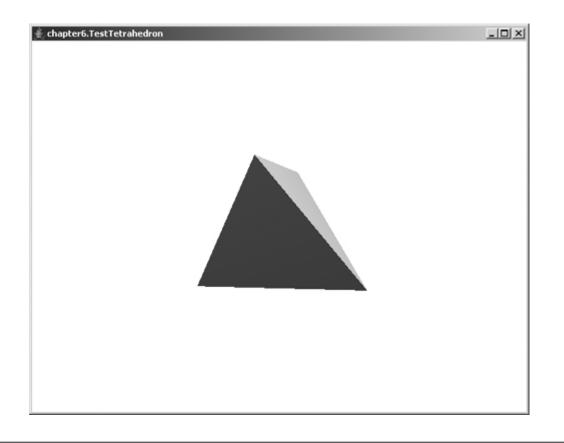
```
1 package chapter6;
 2
 3 import javax.vecmath.*;
 4 import javax.media.j3d.*;
[Page 180] 5
 6 public class Tetrahedron extends IndexedTriangleArray {
 7
     public Tetrahedron() {
       super(4, TriangleArray.COORDINATES | TriangleArray.NORMALS, 12);
 8
       setCoordinate(0, new Point3f(1f,1f,1f));
 9
       setCoordinate(1, new Point3f(1f,-1,-1f));
10
       setCoordinate(2, new Point3f(-1f,1f,-1f));
11
12
       setCoordinate(3, new Point3f(-1f,-1f,1f));
13
       int[] coords = {0,1,2,0,3,1,1,3,2,2,3,0};
14
       float n = (float)(1.0/Math.sqrt(3));
15
       setNormal(0, new Vector3f(n,n,-n));
16
       setNormal(1, new Vector3f(n,-n,n));
17
       setNormal(2, new Vector3f(-n,-n,-n));
18
       setNormal(3, new Vector3f(-n,n,n));
19
       int[] norms = \{0, 0, 0, 1, 1, 1, 2, 2, 2, 3, 3, 3\};
20
       setCoordinateIndices(0, coords);
21
       setNormalIndices(0, norms);
22
   }
23 }
```

#### Listing 6.2. TestTetrahedron.java (This item is displayed on pages 180 - 181 in the print version)



```
28
       su.addBranchGraph(bg);
29
    }
30
31
   private BranchGroup createSceneGraph() {
      BranchGroup root = new BranchGroup();
32
       TransformGroup spin = new TransformGroup();
33
34
       spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
35
      root.addChild(spin);
36
       // object
37
       Appearance ap = new Appearance();
38
       ap.setMaterial(new Material());
[Page 181]39
               Shape3D shape = new Shape3D(new Tetrahedron(), ap);
       // rotating object
40
41
       Transform3D tr = new Transform3D();
42
       tr.setScale(0.25);
      TransformGroup tg = new TransformGroup(tr);
43
44
       spin.addChild(tg);
45
       tg.addChild(shape);
46
       Alpha alpha = new Alpha(-1, 4000);
47
       RotationInterpolator rotator =
48
       new RotationInterpolator(alpha, spin);
49
       BoundingSphere bounds = new BoundingSphere();
50
      rotator.setSchedulingBounds(bounds);
51
       spin.addChild(rotator);
52
       // light and background
53
       Background background = new Background(1.0f, 1.0f, 1.0f);
54
      background.setApplicationBounds(bounds);
55
      root.addChild(background);
56
       AmbientLight light = new AmbientLight
57
         (true, new Color3f(Color.red));
58
       light.setInfluencingBounds(bounds);
59
       root.addChild(light);
       PointLight ptlight = new PointLight(new Color3f(Color.green),
60
61
         new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
62
      ptlight.setInfluencingBounds(bounds);
63
      root.addChild(ptlight);
      PointLight ptlight2 = new PointLight(new Color3f(Color.orange),
64
65
         new Point3f(-2f,2f,2f), new Point3f(1f,0f,0f));
66
       ptlight2.setInfluencingBounds(bounds);
67
       root.addChild(ptlight2);
68
       return root;
69
    }
70 }
```

Figure 6.12. A tetrahedron.



[Page 182]

Two classes are defined in this example: Tetrahedron and TestTetrahedron. The Tetrahedron class extends the IndexedTriangleArray class (line 6) so it can be used as a geometry node component for a Shape3D node in a scene graph. The vertices of the tetrahedron have the coordinates

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Four triangle faces are specified by an array of 12 indexes pointing to the corresponding vertices:

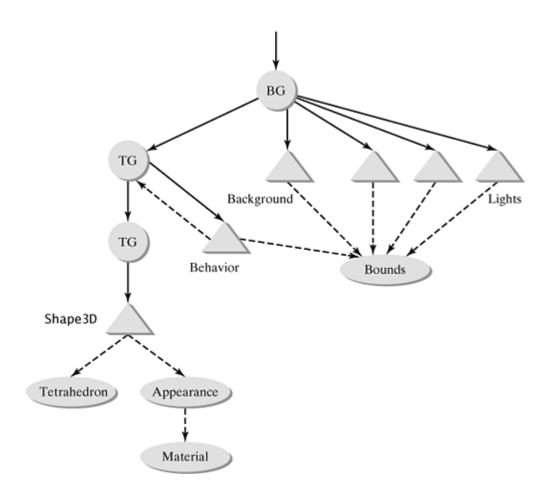
0, 1, 2, 0, 3, 1, 1, 3, 2, 2, 3, 0

Four normals for the four faces are specified as four vectors in the directions:

$$(1, 1, -1), (1, -1, 1), (-1, -1, -1), (-1, 1, 1)$$

The vectors are divided by  $\sqrt{3}$  to obtain unit normal vectors. Each vertex of a face is specified as a normal corresponding to the normal of the face.

The TestTetrahedron class is a typical Java 3D applet/application program that is used to test the Tetrahedron class. It creates an instance of Tetrahedron and associates it with a Shape3D node. The scene graph of the Java 3D program is given in Figure 6.13.



A Shape3D object represents the tetrahedron in the scene graph (line 39). It references the Tetrahedron object as its geometry and an Appearance object. The Appearance object references a Material object to apply lighting.

The Shape3D node is attached to a TransformGroup node to apply a scaling to the tetrahedron. The TransformGroup is attached to another TransformGroup node, which is controlled by a Behavior object called RotationInterpolator to perform the rotation.

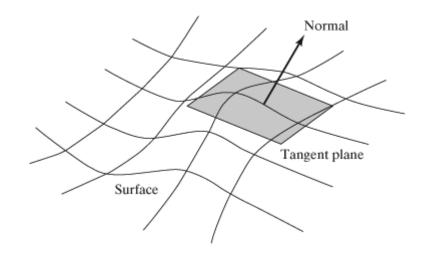
[Page 183]

A background node is defined to create a white background. Three different lights are defined to illuminate the scene. The behavior, the background, and the light nodes all share the same Bounds object, which is a sphere of radius 1.0.

## 6.3.4. Normals

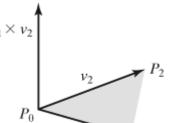
Surface normals are important geometric attributes for sophisticated rendering modes such as lighting. The *normal* of a plane is a vector that is perpendicular to the plane (Figure 6.14). The normal of a surface at a point is the normal of the surface's tangent plane at the point.

Figure 6.14. The surface normal is perpendicular to the tangent plane.



Because the *cross product* of two vectors is perpendicular to both vectors, it can often be used to calculate normals. For example, given three distinct points  $R_0$ ,  $R_1$ ,  $R_2$  in a plane, we can form two vectors in the plane:  $\mu_1 = R_1 - R_0$ ,  $\nu_2 = R_2 - R_0$  (Figure 6.15). The cross product  $\mu_1 \times \nu_2$  is the normal of the plane.

Figure 6.15. Calculating the normal with the cross product.



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Usually the surface normals are represented with unit vectors (vectors of length 1). Any nonzero vector  $\nu$  can be rescaled to a unit vector:  $|\eta||\eta|$  This is known as the *normalization*.

The Vector3f and Vector3d classes have the cross method to calculate the cross product of two threedimensional vectors. The normalize methods of the classes perform the normalization on the vectors. For example, the following code snippet calculates the normal of the plane determined by three points:

```
Point3f p0 = new Point3f(1,1,1);
Point3f p1 = new Point3f(1,-1,-1);
Point3f p2 = new Point3f(-1,1,-1);
p1.sub(p0);
p2.sub(p0);
[Page 184]Vector3f v1 = new Vector3f(p1);
Vector3f v2 = new Vector3f(p2);
Vector3f normal = new Vector3f();
normal.pormal.pormalize();
```

For a geometry formed with planar faces, such as the tetrahedron, the normal for each face can be calculated separately using the method illustrated above. For a smooth surface approximated by a polygon mesh, the normal at a vertex should be calculated from the original surface rather than a polygon. Consider the case that a surface is represented by a parametric equation:

$$X = f(U, V)$$

y = g(u, v)

Z = h(U, V)

Two vectors in the tangent plane can be obtained from the derivatives:

 $(dx|du, dy|du, dz|du) = (f_{U}, g_{U}, h_{U})$ 

 $(dx/dv, dy/dv, dz/dv) = (f_{\nu}, g_{\nu}, h_{\nu})$ 

The surface normal at a point can be found by taking their cross product:

 $D = (f_{U_1} g_{U_1} h_U) \times (f_{V_1} g_{V_1} h_V)$ 

For example, an elliptic paraboloid has the following parametric equation:

 $X = U \cos V$ 

 $y = u \sin v$ 

$$Z = U^2$$

The partial derivatives are given by:

(cos v, sin v, 2u)

 $(-u \sin v, u \cos v, 0)$ 

Therefore the surface normal at a point defined by (u, v) is:

 $(\cos v_{i} \sin v_{i} 2u) \times (-u \sin v_{i} u \cos v_{i} 0) = (-2u^{2} \cos v_{i} 2u^{2} \sin v_{i} u)$ 

The mathematical background related to surfaces and normals is discussed in Appendix A.

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[Page 184 (continued)]

## 6.4. GeometryInfo

## 6.4.1. Using the GeometryInfo Class

An alternative to GeometryArray classes for generating geometry is the GeometryInfo class. This class does not have the methods to partially set the vertex data, but it allows the definitions of more general polygon faces. Using the utility classes NormalGenerator and Stripifier, it is also possible to automatically generate surface normals and stripify the geometry on GeometryInfo objects.

One constructor of GeometryInfo takes a GeometryArray parameter. It provides a conversion from a GeometryArray object to a GeometryInfo object:

public GeometryInfo(GeometryArray ga)

Another constructor of GeometryInfo creates an empty GeometryInfo object with a given primitiveType:

[Page 185]public GeometryInfo(int primitiveType)

The primitiveType is one of:

TRIANGLE\_ARRAY TRIANGLE\_FAN\_ARRAY TRIANGLE\_STRIP\_ARRAY QUAD\_ARRAY POLYGON\_ARRAY

The triangle and quad arrays are interpreted the same way as the corresponding GeometryArray classes. To set vertex data, an entire array of data values must be supplied. For example,

# 

Indexed representation can be achieved by simply setting an index array:

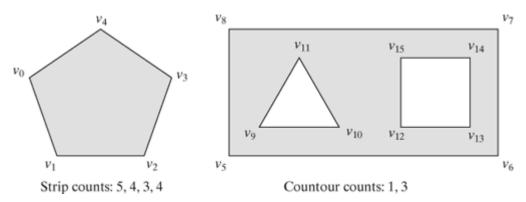
```
void setCoordinateIndices(int[] indices)
void setNormalIndices(int[] indices)
void setColorIndices(int[] indices)
void setTextureCoordinateIndices(int[] indices)
```

Similar to the GeometryArray classes, a stripCounts array is used to define separate strips for GeometryInfo objects with TRIANGLE\_FAN\_ARRAY and TRIANGLE\_STRIP\_ARRAY flags.

A polygon array with the POLYGON\_ARRAY flag can be used to define complex polygons with more than four sides and with holes. A polygon consists of one or more contours. The first contour defines the outer boundary of the polygon and subsequent contours define the holes in the polygon.

The stripCounts array for a POLYGON\_ARRAY specifies the number of vertices of each contour. The contourCounts array specifies the number of contours for each polygon. For example, Figure 6.16 shows the strip counts array specifies the number of contours for each polygon. For example, Figure 6.16 shows the strip counts array specifies the number of contours for each polygon. For example, Figure 6.16 shows the strip counts are specifies to the strip counts are specified to the st

### Figure 6.16. Constructing geometry using the **GeometryInfo** class.



Internally the GeometryInfo class will convert polygons in a POLYGON\_ARRAY primitive to triangles. This triangulation is done automatically using the class Triangulator.

The surface normals of a GeometryInfo object can be generated automatically using the class NormalGenerator. The surface normals are necessary for rendering the objects by considering illumination from light sources. The automatic normal generation can help you avoid some tedious calculations. The NormalGenerator class has a method to generate normals for a GeometryInfo object:

[Page 186]public void generateNormals(GeometryInfo gi);

To generate normals for a GeometryInfo object gi, you may create an instance of NormalGenerator and call the generateNormals method:

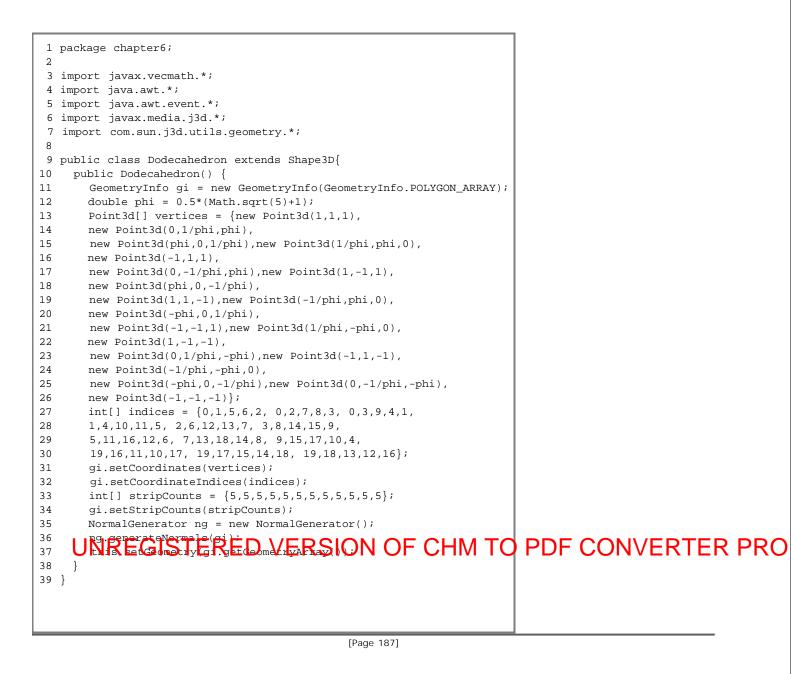
```
NormalGenerator ng = new NormalGenerator();
ng.generateNormals(gi);
```

The other helper class Stripifier helps you change the geometry in a GeometryInfo object to triangle strips. The usage of Stripifier is similar to that of NormalGenerator:

```
Stripifier st = new Stripifier();
st.stripify(gi);
```

Listing 6.3 uses GeometryInfo class to define a dodecahedron, another Platonic solid. This example demonstrates the use of GeometryInfo class. Listing 6.4 shows a test program for the dodecahedron.

Listing 6.3. Dodecahedron.java

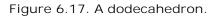


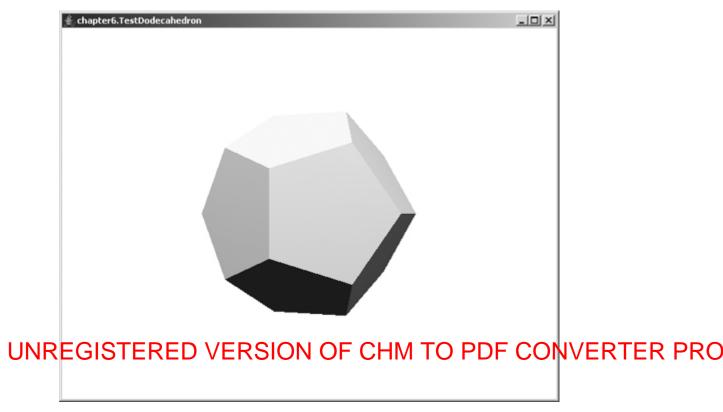
Listing 6.4. TestDodecahedron.java (This item is displayed on pages 187 - 188 in the print version)

1 package chapter6;
2
3 import javax.vecmath.\*;
4 import java.awt.\*;
5 import java.awt.event.\*;
6 import javax.media.j3d.\*;
7 import com.sun.j3d.utils.universe.\*;
8 import java.applet.\*ERSION OF CHM TO PDF CONVERTER PRO
9 import java.applet.\*

```
11
12 public class TestDodecahedron extends Applet {
13
     public static void main(String[] args) {
14
       new MainFrame(new TestDodecahedron(), 640, 480);
15
    }
16
17
    public void init() {
       GraphicsConfiguration gc =
18
19
       SimpleUniverse.getPreferredConfiguration();
       Canvas3D cv = new Canvas3D(gc);
20
       setLayout(new BorderLayout());
21
22
       add(cv, BorderLayout.CENTER);
23
       BranchGroup bg = createSceneGraph();
24
       bg.compile();
25
       SimpleUniverse su = new SimpleUniverse(cv);
26
        su.getViewingPlatform().setNominalViewingTransform();
27
       su.addBranchGraph(bg);
28
    }
29
30
    private BranchGroup createSceneGraph() {
       BranchGroup root = new BranchGroup();
31
32
       TransformGroup spin = new TransformGroup();
33
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
34
       root.addChild(spin);
35
36
       // object
37
       Appearance ap = new Appearance();
38
       ap.setMaterial(new Material());
39
       Shape3D shape = new Dodecahedron();
40
       shape.setAppearance(ap);
41
42
       Transform3D tr = new Transform3D();
43
       tr.setScale(0.25);
44
       TransformGroup tg = new TransformGroup(tr);
45
       spin.addChild(tg);
46
       tg.addChild(shape);
47
48
       Alpha alpha = new Alpha(-1, 4000);
49
       RotationInterpolator rotator =
50
       new RotationInterpolator(alpha, spin);
51
       BoundingSphere bounds = new BoundingSphere();
52
       rotator.setSchedulingBounds(bounds);
53
       spin.addChild(rotator);
54
55
       // background and light
56
       Background background = new Background(1.0f, 1.0f, 1.0f);
57
       background.setApplicationBounds(bounds);
58
       root.addChild(background);
[Page 188]59
               AmbientLight light = new AmbientLight
60
         (true, new Color3f(Color.red));
61
       light.setInfluencingBounds(bounds);
62
       root.addChild(light);
63
       PointLight ptlight = new PointLight(new Color3f(Color.green),
64
         new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
65
       ptlight.setInfluencingBounds(bounds);
66
       root.addChild(ptlight);
67
       PointLight ptlight2 = new PointLight(new Color3f(Color.orange),
68
         new Point3f(-2f,2f,2f), new Point3f(1f,0f,0f));
69
       ptlight2.setInfluencingBounds(bounds);
```

```
70 root.addChild(ptlight2);
71 return root;
72 }
73 }
```





The Dodecahedron class is defined as a subclass of Shape3D. The dodecahedron has 20 vertices and 12 pentagon faces. A GeometryInfo object is created to define the faces and to automatically generate the normals. Vertex coordinates are set directly in the array vertices. The 20 vertices have the following coordinates:

(1, 1, 1),

(0, 1/f, f), (f, 0, 1/f), (1/f, f, 0),

(-1, 1, 1), (0, -1/f, f), (1, -1, 1),

(f, 0, -1/f), (1, 1, -1), (-1/f, f, 0),

(-f, 0, **UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO** (1, -1, -1), (0, 1/f, -f), (-1, 1, -1), (-1, -1, -1)

[Page 189]

where  $\phi = (\sqrt{5} + 1)/2$  The 12 faces are defined with indices to the vertices:

(0, 1, 5, 6, 2), (0, 2, 7, 8, 3), (0, 3, 9, 4, 1),

(1, 4, 10, 11, 5), (2, 6, 12, 13, 7), (3, 8, 14, 15, 9),

(5, 11, 16, 12, 6), (7, 13, 18, 14, 8), (9, 15, 17, 10, 4),

(19, 16, 11, 10, 17), (19, 17, 15, 14, 18), (19, 18, 13, 12, 16)

The stripCount array (line 33) defines the number of polygons and the number of vertices in each polygon face:

5, 5, 5, 5, 5, 5, 5, 5, 5, 5, 5, 5

A NormalGenerator object is created and applied on the GeometryInfo object to generate the normals for the faces (lines 35–36). Finally the geometry constructed in the GeometryInfo object is retrieved to be used as the geometry of the current Shape3D object.

The test program TestDodecahedron is nearly identical to the test program in Listing 6.2. The only significant difference is that the Dodecahedron object is added directly to the scene graph as a leaf node, because it is a Shape3D object.

### 6.4.2. Creating Polygon Meshes

A general curved surface typically requires an array of many small polygon patches to obtain a good approximation. For a surface defined by a parametric equation,

X = f(U, V)

 $\mathcal{Y} = \mathcal{G}(\mathcal{U}, \ \mathcal{V})$ 

Z = h(U, V)

with the two parameters varying in the rectangle  $a \le u \le b$ ,  $c \le v \le d$ , we can usually divide the parameter range into an  $m \ge n$  grid to form the *patches*. The vertices of the grid are defined by the points:

 $U_i = \partial + i(D - \partial)/m, i = 0, 1, 2, ..., m$ 

 $V_j = c + f(d - c)/n, j = 0, 1, 2, ..., n$ 

A quadrilateral patch is defined by four vertices with parameter values:

 $(U_{j_{1}} V_{j_{2}}), (U_{j_{1}+1}, V_{j_{2}}), (U_{j_{1}+1}, V_{j_{1}+1}), (U_{j_{1}} V_{j_{1}+1})$ 

It may be further divided into two triangles:

 $(U_{i}, V_{j}), (U_{i+1}, V_{j}), (U_{i+1}, V_{j+1}) \text{ and } (U_{i}, V_{j}), (U_{i+1}, V_{j+1}), (U_{i}, V_{j+1})$ 

Because of the obvious overlapping of vertices among the adjacent polygons, indexed arrays are often used to

improve the efficiency.

Note that the methods for setting vertex coordinates in the GeometryInfo and GeometryArray classes do not accept two-dimensional arrays. Consequently, the vertices in the grid must be specified in a linear fashion.

Listing 6.5 illustrates the procedure of generating an approximation to a surface with an array of polygons. It uses a GeometryInfo class to generate the geometry for a data set sampled from a two-variable function.

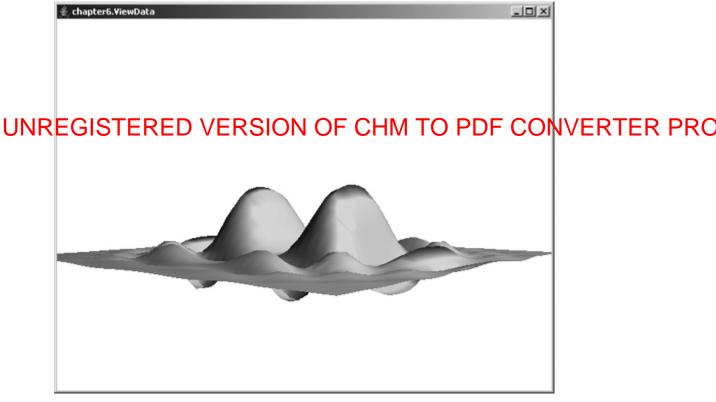
Data visualization is an important application of computer graphics. As the dimension of a dataset increases, the comprehension of the data becomes more difficult. 3D graphical data plotting may greatly enhance the representation of data sets. This example shows a 3D surface plot of a function of two variables:

[Page 190]

$$y = 2\cos(x^2)\sin(z^2)/e^{0.25(x^2+z^2)} - 1$$

Even though the data set used in this example is generated from a fixed function, the method can be easily adapted to plot data from other sources. The plot is rotated continuously about a vertical axis. (See Figure 6.18.)

Figure 6.18. A 3D plot of a two-variable function. (This item is displayed on page 192 in the print version)



UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO (This item is displayed on pages 190 - 191 in the print version)

```
1 package chapter6;
  2
  3 import javax.vecmath.*;
  4 import java.awt.*;
  5 import java.awt.event.*;
  6 import javax.media.j3d.*;
  7 import com.sun.j3d.utils.universe.*;
  8 import com.sun.j3d.utils.geometry.*;
  9 import java.applet.*;
 10 import com.sun.j3d.utils.applet.MainFrame;
 11
 12 public class ViewData extends Applet {
    public static void main(String[] args) {
 13
        new MainFrame(new ViewData(), 640, 480);
 14
 15
     }
 16
 17
     public void init() {
 18
        // create canvas
 19
        GraphicsConfiguration gc =
 20
        SimpleUniverse.getPreferredConfiguration();
 21
        Canvas3D cv = new Canvas3D(gc);
 22
        setLayout(new BorderLayout());
 23
        add(cv, BorderLayout.CENTER);
 24
        BranchGroup bg = createSceneGraph();
 25
        bg.compile();
 26
        SimpleUniverse su = new SimpleUniverse(cv);
 27
         su.getViewingPlatform().setNominalViewingTransform();
 28
        su.addBranchGraph(bg);
 29
     }
 30
 31
      private BranchGroup createSceneGraph() {
 32
        BranchGroup root = new BranchGroup();
        TransformGroup spin = new TransformGroup();
 33
 34
         spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 35
        root.addChild(spin);
 36
 37
        // object
 38
        Appearance ap = new Appearance();
 39
        ap.setMaterial(new Material());
 40
        Shape3D shape = new Shape3D(createGeometry(), ap);
 41
 42
        Transform3D tr = new Transform3D();
 43
        tr.setScale(0.2);
 44
        TransformGroup tg = new TransformGroup(tr);
 45
        spin.addChild(tq);
 46
        tg.addChild(shape);
 47
 48
        Alpha alpha = new Alpha(-1, 12000);
 49
        RotationInterpolator rotator = new RotationInterpolator
50
          (alpha, spin);
[Page 191] 51
                BoundingSphere bounds = new BoundingSphere();
 52
        rotator.setSchedulingBounds(bounds);
 53
        spin.addChild(rotator);
54
 55
        // background and light
 56
        Background background = new Background(1.0f, 1.0f, 1.0f);
 57
        background.setApplicationBounds(bounds);
        root.addChild(background);
 58
```

```
59
        AmbientLight light = new AmbientLight
 60
          (true, new Color3f(Color.red));
 61
        light.setInfluencingBounds(bounds);
 62
        root.addChild(light);
 63
        PointLight ptlight = new PointLight(new Color3f(Color.green),
          new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
 64
        ptlight.setInfluencingBounds(bounds);
 65
 66
        root.addChild(ptlight);
 67
        return root;
 68
      }
 69
 70
     private Geometry createGeometry() {
 71
        int m = 40;
 72
        int n = 40;
 73
        Point3f[] pts = new Point3f[m*n];
 74
        int idx = 0;
 75
        for (int i = 0; i < m; i++) {
 76
          for (int j = 0; j < n; j++) {
            float x = (i - m/2) * 0.2f;
 77
 78
            float z = (j - n/2) * 0.2f;
            float y = 2f * (float)(Math.cos(x*x) * Math.sin(z*z))/
 79
                      ((float)Math.exp(0.25*(x*x+z*z)))-1.0f;
 80
 81
            pts[idx++] = new Point3f(x, y, z);
 82
          }
 83
        }
 84
 85
        int[] coords = new int[2*n*(m-1)];
 86
        idx = 0;
 87
        for (int i = 1; i < m; i++) {
 88
          for (int j = 0; j < n; j++) {
 89
            coords[idx++] = i*n + j;
 90
            coords[idx++] = (i-1)*n + j;
 91
          }
 92
        }
 93
        int[] stripCounts = new int[m-1];
 94
     UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 95
 96
 97
        GeometryInfo gi = new GeometryInfo
 98
          (GeometryInfo.TRIANGLE_STRIP_ARRAY);
 99
        gi.setCoordinates(pts);
100
        gi.setCoordinateIndices(coords);
101
        gi.setStripCounts(stripCounts);
102
103
        NormalGenerator ng = new NormalGenerator();
104
        ng.generateNormals(gi);
105
106
        return gi.getGeometryArray();
107
      }
108 }
```

[Page 192]

We use the data points sampled from the function to construct the geometry. A rectangular grid of *m* x *n* values in NERZED and S treated to evaluate the surface for the function values give the geometry of the surface formed by this grid points. The resulting points are stored in a one-dimensional array pts (line 73). The surface formed by this grid of points is defined as strips of triangles. Every two adjacent rows of points define one strip of triangles.

The geometry of the surface is created using a GeometryInfo object with the primitive data type TRIANGLE\_STRIP\_ARRAY (line 98). The GeometryInfo object is indexed. The array pts specifies the vertex coordinates. The actual triangle strips are defined by a separate array of indices coords and an array of strip counts stripCounts. The coords array defines the triangle strips with the indices to the vertex array. Because the grid has *m* values in the *x*- direction, there are m-1 strips. Each strip is defined by 2n points in two rows. Therefore, the array coords contains 2n(m-1) indices. The indices are specified alternately from the two rows. For example, the first strip has indices

 $n, 0, n + 1, n + 2, 2, \dots$ 

The second strip has indices

 $2n, n, 2n + 1, 2n + 2, n + 2, \dots$ 

Of course all indices are stored in the single array coords. To break the one-dimensional index array into separate strips, the stripCounts array is applied to specify m-1 strips with 2n indices in each strip.

To generate the surface normals the utility class NormalGenerator is used. The resulting geometry is used by a Shape3D object to define the surface.

The scene graph of this example is similar to that of Listing 6.2. Only two lights are used in this program.

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## 6.5. Primitives

For convenience, Java 3D offers utility classes for commonly used geometric primitives. The abstract class Primitive is a subclass of Group and encapsulates predefined geometry attributes. They can be used as high-level components in a scene graph without setting complex geometry, using separate low-level structures such as GeometryArray or GeometryInfo objects.

Figure 6.19 shows the class hierarchy of the primitives defined in the package com.sun.j3d.utils.geometry. The appearance of a primitive can be set through the following methods:

void setAppearance()
void setAppearance(Appearance appearance)
void setAppearance(int subpart, Appearance appearance)

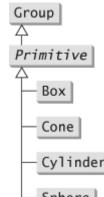


Figure 6.19. Primitive classes.

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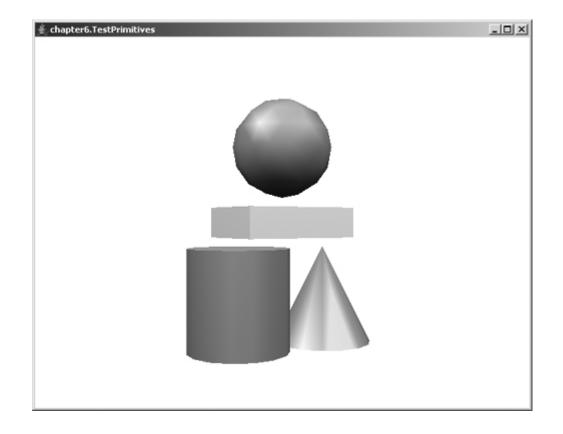
The sizes of the primitives can be set with some of their constructors. For example,

Box(float xdim, float ydim, float zdim, Appearance appearance)
Cone(float radius, float height)
Cylinder(float radius, float height)
Sphere(float radius)

The Primitive class is a subclass of Group. Therefore a primitive object can be added directly to a scene graph as a node.

Listing 6.6 demonstrates the applications of primitives. This program displays instances of the four basic primitives provided by Java 3D utility packages. (See Figure 6.20.)

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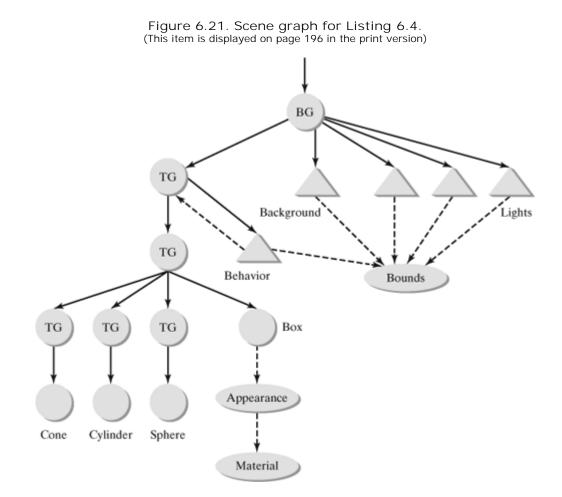
### Listing 6.6. TestPrimitives.java (This item is displayed on pages 193 - 195 in the print version)

```
1 package chapter6;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
9 import java.applet.*;
10 import com.sun.j3d.utils.applet.MainFrame;
11
12 public class TestPrimitives extends Applet {
13 public static void main(String[] args) {
[Page 194]14 new MainFrame(new TestPrimitives(), 640, 480);
15
    }
16
17
    public void init() {
18
      // create canvas
19
      GraphicsConfiguration gc =
20
      SimpleUniverse.getPreferredConfiguration();
21
     Canvas3D cv = new Canvas3D(gc);
      setLayout(new BorderLayout());
22
23
      add(cv, BorderLayout.CENTER);
24
      BranchGroup bg = createSceneGraph();
25
      bg.compile();
26
       SimpleUniverse su = new SimpleUniverse(cv);
```

```
27
        su.getViewingPlatform().setNominalViewingTransform();
28
       su.addBranchGraph(bg);
29
    }
30
31
     private BranchGroup createSceneGraph() {
       BranchGroup root = new BranchGroup();
32
33
       TransformGroup spin = new TransformGroup();
34
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
35
       root.addChild(spin);
36
37
       // primitives
       Appearance ap = new Appearance();
38
39
       ap.setMaterial(new Material());
40
       Box box = new Box(1.2f, 0.3f, 0.8f, ap);
41
       Sphere sphere = new Sphere();
42
       Cylinder cylinder = new Cylinder();
43
       Cone cone = new Cone();
44
45
       Transform3D tr = new Transform3D();
46
       tr.setScale(0.2);
47
       TransformGroup tg = new TransformGroup(tr);
48
       spin.addChild(tg);
49
       tg.addChild(box);
50
       tr.setIdentity();
51
       tr.setTranslation(new Vector3f(0f,1.5f,0f));
       TransformGroup tgSphere = new TransformGroup(tr);
52
53
       tg.addChild(tgSphere);
54
       tgSphere.addChild(sphere);
55
       tr.setTranslation(new Vector3f(-1f,-1.5f,0f));
56
       TransformGroup tgCylinder = new TransformGroup(tr);
57
       tg.addChild(tgCylinder);
58
       tgCylinder.addChild(cylinder);
59
       tr.setTranslation(new Vector3f(1f,-1.5f,0f));
60
       TransformGroup tgCone = new TransformGroup(tr);
61
       tg.addChild(tgCone);
62
       tgCone.addChild(cone);
                                    ERSION OF CHM TO PDF CONVERTER PRO
       NREGISTER
63
64
                         Alpha
65
       RotationInterpolator rotator =
66
       new RotationInterpolator(alpha, spin);
67
       BoundingSphere bounds = new BoundingSphere();
68
       rotator.setSchedulingBounds(bounds);
69
       spin.addChild(rotator);
70
71
       // background and light
72
       Background background = new Background(1.0f, 1.0f, 1.0f);
[Page 195]73
               background.setApplicationBounds(bounds);
       root.addChild(background);
74
75
       AmbientLight light =
76
       new AmbientLight(true, new Color3f(Color.red));
77
       light.setInfluencingBounds(bounds);
78
       root.addChild(light);
79
       PointLight ptlight = new PointLight(new Color3f(Color.green),
80
         new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
81
       ptlight.setInfluencingBounds(bounds);
82
       root.addChild(ptlight);
        ointLight ptlight2 = new PointLight(new Color3f(
83
                                                                   TO PDF CONVERTER PRO
84
85
       ptlight2.setInfluencingBounds(bounds);
```

```
86 root.addChild(ptlight2);
87 return root;
88 }
89 }
```

Four instances of the primitives—a box, a sphere, a cylinder, and a cone—are created and placed in the scene graph as shown in Figure 6.21. The transformation nodes on top of the three primitive nodes help separate the objects in the virtual world. The details of applying transformation nodes will be presented in Chapter 7.



The default constructors are used for creating the Cone, Sphere, and Cylinder objects. The objects will have the surface normals generated and set up for lighting. The Box object is created with a constructor specifying its x-, y-, z-dimensions and its appearance (lines 40–43).

All four objects are attached to a TransformGroup which performs a scaling. Once again, the entire scene is rotated by a RotationInterpolator object through a TransformGroup node. The background and light configuration are similar to those in previous examples.

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## 6.6. Fonts and Texts

Fonts provide a rich source for geometry. The glyphs of text strings are complex geometric shapes predefined in the fonts.

Java 3D provides Text3D and Text2D classes. Text3D extends the Geometry class, so a Text3D object can be used by a Shape3D node to define its geometry. A Text3D object is determined by a 3D font and a string for the text. A Font3D object is a 3D version of a font. A Font3D object is constructed from a regular 2D AWT font and an extrusion defined by the FontExtrusion class. The following is a typical procedure to create a Text3D object:

- Create a java.awt.Font object.
- Create a FontExtrusion object.
- Create a Font3D object using the Font and FontExtrusion objects.
- Create a Text3D object using the Font3D and a String.

For example, the following statements create a 3D text of "Hello" using a bold Serif font of size 1 with a default extrusion:

```
Font font = new Font("Serif", Font.BOLD, 1);
FontExtrusion extrusion = new FontExtrusion();
Font3D font3d = new Font3D(font, extrusion);
Text3D text = new Text3D(font3d, "Hello");
```

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Text2D is a subclass of Shape3D, so it can be used as a leaf node in a scene graph. A Text2D object is implemented as a rectangle with the text string painted as an image. The following code defines a Text2D object of the string "Hello" with a blue italic Serif font of size 16:

Text2D text = new Text2D("Hello", Color.blue, "Serif", 16, Font.Italic);

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## 6.7. Appearance and Attributes

Besides geometry, graphics objects possess attributes that define the appearance when rendered. Different models for the graphics object's appearance exist with significant differences in rendering quality and efficiency.

Color is perhaps the most fundamental attribute. However, there are different ways to generate colors for parts of a graphics object. A simple way is to specify a solid color for each unit of the object, such as points, lines, or polygon faces.

Another approach is to assign different colors for different points by interpolations. This is known as *Gouraud shading*. Colors are specified for vertices of a polygon. At other points the colors are calculated by interpolating the color values at the vertices.

More realistic coloring schemes need to consider the influences of environment elements such as lights as well as the properties of the objects. Colors on an object may be determined by such factors as the reflective properties of the object, the geometry, the light sources, the emissive light, the ambient light, and the view position.

Texture mapping is a powerful technique to achieve sophisticated appearance. For objects with a great deal of detail it is usually more efficient to store the appearance as a raster image and place the image onto the object during rendering.

In Java 3D the Appearance node component specifies the attributes related to the rendering of the node. An Appearance object holds a set of references to attribute objects. Figure 6.22 lists the classes related to appearance.

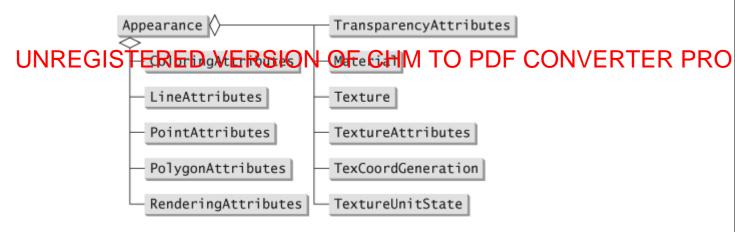


Figure 6.22. Appearance components.

A ColoringAttributes object defines a color to be used to color the associated geometric object when lighting is not applied and *vertex colors* are not defined. This color is ignored if vertex colors for the geometry are defined. It is also not used if lighting is enabled. ColoringAttributes also defines a *shading model*.

- · UNREGISTEREDSIGERSION OF CHM TO PDF CONVERTER PRC
- SHAD\_GOURAUD— Gouraud shading interpolates the colors at the vertices of a polygon or a line to produce

a color at an interior point. The colors on a polygon are not constant. They change smoothly to give a more realistic appearance.

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- SHAD\_FASTEST— This constant selects the fastest shading model for the current platform.
- SHAD\_NICEST— This constant selects the nicest shading model for the current platform.

A PointAttributes object defines the attributes related to rendering of points. The size of points and antialiasing can be specified with PointAttributes class.

A LineAttributes object defines the attributes related to rendering of lines. Line attributes include the line width, line pattern, and antialiasing. Line patterns are defined by the constants in the class:

PATTERN\_SOLID PATTERN\_DASH PATTERN\_DOT PATTERN\_DASH\_DOT PATTERN\_USER\_DEFINED

A PolygonAttributes object defines the attributes related to rendering of polygons. The polygon drawing mode controls the way that a polygon is rendered. Three polygon modes are defined:

POLYGON\_POINT POLYGON\_LINE POLYGON\_FILL

The polygon drawing mode can be set in constructors or by the method setPolygonMode.

The TransparencyAttributes node component provides a way to render the visual object with a certain degree of *transparency*. For example, the following TransparencyAttributes object will cause the visual object to be rendered at a transparency value of 0.6:

```
int tMode = TransparencyAttributes.BLENDED;
float tValue = 0.6f;
TransparencyAttributes ta = new TransparencyAttributes(tMode, tValue);
Appearance ap = new Appearance();
ap.setTransparencyAttributes(ta);
```

A transparency value of 1.0 indicates complete transparency and a value of 0.0 is completely opaque. Note that the transparency value is the opposite of the alpha value in color specifications.

The material settings of an appearance are related to illumination and shading of the objects. Chapter 9 will discuss the details of lighting and illumination. Texture mapping is discussed in Chapters 9 and 12.

The appearance attribute settings are related. The rules for applying geometric *drawing modes* are given below.

- 1. If the polygon drawing mode of PolygonAttributes is set to POLYGON\_POINT, only the vertices of a polygon are rendered. In this mode the PointAttributes settings determine the point rendering characteristics.
- 2. If the polygon drawing mode of PolygonAttributes is set to POLYGON\_LINE, the edges of a polygon are rendered. The visual objects appear in a wireframe form. In this mode the LineAttributes settings control the appearance of the lines.
- 3. If the polygon drawing mode of PolygonAttributes is set to POLYGON\_FILL, the polygons are filled.

The *coloring* of the rendered object depends on the lighting model, the ColoringAttributes settings, and the vertex data of the geometry.

- [Page 199]
- 1. The lighting model is applied if the Appearance references a valid Material object and the Material object enables lighting. The following method of Material can be used to enable or disable lighting:

void setLightingEnable(boolean enable)

In this mode, colors of the object are rendered based on the interactions between light sources and visual objects.

2. If vertex colors are present and not ignored, they are used to render the polygons. The enabling of the vertex colors is controlled by a RenderingAttributes object. The following method sets this state:

void setIgnoreVertexColors(boolean ignore)

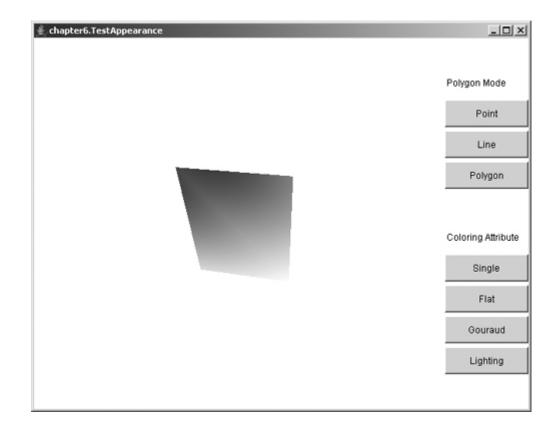
When vertex colors are used, the shading mode of the polygons is determined by the ColoringAttributes object. A flat shading assigns a single color to a polygon and a Gouraud shading interpolates the vertex colors in the interior of a polygon.

3. If lighting is not enabled and the vertex colors of the geometry are not present or ignored, the color specified by the ColoringAttributes object will be used for coloring the geometry.

Listing 6.7 is a class for tetrahedron with color specification. Listing 6.8 demonstrates the effects of various appearance attributes. A rotating tetrahedron is displayed in the main window. The appearance of the tetrahedron is controlled by Polygon Mode buttons that select rendering modes: point, line, polygon, and by Coloring Attribute buttons that select coloring options: single, flat, Gouraud, lighting. (See Figure 6.23.)

Figure 6.23. Rendering a tetrahedron with different appearance attributes. (This item is displayed on page 200 in the print version)

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Listing 6.7. ColorTetrahedron.java

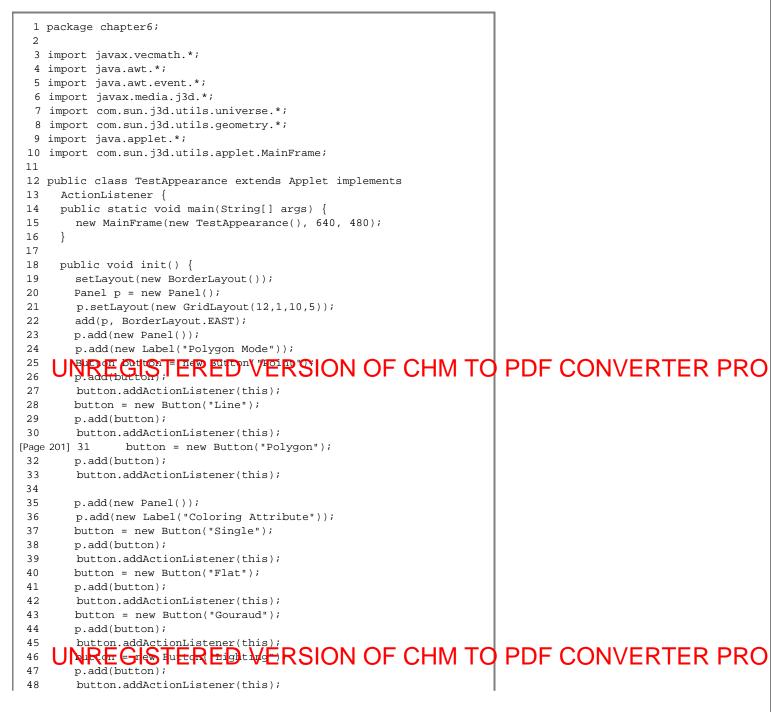
```
1 package chapter6;
 2
 3 import javax.vecmath.*;
 4 import javax.media.j3d.*;
 5
 6 public class ColorTetrahedron extends IndexedTriangleArray{
 7
   public ColorTetrahedron() {
 8
       super(4, TriangleArray.COORDINATES | TriangleArray.NORMALS |
 9
             GeometryArray.COLOR_3, 12);
10
       setCoordinate(0, new Point3f(1f,1f,1f));
11
       setCoordinate(1, new Point3f(1f,-1,-1f));
12
       setCoordinate(2, new Point3f(-1f,1f,-1f));
13
       setCoordinate(3, new Point3f(-1f,-1f,1f));
14
       int[] coords = {0,1,2,0,3,1,1,3,2,2,3,0};
15
       float n = (float)(1.0/Math.sqrt(3));
16
       setNormal(0, new Vector3f(n,n,-n));
17
       setNormal(1, new Vector3f(n,-n,n));
18
       setNormal(2, new Vector3f(-n,-n,-n));
19
       setNormal(3, new Vector3f(-n,n,n));
20
       int[] norms = {0,0,0,1,1,1,2,2,2,3,3,3};
21
       setCoordinateIndices(0, coords);
22
       setNormalIndices(0, norms);
       setColor(0, new Color3f(1f, 0f, 0f));
23
       setColor(1, new Color3f(0f, 1f, 0f));
24
25
       setColor(2, new Color3f(0f, 0f, 1f));
26
       setColor(3, new Color3f(1f, 1f, 1f));
27
       setColorIndices(0, coords);
```

```
28 }
29 }
```

```
[Page 200]
```

### Listing 6.8. TestAppearance.java

(This item is displayed on pages 200 - 203 in the print version)



```
49
 50
        GraphicsConfiguration gc =
 51
         SimpleUniverse.getPreferredConfiguration();
 52
        Canvas3D cv = new Canvas3D(gc);
 53
         add(cv, BorderLayout.CENTER);
 54
        BranchGroup bg = createSceneGraph();
 55
        bg.compile();
        SimpleUniverse su = new SimpleUniverse(cv);
 56
 57
         su.getViewingPlatform().setNominalViewingTransform();
 58
        su.addBranchGraph(bg);
 59
      }
 60
 61
      Appearance ap;
 62
      private BranchGroup createSceneGraph() {
 63
        BranchGroup root = new BranchGroup();
 64
        TransformGroup spin = new TransformGroup();
 65
         spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 66
        root.addChild(spin);
 67
 68
        // allow appearance change
 69
        ap = new Appearance();
         ap.setCapability(Appearance.ALLOW_COLORING_ATTRIBUTES_WRITE);
 70
         ap.setCapability(Appearance.ALLOW_POINT_ATTRIBUTES_WRITE);
 71
 72
         ap.setCapability(Appearance.ALLOW_LINE_ATTRIBUTES_WRITE);
 73
         ap.setCapability(Appearance.ALLOW_POLYGON_ATTRIBUTES_WRITE);
 74
         ap.setCapability(Appearance.ALLOW_RENDERING_ATTRIBUTES_WRITE);
 75
         ap.setCapability(Appearance.ALLOW_MATERIAL_WRITE);
 76
         Shape3D shape = new Shape3D(new ColorTetrahedron(), ap);
 77
 78
        Transform3D tr = new Transform3D();
 79
        tr.setScale(0.25);
 80
        TransformGroup tg = new TransformGroup(tr);
 81
        spin.addChild(tg);
 82
        tg.addChild(shape);
 83
 84
        Alpha alpha = new Alpha(-1, 4000);
 85
        RotationInterpolator rotator =
 86
        new RotationInterpolator(alpha, spin);
 87
        BoundingSphere bounds = new BoundingSphere();
 88
        rotator.setSchedulingBounds(bounds);
 89
        spin.addChild(rotator);
 90
[Page 202] 91
                // background and light
        Background background = new Background(1f, 1f, 1f);
 92
 93
         background.setApplicationBounds(bounds);
        root.addChild(background);
 94
 95
        AmbientLight light = new AmbientLight
 96
          (true, new Color3f(Color.red));
 97
        light.setInfluencingBounds(bounds);
 98
        root.addChild(light);
 99
         PointLight ptlight = new PointLight(new Color3f(Color.cyan),
          new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
100
101
         ptlight.setInfluencingBounds(bounds);
102
        root.addChild(ptlight);
103
        return root;
104
      }
105
106
      public void actionPerformed(ActionEvent actionEvent) {
107
        String cmd = actionEvent.getActionCommand();
```

108	if	("Point".equals(cmd)) {	
109		ap.setPolygonAttributes(new PolygonAttributes(	
110		PolygonAttributes.POLYGON_POINT,	
111		<pre>PolygonAttributes.CULL_BACK,0));</pre>	
112		<pre>ap.setPointAttributes(new PointAttributes(10, false));</pre>	
113	}	else if ("Line".equals(cmd)) {	
114	-	ap.setPolygonAttributes(new PolygonAttributes(	
115		PolygonAttributes.POLYGON_LINE,	
116		PolygonAttributes.CULL_BACK,0));	
117		ap.setLineAttributes(new LineAttributes(3,	
118		LineAttributes.PATTERN_DASH, false));	
119	}	else if ("Polygon".equals(cmd)) {	
120	,	ap.setPolygonAttributes(	
121		PolygonAttributes.POLYGON_FILL,	
122		PolygonAttributes.CULL_BACK,0));	
123	}	else if ("Single".equals(cmd)) {	
124	j	ColoringAttributes ca = new ColoringAttributes();	
125		ca.setColor(0.5f, 0.5f, 0.5f);	
126		ap.setColoringAttributes(ca);	
127		ap.setMaterial(null);	
128		RenderingAttributes ra = new RenderingAttributes();	
129		ra.setIqnoreVertexColors(true);	
130		ap.setRenderingAttributes(ra);	
131	}	else if ("Flat".equals(cmd)) {	
132	J	ColoringAttributes ca = new ColoringAttributes();	
133		ca.setShadeModel(ColoringAttributes.SHADE_FLAT);	
134		ap.setColoringAttributes(ca);	
135		ap.setMaterial(null);	
136		RenderingAttributes ra = new RenderingAttributes();	
137		ra.setIgnoreVertexColors(false);	
138		ap.setRenderingAttributes(ra);	
139	۱	else if ("Gouraud".equals(cmd)) {	
140	J	ColoringAttributes ca = new ColoringAttributes();	
141		ca.setShadeModel(ColoringAttributes.SHADE_GOURAUD);	
142		ap.setColoringAttributes(ca);	
143		ap.setMaterial(null);	
144	LINI		
145	UN	REGISTERED VE RSONTOF OHM TC	PDF CONVERTER PRC
146		ap.setRenderingAttributes(ra);	
147	1	else if ("Lighting".equals(cmd)) {	
148	J	ap.setMaterial(new Material());	
149		RenderingAttributes ra = new RenderingAttributes();	
150		ra.setIgnoreVertexColors(true);	
	203]15		
152	200j10. }		
153	}		
154	,		
101	J		

The ColorTetrahedron class is similar to the class defined in Listing 6.1. It adds vertex colors to its definition (lines 23–26). A ColorTetrahedron instance is used as the geometry for a Shape3D leaf in the TestAppearance program. An Appearance object for the shape is created with several permission bits set:

ap.setCapability(Appearance.ALLOW_COLORING_ATTRIBUTES_WRITE);					
ap.setCapability(Appearance.ALLOW_COLORING_ATTRIBUTES_WRITE); ap.setCapatRietGappearen Railow/ En StrikteGraitEHM	TO I	PDF	CONVE	RTER	PRO
ap.setCapability(Appearance.ALLOW_LINE_ATTRIBUTES_WRITE);					

ap.setCapability(Appearance.ALLOW\_POLYGON\_ATTRIBUTES\_WRITE); ap.setCapability(Appearance.ALLOW\_RENDERING\_ATTRIBUTES\_WRITE); ap.setCapability(Appearance.ALLOW\_MATERIAL\_WRITE);

These settings will allow dynamic changes of coloring attributes, point attributes, line attributes, polygon attributes, and material on the Appearance object. Note that the permission bits must be set through individual method calls. You cannot make just one call by combining the bits.

The buttons control the appearance settings (line 106). There are seven buttons in two groups for polygon modes and coloring attributes.

### Point:

Only the vertices are rendered by setting the PolygonAttributes POLYGON\_POINT. The PointAttributes of the Appearance object is set to a size of 10.

### Line:

The lines of the object are rendered by setting the PolygonAttributes POLYGON\_LINE. The LineAttributes of the Appearance object is set to a dash pattern with a width of 3.

### Polygon:

The faces of the object are rendered by setting the PolygonAttributes POLYGON\_FILL.

### Single:

The object is rendered with a single gray color in a ColoringAttributes setting. The lighting is turned off by setting the material of the Appearance object to null. The vertex colors are ignored by setting a RenderingAttributes object.

### Flat:

The object is rendered with flat colors defined in vertex data. The lighting is turned off by setting the material of the Appearance object to null. The flat shading mode is selected in a ColoringAttributes object.

### Gouraud:

The object is rendered with Gouraud shading using vertex colors. The lighting is turned off by setting the material of the Appearance object to null. The Gouraud shading mode is selected in a ColoringAttributes object.

### Lighting:

The object is illuminated by lights. The Material of the Appearance object is set to a new default instance. The vertex colors are ignored by setting a RenderingAttributes object.

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The mode selection of point, line, or polygon is independent of the color selection of single, flat, Gouraud, or lighting. Consequently, even the point rendering can be illuminated with lights.

If you place a Dodecahedron object in this program, you may find that in the wireframe mode (lines only) there are extra lines rendered besides the pentagons. This is due to the automatic triangulation performed by the GeometryInfo class. The pentagons are divided into triangles.

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### [Page 204 (continued)]

## Key Classes and Methods

- javax.vecmath.Point\* A family of classes encapsulating geometric points.
- javax.vecmath.Vector\* A family of classes encapsulating geometric vectors.
- javax.vecmath.Color\* A family of classes for color values.
- javax.media.j3d.Shape3D A leaf-node class encapsulating a visual object.
- javax.media.j3d.Geometry A node-component class defining a geometry for a Shape3D object.
- javax.media.j3d.Appearance A node-component class defining an appearance for a Shape3D object.
- javax.media.j3d.GeometryArray A family of classes for constructing geometries from vertex specifications.
- javax.media.j3d.GeometryStripArray A family of geometry array classes for constructing strip geometries.
- javax.media.j3d.IndexedGeometryArray A family of classes for constructing geometries from vertex and index specifications.
- javax.media.j3d.IndexedGeometryStripArray A family of classes for constructing strip geometries from vertex and index specifications.
- javax.media.j3d.GeometryInfo A class for constructing and manipulating geometries.
- javax.media.j3d.Primitive A subclass of Group for geometric primitives.
- · UNREGISTERED VERSIONOPOCHMPTO POFICIONVERTER PRO
- javax.media.j3d.TransparencyAttributes A node-component class for transparency.
- javax.media.j3d.PointAttributes A node-component class for point-rendering attributes including point size and antialiasing option.
- javax.media.j3d.LineAttributes A node-component class for line-rendering attributes such as line width, line pattern, and antialiasing.
- **javax.media.j3d.PolygonAttributes** A node-component class for polygon-rendering attributes such as rasterization mode, back-face culling, and offset.
- javax.media.j3d.Font3D A class encapsulating a 3D font.
- javax.media.j3d.Text3D A geometry class representing a 3D text string.
- javax.media.j3d.Text2D A subclass of Shape3D representing a 2D text string in the 3D space.
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# Key Terms

A basic geometric element representing a position in a space.

### vector

A geometric element for a directional quantity.

### polygon mesh

A set of simple polygons such as triangles representing an approximation of a surface.

Platonic solids

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The five regular polyhedra: tetrahedron, cube, octahedron, dodecahedron, and icosahedron.

flat shading

A simple coloring method that fills a polygon patch with a single color.

Gouraud shading UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO A coloring method that assigns colors to a polygon by interpolating the colors on the vertices.

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### [Page 205 (continued)]

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## Chapter Summary

- In this chapter we discuss the fundamentals of constructing visual objects through their geometry and appearance specifications. Geometry defines the object's shape and size, and appearance defines the rendering properties such as color, material, and texture.
- Java 3D includes a javax.vecmath package that defines a large number of classes for points, vectors, and matrices. They are used in other parts of Java 3D for specifying geometric properties, transformations, and other attributes.
- The Shape3D class represents a visual object in a scene graph. Shape3D references Geometry and Appearance objects to specify the geometry and appearance of the shape.
- Java 3D provides a large number of facilities for defining Geometry. GeometryArray and its subclasses define geometry by directly specifying the low-level points, lines, and simple polygons.
- GeometryInfo class allows more general polygons. It also facilitates the automatic generation of normals using NormalGenerator and automatic strip generation using Stripifier.
- Primitives offer high-level prebuilt geometric objects. Java 3D utility packages provide implementations of commonly used primitives including box, cone, cylinder, and sphere.
- Text can also be used as special geometric objects. Text3D is a subclass of Geometry. It defines solid 3D text objects in association with the Font3D, FontExtrusion, and Font classes. Text2D is a subclass of Shape3D. It defines 2D text objects as texture mapped rectangles.
- The appearance attributes of a shape are defined by various node components rooted at an Appearance object. An Appearance node component holds references to other components of classes such as ColoringAttributes, PointAttributes, LineAttributes, PolygonAttributes, TransparencyAttributes, and Material.

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[Page 205 (continued)]

## **Review** Questions

6.1 Construct Point3f objects to represent the following points:

(1, 2, 3), (0, 0, 0), (-1.2, 3.4, -5.6)

6.2 Write Java statements to calculate the three distances between the points defined in Question 6.1.

### [Page 206]

6.3 Construct Vector3f objects to represent the following vectors:

(1, 2, 3), (1, 1, 1), (-1.2, 3.4, -5.6)

- 6.4 Write Java statements to calculate the three angles between the vectors defined in Question 6.3.
- 6.5 Construct a PointArray object for the vertices of a cube centered at the origin. Its edges have length 1.0 and are parallel to the coordinate axes.
- 6.6 Construct a LineArray object for the edges of a tetrahedron.
- 6.7 Use a TriangleArray object to represent the geometry of a tetrahedron.
- 6.8 Use a QuadArray object to represent the geometry of a cube.
- 6.9 Construct a LineStripArray object for the edges of a tetrahedron.

## 6.10 Construct a TriangleStripArray object for the geometry of a tetrahedron. UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

- 6.11 Construct a TriangleFanArray object for the geometry of a tetrahedron.
- 6.12 Use an IndexedQuadArray object to represent the geometry of a cube.

```
6.13 Draw a figure corresponding to the geometry defined by the following TriangleStripArray
object:
int[] stripVertexCounts = {5, 3};
TriangleStripArray tsa = new TriangleStripArray
    (8, GeometryArray.COORDINATES, stripVertexCounts);
Point3f[] coords = new Point3f[8];
coords[0] = new Point3f(0f, 0f, 0f);
coords[1] = new Point3f(0f, 1f, 0f);
coords[2] = new Point3f(0.5f, 0.866f, 0f);
coords[3] = new Point3f(1.5f, 0.866f, 0f);
coords[5] = new Point3f(0f, 1f, 0f);
coords[6] = new Point3f(0f, 1f, 0f);
coords[6] = new Point3f(1.5f, 0.866f, 0f);
tsa.setCoordinates(0, coords);
```

```
6.14 Draw a figure corresponding to the geometry defined by the following TriangleFanArray object:
```

```
int[] stripVertexCounts = {4, 4};
TriangleFanArray tfa = new TriangleFanArray
  (8, GeometryArray.COORDINATES, stripVertexCounts);
Point3f[] coords = new Point3f[8];
coords[0] = new Point3f(0f, 0f, 0f);
coords[1] = new Point3f(1f, 0f, 0f);
coords[2] = new Point3f(0.866f, 0.5f, 0f);
coords[3] = new Point3f(0.5f, 0.866f, 0f);
coords[4] = new Point3f(0f, 0f, 0f);
coords[5] = new Point3f(-1f, 0f, 0f);
coords[6] = new Point3f(-0.866f, -0.5f, 0f);
coords[7] = new Point3f(-0.5f, -0.866f, 0f);
tfa.setCoordinates(0, coords);
```

```
6.15 Draw a figure corresponding to the geometry defined by the following
      IndexedTriangleStripArray Object:
      int[] stripIndexCounts = {5, 3};
      IndexedTriangleStripArray itsa = new
        IndexedTriangleStripArray(6,
        GeometryArray.COORDINATES, 8, stripIndexCounts);
      Point3f[] coords = new Point3f[6];
      coords[0] = new Point3f(0f, 0f, 0f);
      coords[1] = new Point3f(0f, 1f, 0f);
      [Page 207]coords[2] = new Point3f(0.5f, 0.866f, 0f);
      coords[3] = new Point3f(1.5f, 0.866f, 0f);
      coords[4] = new Point3f(1f, 1.73f, 0f);
      coords[5] = new Point3f(2f, 0f, 0f);
      itsa.setCoordinates(0, coords);
      int[] indices = {0, 1, 2, 3, 4, 1, 3, 5};
      itsa.setCoordinateIndices(0, indices);
```

- 6.16 Use a GeometryInfo object to define a cube of length 1.
- 6.17 What are the differences between Box and ColorCube classes?
- 6.18 What are the differences between Text3D and Text2D besides their dimensionality?
- 6.19 If a geometry contains both vertex coordinate and vertex color definition, how can you use the geometry with the vertex colors ignored?
- 6.20 Derive an equation for the surface normals of the Möbius strip with the parametric equation:

$$x = \left(1 + v \cos \frac{u}{2}\right) \cos u$$
$$y = \left(1 + v \cos \frac{u}{2}\right) \sin u$$
$$z = v \sin \frac{u}{2}$$
$$0 \le u \le 2\pi, \qquad -0.3 \le v \le 0.3$$

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## **Programming Exercises**

- 6.1 The octahedron is one of the five Platonic solids. It has eight faces of triangles and six vertices:
  - (0, 0, 1)

(-1, 0, 0), (0, -1, 0), (1, 0, 0), (0, 1, 0)

(0, 0, -1)

Implement an Octahedron class as a descendant of Geometry.

- 6.2 Write a test program for Octahedron class to display an octahedron in wireframe form.
- 6.3 The icosahedron is another Platonic solid with the following vertices:
  - (0, ø, 1),

(1, 0, ø), (-1, 0, ø), (-ø, 1, 0), (0, ø, -1), (ø, 1, 0),

 $(0, -\emptyset, 1), (-\emptyset, -1, 0), (-1, 0, -\emptyset), (1, 0, -\emptyset), (\emptyset, -1, 0),$ 

(0, -ø, -1)

where  $\phi = (\sqrt{5} + 1)/2$  Implement the Icosahedron class as a subclass of Shape3D using the GeometryInfo class. Generate the normals for the geometry using NormalGenerator.

6.4 Write a test program to display the icosahedron defined in Exercise 6.3. Use lighting and rotate the object.

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- 6.5 Create and display a 3D 4 x 4 x 4 grid using the LineArray class.
- 6.6 Use an IndexedQuadArray object to define a frustum with a top square of size 1 x 1, a bottom square of size 2 x 2 and height 1. Rotate the frustum in the virtual space.
- 6.7 Create and display a pyramid using the GeometryInfo class.
- 6.8 Replace the tetrahedron in Listing 6.8 by a dodecahedron and observe the result of triangulation from the GeometryInfo class in the wireframe mode.
- 6.9 Modify the program in Listing 5.1 to allow dynamic change of the 3D text. Implement a menu item and a dialog box to input a string from the user and display the string as a 3D text.
- 6.10 Write a Java 3D program similar to that in Exercise 6.9, but display the string using a Text2D object.
- 6.11 Extend the functions of the program in Listing 6.8 to include settings for different line patterns.
- 6.12 Implement a ColorOctahedron class that assigns different colors to its vertices. Write a test program to display a ColorOctahedron object using Gouraud shading.

- 6.13 Use GeometryInfo to create a Möbius strip defined in Review Question 6.20. Generate normals with the NormalGenerator class. Display the Möbius strip with lighting.
- 6.14 Create a Möbius strip using an IndexedQuadArray object. Set the normals based on the formula derived in Review Question 6.20. Display the Möbius strip with lighting.

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## Chapter 7. Geometric Transformation

(This item omitted from WebBook edition)

Objectives						
<ul> <li>To describe transformations related to 3D graphics.</li> </ul>						
• To construct 3D affine transforms including translation, rotation, scaling, shearing, and reflection.						
<ul> <li>To understand and apply transformation matrices.</li> </ul>						
To apply transforms in scene graphs.						
To construct and apply composite transformations.						
To apply transforms in constructing geometries.						

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## 7.1. Introduction

Transformation plays a crucial role in computer graphics. Through proper geometric transforms, graphics objects can be changed in shape, size, and location to achieve their specifications. Affine transforms are used frequently in modeling the virtual world. The viewing process employs transformations in a critical way as well. A special type of transformation, the *perspective* or *orthogonal projection*, is usually used in a view to construct a mapping from a 3D space to a 2D image. Animation often involves applications of geometric transformation to achieve motions in the scene.

Java 3D provides transformation support at several levels. The matrix classes such as Matrix4d offer the lowlevel data representations of the transforms. The Transform3D class encapsulates the 3D transforms with facilities to set and compose transforms and to apply transforms to points and vectors. The TransformGroup class represents the high-level transform nodes in scene graphs.

Through the use of homogeneous coordinates, all 3D projective transformations (including affine transformations) are completely determined by 4 x 4 transformation matrices. The transforms with direct geometrical interpretations such as rotations and translations can be expressed in matrix forms. However, explicit matrix construction of certain transforms such as general 3D rotations may be complicated. Other representations, such as quaternion for 3D rotations, may provide more convenient intermediate forms for constructions and manipulations.

Transformations can be combined to form new transformations. The composition of simple transforms is a powerful way to construct and manage complex transforms. In Java 3D the composition can occur at the lower level of matrix or Transform3D objects through multiplication of the transforms. It can also occur at the higher level of a scene graph, where a chain of transform nodes creates the effect of a composite transform.

A main application of transformations is to change the geometric characteristics of objects. In a Java 3D scene graph, TransformGroup nodes represent transforms. A TransformGroup node applies the transform defined in

the node to its children. The series of TransformGroup nodes from an object to the Locale will transform the object in various ways. The general tree structure of a scene graph provides great flexibility in manipulating the visual objects with transform nodes.

Another application of transformations is to aid the construction of geometries. The Transform3D class offers convenient methods to apply the transform to points or vectors. To construct geometries that have certain symmetric properties, we may take advantage of the transformation capabilities by generating many points of the geometries through transformations on a set of base points.

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### 7.2. 3D Affine Transformations

A transformation is a mapping from a vector space to itself or to another vector space. Certain families of transformations that preserve some geometric properties are of special significance in computer graphics. For example, projective transforms are crucial in 3D viewing. Affine transforms, a subset of projective transforms, are used extensively in modeling visual objects.

An affine transform maps lines to lines and preserves parallelism. For example, an affine transform may not map a rectangle to a rectangle, but it will always map a rectangle to a parallelogram. As in the 2D case, basic 3D affine transforms include translations, rotations, scalings, shears, and reflections. However, the 3D versions are often more complex, especially for rotations.

The affine transforms that also preserve distances are called rigid motions, Euclidean motions, or isometries. Translations, rotations, and reflections are examples of rigid motions.

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### 7.2.1. Transformation Matrix

Affine transforms can be represented in a matrix form. If a point in a 3D space is represented by three coordinates,



then an affine transform can be written as a matrix equation:

$\begin{bmatrix} x' \end{bmatrix}$		$a_{11}$	$a_{12}$	$a_{13}$	$\begin{bmatrix} x \end{bmatrix}$		$\begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$
<i>y</i> ′	=	<i>a</i> <sub>21</sub>	$a_{22}$	a <sub>23</sub>	y	+	$b_2$
_ z' _		$a_{31}$	$a_{32}$	$a_{33}$	_ z _		$b_3$

Rotations, scalings, and shearings relative to the origin can be represented by the matrix multiplication alone. The addition of the column vector b represents a translation. Because of the required special treatment of the translation, the above transformation is not linear in the space However, using *homogeneous coordinates* to represent 3D points, all affine transforms and projective transforms can be represented as matrix multiplications. The homogeneous coordinate of a 3D point has four components: (x, y, z, w). When w is not 0, it corresponds to a regular 3D coordinate (x/w, y/w, z/w). With homogeneous coordinates, the same affine transformation given above may be represented equivalently as a linear transformation in the space  $A^{t}$ 

$$\begin{bmatrix} x'\\y'\\z'\\1 \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & a_{13} & b_1\\a_{21} & a_{22} & a_{22} & b_2\\a_{31} & a_{32} & a_{33} & b_3\\0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x\\y\\z\\1 \end{bmatrix}$$

The 4 x 4 *transformation matrix* in the equation above completely determines an affine transform. Operations involving the transforms can be represented as corresponding matrix operations. Combining several affine transforms produces another affine transform. The matrix of the composite transform is the product of matrices of corresponding transforms. The inverse matrix of a transform corresponds to the inverse transform. More generally, a projective transformation may be represented with a similar matrix equation:

<b>–</b> –		_				
<i>x'</i>		$a_{11}$	$a_{12}$	$a_{13}$	$a_{14}$	<i>x</i>
y'	_	$a_{21}$	$a_{22}$	$a_{22}$	a <sub>24</sub>	У
z'		$a_{31}$	$a_{32}$	$a_{33}$	a <sub>34</sub>	z
w'		$a_{41}$	$a_{42}$	$a_{43}$	$a_{34} \\ a_{44}$	_w_

An introduction to matrices and their operations can be found in Appendix A.

Java 3D offers several classes supporting transformations. Besides vector classes, javax.vecmath package also contains *matrix classes* representing 3 x 3, 4 x 4, and general matrices: Matrix3f, Matrix3d, Matrix4f, Matrix4d, GMatrix. The following code fragment constructs a Matrix4d object:

double[] array = {1.0, 2.0, 3.0, 1.0, 0.0, 1.0, -1.0, 2.0, 4.0, 0.0, 0.5, -1.0, UNREG STERED VERSION OF CHM TO PDF CONVERTER PRO Matrix4d matrix = new Matrix4d(array);

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GMatrix class can be used to represent a matrix of arbitrary sizes with element type double. For example the following code creates a 3 x 4 matrix:

Basic matrix operations such as addition, multiplication, and inversion are supported. The following is a partial list of the methods in the Matrix4d class for matrix operations. Other classes contain similar methods.

- **void** add(Matrix4d m1)— Add matrix m1 to the current matrix.

- **void** mul(Matrix4d m1)— Multiply matrix m1 on the current matrix.
- **void** invert() Invert the current matrix.
- void add(Matrix4d m1, Matrix4d m2)— Set the current matrix to the sum of the matrices m1 and m2.
- **void** sub(Matrix4d m1, Matrix4d m2)— Set the current matrix to the difference of the matrices m1 and m2.
- void mul(Matrix4d m1, Matrix4d m2) Set the current matrix to the product of the matrices m1 and m2.
- void invert(Matrix4d m1) Set the current matrix to the inverse of the matrix m1.
- **void** transpose() Transpose the current matrix.
- **void** mul(**double** scalar)— Multiply the current matrix by the number scalar.
- **double** determinant() Return the determinant of the current matrix.

Listing 7.1 gives a class for displaying a matrix. Listing 7.2 provides an interactive user interface to view a matrix and perform certain operations on the matrix using the built-in methods of the Matrix4d class.

#### Listing 7.1. MatrixPanel.java

(This item is displayed on pages 212 - 213 in the print version)

```
1 package chapter7;
 2
 3 import java.awt.*;
 4 import javax.vecmath.*;
 5
 6 public class MatrixPanel extends Panel {
 7
     TextField[] fields = new TextField[16];
 8
 9
     public MatrixPanel() {
10
       setLayout(new GridLayout(4, 4));
11
       for (int i = 0; i < 16; i++) {
12
         fields[i] = new TextField(5);
         if (i/4 == i%4)
13
14
            fields[i].setText("1");
15
         else
            fields[i].setText("0");
16
17
         add(fields[i]);
18
       }
19
     }
20
[Page 213]21
             public MatrixPanel(Matrix4d m) {
22
       setLayout(new GridLayout(4, 4));
       for (int i = 0; i < 16; i++) {
23
         fields[i] = new TextField(5);
24
          fields[i].setText("" + m.getElement(i/4, i%4));
25
26
         add(fields[i]);
27
       }
     }
28
29
30
     public void set(Matrix4d m) {
31
       for (int i = 0; i < 16; i++) {
          fields[i].setText("" + m.getElement(i/4, i%4));
32
33
       }
```

```
34
    }
35
36
    public void get(Matrix4d m) {
37
      for (int i = 0; i < 16; i++) {
         m.setElement(i/4, i%4, Double.parseDouble
38
39
           (fields[i].getText()));
40
       }
41
    }
42 }
```

Listing 7.2. TestMatrix.java

(This item is displayed on pages 213 - 214 in the print version)

```
1 package chapter7;
 2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5 import javax.vecmath.*;
 6 import java.applet.*;
 7 import com.sun.j3d.utils.applet.MainFrame;
8
9
  public class TestMatrix extends Applet implements ActionListener {
    public static void main(String[] args) {
10
11
      new MainFrame(new TestMatrix(), 600, 200);
12
    }
13
14
    MatrixPanel mp;
15
    Matrix4d m = new Matrix4d();
16
    TextField tf;
17
18
    public void init() {
19
    UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
20
21
      mp = new MatrixPanel();
22
      add(mp, BorderLayout.CENTER);
23
24
      Panel p = new Panel();
25
      p.setLayout(new GridLayout(6,1));
26
      Button button = new Button("Identity");
27
      button.addActionListener(this);
28
      p.add(button);
29
      button = new Button("Zero");
30
      button.addActionListener(this);
31
      p.add(button);
32
      button = new Button("Negate");
33
      button.addActionListener(this);
34
      p.add(button);
      button = new Button("Transpose");
35
[Page 214]36
             button.addActionListener(this);
37
      p.add(button);
38
      button = new Button("Invert");
39
       button.addActionListener(this)
     JNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
40
41
      button.addActionListener(this);
42
```

```
43
       p.add(button);
       this.add(p, BorderLayout.EAST);
44
45
46
       tf = new TextField();
47
       add(tf, BorderLayout.SOUTH);
48
    }
49
50
     public void actionPerformed(ActionEvent e) {
51
       String cmd = e.getActionCommand();
52
       if ("Identity".equals(cmd)) {
53
         mp.get(m);
         m.setIdentity();
54
55
         mp.set(m);
56
       } else if ("Zero".equals(cmd)) {
57
         mp.get(m);
58
         m.setZero();
59
         mp.set(m);
60
       } else if ("Negate".equals(cmd)) {
61
         mp.get(m);
62
         m.negate();
63
         mp.set(m);
       } else if ("Transpose".equals(cmd)) {
64
65
         mp.get(m);
66
         m.transpose();
67
         mp.set(m);
68
      } else if ("Invert".equals(cmd)) {
69
         mp.get(m);
70
         m.invert();
71
        mp.set(m);
72
       } else if ("Determinant".equals(cmd)) {
73
         mp.get(m);
74
         tf.setText("" + m.determinant());
75
       }
76
     }
77 }
```

The MatrixPanel class is a visual component to display a 4 x 4 matrix. It contains 16 text fields for the 16 elements of the matrix (line 7). It has a constructor that takes a Matrix4d object to initialize the display (line 21). Its default constructor initializes the display to an identity matrix (line 9). The method set(Matrix4d m) sets the display to the matrix given. The method get(Matrix4d m) retrieves the matrix from the display.

The TestMatrix class is the main test program. It creates a MatrixPanel object to represent a Matrix4d object (line 21) (Figure 7.1). Six buttons are placed in the EAST region of the frame to perform the corresponding matrix operations defined by methods of the Matrix4d class.

- Identity Set the matrix to the identity matrix using the identity() method.
- Zero Set the matrix to the zero matrix using the zero() method.
- Negative Set the matrix to its negative matrix using the negate() method.
- Transpose Set the matrix to its transpose using the transpose() method.

[Page 215]

- Invert Invert the matrix and display the inverse matrix using the invert() method.
- Determinant Calculate the determinant of the matrix and display the result in the bottom text field using the determinant() method.

Figure 7.1. A test program for matrix operations. The transformation matrix is shown in a grid of text fields. A user may edit the entries directly. Six operations on the matrix are provided. The result of the determinant is displayed in the text field at the bottom.

🛓 chapter7.Te	estMatrix			_ 🗆 ×
2.0	-1.0	3.0	5.0	Identity
2.0	1.0	0.0	-2.0	Zero
2.0	1.0	0.0	-2.0	Negate
0.0	5.0	-1.0	0.0	Transpose
				Invert
0.0	0.0	0.0	1.0	Determinant
26.0			1	

### 7.2.2. Transform3D

Java 3D includes the class Transform3D to represent a 3D affine or projective transform. In a scene graph, a TransformGroup node uses a Transform3D object to define its transformation. Transform3D internally maintains a 4 x 4 double matrix for the transform. To create a Transform3D object you may use one of many available constructors. The default constructor creates an identity matrix. You may supply a matrix object, an array, or other form Reference matrix for matrix for matrix for the transform Date of the following the transform Date of the following the transform of the transform terms to create a transform the transform of many available constructors. The default constructor creates an identity matrix. You may supply a matrix object, an array, or other form Reference matrix for the transform to the following the transform of the transform terms to the transform terms to the following the transform of the transform terms to the transform terms terms to the terms terms to the terms terms terms to the terms terms terms terms to the terms term

Transform3D contains a large number of convenience methods to set and manipulate the transform. Some of the methods that directly handle the transformation matrix are listed below.

- **void** set(Matrix4d m1)— Set the transformation matrix to m1.
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- **void** set(GMatrix m1)— Set the transformation matrix to m1.
- **void** set(**double**[] array)— Set the transformation matrix to array.
- **void** set(**float**[] array)— Set the transformation matrix to array.
- **void** get(Matrix4d m1)— Get the transformation matrix to m1.
- **void** get(Matrix4f m1)— Get the transformation matrix to m1.
- **void** get(GMatrix m1)— Get the transformation matrix to m1.

[Page 216]

- **void** get(**double**[] array)— Get the transformation matrix to array.
- **void** get(**float**[] array)— Get the transformation matrix to array.

The transformation can also be defined in terms of geometric specifications such as translation, scaling, rotation, and shearing.

A translation is represented by the *transformation matrix* 

1	0	0	$b_1$
0	1	0	$b_2$
0	0	1	$b_3$
0	0	0	1

Under the translation, each point is moved by the constant amounts  $b_1$ ,  $b_2$ ,  $b_3$  in  $x_-$ ,  $y_-$ ,  $z_-$  directions, respectively. Clearly the shape and orientation of a geometric figure will not change under a translation. The inverse of a translation by  $b_1$ ,  $b_2$ ,  $b_3$  is a translation by  $-b_1$ ,  $-b_2$ ,  $-b_3$ .

Transform3D includes the following methods to set translations:

```
void set(Vector3d trans)
void set(Vector3f trans)
void setTranslation(Vector3d trans)
void setTranslation(Vector3f trans)
```

The set methods replace the entire transform with the specified translation. The setTranslation methods modify only the translation components of the existing transform.

A scaling by the factors  $s_1$ ,  $s_2$ ,  $s_3$  in x-, y-, z-directions has the matrix representation:

<i>s</i> <sub>1</sub>	0	0	0
0	$s_2$	0	0
0	0	<i>s</i> <sub>3</sub>	0
0	0	0	1

If all the scaling factors are nonzero, the scaling transform is invertible. The inverse is also a scaling with factors  $1/s_1$ ,  $1/s_2$ ,  $1/s_3$ . A scaling is uniform if  $s_1 = s_2 = s_3$ .

Transform3D includes the following methods to set scales:

```
void set(double scale)
void setScale(double scale)
void setScale(Vector3d scales)
```

The set method replaces the entire transform with a scaling. The setScale methods modify only the scaling components of the existing transform.

A 3D reflection is performed about a plane. A simple *reflection* about the *xy*-plane, for example, is given by the following matrix:

1	0	0	0
0	1	0	0
0	0	-1	0
0	0	0	1

A reflection is always invertible, and the inverse of a reflection is itself. More generally, a reflection about a plane through the origin with the normal vector u can be expressed as:

# $T(x) = x = \frac{2x \cdot u}{UNREGISTERED}$ VERSION OF CHM TO PDF CONVERTER PRO

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A matrix representation may be derived from this equation. An alternative way to construct such a general reflection will be considered later in this chapter.

A 3D *shear* shifts a point along a plane, and the amount of the shift depends on the distance of the point to the plane. A simple shear that changes only the *x*-coordinates has the following matrix:

1	0	$sh_x$	0
0	1	0	0
0	0	1	0
0	0	0	1

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The  $\not\!$  and z-coordinates are not changed by this transform. The x-coordinates are shifted according to the

equation:

 $X' = X + Sh_X Z$ 

A more general (x, y)-shear shifts both x- and y-coordinates:

1	0	$sh_x$	0
0	1	$sh_y$	0
0	0	1	0
0	0	0	1

Shearing is invertible. The inverse of the above shear is another shear of the same type with parameters  $-sh_{\chi_i} - sh_{\gamma_i}$ 

#### 7.2.3. Rotation

3D rotations are complex operations. A general 3D *rotation* has an axis of rotation that can be any line in the space. Around the axis all points are rotated by a fixed angle. A rotation of angle about the *z*-axis can be represented by the following matrix:

$\cos \theta$	$-\sin\theta$	0	0
$\sin \theta$	$\cos \theta$	0	0
0	0	1	0
0	0	0	1

Even though any rotation can be represented as a transformation matrix, it is often difficult to obtain the transformation matrix directly from a geometric specification of a general rotation. For example, it may be easy to get matrices for rotations about the  $x_{-}$ ,  $y_{-}$ , or z-axis, but what is the matrix for the rotation of angle p/3 about the axis (1,1,1)? One representation of a general 3D rotation that offers a more direct connection to its geometric properties involves the use of quaternion. The *quaternion* is a number system extending the field of complex numbers. An introduction to quaternion can be found in Appendix A.

A point (x, y, z) in 3D space with a *pure quaternion* (a quaternion with real part 0):

p = Xi + Yi + Zk

Let *q* be a fixed quaternion. A transformation in the 3D space may be defined by:

## $T_q(p) = qp\overline{q}$

If q is a unit quaternion, then it can be shown that the transformation defined above is a rotation. In this case q can be written as

 $q = \cos\frac{\theta}{2} + u\sin\frac{\theta}{2}, \qquad u = ai + bj + ck$ 

[Page 218]

The unit vector u defines the direction of the axis of rotation, and the axis goes through the origin. The angle of rotation is given by u.

Java 3D includes the classes Quat4f and Quat4d to represent quaternions. Besides the operations inherent from Tuple4\* classes, standard operations of quaternions such as conjugate, multiply, inverse, and normalize are supported in the quaternion classes. Because of the connection with rotations, the quaternion classes even support convenient methods to directly set a rotation quaternion based on the specified axis and angle:

```
void set(AxisAngle4d r)
```

The Transform3D class provides constructors and methods to directly accept quaternion parameters as rotation specifications:

```
Transform3D(Quat4d q, Vector3d translation, double scale)
Transform3D(Quat4f q, Vector3d translation, double scale)
Transform3D(Quat4f q, Vector3f translation, float scale)
void set(Quat4d q)
void set(Quat4f q)
```

Another popular way to represent a 3D rotation is to use three rotations  $R_3 R_2 R_1$  of certain angles about the coordinate axes. The axis for  $R_1$  is different from the axes of  $R_1$  and  $R_3$ . The three angles are known as the *Euler angles*. There are different choices for the axes and different terms to describe the anglesfor example, (elevation, azimuth, tilt), (roll, pitch, yaw), (precession, nutation, spin), and (heading, altitude, bank). Transform3D class provides a method to set the rotation based on Euler angles:

### void setEuler(Vector3d eulerAngles) UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

The Vector3d object specifies the Euler angles about the x, y, z-axes. The angles are also known as bank, altitude, heading. However, there is no method in Transform3D to retrieve the *Euler angles*. You may use a get method to retrieve a quaternion and then convert the quaternion to Euler angles. The code in Listing 7.3 performs the conversion from a quaternion to Euler angles.

Listing 7.3. quatToEuler

```
1 public static Vector3d quatToEuler(Quat4d q1) {
 2
   double sqw = q1.w*q1.w;
 3
    double sqx = q1.x*q1.x;
 4
    double sqy = q1.y*q1.y;
 5
    double sqz = q1.z*q1.z;
 6
    double heading = Math.atan2(2.0 * (q1.x*q1.y + q1.z*q1.w),
7
      (sqx - sqy - sqz + sqw));
8
    double bank = Math.atan2(2.0 * (q1.y*q1.z + q1.x*q1.w),
9
      (-sqx - sqy + sqz + sqw));
10
   double attitude = Math.asin(-2.0 * (q1.x*q1.z - q1.y*q1.w));
     return new Vector3d(bank, attitude, heading);
11
12 J UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
```

Transform3D contains methods for transformation matrix operations similar to those in the Matrix4d class. It also allows direct application of the transform to points or vectors. This feature facilitates construction of geometries through transformations and will be discussed later in this chapter.

Listing 7.4 demonstrates the features of the Transform3D class graphically. (See Figure 7.2.) Listing 7.5 gives a class for displaying a set of coordinate axes. A transformation matrix corresponding to a Transform3D object is displayed and can be edited by the user. The rotation, translation, and scale components of the transform are extracted and displayed separately. The user can also specify these components and apply them to the transform. The transformation may be applied to a visual object, a set of 3D coordinate axes, so its effect can be seen immediately. The program provides a tool to explore the relationship between the transformation matrices and the geometric interpretations of transforms. (See Figure 7.2.)

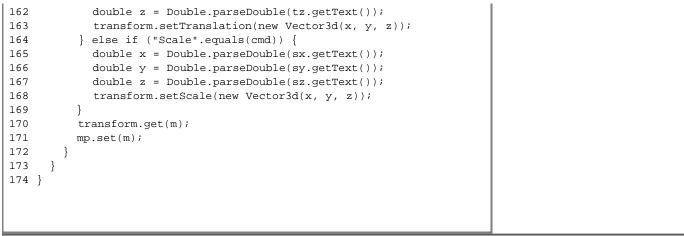
[Page 219]

Listing 7.4. TestTransform.java (This item is displayed on pages 219 - 221 in the print version)

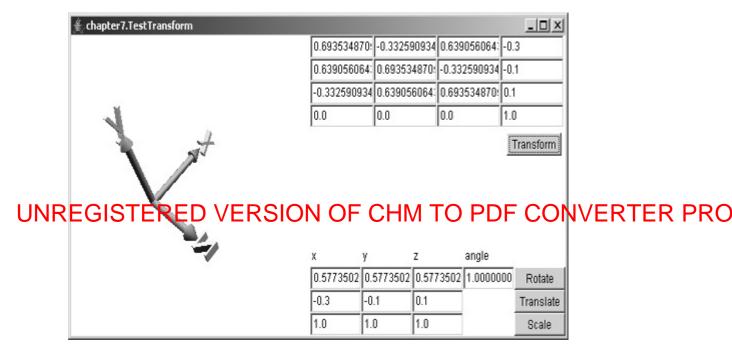
1 package chapter7; 2 3 import javax.vecmath.\*; 4 import java.awt.\*; 5 import java.awt.event.\*; 6 import javax.media.j3d.\*; 7 import com.sun.j3d.utils.universe.\*; 8 import com.sun.j3d.utils.geometry.\*; 9 import java.applet.\*; 10 import com.sun.j3d.utils.applet.MainFrame; 11 12 public class TestTransform extends Applet implements 13 ActionListener { public static void main(String[] args) { 14 15 new MainFrame(new TestTransform(), 640, 300); 16 17 18 TransformGroup trGroup; 19 Transform3D transform = new Transform3D(); 20 MatrixPanel mp = new MatrixPanel(); 21 TextField rx = new TextField(); 22 TextField ry = new TextField(); 23 TextField rz = new TextField(); 24 TextField ra = new TextField(); 25 TextField tx = new TextField(); 26 TextField ty = new TextField(); 27 TextField tz = new TextField(); TextField sx = new TextField(); 28 TextField sy = new TextField(); 29 30 TextField sz = new TextField(); 31 32 public void init() { 33 setLayout(new BorderLayout()); 34 35 Panel eastPanel = new Panel(); 36 eastPanel.setLayout(new BorderLayout()); 37 eastPanel.add(mp, BorderLayout.NORTH); 38 add(eastPanel, BorderLayout.EAST); 39 40 Button button = new Button("Transform"); 41 button.addActionListener(this); 42 Panel p = new Panel(); p.add(button); 43

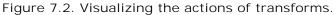
```
44
        eastPanel.add(p, BorderLayout.EAST);
 45
 46
       p = new Panel();
        p.setLayout(new GridLayout(4,5));
 47
 48
        p.add(new Label("x"));
       p.add(new Label("y"));
 49
 50
       p.add(new Label("z"));
 51
       p.add(new Label("angle"));
       p.add(new Label(""));
 52
 53
 54
       p.add(rx);
[Page 220] 55
             p.add(ry);
       p.add(rz);
 56
 57
       p.add(ra);
 58
       button = new Button("Rotate");
 59
        button.addActionListener(this);
 60
       p.add(button);
 61
       p.add(tx);
 62
 63
       p.add(ty);
 64
       p.add(tz);
 65
       p.add(new Panel());
       button = new Button("Translate");
 66
       button.addActionListener(this);
 67
 68
       p.add(button);
 69
 70
       p.add(sx);
 71
       p.add(sy);
 72
       p.add(sz);
 73
       p.add(new Panel());
 74
       button = new Button("Scale");
 75
       button.addActionListener(this);
 76
       p.add(button);
 77
 78
        eastPanel.add(p, BorderLayout.SOUTH);
 79
    UNRECONSTREED VERSION OF CHM TO PDF CONVERTER PRO
 80
 81
        Canvas3D cv = new Canvas3D(gc);
 82
 83
        add(cv, BorderLayout.CENTER);
 84
        BranchGroup bg = createSceneGraph();
 85
       bg.compile();
        SimpleUniverse su = new SimpleUniverse(cv);
 86
 87
        su.getViewingPlatform().setNominalViewingTransform();
 88
        su.addBranchGraph(bg);
 89
     }
 90
 91
     private BranchGroup createSceneGraph() {
 92
       BranchGroup root = new BranchGroup();
 93
        trGroup = new TransformGroup();
 94
        trGroup.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 95
       root.addChild(trGroup);
 96
 97
       // object
 98
        Appearance ap = new Appearance();
 99
        ap.setMaterial(new Material());
100
        VREGISTERE
                              D VERSION OF CHM TO PDF CONVERTER PRO
101
102
        Transform3D tr = new Transform3D();
```

```
103
        tr.setScale(0.5);
104
        TransformGroup tg = new TransformGroup(tr);
105
        trGroup.addChild(tg);
106
        tg.addChild(shape);
107
108
        // background and light
109
        BoundingSphere bounds = new BoundingSphere();
110
        Background background = new Background(1.0f, 1.0f, 1.0f);
111
        background.setApplicationBounds(bounds);
        root.addChild(background);
112
        AmbientLight light = new AmbientLight
113
114
          (true, new Color3f(Color.red));
[Page 221]115
                light.setInfluencingBounds(bounds);
116
        root.addChild(light);
117
        PointLight ptlight = new PointLight(new Color3f(Color.green),
118
          new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
119
        ptlight.setInfluencingBounds(bounds);
120
        root.addChild(ptlight);
121
        PointLight ptlight2 = new PointLight(new Color3f(Color.orange),
122
          new Point3f(-2f,2f,2f), new Point3f(1f,0f,0f));
123
        ptlight2.setInfluencingBounds(bounds);
124
        root.addChild(ptlight2);
125
        return root;
126
    }
127
128
     public void actionPerformed(ActionEvent e) {
129
        Matrix4d m = new Matrix4d();
130
        mp.get(m);
131
        transform.set(m);
132
        String cmd = e.getActionCommand();
133
       if ("Transform".equals(cmd)) {
134
          Quat4d quat = new Quat4d();
135
          Vector3d translation = new Vector3d();
136
          transform.get(quat, translation);
137
          Vector3d scale = new Vector3d();
138
          transform.getScale(scale);
139
          AxisAngle4d rotation = new AxisAngle4d();
140
          rotation.set(quat);
141
          rx.setText("" + rotation.x);
142
          ry.setText("" + rotation.y);
          rz.setText("" + rotation.z);
143
          ra.setText("" + rotation.angle);
144
          tx.setText("" + translation.x);
145
          ty.setText("" + translation.y);
146
          tz.setText("" + translation.z);
147
          sx.setText("" + scale.x);
148
          sy.setText("" + scale.y);
149
150
          sz.setText("" + scale.z);
151
          trGroup.setTransform(transform);
152
        } else {
153
          if ("Rotate".equals(cmd)) {
154
            double x = Double.parseDouble(rx.getText());
            double y = Double.parseDouble(ry.getText());
155
156
            double z = Double.parseDouble(rz.getText());
157
            double a = Double.parseDouble(ra.getText());
            transform.setRotation(new AxisAngle4d(x, y, z, a));
158
159
          } else if ("Translate".equals(cmd)) {
160
            double x = Double.parseDouble(tx.getText());
161
            double y = Double.parseDouble(ty.getText());
```



[Page 222]





Listing 7.5. Axes.java

(This item is displayed on pages 222 - 223 in the print version)



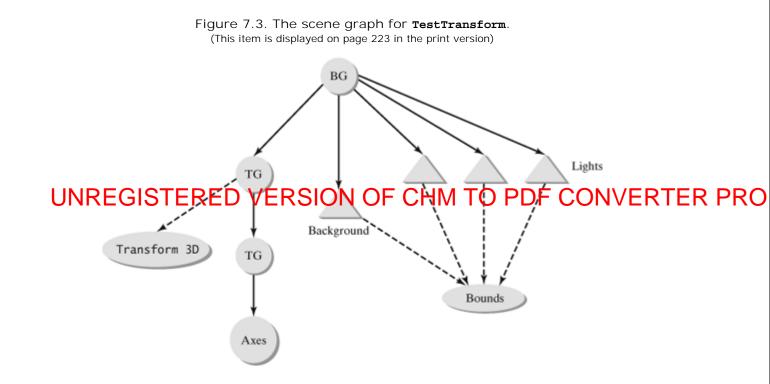
```
9
10 public class Axes extends Group {
11
    public Axes() {
       Appearance ap = new Appearance();
12
13
       ap.setMaterial(new Material());
       Font3D font = new Font3D(new Font("SanSerif", Font.PLAIN, 1),
14
15
                                 new FontExtrusion());
       Text3D x = new Text3D(font, "x");
16
17
       Shape3D xShape = new Shape3D(x, ap);
       Text3D y = new Text3D(font, "y");
18
19
       Shape3D yShape = new Shape3D(y, ap);
20
       Text3D z = new Text3D(font, "z");
21
       Shape3D zShape = new Shape3D(z, ap);
22
       // transform for texts
23
       Transform3D tTr = new Transform3D();
24
       tTr.setTranslation(new Vector3d(-0.12, 0.6, -0.04));
25
       tTr.setScale(0.5);
26
       // transform for arrows
27
       Transform3D aTr = new Transform3D();
28
      aTr.setTranslation(new Vector3d(0, 0.5, 0));
29
       // x axis
       Cylinder xAxis = new Cylinder(0.05f, 1f);
30
       Transform3D xTr = new Transform3D();
31
       xTr.setRotation(new AxisAngle4d(0, 0, 1, -Math.PI/2));
32
33
       xTr.setTranslation(new Vector3d(0.5, 0, 0));
34
      TransformGroup xTg = new TransformGroup(xTr);
35
       xTg.addChild(xAxis);
36
       this.addChild(xTg);
37
       TransformGroup xTextTg = new TransformGroup(tTr);
[Page 223]38
               xTextTg.addChild(xShape);
39
       xTg.addChild(xTextTg);
40
       Cone xArrow = new Cone(0.1f, 0.2f);
41
       TransformGroup xArrowTg = new TransformGroup(aTr);
42
       xArrowTg.addChild(xArrow);
43
       xTg.addChild(xArrowTg);
44
       // y axis
       Cylinder yAxis = new Cylinder(0.05f, 1f);
45
46
       Transform3D yTr = new Transform3D();
47
       yTr.setTranslation(new Vector3d(0, 0.5, 0));
48
       TransformGroup yTg = new TransformGroup(yTr);
49
       yTg.addChild(yAxis);
50
       this.addChild(yTg);
51
       TransformGroup yTextTg = new TransformGroup(tTr);
52
       yTextTg.addChild(yShape);
53
       yTg.addChild(yTextTg);
54
       Cone yArrow = new Cone(0.1f, 0.2f);
55
       TransformGroup yArrowTg = new TransformGroup(aTr);
56
       yArrowTg.addChild(yArrow);
57
       yTg.addChild(yArrowTg);
58
       // z axis
59
       Cylinder zAxis = new Cylinder(0.05f, 1f);
60
       Transform3D zTr = new Transform3D();
61
       zTr.setRotation(new AxisAngle4d(1, 0, 0, Math.PI/2));
62
       zTr.setTranslation(new Vector3d(0, 0, 0.5));
63
       TransformGroup zTg = new TransformGroup(zTr);
64
       zTg.addChild(zAxis);
65
       this.addChild(zTg);
66
       TransformGroup zTextTg = new TransformGroup(tTr);
67
       zTextTg.addChild(zShape);
```

```
68 zTg.addChild(zTextTg);
69 Cone zArrow = new Cone(0.1f, 0.2f);
70 TransformGroup zArrowTg = new TransformGroup(aTr);
71 zArrowTg.addChild(zArrow);
72 zTg.addChild(zArrowTg);
73 }
74 }
```

[Page 224]

The program TestTransform constructs a window to allow the user to interactively modify the transform and apply it to a scene. The Java 3D scene rendered in a Canvas3D is a set of 3D axes labeled with x, y, and z. The visual object is defined by the class Axes, and the detailed discussion of the Axes class will be given in the next section.

The Axes object goes through a fixed TransformGroup node to scale its size. The resulting branch is attached to another TransformGroup node that allows dynamic change of its transformation. The Transform3D object controls this node, and it can be set dynamically at runtime (Figure 7.3).



Similar to Listing 7.2, a MatrixPanel object is created to represent the transformation matrix. Three different aspects of the transformationrotation, translation, and scaleare extracted and displayed in several TextField objects. The x-, y-, z-components are displayed separately. The rotation also includes an angle specification.

When the button "Transform" is clicked (line 133), the matrix specified in the MatrixPanel object is retrieved. The transform is set according Curle matrix Rise is in the solution and is all are recalled to the TER PRO transform. The rotation expressed as a quaternion and the translation as a vector can be obtained with the following method of Transform3D:

double get(Quat4d rotation, Vector3d translation)

The above method also returns a uniform scaling factor. To obtain nonuniform scaling factors in x-, y-, and z-directions, the following method is used:

void getScale(Vector3d scale)

The Quat4d object obtained from the get method is converted to an AxisAngle4d object for easy access to the axis and angle of the rotation. The rotation, translation, and scale information extracted is displayed in the text fields. The transform is also performed on the 3D scene by setting the transform of the TransformGroup node with the following method:

void setTransform(Transform3D transform)

The actions for the buttons labeled "Rotate," "Translate," and "Scale" are opposite of those for the "Transform." When the button "Rotate" is clicked (line 153), the axis and the angle of the rotation are read from the text fields. The values are used to set the rotation of the Transform3D object with the method

```
void setRotation(AxisAngle4d rotation)
```

Similarly, the buttons "Translate" and "Scale" apply the specified translation and scaling to the transform.

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### 7.3. Transformations in Scene Graphs

Transformations in a Java 3D scene graph are implemented by the class TransformGroup. A TransformGroup object defines a scene-graph group node that represents a specific transformation. The exact form of the transformation is specified by a Transform3D object referenced by the node. The transformation is usually affine, but it can be any type of transforms that the TransformGroup object Transform3D class can represent. The transformation defined by the TransformGroup node is applied to all of its child nodes.

The following code shows an example of setting up a transformation node using the Matrix4d, Transform3D, and TransformGroup objects:

TransformGroup nodes can be used to change the shapes, sizes, and locations of geometric objects in the 3D world space. For example, the Tetrahedron class defined in the previous chapter is centered at the origin. To place an instance of Shape3D leaf node with a Tetrahedron geometry centered at (0.5, 0, -1), you may create a TransformGroup node with a translation of (0.5, 0, -1) and add the tetrahedron shape as its child:

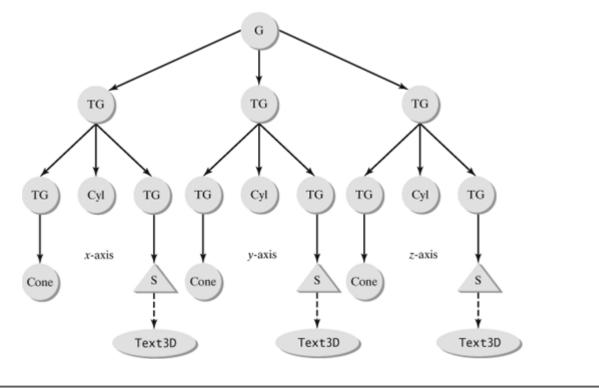
Tetrahedron geom = new Tetrahedron(); Shape3D shape = new Shape3D(); shape.setGeometry(geom); Transform3D tr = new Transform3D(); tr.setTranslation(new Vector3d(0.5,0,-1)); TransformGroup tg = new TransformGroup(tr); tg.addOhild(shap) STERED VERSION OF CHM TO PDF CONVERTER PRO

A TransformGroup node may be a child of another TransformGroup node. A hierarchy of TransformGroup and other nodes can be constructed to represent a complex structure of geometric models. For example, a table may be modeled as a table top with four legs. Each leg may be attached to a TransformGroup node that moves the leg to an appropriate position relative the table top. If you want to move the entire table as one object, you may then place another TransformGroup node on top of the table model.

In Listing 7.2, the Axes class constructs three perpendicular coordinate axes. Each axis consists of a cylinder for the axis line, a cone for the arrow, and a 3D text for the label. The scene graph of Axes is shown in Figure 7.4.

Figure 7.4. The scene graph for Axes class.

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[Page 226]

The Cylinder and Cone classes allow the specifications of radius and height in their constructors. However, they have fixed positions and orientations along the y-direction. Transformations are necessary to move them to the desired positions. The y-axis needs to move up by 0.5 so it will start from the origin. The x-axis and z-axis need to be rotated in addition to the translation. The arrows on the axes formed with Cone objects will go through similar transforms as their associated axes, but an additional translation is required to move the arrow to the top of the axis. This translation is represented as a separate TransformGroup node that is a child of the transform node for the axis and the parent of the arrow. Consequently, the translation is applied only to the cone-shaped arrow, and the axis transform is applied to both the axis and the translated arrow. In the similar fashion, the text label "x," "y," or "z" will first go through its own translation to appropriate positions relative to the axis. Then the same axis transform will be applied to move the label together with the axis and arrow to the final position.

Listing 7.6 demonstrates the usage of TransformGroup nodes and the construction of general rotations about arbitrary axes. The program illustrates the rotation of a cube around a general axis by displaying eight cubes at different stages of the rotation (Figure 7.5). The different positioning of the eight cubes is achieved by the TransformGroup nodes in the scene graph.

Listing 7.6. Rotation.java

(This item is displayed on pages 226 - 227 in the print version)

```
1 package chapter7;
2
3 import javax.vecmath.*;
4 import java.awt.*;
5 import java.awt.event.*;
6 import javax.media.j3d.*;
7 import com.sun.j3d.utils.universe.*;
8 import com.sun.j3d.utils.geometry.*;
9 import java.applet.*;
```

```
10 import com.sun.j3d.utils.applet.MainFrame;
```

```
11
12 public class Rotation extends Applet {
13
    public static void main(String[] args) {
14
       new MainFrame(new Rotation(), 640, 480);
15
    }
16
17
    public void init() {
      // create canvas
18
19
       GraphicsConfiguration gc =
20
         SimpleUniverse.getPreferredConfiguration();
21
       Canvas3D cv = new Canvas3D(gc);
22
       setLayout(new BorderLayout());
23
       add(cv, BorderLayout.CENTER);
24
       BranchGroup bg = createSceneGraph();
25
       bq.compile();
26
       SimpleUniverse su = new SimpleUniverse(cv);
27
       su.getViewingPlatform().setNominalViewingTransform();
28
       su.addBranchGraph(bg);
29
    }
30
31
    private BranchGroup createSceneGraph() {
32
       BranchGroup root = new BranchGroup();
       Background background = new Background(1.0f, 1.0f, 1.0f);
33
       BoundingSphere bounds = new BoundingSphere();
34
35
       background.setApplicationBounds(bounds);
36
       root.addChild(background);
37
       Shape3D shape;
38
       Appearance ap = new Appearance();
[Page 227]39
              PolygonAttributes pa = new PolygonAttributes();
40
       ap.setPolygonAttributes(pa);
41
       ColoringAttributes ca = new ColoringAttributes(Of, Of, Of,
42
         ColoringAttributes.SHADE_FLAT);
43
       ap.setColoringAttributes(ca);
44
45
       LineArray axis = new LineArray(2, LineArray.COORDINATES);
       axis.setCoordinate(0, new Point3d(-0.8, -0.8, -0.8));
46
      JNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
47
48
49
       Shape3D axisG = new Shape3D(axis, ap);
50
       root.addChild(axisG);
51
52
       Transform3D tr = new Transform3D();
       tr.setTranslation(new Vector3f(-0.5f, 0f, 0f));
53
54
       tr.setScale(0.1);
55
       TransformGroup tg;
56
      TransformGroup rot;
57
      for (int i = 0; i < 8; i++) {
58
         shape = new ColorCube();
59
         shape.setAppearance(ap);
60
         tg = new TransformGroup(tr);
61
         Transform3D trRot = new Transform3D();
62
         trRot.set(new AxisAngle4d(0.5,0.5,0.5, Math.PI/4*i));
63
         rot = new TransformGroup(trRot);
         root.addChild(rot);
64
65
         rot.addChild(tq);
66
         tg.addChild(shape);
67
         REGISTERED VERSION OF CHM TO PDF CONVERTER PRO
68
69
```

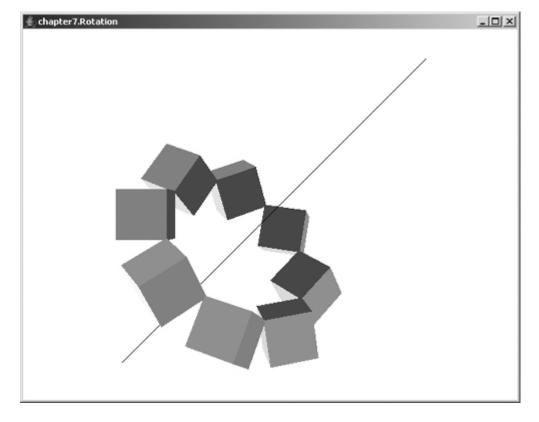
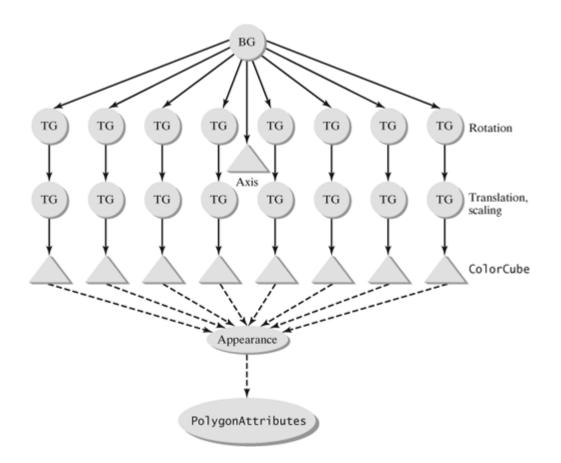


Figure 7.5. The rotated cubes about a general axis.

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The scene graph of the program is shown in Figure 7.6. Eight ColorCube objects are created, and they first go through an identical transformation of translation and scaling to resize and reposition. Then each transformed cube is attached to another TransformGroup node. These transform-group nodes are set to rotations about the same axis with different and evenly spread angles. This creates a scene with cubes at various stages of the revolution around the axis.

Figure 7.6. A partial scene graph for **Rotation** class.



The axis of rotation is a line through the origin and the point (1, 1, 1). The axis is also displayed in the scene as a LineArray geometry. The line is defined with two points (-0.8, -0.8, -0.8) and (0.5, 0.5, 0.5).

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$$\frac{2\pi}{8}i, \qquad i=0,1,\ldots,7$$

Note

For clarity of presentation, the rotation transform and the initial translation/scaling are implemented as separate cascaded TransformGroup nodes. It would be more efficient to combine them into one node. The optimization performed by Java 3D when compiling the scene graph may in fact automatically combine transformation nodes of this type.



### 7.4. Composite Transforms

Two or more transformations can be combined to form a composite transformation. For example, if  $T_1$ ,  $T_2$  are two transformations, then the composite transformation is defined as

[Page 229]

 $(\mathcal{T}_2\mathcal{T}_1)(\rho) = (\mathcal{T}_2(\mathcal{T}_1(\rho)))$ 

Note that the composition of two transforms is not commutative:  $7_1 7_2 \neq 7_2 7_1$  in general. In our notation, composite transforms are applied from right to left. For example,  $7_2 7_1$  denotes the composite transform that applies  $7_1$  first, followed by  $7_2$ .

In matrix form, the composition of transformations corresponds to matrix multiplication. If the transformation matrices for  $T_1$ ,  $T_2$  are  $M_1$ ,  $M_2$ , respectively, then the matrix for the composite transform  $T_2$   $T_1$  is the matrix  $M_2M_1$ .

The Transform3D class includes several methods for multiplying transformation matrices to form composite transforms:

- **void** mul(Transform3D t) Multiply the transform t to the current transform on the right.
- **void** mul(Transform3D t1, Transform3D t2)— Multiply the transforms t1 by t2.
- **void** mulInverse(Transform3D t)— Multiply the inverse of the transform t to the current transform on the right.
- **void** mulInverse(Transform3D t1, Transform3D t2)— Multiply the transform t1 by the inverse of the transform t2 on the right.
- **void** mulTransposeBoth(Transform3D t1, Transform3D t2)— Multiply the transpose of the transform t1 by the transpose of the transform t2 on the right.
- **void** mulTransposeLeft(Transform3D t1, Transform3D t2)— Multiply the transpose of the transform t1 by the transform t2 on the right.
- **void** mulTransposeRight(Transform3D t1, Transform3D t2)— Multiply the transform t1 by the transpose of the transform t2 on the right.

When setting up a complex transform, it is often easier to compose the transform from some simpler transforms than to directly construct the matrix.

Suppose that we want to construct a p/3 rotation about the axis through (1, 1, 0) and (1, 2, 1). Because the axis does not go through the origin, we cannot directly apply the quaternion approach. However, we can first perform a translation to move the axis so that it goes through the origin, then perform the rotation about the new axis, and finally apply an inverse translation to send the axis back to its original location. Let *T* be the translation by (-1, -1, 0). Then T(1, 1, 0) = (0, 0, 0) and T(1, 2, 1) = (0, 1, 1). Let *R* be the rotation of p/3 about the axis through the origin and (0, 1, 1). Then the original rotation can be decomposed into  $T^1 RT$ .

This pattern of decomposition is very common. If a particular transformation is known in a standard position, a similar transformation in a more general position can be obtained by first transforming to the standard position, performing the given transformation in the standard form, then transforming back to the original position.

Consider another example on reflection. The reflection about the  $x_{y}$ -plane is easy to construct, as shown earlier. A general reflection matrix will be more difficult to find. However, we may try to reduce the general problem to the simpler  $x_{y}$ -plane reflection. Suppose that the reflection plane is a plane through the origin given by the equation:

 $\partial X + by + cz = 0$ 

Instead of finding the transformation matrix directly, you may use a composite transform. First a rotation can be constructed to map the reflection plane to the xy-plane. Then the easy reflection about the xy-plane is performed. Finally the inverse rotation that maps the xy-plane back to the original reflection plane will complete the composite transformation. The composite transform is equivalent to the original reflection.

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To obtain a rotation that maps the above reflection plane to the xy-plane, it is equivalent to map the normal vector (*a*, *b*, *c*) to (0, 0, *d*), the normal vector for the xy-plane. The axis of rotation is (*b*, - *a*, 0). The quaternion for the rotation has the form:

$$q = \cos(\theta/2) + \left(\frac{b}{\sqrt{a^2 + b^2}}i - \frac{a}{\sqrt{a^2 + b^2}}j\right)\sin(\theta/2)$$

The appropriate rotation angle should satisfy the condition:

$$\cos\theta = c/\sqrt{a^2 + b^2 + c^2}, \qquad 0 \le \theta < \pi$$

Denote this rotation by R, and the reflection about xy-plane by F. Then the reflection about the plane can be written as:

# R<sup>1</sup>FR UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

Listing 7.7 illustrates the construction of reflections using this method. A plane in a general position is acting as a "mirror" for a reflection. A 3D text "Java" is rotating in the scene. Its mirror image about the plane is also displayed. The plane is shown in a semitransparent form to give an effect of mirror reflection for the transformed object (Figure 7.7).

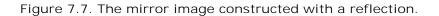
Listing 7.7. Mirror.java

(This item is displayed on pages 230 - 232 in the print version)

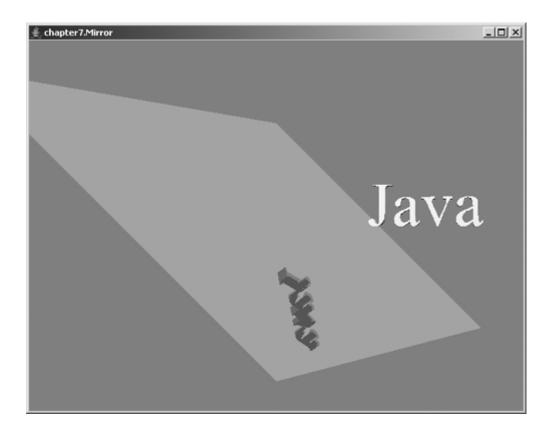


```
14
        new MainFrame(new Mirror(), 640, 480);
     }
 15
16
 17
     public void init() {
18
        // create canvas
19
        GraphicsConfiguration gc =
 20
        SimpleUniverse.getPreferredConfiguration();
        Canvas3D cv = new Canvas3D(qc);
 21
        setLayout(new BorderLayout());
 22
 23
        add(cv, BorderLayout.CENTER);
 24
        BranchGroup bg = createSceneGraph();
 25
        bq.compile();
 26
        SimpleUniverse su = new SimpleUniverse(cv);
 27
        su.getViewingPlatform().setNominalViewingTransform();
 28
        su.addBranchGraph(bg);
 29
     }
30
 31
     private BranchGroup createSceneGraph() {
 32
       // object
 33
        Appearance ap = new Appearance();
 34
        ap.setMaterial(new Material());
 35
        Font3D font = new Font3D(new Font("Serif", Font.PLAIN, 1),
36
         new FontExtrusion());
37
        Shape3D shape = new Shape3D(new Text3D(font, "Java"), ap);
[Page 231] 38
               // translation
        Transform3D trans = new Transform3D();
39
        trans.setTranslation(new Vector3d(-0.5,0,0));
 40
 41
        TransformGroup transg = new TransformGroup(trans);
 42
        transg.addChild(shape);
 43
        // rotation
 44
       TransformGroup spin = new TransformGroup();
 45
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 46
        spin.addChild(transg);
 47
        // scaling, translation
 48
        Transform3D tr = new Transform3D();
 49
        tr.setScale(0.25);
 50
        tr.setTranslation(new Vector3d(0.5,0,0));
 51
        TransformGroup tg = new TransformGroup(tr);
 52
        tg.addChild(spin);
 53
        // shared group
 54
        SharedGroup share = new SharedGroup();
 55
        share.addChild(tg);
 56
        // link leaf nodes to shared group
 57
        Link link1 = new Link(share);
        Link link2 = new Link(share);
 58
 59
        // reflection
 60
        Transform3D reflection = getReflection(1,1,1);
 61
        TransformGroup reflectionGroup = new TransformGroup(reflection);
 62
        reflectionGroup.addChild(link2);
 63
        // the mirror
 64
        QuadArray qa = new QuadArray(4, QuadArray.COORDINATES);
 65
        qa.setCoordinate(0, new Point3d(0,-0.5,0.5));
 66
        qa.setCoordinate(1, new Point3d(1,-0.5,-0.5));
 67
        qa.setCoordinate(2, new Point3d(0,0.5,-0.5));
 68
        qa.setCoordinate(3, new Point3d(-1,0.5,0.5));
 69
        ap = new Appearance();
 70
        ap.setTransparencyAttributes(
 71
          new TransparencyAttributes
 72
             (TransparencyAttributes.BLENDED, 0.7f));
```

```
73
        Shape3D mirror = new Shape3D(qa, ap);
 74
        // rotator
 75
        Alpha alpha = new Alpha(-1, 4000);
 76
        RotationInterpolator rotator = new RotationInterpolator
 77
          (alpha, spin);
 78
        BoundingSphere bounds = new BoundingSphere();
 79
        rotator.setSchedulingBounds(bounds);
 80
        // background and lights
        Background background = new Background(0.5f, 0.5f, 0.5f);
 81
 82
        background.setApplicationBounds(bounds);
        AmbientLight light = new AmbientLight
 83
 84
          (true, new Color3f(Color.red));
 85
        light.setInfluencingBounds(bounds);
 86
        PointLight ptlight = new PointLight(new Color3f(Color.green),
 87
         new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
 88
        ptlight.setInfluencingBounds(bounds);
 89
        PointLight ptlight2 = new PointLight(new Color3f(Color.orange),
 90
          new Point3f(-2f,2f,2f), new Point3f(1f,0f,0f));
        ptlight2.setInfluencingBounds(bounds);
 91
 92
        // branch group
 93
        BranchGroup root = new BranchGroup();
 94
        root.addChild(link1);
 95
        root.addChild(reflectionGroup);
 96
        root.addChild(mirror);
 97
        root.addChild(rotator);
[Page 232] 98
               root.addChild(background);
 99
        root.addChild(light);
100
        root.addChild(ptlight);
101
        root.addChild(ptlight2);
102
        return root;
103
    }
104
105
      static Transform3D getReflection(double a, double b, double c) {
106
        Transform3D transform = new Transform3D();
107
        double theta = Math.acos(c/Math.sqrt(a*a+b*b+c*c));
108
        double r = Math.sqrt(a*a+b*b);
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108
110
111
        Transform3D ref = new Transform3D();
112
        ref.setScale(new Vector3d(1,1,-1));
113
        transform.mulInverse(rot);
114
        transform.mul(ref);
115
        transform.mul(rot);
116
        return transform;
117
     }
118 }
```

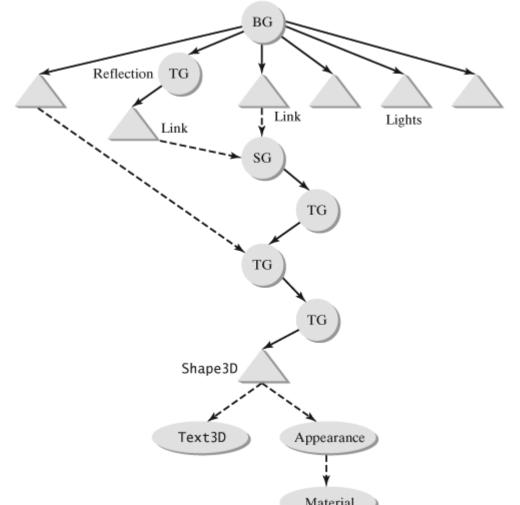


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The program constructs a "mirror" and shows a rotating object and its mirror image. The scene graph is shown in Figure 7.8.

Figure 7.8. The scene graph for the **Mirror** class. (This item is displayed on page 233 in the print version)



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The mirror (reflection plane) is chosen to go through the origin and have the normal vector (1, 1, 1). The mirror itself is rendered in the scene as a semitransparent rectangle using a QuadArray object (line 64).

The method getReflection (line 105) performs the calculations derived above for the reflection about the given plane. The composite transform consists of a rotation to rotate the plane to the standard xy-plane, a simple reflection about the xy-plane, and an inverse rotation:  $\mathcal{R}^1 \mathcal{F} \mathcal{R}$ . The inverse rotation is obtained by using the mulInverse method. The reflection and the rotation are multiplied with the mul method. The resulting composite transform is returned as a Transform3D object.

[Page 233]

The object used for the reflection is a rotating 3D text "Java." In order to show the reflection faithfully, the visual object is placed in a *SharedGroup* branch. Both the original and the reflected object share the same branch through two Link leaf nodes. The link for the mirrored object goes through the reflection transform node.

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### 7.5. Constructing Geometries with Transformations

Transformations are useful not only in transforming the completed objects, but also in constructing primitives. Geometric primitives often exhibit certain degrees of symmetry. As a result, some vertices of a primitive may be obtained by transforming other vertices. In this section, we will discuss several techniques of generating 3D geometries with affine transforms and other operations.

The Transform3D class provides methods for applying the transform represented by the object to points or vectors:

```
void transform(Point3d p)
void transform(Point3d p, Point3d pOut)
void transform(Point3f p)
[Page 234]void transform(Point3f p, Point3f pOut)
void transform(Vector3d v)
void transform(Vector3d v, Vector3d vOut)
void transform(Vector3f v)
void transform(Vector3f v, Vector3f vOut)
void transform(Vector4d v)
void transform(Vector4d v, Vector4d vOut)
void transform(Vector4f v)
void transform(Vector4f v)
void transform(Vector4f v)
```

The methods with one parameter transform the point or vector in place. The methods with two parameters perform the transformation on the first parameter nondestructively and save the result in the second parameter.

#### 7.5.1. Extrusion

A simple way to create a 3D surface is to extrude (or sweep) a 2D curve through space. A 3D text created with Font 3D is an example of extrusion.

Extrusion can be implemented with translations. Starting with the points on the curve, we apply a translation along the direction of extrusion to generate other points. For example, the following method takes a 2D shape object and performs an extrusion along the z-axis.

Listing 7.8. extrudeShape Method

(This item is displayed on pages 234 - 235 in the print version)

```
1
    // Assumption: only one continuous curve in the Shape object
 2
    Geometry extrudeShape(Shape curve, float depth) {
 3
      PathIterator iter = curve.getPathIterator(new AffineTransform());
 4
      Vector ptsList = new Vector();
 5
      float[] seg = new float[6];
 6
      float x = 0, y = 0;
 7
      float x0 = 0, y0 = 0;
 8
      while (!iter.isDone()) {
 9
        int segType = iter.currentSegment(seg);
10
        switch (segType) {
11
          case PathIterator.SEG_MOVETO:
12
           x = x0 = seg[0];
13
           y = y0 = seg[1];
```

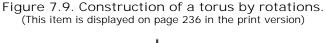
```
14
            ptsList.add(new Point3f(x,y,0));
15
           break;
16
          case PathIterator.SEG_LINETO:
17
           x = seg[0];
18
           y = seg[1];
19
            ptsList.add(new Point3f(x,y,0));
20
           break;
21
          case PathIterator.SEG_QUADTO:
           for (int i = 1; i < 10; i++) {
22
23
             float t = (float)i/10f;
              float xi = (1-t)*(1-t)*x + 2*t*(1-t)*seg[0] + t*t*seg[2];
24
25
              float yi = (1-t)*(1-t)*y + 2*t*(1-t)*seg[1] + t*t*seg[3];
26
              ptsList.add(new Point3f(xi,yi,0));
27
           }
28
           x = seg[2];
29
           y = seg[3];
30
            ptsList.add(new Point3f(x,y,0));
31
           break;
32
          case PathIterator.SEG_CUBICTO:
33
            for (int i = 1; i < 20; i++) {
              float t = (float)i/20f;
34
[Page 235]35
                     float xi = (1-t)*(1-t)*(1-t)*x + 3*t*(1-t)*(1-t)*seg[0] +
              3*t*t*(1-t)*seg[2] + t*t*t*seg[4];
36
37
              float yi = (1-t)*(1-t)*(1-t)*y + 3*t*(1-t)*(1-t)*seg[1] +
38
              3*t*t*(1-t)*seg[3] + t*t*t*seg[5];
39
              ptsList.add(new Point3f(xi,yi,0));
40
           }
41
           x = seg[2];
42
           y = seg[3];
43
            ptsList.add(new Point3f(x,y,0));
44
           break;
45
          case PathIterator.SEG_CLOSE:
46
           x = x0;
47
            y = y0;
48
            ptsList.add(new Point3f(x,y,0));
49
            break;
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50
            FG
51
52
     }
53
      int n = ptsList.size();
54
      IndexedQuadArray qa = new IndexedQuadArray(2*n,
55
        IndexedQuadArray.COORDINATES, 4*(n-1));
56
      Transform3D trans = new Transform3D();
     trans.setTranslation(new Vector3f(0,0,depth));
57
58
     for (int i = 0; i < n; i++) {
59
       Point3f pt = (Point3f)ptsList.get(i);
60
        qa.setCoordinate(2*i, pt);
61
        trans.transform(pt);
62
        qa.setCoordinate(2*i+1, pt);
63
      }
64
     int quadIndex = 0;
65
      for (int i = 0; i < n-1; i++) {
66
          ga.setCoordinateIndex(quadIndex++, 2*i);
          ga.setCoordinateIndex(quadIndex++, 2*i+1);
67
68
          qa.setCoordinateIndex(quadIndex++, 2*(i+1)+1);
69
          qa.setCoordinateIndex(quadIndex++, 2*(i+1));
70
         IREGISTERED WERSION OF CHM TO PDF CONVERTER PRO
71
72
      NormalGenerator ng = new NormalGenerator();
```

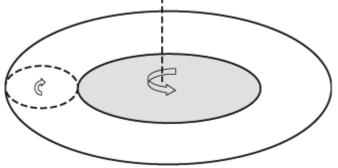
```
73 ng.generateNormals(gi);
74 return gi.getGeometryArray();
75 }
```

For simplicity, the method assumes that the Shape object only has one continuous curve definition. The general case can be handled in a similar manner. The parameter depth defines the depth of the extrusion.

#### 7.5.2. Rotation

Many surfaces can be obtained through rotations. For example, a cylinder may be obtained by rotating a line, and a sphere is the result of rotating a semicircle. A *torus* can be constructed by rotating a circle about an axis outside the circle. Furthermore, the circle itself can be obtained by rotating a point. Therefore, to obtain a polygon mesh for the torus, we can start from a single point. Rotating the point repeatedly with different angles generates a set of points for the circle. Rotating the circle points about a different axis generates the vertices for the torus. This procedure is illustrated in Figure 7.9.





Given a set of base points on the curve, to create a rotated surface with *n* strips, we may set up a rotation of the angle 2p/*n*. By successively applying the rotation to the curve points, we will be able to generate the vertices for a quadrangle array. Listing 7.9 shows the construction of a torus via two different rotations. Listing 7.10 gives a program for displaying two tori. The vertices of the torus geometry are generated with applications of transforms. In the test program, two linked tori are shown rotating in the space.

Listing 7.9. Torus.java

[Page 236]

(This item is displayed on pages 236 - 237 in the print version)

```
1 package chapter7;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
9
10 public class Torus extends Shape3D {
    public Torus(double r1, double r2) {
11
12
      int m = 20;
13
      int n = 40;
14
      Point3d[] pts = new Point3d[m];
15
       pts[0] = new Point3d(r1+r2, 0, 0);
16
       double theta = 2.0 * Math.PI / m;
17
       double c = Math.cos(theta);
18
       double s = Math.sin(theta);
19
       double[] mat = {c, -s, 0, r2*(1-c),
20
                       s, c, 0, -r2*s,
                       0, 0, 1, 0,
21
22
                       0, 0, 0, 1;
23
       Transform3D rot1 = new Transform3D(mat);
24
       for (int i = 1; i < m; i++) {
25
         pts[i] = new Point3d();
26
         rot1.transform(pts[i-1], pts[i]);
27
       }
28
29
       Transform3D rot2 = new Transform3D();
30
       rot2.rotY(2.0*Math.PI/n);
31
       IndexedQuadArray qa = new IndexedQuadArray(m*n,
32
         IndexedQuadArray.COORDINATES, 4*m*n);
33
       int quadIndex = 0;
34
       for (int i = 0; i < n; i++) {
35
         qa.setCoordinates(i*m, pts);
36
          ŘÉĞÍSTERED XÉRSION OF CHM TO PDF CONVERTER PRO
[Page 2018
38
           int[] quadCoords = {i*m+j, ((i+1)%n)*m+j,
39
             ((i+1)%n)*m+((j+1)%m), i*m+((j+1)%m)};
40
           qa.setCoordinateIndices(quadIndex, quadCoords);
41
           quadIndex += 4;
42
        }
43
       }
44
       GeometryInfo gi = new GeometryInfo(qa);
45
       NormalGenerator ng = new NormalGenerator();
46
       ng.generateNormals(gi);
47
       this.setGeometry(gi.getGeometryArray());
48
    }
49 }
50
```

Listing 710 Test orus java UNREGISTERED WERSION 20F3 CHIMINT COPDF CONVERTER PRO

```
1 package chapter7;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
9 import java.applet.*;
10 import com.sun.j3d.utils.applet.MainFrame;
11
12 public class TestTorus extends Applet {
   public static void main(String[] args) {
13
14
      new MainFrame(new TestTorus(), 640, 480);
15
    }
16
   public void init() {
17
18
      // create canvas
19
      GraphicsConfiguration gc =
20
      SimpleUniverse.getPreferredConfiguration();
     Canvas3D cv = new Canvas3D(gc);
21
      setLayout(new BorderLayout());
22
23
      add(cv, BorderLayout.CENTER);
24
      BranchGroup bg = createSceneGraph();
25
     bg.compile();
26
      SimpleUniverse su = new SimpleUniverse(cv);
27
       su.getViewingPlatform().setNominalViewingTransform();
28
       su.addBranchGraph(bg);
29
    }
30
31
   private BranchGroup createSceneGraph() {
32
      BranchGroup root = new BranchGroup();
33
       TransformGroup spin = new TransformGroup();
34
       spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
35
       root.addChild(spin);
36
       Transform3D tr = new Transform3D();
37
38
       tr.setScale(0.8);
39
       tr.setRotation(new AxisAngle4d(1, 0, 0, Math.PI/6));
40
       TransformGroup tg = new TransformGroup(tr);
41
       spin.addChild(tg);
42
[Page 238]43
               // object
       Shape3D torus1 = new Torus(0.2, 0.5);
44
45
       Appearance ap = new Appearance();
46
       ap.setMaterial(new Material());
47
       torus1.setAppearance(ap);
48
       tg.addChild(torus1);
49
50
       Shape3D torus2 = new Torus(0.2, 0.5);
51
       ap = new Appearance();
52
       ap.setMaterial(new Material());
53
       ap.setTransparencyAttributes(
54
        new TransparencyAttributes
55
            (TransparencyAttributes.BLENDED, 0.5f));
       torus2.setAppearance(ap);
56
57
       Transform3D tr2 = new Transform3D();
58
       tr2.setRotation(new AxisAngle4d(1, 0, 0, Math.PI/2));
59
       tr2.setTranslation(new Vector3d(0.5,0,0));
```

```
60
       TransformGroup tg2 = new TransformGroup(tr2);
61
       tg.addChild(tg2);
62
       tg2.addChild(torus2);
63
64
       Alpha alpha = new Alpha(-1, 8000);
65
       RotationInterpolator rotator = new RotationInterpolator
66
         (alpha, spin);
67
       BoundingSphere bounds = new BoundingSphere();
68
       rotator.setSchedulingBounds(bounds);
69
       spin.addChild(rotator);
70
71
       // background and lights
72
       Background background = new Background(1.0f, 1.0f, 1.0f);
73
       background.setApplicationBounds(bounds);
74
       root.addChild(background);
75
       AmbientLight light = new AmbientLight
76
         (true, new Color3f(Color.blue));
77
       light.setInfluencingBounds(bounds);
78
       root.addChild(light);
79
       PointLight ptlight = new PointLight(new Color3f(Color.white),
         new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
80
       ptlight.setInfluencingBounds(bounds);
81
82
       root.addChild(ptlight);
83
       return root;
84
    }
85 }
```

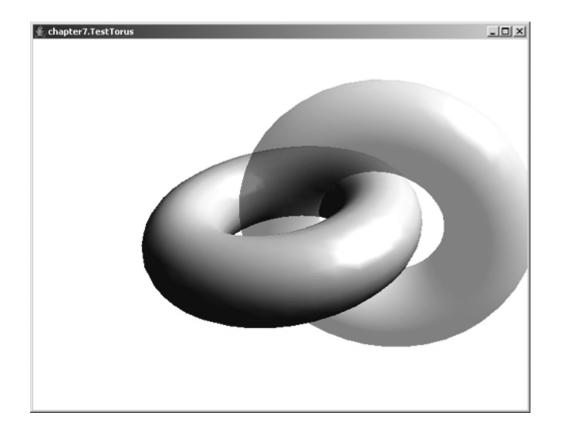
The Torus class extends Shape3D. The geometry is constructed with IndexedQuadArray. A rotation rot1 (line 23) is set to generate the points of a circle from a single point. The generated points on the circle are stored in the array pts. Another rotation rot2 (line 29) is set to generate the points on the torus from the circle points. The grid of points on the torus are generated one column at a time and are entered into the IndexedQuadArray (line 35). Then the indices for the quadrilaterals are entered (line 40). To generate normals, the IndexedQuadArray opicitie concerned a request of points of a circle point.

The TestTorus class displays two instances of Torus in different positions (Figure 7.10). They are positioned in such a way that one torus passes through the hole of the other. One of the tori is set to be semitransparent using a TransparencyAttributes object. The entire figure is rotating to allow viewing from different angles.

[Page 239]

Figure 7.10. Two instances of **Torus** primitive whose vertices are generated by two sets of rotations.

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### 7.5.3. Transformation and Shared Branch: An Example

The construction of complex visual contents often involves transformations at different levels. Listing 7.11 gives a class for displaying an arrow geometry. Listing 7.12 illustrates the combination of shared branches and transforms to reuse symmetric substructures. A 3D logo with 16 arrows and a ring around them is shown rotating about a vertical axis (Figure 7.11).

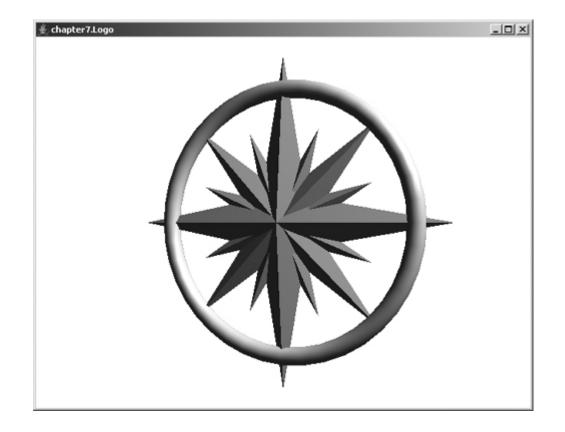
Listing 7.11. Arrow.java

(This item is displayed on pages 239 - 240 in the print version)

```
1 package chapter7;
2
 3 import javax.vecmath.*;
 4 import javax.media.j3d.*;
5
 6 public class Arrow extends IndexedTriangleArray {
7
   float w = 1f;
   float h = 0.15f;
8
9
   float d = 0.1f_i
10
11
   public Arrow() {
     super(5, TriangleArray.COORDINATES | TriangleArray.NORMALS, 12);
12
13
     Point3f[] pts = {new Point3f(0f,0f,d),
14
       new Point3f(w,0f,0f),
15
        new Point3f(h,h,Of),
16
       new Point3f(h,-h,0f),
17
       new Point3f(0f,0f,-d)};
18
     setCoordinates(0, pts);
      int[] coords = {0,1,2,0,3,1,4,1,3,4,2,1};
19
      setCoordinateIndices(0, coords);
20
21
      Vector3f v1 = new Vector3f();
[Page 240]22
             v1.sub(pts[1], pts[0]);
23
      v1.normalize();
24
      Vector3f v2 = new Vector3f();
25
      v2.sub(pts[2], pts[0]);
26
      v2.normalize();
27
      Vector3f v = new Vector3f();
28
      v.cross(v1, v2);
29
      setNormal(0, v);
30
      v.y = -v.y;
31
      setNormal(1, v);
32
      v.z = -v.zi
33
      setNormal(2, v);
34
     v.y = -v.y;
35
      setNormal(3, v);
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36
37
38
   }
39 }
```

Figure 7.11. A 3D logo.

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### Listing 7.12. Logo.java

(This item is displayed on pages 240 - 242 in the print version)

```
1 package chapter7;
  2
  3 import javax.vecmath.*;
  4 import java.awt.*;
  5 import java.awt.event.*;
  6 import javax.media.j3d.*;
  7 import com.sun.j3d.utils.universe.*;
  8 import com.sun.j3d.utils.geometry.*;
[Page 241] 9 import java.applet.*;
 10 import com.sun.j3d.utils.applet.MainFrame;
11
 12 public class Logo extends Applet {
13 public static void main(String[] args) {
 14
        new MainFrame(new Logo(), 640, 480);
 15
      }
 16
     public void init() {
 17
 18
        // create canvas
 19
        GraphicsConfiguration gc =
 20
          SimpleUniverse.getPreferredConfiguration();
 21
        Canvas3D cv = new Canvas3D(gc);
 22
        setLayout(new BorderLayout());
 23
        add(cv, BorderLayout.CENTER);
 24
        BranchGroup bg = createSceneGraph();
 25
        bg.compile();
 26
        SimpleUniverse su = new SimpleUniverse(cv);
```

```
27
        su.getViewingPlatform().setNominalViewingTransform();
 28
        su.addBranchGraph(bg);
29
     }
30
31
     private BranchGroup createSceneGraph() {
32
       BranchGroup root = new BranchGroup();
33
        TransformGroup spin = new TransformGroup();
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 34
35
       root.addChild(spin);
36
37
       Transform3D tr = new Transform3D();
38
       tr.setScale(0.9);
39
        tr.setRotation(new AxisAngle4d(1, 0, 0, Math.PI/2));
 40
       TransformGroup tg = new TransformGroup(tr);
 41
       spin.addChild(tg);
 42
       // torus
 43
       Shape3D torus = new Torus(0.04, 0.6);
 44
       Appearance ap = new Appearance();
 45
       ap.setMaterial(new Material());
 46
       torus.setAppearance(ap);
 47
       tg.addChild(torus);
 48
       // shared group of 4 arrows
       SharedGroup sg = new SharedGroup();
 49
50
       Shape3D arrow;
51
       Transform3D tra;
52
       TransformGroup tga;
53
       for (int i = 0; i < 4; i++) {
54
         arrow = new Shape3D(new Arrow(), ap);
55
         tra = new Transform3D();
56
         tra.setRotation(new AxisAngle4d(0, 0, 1, i*Math.PI/2));
57
         tga = new TransformGroup(tra);
58
         sg.addChild(tga);
59
         tga.addChild(arrow);
60
       }
61
        // four links to shared group
62
       Link link = new Link();
    UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 63
 64
65
        tr.setScale(0.675);
 66
       tg = new TransformGroup(tr);
67
       tg.addChild(link);
68
       spin.addChild(tg);
69
[Page 242] 70
               link = new Link();
71
       link.setSharedGroup(sg);
       tr = new Transform3D();
72
73
       tr.setScale(0.55);
74
       tr.setRotation(new AxisAngle4d(0, 0, 1, Math.PI/4));
75
       tq = new TransformGroup(tr);
76
       tg.addChild(link);
77
       spin.addChild(tg);
78
79
       link = new Link();
       link.setSharedGroup(sg);
80
81
       tr = new Transform3D();
82
       tr.setScale(0.4);
    UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
83
84
85
        tg.addChild(link);
```

86		
87		
88		
89	1 ( ))	
90		
91		
92		Math.PI/8));
93		
94	5	
95		
96		
97		
98	-	
99	<pre>new RotationInterpolator(alpha, spin);</pre>	
100	BoundingSphere bounds = new BoundingSphere	();
101	rotator.setSchedulingBounds(bounds);	
102	<pre>spin.addChild(rotator);</pre>	
103	// background and lights	
104	Background background = new Background(1.0	f, 1.0f, 1.0f);
105	<pre>background.setApplicationBounds(bounds);</pre>	
106	root.addChild(background);	
107	AmbientLight light = new AmbientLight	
108	<pre>(true, new Color3f(Color.red));</pre>	
109	<pre>light.setInfluencingBounds(bounds);</pre>	
110	root.addChild(light);	
111	. PointLight ptlight = new PointLight(new Co	lor3f(Color.white),
112	new Point3f(2f,2f,2f), new Point3f(1f,0f,0	f));
113	<pre>ptlight.setInfluencingBounds(bounds);</pre>	
114	root.addChild(ptlight);	
115	return root;	
116	5 }	
117		

The ring is an instance of the Torus class defined in Listing 7.6. The sixteen arrows (spokes) possess a high degree of symmetries and similarities. To take advantage of the symmetries and simplify the modeling procedure, transforms and shared branches are applied.

The Arrow class defines the geometry for a single arrow primitive. It extends the class IndexedTriangleArray. Five vertices and four faces are defined for the geometry. The surface normal of a face is calculated by a cross product of the vectors of two sides. The normals of other faces are obtained from the first one by symmetries.

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Four Arrow objects are grouped together through transforms to form a shared branch (lines 48–60). The four arrows are in the directions of 0, 90, 180, 270 degrees.

Four different Link objects to the SharedGroup node are created for the total of sixteen arrows (lines 61–95). Each link goes through a transform for appropriate rotation and scaling.

The entire assembled logo is made to rotate in the scene using a RotationInterpolator object, as seen in many other examples. The logo has an appearance bundle that includes a Material object. It is illuminated by two lights. The background of the scene is again set to white.

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#### [Page 243 (continued)]

## Key Classes and Methods

- javax.vecmath.Matrix4d A class encapsulating a 4 x 4 double matrix.
- javax.vecmath.Matrix4f A class encapsulating a 4 x 4 float matrix.
- javax.media.j3d.Transform3D A class encapsulating a 3D transformation.
- javax.media.j3d.Transform3D.set(...) Methods to set the transformation.
- javax.media.j3d.Transform3D.setTranslation(...) Methods to set the translation component.
- javax.media.j3d.Transform3D.setRotation(...) Methods to set the rotation component.
- javax.media.j3d.Transform3D.setScale(...) Methods to set the scale component.
- javax.media.j3d.Transform3D.mul(...) Methods to multiply another transform.
- javax.media.j3d.Transform3D.mulInverse(...) Methods to multiply the inverse of another transform.
- javax.media.j3d.Transform3D.transform(...) Methods to apply the transform to points and vectors.
- javax.media.j3d.TransformGroup A group node class for transformation.
- javax.vecmath.Quat4d A class encapsulating the quaternion with double components.
- javax.vecmath.Quat4f A class encapsulating the quaternion with float components.

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#### [Page 243 (continued)]

### Key Terms affine transform

A geometric transform that preserves parallelism.

### projective transform

A geometric transform that preserves points, lines, and their incidence relations.

### Euler angles

A method to specify a 3D rotation with three rotations about main coordinate axes.

### composite transformation

A transformation as a product of several transformations.

### 3D transformation matrix

A matrix representing a 3D projective transform.

#### quaternion representation

A method to represent a 3D rotation with a quaternion.

### 3D translation

A geometric transform that moves all points by a constant value.

### 3D rotation

A geometric transform that rotates a point around a fixed axis by a constant angle.

### 3D scaling

A geometric transform that scales the coordinates by constant factors. The scaling is uniform if the three factors in  $x_{-}, y_{-}, z_{-}$  components are the same.

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3D shearing

A geometric transform that shifts the points parallel to a plane.

### 3D reflection

A geometric transform that flips the points about a fixed plane.

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#### [Page 244]

## Chapter Summary

- In this chapter, we introduce the concepts and applications of 3D transformations, especially the family of affine transforms.
- A 3D transform is represented as a matrix. Matrix classes are provided in the package javax.vecmath. In Java 3D, the Transform3D class encapsulates the transformation matrix and the various operations related to the transform. The class includes a large number of methods for setting the transform, performing matrix operations, composing with other transforms, and transforming points and vectors.
- The TransformGroup nodes provide the presence of transforms in Java scene graphs. A TransformGroup node references a Transform3D object to define its transformation and applies the transformation to its child nodes.
- 3D rotations are complex transformations. Three different representations of rotations are introduced. The matrix representation is consistent with other affine transforms, but its relation to geometric parameters is often implicit. The quaternion representation for general 3D rotations is explicit and convenient because of its direct connection with the rotation axis and angle. Euler angles offer another intuitive representation for 3D rotations.
- Composition of transforms is useful especially in construction of complex transforms. A complex transform can often be decomposed into a composite transform of simpler transforms.
- Another application of transforms is in the construction of geometries. The symmetries and regularities in a geometric figure will often be associated with certain transformations. The points on such a geometry may be generated conveniently through the transformations. An extruded surface is obtained by sweeping a curve. Translations are related to extrusion. A rotated surface is generated by rotating a curve.

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## **Review** Questions

- 7.1 Find the transformation matrix of the translation that maps the point (3, -1, 2) to (0, 5, -1).
- 7.2 Find the transformation matrix of the rotation about the  $\gamma$ -axis by 30 degrees.
- 7.3 Find the transformation matrix of the reflection about the plane through the origin with the normal vector (1, 1, 1).
- 7.4 Derive the transformation matrix of the reflection about the plane through the origin with the normal vector u as defined below:

$$T(x) = x - \frac{2x \cdot u}{\|u\|^2}u$$

7.5 Calculate the quaternion product:

$$(1 + 3i - j + k) \cdot (2i + j - 3k)$$

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- 7.6 Let  $u = (\chi_{u}, \chi_{u}, Z_{u})$  and  $v = (\chi_{v}, \chi_{v}, Z_{v})$  be two orthogonal unit vectors. Find a rotation that maps u to the x-axis, v to the y-axis, and  $u \times v$  to the z-axis.
- 7.7 An (x, y)-shear is defined by the matrix:

$$\begin{array}{c|cccc} 1 & 0 & sh_x & 0 \\ \hline UNR \stackrel{P}{=} G \stackrel{P}{=} S \stackrel{P}{=} R \stackrel{P}{=} D \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{array} \\ \end{array} VERSION OF CHM TO PDF CONVERTER PRO$$

Given the orthogonal unit vectors u and v, derive a composite transform that performs a (u, v)-shear by the factors  $(sh_{u}, sh_{v})$ .

7.8 Find the transformation matrix for the 3D rotation represented by the quaternion

$$Q = W + Xi + Yi + Zk$$

7.9 If  $R_x$  is a rotation about the *x*-axis of 30 degrees and  $R_y$  a rotation about the *y*-axis of 60 degrees, describe the composite rotation  $R_y R_x$  in terms of its axis and angle.

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## Programming Exercises

- 7.1 Write a Java 3D program to display two tetrahedra with a common triangle face.
- 7.2 Display two cones with their vertices pointing to each other.
- 7.3 Display a cone with its vertex pointing in the direction (1, 1, 1).
- 7.4 Modify Listing 7.4 to include an (x, y)-shear operation. Allow the user to specify the factors  $(sh_{x_i} sh_{y})$ .
- 7.5 Modify Listing 7.4 to include rotation specification with Euler angles.
- 7.6 Modify Listing 7.7 to construct the reflection matrix directly from the following formula:

$$T(x) = x - \frac{2x \cdot u}{\|u\|^2}u$$

- 7.7 Create and display a simple table with a square top and four cylindrical legs. Use only predefined primitives and transformations to create the visual object. Rotate the table continuously in the scene.
- 7.8 Create a geometry that is formed by rotating the figure in Figure 7.12 about the *y*-axis. Write a test program to display the object.

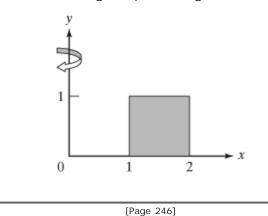


Figure 7.12. Rotating a square to generate a 3D object.

7.9 Implement a Shape3D class RotatedShape that represents a surface obtained by rotating a 2D Shape object about the *y*-axis. It should contain at least one constructor: **public** RotatedShape(Shape curve)

You may assume that the 2D shape is a single continuous curve (with only one SEG\_MOVETO). Write a test program to display a rotated surface.

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## Chapter 8. Views

(This item omitted from WebBook edition)

Objectives
• To present the concept of view in the 3D rendering process.
<ul> <li>To identify the parallel and perspective projections.</li> </ul>
<ul> <li>To specify the viewing matrix.</li> </ul>
To specify the projection matrix.
To apply the Java 3D standard view model.
To apply the Java 3D compatibility-mode view model.
• To apply picking in a 3D scene.
<ul> <li>To understand head tracking in view models.</li> </ul>
<ul> <li>To apply input devices, sensors, and head tracking in Java 3D.</li> </ul>
• To use the avatar in SimpleUniverse.

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## 8.1. Introduction

After a virtual world of graphics objects is constructed, it can be rendered to produce images of the world from various perspectives through a viewing process. The rendering of a scene is characterized by numerous attributes that affect different aspects of the viewing. In this chapter we focus on the geometric aspects of the rendering process. The methods for achieving realistic appearance in rendering visual objects will be discussed in later chapters.

The geometric configuration that defines the process of mapping a 3D virtual world scene to a 2D image is called a *view*. A view is the digital analogy of a camera. It defines the way that the virtual world and the graphics model are visualized. The views in a modern computer graphics system can be quite sophisticated and may have a large number of parameters. The viewpoint of a view is typically located in the virtual world, and it "sees" the virtual world from a specific viewing orientation and direction. A view has certain defining properties, such as the type of 3D-to-2D projections, the field of view, front and back clipping planes, view plate size, and so on. A view may resemble a static camera, or it may act like an eye of a person that can change its position and properties dynamically.

Most low-level graphics APIs support only a *camera-based view* model. It is typically specified with two sets of parameters: the projection properties and the camera positioning. A limitation of the static view model is the difficulty in programming the dynamic view changes. For example, the viewing device in a graphics system may be a head-mounted camera with a head-tracking system. The *head-tracking* information is sent back to the system, causing continuous changes in view properties. The dynamic view will be quite complex for the application program to implement and will likely be platform dependent. Java 3D provides a versatile view system that incorporates both traditional view settings and supports for dynamic view changes. The effects of physical environment changes to the view can be automatically included through separate objects without explicitly changing the basic viewing structure. Applications can use the same scene graph for a variety of display options.

Another topic related to viewing is *picking*. View projection maps a 3D volume to a 2D image. Picking is a process of selecting world-space objects through the projected 2D image. It is therefore a partial inverse operation of projection. Picking facilitates interactions with a 3D scene from the rendered image. Through picking operations, for example, a user may select an object from the screen image and rotate or move the object with a mouse. Java 3D provides extensive support for picking at different levels.

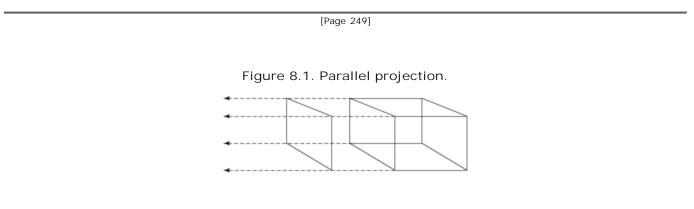
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The viewing of a 3D scene with a 2D image is achieved through a transformation called *projection*. There are two main types: *parallel projections* and *perspective projections*. In each case, a plane known as the *view plane* is placed in the virtual world. The projection maps the points in the virtual world to the plane. In order to make implementations feasible, certain restrictions on the projections will be necessary. Only a finite window (usually rectangular) on the view plane will actually be used for rendered images. This window is called a *view plate*. It is analogous to a frame of film in an ordinary camera. Only the points in the 3D space that project to the view plate need to be calculated. The points very close to or far away from the viewer are also excluded. This results in a finite volume in the 3D space that will actually participate in the projection. This volume is known as the *view frustum*.

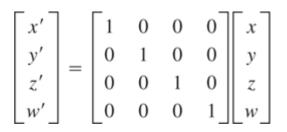
A *parallel projection* projects 3D points to a view plane through parallel lines in a fixed direction. When the lines of the projection are perpendicular to the view plane, the parallel projection is called *orthographic*. Three orthographic projections along the three axes are known as the *front-elevation*, *top-elevation*, and *side-elevation* projections. They are often used in engineering drawings. The view volume for a view with a parallel projection is a parallelogram. (See Figure 8.1.)



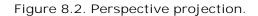
The formulas for parallel projections are relatively simple. Suppose that the view plane is the xy-plane and the projection is in the direction of the z-axis. Then a point (x, y, z) in the 3D space is simply mapped to the point (x, y) in the 2D view plane. The transformation is given by the matrix equation

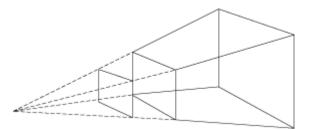
$\begin{bmatrix} x' \end{bmatrix}$		1	0	0	0	$\begin{bmatrix} x \end{bmatrix}$
y' z'	_	0	1	0	0	y
<i>z</i> ′	=	0	0	0	0	z
_w'_		0	0	0	1	$\lfloor w \rfloor$

In fact for purposes such as determining the hidden portions of objects, it is usually desirable to retain the information of the *z*-coordinates while performing the projection. Therefore, this parallel projection is essentially the identity transform:



In a *perspective projection*, all projection lines converge to the viewpoint (the viewer or eye position) (Figure 8.2). Objects closer to the viewer will appear larger than the distant objects. This mode resembles the projection in human eyes and regular cameras.





The mathematical formulas for perspective projection are more complex. Assume that the view plane is the xy-plane and the eye is at (0, 0, d) looking down the z-axis, with the y-axis being the view up direction, as illustrated in Figure 8.3.

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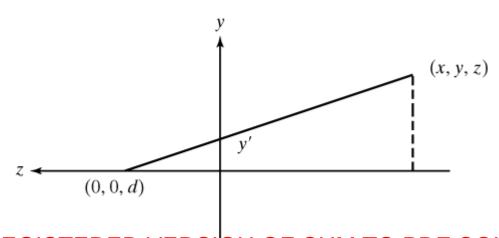


Figure 8.3. An example of perspective projection.

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Considering the two similar triangles, we have

$$\frac{y'}{d} = \frac{y}{d+(-z)}$$

or

$$y' = \frac{y}{1 - z/d}$$

Similarly, in the *x*-direction

$$x' = \frac{x}{1 - z/d}$$

Therefore the transformation is not linear in the 3D space. However, it can be expressed in a linear form with homogeneous coordinates, as shown in the following equation:

<i>x</i> ′		1	0	0	0	$\begin{bmatrix} x \end{bmatrix}$
<i>y</i> ′	_	0	1	0	0	y
<i>z</i> ′	-	0	0	0 - 1/d	0	z
_w'_		0	0	-1/d	1	$\begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix}$

If the *z*-coordinate is to be retained, then the transformation becomes

$\begin{bmatrix} x' \end{bmatrix}$		1	0	$0 \\ 0 \\ 1 \\ -1/d$	0	$\begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix}$
y'	_	0	1	0	0	y
<i>z</i> ′	_	0	0	1	0	z
_w'_		0	0	-1/d	1	w

In fact, using homogeneous coordinates and the 4 x 4 transformation matrices, parallel projections and

perspective projections can be treated in a uniform way. Both types of projections are projective transformations and can be represented with 4 x 4 matrices. Clearly if d approaches infinity,

$$\lim_{d \to \infty} (-1/d) = 0$$

The above matrix becomes the parallel projection matrix introduced earlier. A parallel projection can be regarded as a special case of perspective projection with the viewpoint at infinity. The viewpoint for the perspective projection has coordinates (0, 0, a), or homogeneous coordinates (0, 0, 1, 1/a). As  $a \rightarrow \infty$ , the viewpoint approaches (0, 0, 1, 0), a point at infinity in homogeneous coordinates.

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## 8.3. Specification of a View

The complete specification of a view can be divided into two parts: the view-volume definition and the view positioning. If a view is regarded as a camera, then the view volume corresponds to the characteristics of the camera itself, such as the focal length and the film size, and the view positioning corresponds to the position and aiming direction of the camera.

The definition of a view volume is often represented by a *projection matrix*. The view positioning is represented by a *viewing matrix*.

The following parameters are related to the definition of a view volume or projection matrix:

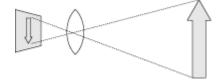
- Projection parallel or perspective projection.
- View plate the window for the rendered image. It is usually a rectangular region. In a real camera the view plate corresponds to the film frame.
- Field of view (fov) the horizontal angle between the left and right plane of the frustum. The vertical field of view and the diagonal field of view can be defined similarly.
- Focal length the distance between the view plate and the view point.
- Aspect ratio the ratio of width over length of the view planes.
- Front clip plane the front or near plane of the frustum.
- Back clip plane the back or far plane of the frustum.

Not all the above parameters are independent. For example, the focal length, the horizontal field of view, and the width of the view plate are related by the formula:

$$\tan\frac{fov}{2} = \frac{width/2}{f}$$

A 35 mm camera with a standard 50 mm lens has a film size 36 mm by 24 mm, a field of view of 40 degrees, and an aspect ratio of 1.5. In a real camera, the film is placed behind the lens and the projected image is upside down, as illustrated in Figure 8.4. In computer graphics, however, the film is exactly symmetrical to the image plate. Rather than using the inverted images, it is more convenient to formulate the viewing system with the view plate in front of the eye.

Figure 8.4. A real camera projection.



The *projection matrix* is defined in the eye coordinate system in which the eye is located at the origin looking at the negative direction of the z-axis with the y-axis as the up direction. The projection matrix encapsulates the view-volume settings by defining a projective transform that maps the given view volume (a frustum or box) to a standard volume, typically the cube with vertices  $(\pm 1, \pm 1, \pm 1)$ . For example, consider a view frustum defined by the front plane with vertices  $(\pm a, \pm b, -c)$  and the back plane with vertices  $(\pm a, \pm b, -d)$ . In the x- and y-directions, using the arguments in Section 8.2, the projection has the form

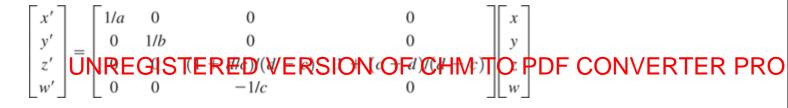
$$x' = \frac{x/a}{-z/c}$$
$$y' = \frac{y/b}{-z/c}$$

#### [Page 252]

In the z-direction, the transform maps the interval [-d, -c] to [-1, 1] and has the form

$$z' = \frac{1 + (1 + d/c)(z + c)/(d - c)}{-z/c}$$

Therefore, the projection can be expressed in the matrix form:



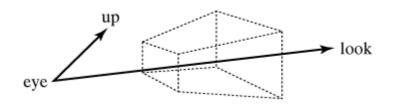
To completely define a camera or eye's positioning in the virtual space, it is necessary to specify the location of the camera, the direction in which the camera is pointing, and the direction that the camera considers as the "up" direction. The following parameters are usually associated with the definition of camera positioning or the *viewing matrix*.

- Viewpoint, view-reference point (vrp, eye) the camera or eye position, the 3D point where the camera is located.
- View center (look) the center of the view plate or the point that the eye is looking at.
- View up direction (up) the upward direction from a viewer's perspective.
- View plane the plane of the projected image.
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The viewpoint is easily specified with a 3D point. However, the viewpoint alone is not enough to completely define the camera's positioning. Clearly, at a fixed point, the camera can still point in different directions. There are several ways to define such an orientation of an object in a 3D space. For example, the pitch–roll–yaw specification is often used to describe an aircraft position.

In computer graphics, a commonly used method for defining camera orientation is to specify the view reference point, the view center, and the view up direction, as illustrated in Figure 8.5.

Figure 8.5. Viewing matrix definition with eye, look, and up.



A viewing matrix specifies the camera position by defining a transform that changes the camera from its standard position. The standard camera position (when the viewing matrix is identity) is the one defined by the eye coordinate system, typically with the eye at the origin looking down the z-axis and with the y-axis as the up direction. If the viewpoint is moved to (a, b, c) without changing its orientation, the viewing matrix will be:

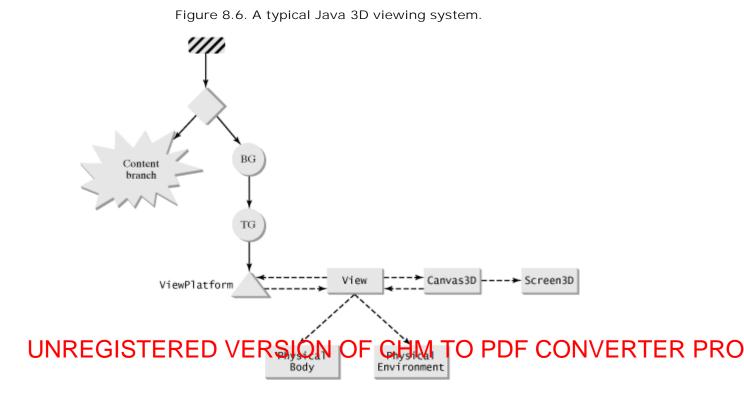
1	0	0	-a
0	1	0	-a -b
0	0	1	-c
0	0	0	1

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## 8.4. Java 3D View Model

Java3D provides a very versatile viewing system that supports dynamic adjustments based on environmental changes as well as traditional static camera based viewing. The scene graph in Figure 8.6 illustrates a typical view setting. Attached to a Locale object are a content branch that defines the virtual world graphics model, and a view branch that defines a view to render the scene.



Java 3D classes that are directly related to viewing include: ViewPlatform, View, PhysicalBody, PhysicalEnvironment, Canvas3D, Screen3D.

## 8.4.1. Configuring a Java 3D View

A ViewPlatform object is a leaf node of the scene graph. It defines the presence of the view in the virtual world. Like other scene-graph nodes, the ViewPlatform object may go through a chain of transforms and other nodes, and it will eventually be attached to a Locale object. The TransformGroup node connected to the ViewPlatform defines the view-platform transformation that primarily determines the position and orientation of the view, or the viewing matrix. The viewing matrix may be affected by other factors such as the head-tracking sensor input. The Transform3D class has a method that helps in the construction of this transform:

void lookAt(Point3d eye, Point3d look, Vector3d up)

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The transform is constructed to position the ViewPlatform so that the eye is located at the given point looking

at the specified center of the view plate with the given upward direction. The inverse of the transform defined by the method can be placed in the TransformGroup above the ViewPlatform to realize the specified positioning of the ViewPlatform.

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The View object is the heart of the view system. It defines the main configuration of the view with properties such as the projection type and the view volume—that is, the projection matrix of the view. It can also accommodate the dynamic changes in view parameters through its connections with the PhysicalBody and PhysicalEnvironment objects. The methods of the View class for setting the view volume or projection matrix include:

```
void setFieldOfView(double fov)
void setFrontClipDistance(double d)
void setBackClipDistance(double d)
void setProjectionPolicy(int projection)
```

The PhysicalBody and PhysicalEnvironment objects provide supports for automatic calibrations with dynamic viewing systems such as head-mounted-camera and head-tracking sensors. The PhysicalBody describes the physical characteristics of the user's body or head. The PhysicalEnvironment contains information about the user's physical environment such as the tracking sensors.

The Canvas3D class is a subclass of AWT Canvas class and can be placed in an AWT container. A Canvas3D object represents the rendering surface. The following constructor is typically used to construct a Canvas3D object:

```
public Canvas3D(GraphicsConfiguration gc)
```

A separate Screen3D class is defined to describe the display devices. It is referenced by a Canvas3D object. The separation of the device description avoids duplication of the same information for multiple Canvas3D objects. The Screen3D class has no public constructor, and its instance can be retrieved by the method getScreen3D of the Canvas3D class.

## 8.4.2. The Compatibility Mode

Java 3D also offers a compatibility view mode that supports traditional camera-based model resembling OpenGL view specification. To enable the *compatibility mode*, the following method of the View object can be used:

```
public void setCompatibilityModeEnable(boolean enabled)
```

The Transform3D class contains methods for constructing the viewing matrix and the projection matrix. The viewing matrix can be constructed using the same eye-look-up approach

```
public void lookAt(Point3d eye, Point3d look, Vector3d up)
```

The projection matrix can be constructed with one of the three different methods:

public void perspective(double fov, double aspect, double near, double far) public void frustum(double left, double right, double bottom, double top, double near, double far) public void ortho(double left, double right, double bottom, [Page 255]

The coordinates in these methods are relative to the eye position or vrp. The perspective method defines a perspective projection matrix by specifying the horizontal field of view, the aspect ratio, and the near and far clip planes. Both the frustum method and the ortho method define the projection matrix by specifying the corner coordinates of the view volume. (left, bottom, -near) and (left, bottom, -near) define the lower left corner and the upper right corner of the near plane. The depth of the far plane is defined by -far. The frustum method defines a perspective projection and the ortho method a parallel projection.

For example, the following two calls define the same perspective projection:

perspective(Math.PI/2, 2, 1, 2); frustum(-1,1, -0.5, 0.5, 1, 2);

The view volume has a horizontal field of view p/2 and an aspect ratio of 2.0. The near-plane distance is 1 and the far-plane distance 2. The near plane is 2 x 1 and the far plane 4 x 2. Assuming the near plane is the view plate, the projection can be written as:

$$x' = \frac{x}{-z}$$

$$y' = \frac{2y}{-z}$$



The projection matrix for the projection is given by:

1	0	0	0
0	2	0	0
0	0	3	4
0	0	-1	0

The appropriately constructed projection matrix and viewing matrix can be set for the view using the following methods of the convertee of the view using the following methods of the convertee of the view using the following the following methods of the view using the following the following methods of the view using the following the following methods of the view using the view using the following methods of the view using the view usin

public void setVpcToEc(Transform3D viewingMatrix)

```
public void setLeftProjection(Transform3D projectionMatrix)
public void setRightProjection(Transform3D projectionMatrix)
```

In the compatibility mode virtually all view parameters are set in the View object. On the other hand, in the standard (noncompatibility) Java 3D view mode, the final view settings may also be influenced by other objects such as PhysicalBody and PhysicalEnvironment. The above methods for directly setting the projection matrix and the viewing matrix are not valid in the noncompatibility mode.

The compatibility mode is a restricted view mode that does not have all the Java 3D view features. It is intended to be a simple mode compatible with OpenGL style calls.

Listing 8.1 displays a rotating tetrahedron using a manually constructed view in compatibility mode. It illustrates a minimal Java 3D view setting. (See Figure 8.7.)

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Listing 8.1. CompatibilityMode.java

(This item is displayed on pages 256 - 257 in the print version)

```
1 package chapter8;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
9 import chapter6.*;
10 import java.applet.*;
11 import com.sun.j3d.utils.applet.MainFrame;
12
13 public class CompatibilityMode extends Applet {
14
    public static void main(String[] args) {
15
       new MainFrame(new CompatibilityMode(), 640, 650);
16
    }
17
18
   public void init() {
19
     // create canvas
    GraphicsConfiguration gc =
20
21
     SimpleUniverse.getPreferredConfiguration();
22
    Canvas3D cv = new Canvas3D(gc);
23
    setLayout(new BorderLayout());
24
    add(cv, BorderLayout.CENTER);
25
     VirtualUniverse universe = new VirtualUniverse();
26
    Locale locale = new Locale(universe);
27
    BranchGroup bg = createView(cv);
28
     locale.addBranchGraph(bg);
29
     bg = createContent();
30
     bg.compile();
31
      locale.addBranchGraph(bg);
32 }
33
34 private BranchGroup createView(Canvas3D cv) {
35
    BranchGroup bg = new BranchGroup();
     ViewPlatform platform = new ViewPlatform();
36
37
   bg.addChild(platform);
38
   View view = new View();
```

```
39
      view.addCanvas3D(cv);
40
      view.setCompatibilityModeEnable(true);
41
      view.attachViewPlatform(platform);
42
      Transform3D projection = new Transform3D();
43
     projection.frustum(-0.1, 0.1, -0.1, 0.1, 0.2, 10);
44
      view.setLeftProjection(projection);
45
     Transform3D viewing = new Transform3D();
46
     Point3d eye = new Point3d(0,0,1);
     Point3d look = new Point3d(0,0,-1);
47
     Vector3d up = new Vector3d(0,1,0);
48
49
     viewing.lookAt(eye, look, up);
50
     view.setVpcToEc(viewing);
     PhysicalBody body = new PhysicalBody();
51
52
      view.setPhysicalBody(body);
53
      PhysicalEnvironment env = new PhysicalEnvironment();
54
      view.setPhysicalEnvironment(env);
55
     return bg;
56
  }
57
[Page 257]58 private BranchGroup createContent() {
59
      BranchGroup root = new BranchGroup();
60
      TransformGroup spin = new TransformGroup();
61
      spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
62
     root.addChild(spin);
63
     // object
     Appearance ap = new Appearance();
64
65
      ap.setMaterial(new Material());
      Shape3D shape = new Shape3D(new Tetrahedron(), ap);
66
67
     // rotating object
68
     Transform3D tr = new Transform3D();
69
     tr.setScale(0.25);
70
     TransformGroup tg = new TransformGroup(tr);
71
     spin.addChild(tg);
72
      tg.addChild(shape);
73
     Alpha alpha = new Alpha(-1, 4000);
74
      RotationInterpolator rotator =
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75
76
77
      rotator.setSchedulingBounds(bounds);
78
      spin.addChild(rotator);
79
      // light and background
      Background background = new Background(1.0f, 1.0f, 1.0f);
80
      background.setApplicationBounds(bounds);
81
82
      root.addChild(background);
83
     AmbientLight light =
84
     new AmbientLight(true, new Color3f(Color.red));
85
      light.setInfluencingBounds(bounds);
86
      root.addChild(light);
87
      PointLight ptlight = new PointLight(new Color3f(Color.green),
88
          new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
89
      ptlight.setInfluencingBounds(bounds);
90
      root.addChild(ptlight);
91
      PointLight ptlight2 = new PointLight(new Color3f(Color.orange),
92
          new Point3f(-2f,2f,2f), new Point3f(1f,0f,0f));
93
      ptlight2.setInfluencingBounds(bounds);
94
      root.addChild(ptlight2);
95
      JNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
96
97 }
```

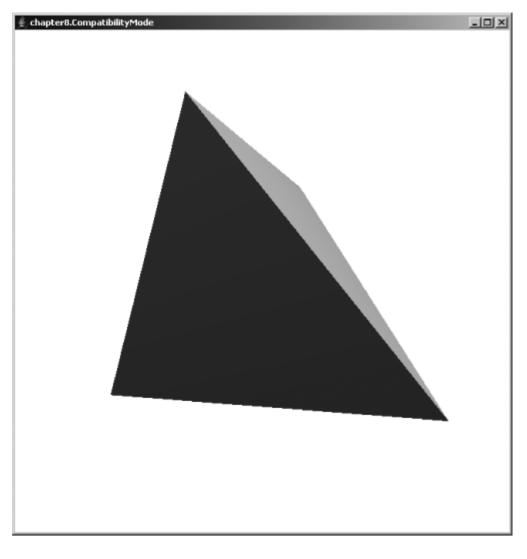


Figure 8.7. A view using compatibility mode. (This item is displayed on page 258 in the print version)

[Page 257]

This program creates all the components of the scene graph directly without using the utility classes. The Canvas3D, VirtualUniverse, and Locale objects are created in the constructor. The createView method (line 34) creates the view branch of the scene and the createContent method creates the content branch.

The createView method constructs the objects in the view branch: a BranchGroup, a ViewPlatform, a View, a PhysicalBody, and a PhysicalEnvironment. It enables the compatibility mode for the View object (line 40). The projection matrix is set to a perspective projection by calling the method frustum (line 43). The near clip plane is defined by the corners (-0.1, -0.1, -0.2) and (0.1, 0.1, -0.2). The far clip-plane distance is 10. The viewing matrix is created with the method lookAt to place the eye at (0, 0, 1) looking at the point (0,0, -1) with (0, 1, 0) as the up direction (line 49). Both the projection and viewing matrices are set in the View object

directly with the methods setLeftProjection and setVpcToEc. Even though head tracking is not available in compatibility mode, it is still necessary to supply the PhysicalBody and PhysicalEnvironment objects to the View.

The createContent method constructs the content branch of the scene graph. It consists of a rotating tetrahedron similar to the program in Listing 6.1.

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## 8.4.3. View Settings in **SimpleUniverse**

The SimpleUniverse utility class provides a default implementation for the viewing system illustrated in Figure 8.4. The SimpleUniverse further divides the view-related components objects into two classes: the Viewer class and the ViewingPlatform class. The Viewer object consists of a View object, a ViewAvatar object, a PhysicalBody object, a Physical Environment object, and a set of Canvas3D objects. The ViewingPlatform object and a MultiTransformGroup object that holds a series of TransformGroup nodes linked together. The default ViewingPlatform has one Trans formGroup node in its MultiTransformGroup object, but SimpleUniverse has constructors to specify multiple TransformGroup nodes:

```
SimpleUniverse(int numTrans)
SimpleUniverse(Canvas3D canvas, int numTrans)
```

To retrieve the View from a SimpleUniverse object, you may use the following statement:

```
View view = su.getViewer().getView();
```

To obtain the TransformGroup node above the ViewPlatform, you may make the following method calls:

TransformGroup tg = su.getViewingPlatform().getViewPlatformTransform();

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To get a specific TransformGroup in the MultiTransformGroup object, use the following calls:

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su.getViewingPlatform().getMultiTransformGroup().getTransformGroup(idx);

The default view settings in a SimpleUniverse object are given below:

- Compatibility mode: false
- Left projection: identity
- Right projection: identity
- vpc-to-ec transform: identity
- Field of view: p/4
- Front clip distance: 0.1

```
• Back clin distance: 10
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The following code fragment changes the default settings in a SimpleUniverse object. The ViewPlatform is
```

moved to (1,1,1) looking at the origin. The field of view is set to 0.4p:

```
SimpleUniverse su = new SimpleUniverse(cv);
TransformGroup tg =
    su.getViewingPlatform().getMultiTransformGroup().getTransformGroup(0);
Transform3D tx = new Transform3D();
tx.lookAt(new Point3d(1,1,1), new Point3d(0,0,0), new Vector3d(0,1,0));
tx.invert();
tg.setTransform(tx);
View view = su.getViewer().getView();
view.setFieldOfView(0.4*Math.PI);
```

Listing 8.2 illustrates the applications of SimpleUniverse and the effects of controlling standard Java 3D views. This example displays a dodecahedron in a rotating view. The visual object in the content branch, a dodecahedron, is in a fixed position. However, the view is set to rotate about the y-axis, allowing the user to see the different sides of the dodecahedron (See Figure 8.8.)



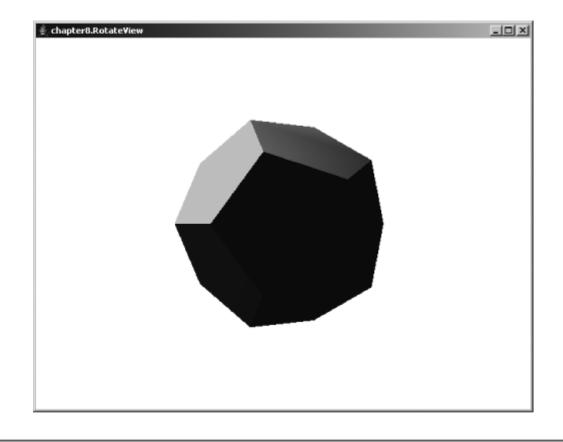
(This item is displayed on pages 259 - 260 in the print version)

```
1 package chapter8;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
 9 import chapter6.*;
10 import java.applet.*;
11 import com.sun.j3d.utils.applet.MainFrame;
12
13 public class RotateView extends Applet {
   public static void main(String[] args) {
14
15
       new MainFrame(new RotateView(), 640, 480);
16
    }
17
18
    public void init() {
      // create canvas
19
[Page 260]20
              GraphicsConfiguration gc =
         SimpleUniverse.getPreferredConfiguration();
21
22
       Canvas3D cv = new Canvas3D(gc);
23
       setLayout(new BorderLayout());
24
       add(cv, BorderLayout.CENTER);
25
       SimpleUniverse su = new SimpleUniverse(cv, 2);
26
       su.getViewingPlatform().setNominalViewingTransform();
27
       BranchGroup bg = createSceneGraph(su.getViewingPlatform().
28
         getMultiTransformGroup().getTransformGroup(0));
29
       bg.compile();
30
       su.addBranchGraph(bg);
31
    }
32
33
    private BranchGroup createSceneGraph(TransformGroup vtg) {
34
       BranchGroup root = new BranchGroup();
35
       // object
36
       Appearance ap = new Appearance();
37
       ap.setMaterial(new Material());
```

```
38
       Shape3D shape = new Dodecahedron();
39
       shape.setAppearance(ap);
40
       Transform3D tr = new Transform3D();
41
       tr.setScale(0.25);
42
       TransformGroup tg = new TransformGroup(tr);
43
       root.addChild(tg);
44
       tg.addChild(shape);
45
       // view rotator
46
       Alpha alpha = new Alpha(-1, 4000);
47
       RotationInterpolator rotator =
48
       new RotationInterpolator(alpha, vtg);
       BoundingSphere bounds = new BoundingSphere();
49
50
       rotator.setSchedulingBounds(bounds);
51
       root.addChild(rotator);
52
       // lights
       Background background = new Background(1.0f, 1.0f, 1.0f);
53
54
       background.setApplicationBounds(bounds);
55
       root.addChild(background);
       AmbientLight light = new AmbientLight
56
57
         (true, new Color3f(Color.red));
       light.setInfluencingBounds(bounds);
58
59
       root.addChild(light);
60
       PointLight ptlight = new PointLight(new Color3f(Color.green),
61
          new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
62
       ptlight.setInfluencingBounds(bounds);
63
       root.addChild(ptlight);
64
       PointLight ptlight2 = new PointLight(new Color3f(Color.orange),
65
         new Point3f(-2f,2f,2f), new Point3f(1f,0f,0f));
66
       ptlight2.setInfluencingBounds(bounds);
67
       root.addChild(ptlight2);
68
       return root;
69
     }
70 }
```

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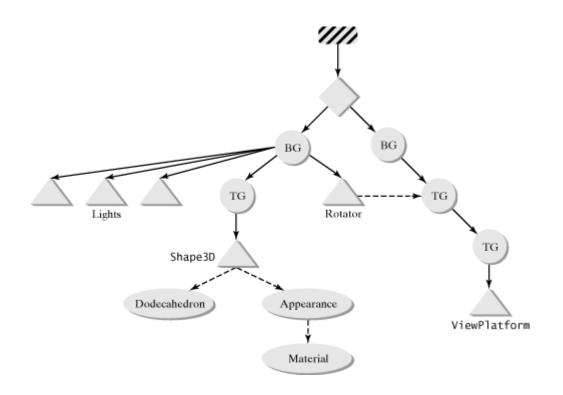
Figure 8.8. A rotating view lets you see the back sides of an object. (This item is displayed on page 261 in the print version)



[Page 260]

The scene graph is shown in Figure 8.9. This program is similar to Listing 6.3. However, in this case the rotation behavior is not applied to the visual object (a dodecahedron) but to the view (line 48). The object appears to be rotating in the opposite direction. But because the lights do not move, the lighting of the faces does not change as the view rotates. We can even see the unlit back faces.

Figure 8.9. The scene graph of the view-rotation example. (This item is displayed on page 261 in the print version)



The SimpleUniverse is created with two TransformGroup nodes (line 25). One transform node is used by the setNominalViewTransform method to move the view back. The other transform node is the target of the rotation.

[Page 261]

## 8.4.4. Creating Your Own View

Even though simple in our septrovides a corporter way of construct the view branch for many lava Septer PRC applications, it may not be adequate in some cases. You can always construct the view branch manually by setting up the appropriate view-related objects such as View, ViewPlatform, PhysicalBody, PhysicalEnvironment, and so on. The following code illustrates the procedure to manually *create a view branch:* 

```
[Page 262]
View view = new View();
view.setProjectionPolicy(View.PARALLEL_PROJECTION);
ViewPlatform vp = new ViewPlatform();
view.addCanvas3D(cv);
view.attachViewPlatform(vp);
view.setPhysicalBody(new PhysicalBody());
view.setPhysicalEnvironment(new PhysicalEnvironment());
Transform3D trans = new Transform3D();
trans.lookAt(eye, center, vup);
trans.invert();
TransformGroup tg = new TransformGroup(trans);
tg.addChild(vp);
BranchGroup
                            DWERSION OF CHM TO PDF CONVERTER PRO
bgView.addChild(tq)?
```

A scene graph may contain more than one view. Multiple views on a single scene graph allow you to see the same virtual world from different perspectives.

Listing 8.3 shows an application with multiple views. The same object, a rotating 3D text, is rendered with four different views. One is a standard perspective view provided by the SimpleUniverse. The other three have parallel projections in the  $x_{-}$ ,  $y_{-}$ , and  $z_{-}$  directions. (See Figure 8.10.)

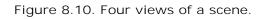
#### Listing 8.3. MultipleViews.java

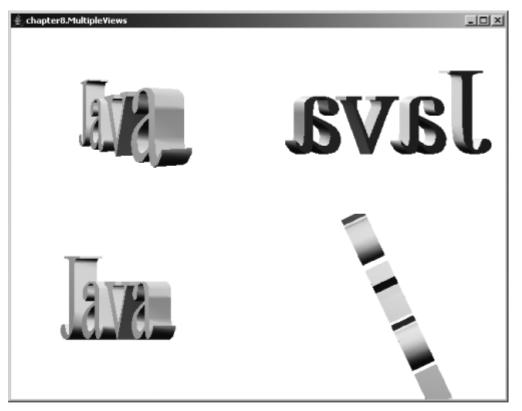
(This item is displayed on pages 262 - 264 in the print version)

```
1 package chapter8;
 2
 3 import javax.vecmath.*;
  4 import java.awt.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
 9 import java.applet.*;
10 import com.sun.j3d.utils.applet.MainFrame;
11
12 public class MultipleViews extends Applet {
13 public static void main(String[] args) {
14
        new MainFrame(new MultipleViews(), 640, 480);
15
    }
16
17
    public void init() {
18
      // create 4 Canvas3D objects
19
        this.setLayout(new GridLayout(2,2));
20
        GraphicsConfiguration gc =
 21
        SimpleUniverse.getPreferredConfiguration();
22
       // first view: standard
23
       Canvas3D cv = new Canvas3D(gc);
 24
       add(cv);
 25
      SimpleUniverse su = new SimpleUniverse(cv);
 26
       su.getViewingPlatform().setNominalViewingTransform();
27
       // second view: x direction
28
       cv = new Canvas3D(gc);
29
       add(cv);
30
       BranchGroup bgView = createView(cv, new Point3d(2.7,0,0),
31
        new Point3d(0,0,0), new Vector3d(0,1,0));
32
       su.addBranchGraph(bgView);
33
       // third view: z direction
[Page 263] 34
               cv = new Canvas3D(gc);
       add(cv);
35
       bgView = createView(cv, new Point3d(0, 0, 2.7),
36
37
        new Point3d(0,0,0), new Vector3d(0,1,0));
38
       su.addBranchGraph(bgView);
 39
       // fourth view: y direction
 40
       cv = new Canvas3D(qc);
 41
       add(cv);
 42
       bgView = createView(cv, new Point3d(0,2.7,0),
 43
        new Point3d(0,0,0), new Vector3d(0,0,1));
 44
        su.addBranchGraph(bgView);
 45
       // content branch
 46
        BranchGroup bg = createSceneGraph();
 47
       bg.compile();
 48
       su.addBranchGraph(bg);
```

```
49
      }
 50
      private BranchGroup createView(Canvas3D cv, Point3d eye,
 51
        Point3d center, Vector3d vup) {
 52
 53
        View view = new View();
 54
        view.setProjectionPolicy(View.PARALLEL_PROJECTION);
 55
        ViewPlatform vp = new ViewPlatform();
 56
        view.addCanvas3D(cv);
        view.attachViewPlatform(vp);
 57
 58
        view.setPhysicalBody(new PhysicalBody());
        view.setPhysicalEnvironment(new PhysicalEnvironment());
 59
        Transform3D trans = new Transform3D();
 60
 61
        trans.lookAt(eve, center, vup);
 62
        trans.invert();
 63
        TransformGroup tg = new TransformGroup(trans);
 64
        tg.addChild(vp);
 65
        BranchGroup bgView = new BranchGroup();
 66
        bgView.addChild(tg);
 67
        return bgView;
 68
     }
 69
 70
     private BranchGroup createSceneGraph() {
        BranchGroup root = new BranchGroup();
 71
 72
        TransformGroup spin = new TransformGroup();
 73
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 74
       root.addChild(spin);
 75
        // object
 76
        Font3D font = new Font3D(new Font("Serif", Font.PLAIN, 1),
 77
         new FontExtrusion());
 78
        Text3D text = new Text3D(font, "Java");
 79
        Appearance ap = new Appearance();
 80
        ap.setMaterial(new Material());
 81
        Shape3D shape = new Shape3D(text, ap);
 82
        Transform3D tr = new Transform3D();
 83
        tr.setTranslation(new Vector3f(-1f, -0.25f, 0f));
 84
        TransformGroup tg = new TransformGroup(tr);
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 85
 86
 87
        // rotator
 88
        Alpha alpha = new Alpha(-1, 24000);
 89
        RotationInterpolator rotator = new RotationInterpolator
 90
          (alpha, spin);
 91
        BoundingSphere bounds = new BoundingSphere();
 92
        rotator.setSchedulingBounds(bounds);
 93
        spin.addChild(rotator);
               // background and light
[Page 264] 94
        Background background = new Background(1.0f, 1.0f, 1.0f);
 95
 96
        background.setApplicationBounds(bounds);
 97
        root.addChild(background);
        AmbientLight light = new AmbientLight
 98
 99
          (true, new Color3f(Color.red));
100
        light.setInfluencingBounds(bounds);
101
        root.addChild(light);
102
        PointLight ptlight = new PointLight(new Color3f(Color.green),
103
          new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
        ptlight.setInfluencingBounds(bounds);
104
       NREGISTERED VERSION OF GHMATO PDF CONVERTER PRO
105
106
107
          new Point3f(-2f,2f,2f), new Point3f(1f,0f,0f));
```

```
108 ptlight2.setInfluencingBounds(bounds);
109 root.addChild(ptlight2);
110 return root;
111 }
112 }
```





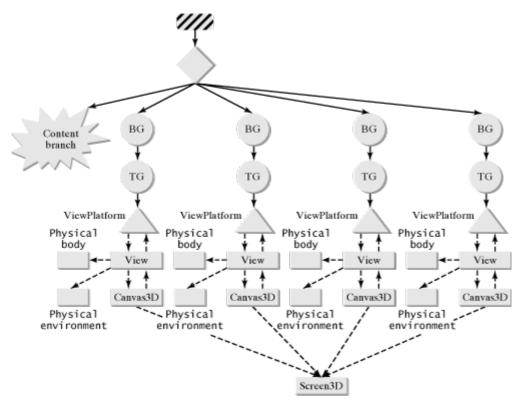
This program creates four different views in the same scene graph. One view is the standard view in a SimpleUniverse with a perspective projection. The other three have parallel projections along the x-, y-, z- axes. Consequently, they are the front-elevation, top-elevation, and side-elevation projections found in engineering drawings.

The scene graph for the example is given in Figure 8.11. Four Canvas3D objects are placed in a grid. The createView method (line 51) creates the necessary objects for a parallel view. Each view has separate instances of BranchGroup, TransformGroup, ViewPlatform, View, PhysicalBody, PhysicalEnvironment. The type of projection is set with a method in View

view.setProjectionPolicy(View.PARALLEL\_PROJECTION);

[Page 265]

Figure 8.11. Scene graph of the multiple-view example.



The viewing matrix is set through the TransformGroup. The inverse of the matrix defined by the lookAt method is the appropriate matrix for the TransformGroup:

Transfold REGISTERED VERSION OF CHM TO PDF CONVERTER PRO

trans.lookAt(eye, center, vup); trans.invert(); TransformGroup tg = new TransformGroup(trans);

Three calls to createView method are made to create three different views. Each view rooted at a BranchGroup is attached to the Locale. The three views are linked to three Canvas3D objects to display the rendered images.

The method createSceneGraph sets up the content branch of the scene graph. The scene contains a rotating 3D text "Java," a background, and lights.

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[Page 265 (continued)]

## 8.5. Picking

It is sometimes necessary to consider the inverse process of the viewing. Given a point in the rendered view plate, one might want to determine the visual objects that project to the point. This is the process known as *picking*. A typical use of picking is to allow a user to select objects from the rendered image using a mouse.

Clearly a point in the 2D view plate does not correspond to a single point in the 3D virtual world under the projection. Instead, a ray of points will be projected to the point. If we treat the point more realistically as a disk of a positive radius, to allow a certain tolerance instead of an ideal point, then the pre-images of the point will be a cone (in perspective projections) or a cylinder (in parallel projections).

#### [Page 266]

Consider the simple projection given in Figure 8.3. If the coordinates (x, y) are in the view plate, the coordinates (x, y, z) of the pick ray satisfy the equations

x = x'(1 - z'd)y = y'(1 - z'd)

If one chooses the parameter  $t = 1 - \mathcal{Z} d$ , then the line equation of the pick ray is

 $x = x^{t}t$  $y = y^{t}t$ z = o(1 - t)

If the point is considered as a disk with radius r, then the pick cone has the equation

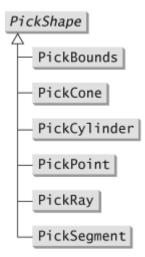
$$\left(\frac{x}{1-z/d} - x'\right)^2 + \left(\frac{y}{1-z/d} - y'\right)^2 = r^2$$

Java 3D offers several levels of support for picking operations. The core picking functionalities are supported by the PickShape classes, the SceneGraphPath class, and the pick methods in BranchGroup and Locale classes. The classes in the utility packages com.sun.j3d.utils.picking and com.sun.j3d.utils.picking.behavior provide high-level supports for picking operations.

A basic picking operation is performed by creating a PickShape object and calling a pick method in a BranchGroup or Locale. The results of the picking are returned as SceneGraphPath objects.

The PickShape family of classes defines various picking shapes. Figure 8.12. shows the hierarchy of pick shapes.

Figure 8.12. PickShape class hierarchy.



The BranchGroup and Locale classes contain the following methods to perform picking:

```
SceneGraphPath[] pickAll(PickShape pickShape)
SceneGraphPath[] pickAllSorted(PickShape pickShape)
SceneGraphPath pickAny(PickShape pickShape)
SceneGraphPath pickClosest(PickShape pickShape)
```

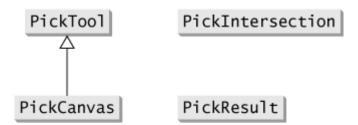
A SceneGraphPath object represents a path from the Locale object to a terminal node in a scene graph. SceneGraphPath is useful for picking, because in the result of a picking operation it is often necessary to know the entire path rather than just the picked node.

The following code fragment outlines the procedure to perform a picking on a BranchGroup:

```
[Page 267]Point3d origin = new Point3d(0,0,0);
Vecton3d Operion Ster PickShape = new PickShape = new PickShape (origin, direction);
SceneGraphPath[] paths = branchGroup.pickAll(pickShape);
for (int i = 0; i < paths.length; i++) {
        <operations on paths[i]...>
}
```

The most common application of picking is to allow users to select objects on a rendered image. To simplify this process, the utility package com.sun.j3d.utils.picking contains four classes for performing general picking operations on a branch of a scene graph (Figure 8.13).

Figure 8.13. Picking utility classes.



The PickTool class provides a convenient way to set up a pick shape and perform picking on a branch of scene graph. It has the following pick methods:

```
PickResult[] pickAll()
PickResult[] pickAllSorted()
PickResult pickAny()
PickResult pickClosest()
```

The PickCanvas subclass simplifies the pick shape setup by an association with a canvas. A mouse event can be used to automatically generate pick shape. The following constructor of PickCanvas establishes a connection with a Canvas3D object and a BranchGroup object. The picking operation will be performed on the branch, and the picking shape can be formed based on the mouse event on the canvas:

public PickCanvas(Canvas3D cv, BranchGroup bg)

A similar constructor exists for a Locale object:

public PickCanvas(Canvas3D cv, Locale lc)

The results of picking are returned in PickResult objects. PickResult contains information such as the picked node object, the SceneGraphPath, and the intersection. The PickIntersection class contains more detailed information about the intersection of the pick shape and the picked node.

Listing 8.4 illustrates a simple application of the picking utility classes. The scene in this example consists of six primitives: a sphere, a box, a cylinder, a cone, a tetrahedron, and a dodecahedron. They are rotating about the y-axis in a wireframe form. When the user clicks on one of the primitives, the object will take on an illuminated colored appearance. (See Figure 8.14.)

Listing 8.4. Picking.java

(This item is displayed on pages 267 - 270 in the print version)

```
1 package chapter8;
2
3 import javax.vecmath.*;
[Page 268] 4 import java.awt.*;
5 import java.awt.event.*;
6 import javax.media.j3d.*;
7 import com.sun.j3d.utils.universe.*;
8 import com.sun.j3d.utils.geometry.*;
9 import com.sun.j3d.utils.picking.*;
10 import chapter6.*;
11 import java.applet.*;
12 import com.sun.j3d.utils.applet.MainFrame;
13
```

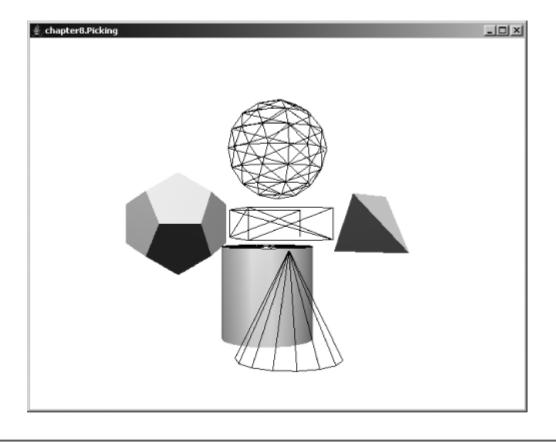
```
14 public class Picking extends Applet implements MouseListener{
     public static void main(String[] args) {
15
       new MainFrame(new Picking(), 640, 480);
16
17
     }
18
     PickCanvas pc;
19
     Appearance lit = new Appearance();
20
21
    public void init() {
22
23
       // create canvas
24
       GraphicsConfiguration gc =
 25
        SimpleUniverse.getPreferredConfiguration();
26
       Canvas3D cv = new Canvas3D(gc);
 27
       setLayout(new BorderLayout());
 28
       add(cv, BorderLayout.CENTER);
 29
       cv.addMouseListener(this);
 30
       BranchGroup bg = createSceneGraph();
31
       bg.compile();
32
       pc = new PickCanvas(cv, bg);
33
       pc.setMode(PickTool.GEOMETRY);
 34
        SimpleUniverse su = new SimpleUniverse(cv);
 35
        su.getViewingPlatform().setNominalViewingTransform();
 36
        su.addBranchGraph(bg);
37
     }
38
     private BranchGroup createSceneGraph() {
 39
 40
       BranchGroup root = new BranchGroup();
 41
        TransformGroup spin = new TransformGroup();
 42
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 43
       root.addChild(spin);
 44
       // appearance
 45
       Appearance wireframe = new Appearance();
 46
        wireframe.setPolygonAttributes(new PolygonAttributes(
 47
          PolygonAttributes.POLYGON_LINE,
 48
            PolygonAttributes.CULL_BACK, 0f));
 49
        wireframe.setColoringAttributes(new ColoringAttributes(
    UNREGISTERED WERSION OF CHM TO PDF CONVERTER PRO
 50
 51
52
       // objects
53
       Box box =
 54
       new Box(1.2f, 0.3f, 0.8f, Primitive.ENABLE_GEOMETRY_PICKING
55
         Primitive.ENABLE_APPEARANCE_MODIFY |
         Primitive.GENERATE_NORMALS, wireframe);
56
57
       Sphere sphere = new Sphere
         (1f, Primitive.ENABLE_GEOMETRY_PICKING |
58
59
         Primitive.ENABLE_APPEARANCE_MODIFY |
         Primitive.GENERATE_NORMALS, wireframe);
 60
       Cylinder cylinder = new Cylinder(1.0f, 2.0f,
 61
 62
         Primitive.ENABLE_GEOMETRY_PICKING |
63
         Primitive.ENABLE_APPEARANCE_MODIFY
64
         Primitive.GENERATE_NORMALS, wireframe);
[Page 269] 65
               Cone cone = new Cone
66
         (1.0f, 2.0f, Primitive.ENABLE_GEOMETRY_PICKING |
         Primitive.ENABLE_APPEARANCE_MODIFY |
67
          Primitive.GENERATE_NORMALS, wireframe);
68
 69
        Transform3D tr = new Transform3D();
       NREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 70
 71
 72
       spin.addChild(tg);
```

```
73
        tg.addChild(box);
 74
        tr.setIdentity();
 75
        tr.setTranslation(new Vector3f(0f,1.5f,0f));
 76
        TransformGroup tgSphere = new TransformGroup(tr);
 77
        tg.addChild(tgSphere);
 78
        tgSphere.addChild(sphere);
 79
         tr.setTranslation(new Vector3f(-1f,-1.5f,0f));
 80
        TransformGroup tgCylinder = new TransformGroup(tr);
 81
        tg.addChild(tgCylinder);
 82
        tgCylinder.addChild(cylinder);
 83
        tr.setTranslation(new Vector3f(1f,-1.5f,0f));
 84
        TransformGroup tgCone = new TransformGroup(tr);
 85
        tg.addChild(tgCone);
 86
        tgCone.addChild(cone);
 87
        Shape3D tetra = new Shape3D(new Tetrahedron(), wireframe);
 88
         PickTool.setCapabilities(tetra, PickTool.INTERSECT_TEST);
 89
         tetra.setCapability(Shape3D.ALLOW_APPEARANCE_WRITE);
 90
        tr = new Transform3D();
 91
        tr.setScale(0.12);
 92
        tr.setTranslation(new Vector3f(0f, 0f, -0.4f));
 93
        tg = new TransformGroup(tr);
 94
        spin.addChild(tg);
 95
        tg.addChild(tetra);
 96
        Shape3D shape = new Dodecahedron();
 97
        shape.setAppearance(wireframe);
 98
        PickTool.setCapabilities(shape, PickTool.INTERSECT_TEST);
 99
        shape.setCapability(Shape3D.ALLOW_APPEARANCE_WRITE);
100
        tr = new Transform3D();
101
        tr.setScale(0.12);
102
        tr.setTranslation(new Vector3f(0f, 0f, 0.4f));
103
        tg = new TransformGroup(tr);
104
        spin.addChild(tg);
105
        tg.addChild(shape);
106
        // rotation
107
        Alpha alpha = new Alpha(-1, 4000);
108
        RotationInterpolator rotator =
109
        new RotationInterpolator(alpha, spin);
110
        BoundingSphere bounds = new BoundingSphere();
111
        rotator.setSchedulingBounds(bounds);
112
        spin.addChild(rotator);
113
        // background and light
114
        Background background = new Background(1.0f, 1.0f, 1.0f);
115
        background.setApplicationBounds(bounds);
116
        root.addChild(background);
117
        AmbientLight light =
118
        new AmbientLight(true, new Color3f(Color.red));
119
        light.setInfluencingBounds(bounds);
120
        root.addChild(light);
121
        PointLight ptlight = new PointLight(new Color3f(Color.green),
122
          new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
123
        ptlight.setInfluencingBounds(bounds);
124
        root.addChild(ptlight);
125
        PointLight ptlight2 = new PointLight(new Color3f(Color.orange),
[Page 270]126
                  new Point3f(-2f,2f,2f), new Point3f(1f,0f,0f));
127
        ptlight2.setInfluencingBounds(bounds);
128
        root.addChild(ptlight2);
129
        return root;
130
      }
131
```

```
132
      public void mouseClicked(java.awt.event.MouseEvent mouseEvent) {
133
        pc.setShapeLocation(mouseEvent);
        PickResult[] results = pc.pickAll();
134
135
       for (int i = 0; (results != null) &&
136
          (i < results.length); i++) {</pre>
137
          Node node = results[i].getObject();
          if (node instanceof Shape3D) {
138
139
            ((Shape3D)node).setAppearance(lit);
140
            System.out.println(node.toString());
141
          }
142
        }
     }
143
144
145
      public void mouseEntered(java.awt.event.MouseEvent mouseEvent) {
146
      }
147
      public void mouseExited(java.awt.event.MouseEvent mouseEvent) {
148
149
    }
150
151
      public void mousePressed(java.awt.event.MouseEvent mouseEvent) {
152
      }
153
154
      public void mouseReleased(java.awt.event.MouseEvent mouseEvent) {
155
      }
156 }
```

Figure 8.14. Picking demo.

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[Page 271]

Six visual objects—a sphere, a box, a cone, a cylinder, a tetrahedron, and a dodecahedron—are displayed in the wireframe form initially. When an object is clicked on with the mouse, it will change its appearance. It will become filled and illuminated by the lights.

The visual objects are created with a wireframe appearance. Permissions on each object are granted for picking and for appearance change.

A PickCanvas object is created (line 32) to perform the pick operation when a mouse click event is received on the Canvas3D object. The picked Shape3D object will change its appearance to enable lighting.

In the event handler mouseClicked, the picking shape is set according to the mouse location:

pc.setShapeLocation(mouseEvent);

The pickAll() method is called to retrieve all picked objects (line 134). For each of the picked Shape3D nodes, its appearance is changed.

Note that a primitive object may contain several Shape3D nodes, and a pick operation may not necessarily pick all the nodes associated with the primitive.

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#### [Page 271 (continued)]

## 8.6. Head Tracking

The settings of a view depend on the location and orientation of the eyes. If the viewer's head position changes, the view needs to be adjusted accordingly. Dynamically recalculating the projection matrix and viewing matrix for a view can be a very tedious task for application programmers. It is therefore desirable for an API to offer the head-tracking feature.

Java 3D view model provides support for automatic head tracking through a set of classes including View, Sensor, PhysicalBody, and PhysicalEnvironment.

The head tracking is based on the input from certain *6DOF* (six-degrees-of-freedom) tracking devices. Java 3D provides the InputDevice interface to define input devices. An implementation of InputDevice for a specific device offers an array of Sensor. A Sensor object provides the input data from the device. The following methods of InputDevice initialize the device and retrieve a Sensor object:

void initialize()
Sensor getSensor(int sensorIndex)

The PhysicalEnvironment object holds all registered input devices. To register an input device, you may use the following method of PhysicalEnvironment:

void addInputDevice(InputDevice device)

The PhysicalEnvironment object also maintains a list of associations between the 6DOF entities and sensors. For example, in a default PhysicalEnvironment object, the three predefined 6DOF entities—UserHead, DominantHand, and NondominantHand—have indices 0, 1, and 2, respectively. To assign a sensor to the UserHead, you may call the following method in PhysicalEnvironment:

setSensor(0, sensor);

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The head tracking in a view is by default disabled. To *enable head tracking*, call the following method in View:

view.setTrackingEnable(true);

There are two different mounting options for a display in a head-tracked view: room mounted and head mounted. To set this option, call the following method in View:

void setViewPolicy(int viewPolicy)

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The following flags can be used to set room-mounted or head-mounted view policies:

SCREEN\_VIEW HMD\_VIEW

In the head-mounted mode, it is also necessary to change the monoscopic view policy in the Canvas 3D object from vertice verti

canvas.setMonoscopicViewPolicy(View.LEFT\_EYE\_VIEW);

The visual representation of the viewer itself in the scene is called the *avatar*. The Viewer object in a SimpleUniverse object provides an option to include a viewer avatar:

```
ViewerAvatar avatar = new ViewerAvatar();
su.getViewer().setAvatar(avatar);
```

The ViewerAvatar is a subclass of BranchGroup, so the shapes for the avatar can be added to it as child nodes. The location of the avatar defined here is associated with the view platform, and it may not be the actual head position. Listing 8.5 demonstrates the head-tracking feature of the Java 3D view model using a "virtual input device." The class in Listing 8.5 uses the LineAxes class in Listing 8.6. The scene contains a simple rotating color cube on a background image. The virtual input device in a separate window provides a 6DOF input to control the head position. An avatar consisting of three axis lines is also added to the scene. The avatar is visible when the head is moved behind it.

Listing 8.5. HeadTracking.java

(This item is displayed on pages 272 - 273 in the print version)

```
1 package chapter8;
 2
 3 import java.awt.*;
 4 import java.awt.event.*;
 5 import com.sun.j3d.utils.geometry.ColorCube;
 6 import com.sun.j3d.utils.universe.*;
 7 import javax.media.j3d.*;
 8 import javax.vecmath.*;
 9 import java.net.URL;
10 import java.awt.image.*;
11 import javax.imageio.*;
12 import java.applet.*;
13 import com.sun.j3d.utils.applet.MainFrame;
14
15 public class HeadTracking extends Applet {
16
    public static void main(String[] args) {
17
       new MainFrame(new HeadTracking(), 500, 500);
18
     }
19
20
   public void init() {
21
      // create canvas
22
       GraphicsConfiguration gc =
23
       SimpleUniverse.getPreferredConfiguration();
24
       Canvas3D cv = new Canvas3D(qc);
25
      setLayout(new BorderLayout());
26
       add(cv, BorderLayout.CENTER);
27
       BranchGroup scene = createSceneGraph();
28
       SimpleUniverse su = new SimpleUniverse(cv);
29
       // add avatar
30
       LineAxes axes = new LineAxes(0.2f);
31
       Shape3D shape = new Shape3D(axes);
32
       ViewerAvatar va = new ViewerAvatar();
33
       va.addChild(shape);
34
       su.getViewer().setAvatar(va);
[Page 273]35
              // install the VirtualInputDevice
36
       String[] args = new String[0];
37
       InputDevice device = new VirtualInputDevice( args );
38
       device.initialize();
39
       PhysicalEnvironment pe = su.getViewer().getPhysicalEnvironment();
```

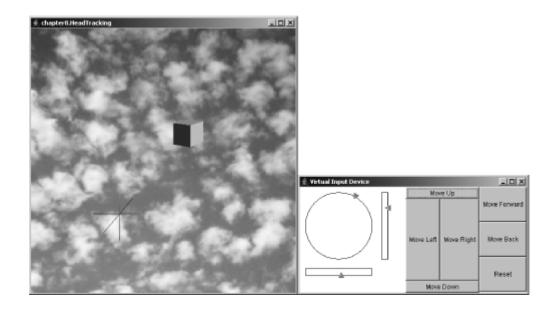
```
40
       pe.addInputDevice(device);
41
       pe.setSensor(0, device.getSensor(0));
42
       // set up head tracking
43
       su.getViewingPlatform().setNominalViewingTransform();
44
        pe.setCoexistenceCenterInPworldPolicy(View.NOMINAL_HEAD);
45
       View view = su.getViewer().getView();
46
       view.setUserHeadToVworldEnable(true);
       view.setCoexistenceCenteringEnable(false);
47
       Screen3D screen = cv.getScreen3D();
48
49
       Transform3D tr = new Transform3D();
       tr.setTranslation(new Vector3d(0.1, 0.1, 0.0));
50
51
       screen.setTrackerBaseToImagePlate(tr);
52
       view.setTrackingEnable(true);
53
       su.addBranchGraph(scene);
54
    }
55
56
     public BranchGroup createSceneGraph() {
57
       BranchGroup objRoot = new BranchGroup();
58
       TransformGroup objTrans = new TransformGroup();
59
       objTrans.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
60
       objRoot.addChild(objTrans);
61
       objTrans.addChild(new ColorCube(0.2));
       Transform3D yAxis = new Transform3D();
62
       Alpha rotationAlpha = new Alpha(-1, Alpha.INCREASING_ENABLE,
63
64
       0, 0,
65
       4000, 0, 0,
       0, 0, 0);
66
67
       RotationInterpolator rotator =
68
       new RotationInterpolator(rotationAlpha, objTrans, yAxis,
69
       0.0f, (float) Math.PI*2.0f);
70
       BoundingSphere bounds =
71
       new BoundingSphere(new Point3d(0.0,0.0,0.0), 100.0);
72
       rotator.setSchedulingBounds(bounds);
73
       objTrans.addChild(rotator);
74
       // background
       URL url = getClass().getClassLoader().getResource
75
      JNRECISTERED VERSION OF CHM TO PDF CONVERTER PRO
76
77
78
       try {
79
         bi = ImageIO.read(url);
80
       } catch (Exception ex) {
81
         ex.printStackTrace();
82
       }
       ImageComponent2D image =
83
84
       new ImageComponent2D(ImageComponent2D.FORMAT_RGB, bi);
85
       Background background = new Background(image);
86
       background.setApplicationBounds(bounds);
87
       objRoot.addChild(background);
88
       return objRoot;
89
    }
90 }
```

Listing RECONVERTER PRO

```
1 package chapter8;
 2
[Page 274] 3 import javax.media.j3d.*;
 4 import javax.vecmath.*;
 5
 6 public class LineAxes extends LineArray{
 7
    public LineAxes(float len) {
       super(6, LineArray.COORDINATES | LineArray.COLOR_3);
 8
9
      setCoordinate(0, new Point3f(-len,0f,0f));
10
      setCoordinate(1, new Point3f(len,0,0f));
11
      setCoordinate(2, new Point3f(0f,-len,0f));
12
      setCoordinate(3, new Point3f(0f,len,0f));
13
      setCoordinate(4, new Point3f(0f,0f,-len));
14
      setCoordinate(5, new Point3f(0f,0f,len));
       Color3f c0 = new Color3f(0f, 0f, 0f);
15
16
       Color3f c1 = new Color3f(1f, 0f, 0f);
17
       Color3f c2 = new Color3f(0f, 1f, 0f);
18
       Color3f c3 = new Color3f(0f, 0f, 1f);
19
      setColor(0, c0);
      setColor(1, c1);
20
21
     setColor(2, c0);
22
     setColor(3, c2);
23
     setColor(4, c0);
24
       setColor(5, c3);
25
   }
26 }
```

To demonstrate the view with head tracking, it is necessary to have a head-tracking device. A VirtualInputDevice class (which depends on three other classes: PositionControls, RotationControls, and WheelControls ) is included in the demo programs of the Java 3D package. It is an implementation of the InputDevice interface that provides 6DOF input through a separate control window. The control window, as shown in Figure 8.15, allows movements in three directions and rotations about three axes. The VirtualInputDevice is used in this example to avoid dependency on special hardware devices (line 37).

Figure 8.15. A head-tracking example. A virtual input device provides the simulated tracking input to the head-tracked view.

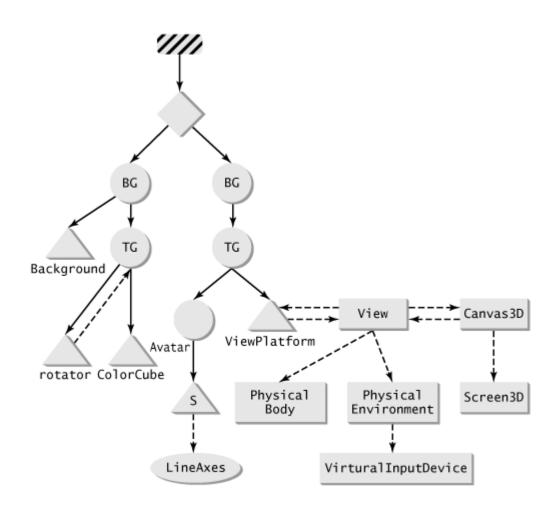


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The scene graph is shown in Figure 8.16. The graphics content branch contains a rotating cube on an imagebased background. The view branch is constructed with SimpleUniverse. A ViewerAvatar is added to help visualize the effects of head tracking (lines 29–34). The avatar is a set of coordinate axes defined by the geometry class LineAxes. LineAxes is a subclass of LineArray and it defines three colored line segments.

Figure 8.16. The scene graph for the head-tracking example.

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An instance of VirtualInputDevice is added to the PhysicalEnvironment (line 40). The first Sensor object from the VirtualInputDevice is retrieved and assigned as the sensor for the UserHead entity in PhysicalEnvironment (line 41). The head tracking is enabled by calling the setTrackingEnable method in View (line 52).

When head tracking is enabled, the origin of the default screen coordinate system is located at the lower left corner of the physical display. This is usually inconvenient. To change the origin, a translation is performed by calling the method setTrackerBaseToImagePlate (Transform3D) in Screen3D (line 51).

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[Page 275 (continued)]

## Key Classes and Methods

- javax.media.j3d.View A class encapsulating a 3D view.
- javax.media.j3d.ViewPlatform A leaf-node class representing the presence of a view in the virtual world.
- javax.media.j3d.Canvas3D An AWT component representing the drawing surface of Java 3D.
- javax.media.j3d.Screen3D A class encapsulating the physical display screen.
- javax.media.j3d.PhysicalBody A class encapsulating the body of the user.

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- javax.media.j3d.PhysicalEnvironment A class encapsulating the physical environment, including the sensor input devices.
- javax.media.j3d.InputDevice An interface defining an input device for tracking.
- javax.media.j3d.Sensor A class encapsulating tracking-device input values.
- **com.sun.j3d.util.universe.ViewerAvatar** A BranchGroup class for avatar objects attached to a Viewer in SimpleUniverse.
- javax.media.j3d.PickShape The root class of a family of classes for the picking shapes.
- javax.media.j3d.BranchGroup.pickAll(PickShape) A method to pick all child objects that intersect the pick shape. It is also available in Locale.
- javax.media.j3d.BranchGroup.pickAny(PickShape) A method to pick any child object that intersects to NREGISTER PRO
- javax.media.j3d.BranchGroup.pickSorted(PickShape) A method to pick all child objects that intersect the pick shape. It is also available in Locale.
- javax.media.j3d.BranchGroup.pickClosest(PickShape) A method to pick the closest child object that intersects the pick shape. It is also available in Locale.
- **com.sun.j3d.utils.picking.PickCanvas** A utility class for performing picking based on canvas coordinates.
- javax.media.j3d.View.setTrackingEnable(boolean) A method to enable head tracking.

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## [Pa

## Key Terms view volume

The portion of the virtual space that is visible in a view.

## projection matrix

A matrix defining the view volume.

## viewing matrix

A matrix defining the location and orientation of a view in the virtual space.

## perspective projection

A projection in which all projectors pass through a fixed point.

## parallel projection

A projection in which all projectors are parallel.

### vrp

View reference point, eye, or viewpoint. A point representing the eye position or center of projection.

## view center

A center location defining the direction in which the eye is looking.

## view up direction

A direction that is considered up from the viewer's perspective.

## FOV

Field of view. An angle for the visible portion of a view.

front clip plane

The front plane of a view frustum.

#### back clip plane

The back plane of a view frustum.

#### aspect ratio

The ratio of height and width for an image.

#### compatibility mode

A special Java 3D view mode that is highly compatible with traditional OpenGL view settings.

## 6DOF

Six degrees of freedom. A device that provides 3D location and orientation information.

#### avatar

A visual representation of the viewer itself in a 3D scene.

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## Chapter Summary

• In this chapter, you learn the concepts of 3D views. A view defines the geometric aspects of rendering a virtual world scene to a 2D image. There are two sets of attributes for the definition of a view: those related to view projection and volume, and those related to the view positioning.

## [Page 277]

- The projection matrix captures the projection and view-volume settings of a view. Two types of
  projections are commonly used in computer graphics: perspective projection and parallel projection. Both
  of them can be represented as matrices with homogenous coordinates and projective transformations.
  The projection matrix defines a projective transform that maps the specified view volume to a canonical
  volume such as a cube centered at the origin.
- The viewing matrix represents the camera's position and orientation in the virtual world. It is typically specified with a point for the camera's location, a point at which the camera is looking, and an up direction for the camera. The viewing matrix defines a transform that maps the camera from the specified position to a canonical position.
- Java 3D provides two different view modes: the compatibility mode and the standard noncompatibility mode. The compatibility mode offers a simple way to set up a static camera-based view similar to lower-level APIs such as OpenGL. The standard mode provides more powerful features such as supports for head-mount cameras and head tracking.
- Picking is a partial inversion of the viewing process. Picking refers to the selection of virtual world objects based on the specifications of certain pick shapes. A typical application of picking is to allow the user to select objects in a rendered image.
- Java 3D contains basic support for picking in scene graphs through the pick shape classes, pick methods in Locale and BranchGroup, and the BranchGroupPath class for pick results. Java 3D utility classes provide convenient classes to simplify common picking operations such as picking through mouse actions on a canvas.
- Head tracking is integrated in the Java 3D view model. When enabled, the head-tracking feature automatically calculates the appropriate view matrices based on the head-position information from input devices.

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## **Review** Questions

- 8.1 If a view frustum has a field of view p/4, and the two points (-1, 0, 0) and (1, 0, 0) are on the two horizontal boundaries of the frustum, find the viewpoint. (This is exactly the transform performed by setNominalViewTransform()).
- 8.2 Derive a matrix for the parallel projection along the direction (1, 0, 1) to the *xy*-plane.
- 8.3 Derive a matrix for the perspective projection with vrp at the origin and the view plate perpendicular to *z*-axis centered at (0, 0, 1).
- 8.4 Find the projection matrix for the view volume specified by the following method call: frustum(-3,3,-2,2,1,10)
- 8.5 Find the projection matrix for the view volume specified by the following method call: frustum(-2,2,-1,1,2,4)
- 8.6 Find the projection matrix for the view volume specified by the following method call: perspective(Math.PI/3,1.5,1,10)

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8.7 Find the projection matrix for the view volume specified by the following method call: ortho(-3,3,-2,2,1,10)

## 8.8 Find the projection matrix for the view volume specified by the following method call: UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

- 8.9 Find the viewing matrix for changing the view up direction to (1, 1, 0).
- 8.10 Find the viewing matrix specified by the following method call: Point3d eye = new Point3d(0,0,0); Point3d look = new Point3d(0,0,1); Vector3d up = new Vector3d(0,-1,0); lookAt(eye, look, up);
- 8.11 Find the viewing matrix specified by the following method call: Point3d eye = new Point3d(0,0,-1); Point3d look = new Point3d(0,0,0); Vector3d up = new Vector3d(1,0,0); lookAt(eye, look, up);

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## **Programming Exercises**

- 8.1 Write a Java 3D program to display a rotating ColorCube using a SimpleUniverse object. Modify the view platform transform to move the ViewPlatform to (0, 0, 3).
- 8.2 Modify the program in Listing 8.1 to use a parallel projection in the view.
- 8.3 Use a SimpleUniverse object to set up a view and to display a sphere. Move the sphere close to the view until it is partially truncated by the front clipping plane.
- 8.4 Write a program to examine the matrix generated by the lookAt method of the Transform3D class. Allow users to enter the parameters for the method and print the resulting matrix.
- 8.5 Write a program to examine the matrix generated by the perspective method of the Transform3D class. Allow users to enter the parameters for the method and print the resulting matrix.
- 8.6 Write a program to examine the matrix generated by the frustum method of the Transform3D class. Allow users to enter the parameters for the method and print the resulting matrix.
- 8.7 Write a program to examine the matrix generated by the ortho method of the Transform3D class. Allow users to enter the parameters for the method and print the resulting matrix.
- 8.8 Write a Java 3D program with a compatibility-mode view. Use a perspective projection with a field of view p/3. Place the view at (0, 0, 1) looking down the *z*-axis. Display an Axes object defined in Chapter 7.
- 8.9 Write a program with two different views. One view is positioned at (0, 0, 2) looking along the negative z-axis with the y-axis as up direction. The other view is positioned at looking along the z-axis with the pogative y-axis as up direction. Place a rotating 3D text near the origin

Zaxis with the negative ∠axis as up direction. Place a rotating 3D text near the origin. UNREGISTERED VERSION OF CHM TO PDF CONVERTER 8.10 Write a program with four views with different fields of view. All views are positioned at (0, 0, 2)

- 8.10 Write a program with four views with different fields of view. All views are positioned at (0, 0, 2) looking along the negative z-axis with the y-axis as up direction. The fields of view are set to p/8, p/4, p/2, and 3p/4. Place a 3D text and an Axes object (from Chapter 7) in the scene.
- 8.11 Construct a scene with a sphere and a cone, each attached to a TransformGroup node. Implement a picking operation with a PickCanvas. If an object is picked by a mouse click, it will rotate by p/4.
- 8.12 Construct a scene with two spheres. Implement a picking operation with Pick Canvas. If a sphere is picked by a mouse click, it changes to a cube. (*Hint:* You may use Switch nodes.)
- 8.13 Modify Listing 8.5 to create a head-mounted head-tracking view.

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## Chapter 9. Lighting and Texturing

(This item omitted from WebBook edition)

Objectives			
To understand lighting models.			
To identify point lights, directional lights, and spotlights.			
To identify material properties.			
• To understand Java 3D coloring modes.			
• To create lit scenes with lights, surface normals, and materials.			
• To construct and apply fog nodes for atmospheric attenuation and depth cueing.			
• To apply 2D texture mapping and texture cube mapping.			
<ul> <li>To understand texture-coordinates generation.</li> </ul>			

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## 9.1. Introduction

Geometry defines the shapes and metrics of visual objects. Colors, textures, and other appearance details constitute other important aspects of the rendering. Often the most computationally intensive tasks of graphics rendering are related to achieving high-quality, photorealistic appearance of the visual objects.

Various methods of defining appearance exist, with different levels of rendering quality and computational demand. Some of the simplest ways to render visual objects include:

- Draw the vertices of the objects only.
- Draw the outlines of the objects only (wireframe mode).
- Use a single color for all surfaces of an object.
- Use flat colors for faces of an object.

These simple coloring approaches are relatively easy to implement. However, they usually do not provide the quality that can match the real images seen by human eyes or captured by photography.

In order to create photorealistic 3D graphics renderings, more sophisticated lighting and shading models are needed. Illumination and texture models are computer graphics tools to enhance photorealism of the

#### renderings.

A real image seen by an eye is formed by light energy emitted and reflected from the visual objects of a scene. The transmission and interaction of lights in an environment can be very complex. Light sources have different characteristics. Objects have different characteristics in reflection and refraction. Lights reflected off objects may travel complex paths in the scene.

To model such a complex system exactly in computers is usually not feasible. Different approximation methods are therefore necessary in order to implement a practical graphics system. A computer graphics system usually applies simplified illumination models to achieve a reasonably realistic rendering of the scene. The Phong illumination model is widely used. It incorporates light characteristics, geometry structures, and material properties to obtain effective and efficient lighting calculations.

Commonly used techniques for enhancing rendering quality also include atmospheric attenuation and texture mapping. An artificial fog is used to blend the distant objects in atmospheric attenuation and depth cueing. It creates a foggy appearance. The texture-mapping technique maps images to surfaces of visual objects. It has the advantage of creating a great deal of surface detail without complex modeling.

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## 9.2. Lights

Lights provide the sources for illuminating the graphics objects in a virtual world. Lights have color attributes, positions, directions, and other characteristics depending on their specific types. There are typically four types of lights in graphics systems: ambient lights, directional lights, point lights, and spotlights.

An *ambient light* is uniform in all directions and locations. It generally provides a simplified representation of the numerous and weak interobject reflections existing in the real-world scene (Figure 9.1).

Figure 9.1. An ambient light represents weak random reflections.

# 

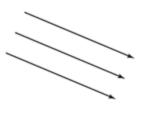
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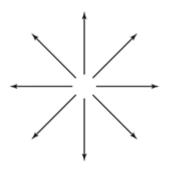
A directional light has a fixed direction. All light rays travel along this direction. A *directional light* does not have a specific location, although it can be conveniently regarded as being located at infinity. It is a good model for a distant light source such as the sun (Figure 9.2).

Figure 9.2. A directional light emits parallel light rays.

A point light has a location in the virtual world. It emits in all directions (Figure 9.3). A *point light* typically has an attenuation that describes the decrease of the intensity as the distance from the light increases. The attenuation is usually expressed as a coefficient (a function of distance) from 0.0 to 1.0 multiplied on the original intensity of the light.

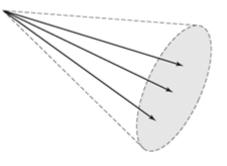
Figure 9.3. A point light has a specific location and emits light rays in all directions.



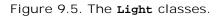


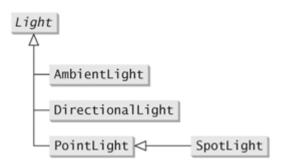
A *spotlight* is similar to a point light, but the directions of its emission are restricted. A spotlight radiates light rays only in a focused, cone-shaped region (Figure 9.4). Besides the attenuation associated with the distance to the light, as in a point light, a spotlight may also define an attenuation as a light ray moves away from the central direction of the cone.





[Page 284] Java 3D offers a family of Light classes for different types of lights described above. The Light class merarchy R PRO is shown in Figure 9.5.





Some of the constructors for Light Classes are instead below.

AmbientLight() AmbientLight(boolean lightOn, Color3f color) AmbientLight(Color3f color) DirectionalLight() DirectionalLight(**boolean** lightOn, Color3f color, Vector3f direction) DirectionalLight(Color3f color, Vector3f direction) PointLight() PointLight(boolean lightOn, Color3f color, Point3f position, Point3f attenuation) PointLight(Color3f color, Point3f position, Point3f attenuation) SpotLight() SpotLight(boolean lightOn, Color3f color, Point3f position, Point3f attenuation, Vector3f direction, float spreadAngle, float concentration) SpotLight(Color3f color, Point3f position, Point3f attenuation, Vector3f direction, **float** spreadAngle, **float** concentration)

A light can be turned on or off. Besides the flag in the constructors, the on/off state can be set by calling the following method:

void setEnable(boolean state)

The *attenuation* of PointLight and SpotLight due to the distance d to the light is defined with a quadratic model.

 $\mathcal{A}(\mathcal{A}) = 1/(\mathcal{A}_0 + \mathcal{A}_1\mathcal{A} + \mathcal{A}_2\mathcal{A})$ 

The attenuation can be defined with constructors or set with the method:

void setAttenuation(Point3f attenuation)

The Point3f parameter specifies the coefficients  $(a_0, a_1, a_2)$  for the attenuation. For example, the coefficients (1, 0, 0) represent no attenuation for the light, A(a) = 1. The coefficients (1, 1, 0) represent the attenuation function A(a) = 1/(1 + a), so at 1 meter away from the light the attenuation function has value 0.5 and at 4 meters away the attenuation is 0.2.

The attenuation due to the angle between a light ray and the central direction in a SpotLight is defined by an exponential function of the cosine value of the angle

 $A() = \cos^{\prime\prime}$ 

The function has the value 1 when the angle is 0, so there is no attenuation at the central direction. The parameter n is the concentration exponent that takes a value from 0 to 128. It can be set by constructors or the method

void setConcentration(float concentration)

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The value A() decreases as the angle increases. If the concentration exponent is large, this decrease of A() will be faster, resulting in a more concentrated spotlight. If n = 0, there will be no attenuation as the angle increases.

For the efficiency of rendering, a Light object has an associated influence bound. A visual object is affected by

a Light object only if it is located within the influence bound of the light. For each light created, it is necessary to set an appropriate influence bound to avoid an unnecessarily lengthy rendering process. The following method sets the influence bound:

void setInfluencingBounds(Bound bounds)

The influence bound can also be specified with a bounding leaf node

void setInfluencingBoundingLeaf(BoundingLeaf bounds)

Listing 9.1 illustrates the effects of different types of lights. The program displays a sphere illuminated with different light sources (Figure 9.6). A list of checkboxes for the light types can be used to individually turn each type of lights on or off.

Listing 9.1. TestLights.java

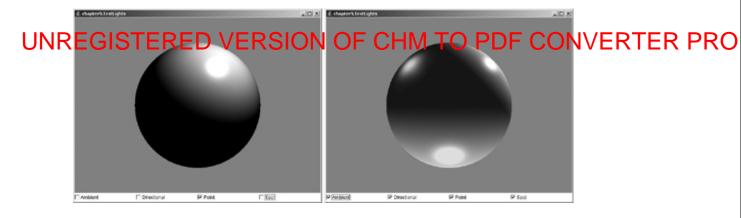
(This item is displayed on pages 285 - 287 in the print version)

```
1 package chapter9;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
 9 import java.applet.*;
10 import com.sun.j3d.utils.applet.MainFrame;
11
12 public class TestLights extends Applet implements ItemListener {
13
    public static void main(String[] args) {
14
      new MainFrame(new TestLights(), 640, 480);
15
    }
16
17
   UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
18
19
     PointLight pLight;
     SpotLight sLight;
20
21
    SpotLight sLight2;
22
23
   public void init() {
24
      // create canvas
25
      GraphicsConfiguration gc =
26
         SimpleUniverse.getPreferredConfiguration();
27
      Canvas3D cv = new Canvas3D(gc);
28
       setLayout(new BorderLayout());
29
       add(cv, BorderLayout.CENTER);
30
31
      Panel menu = new Panel();
32
       menu.setLayout(new GridLayout(1,4));
33
       add(menu, BorderLayout.SOUTH);
34
      Checkbox mi = new Checkbox("Ambient", true);
35
      menu.add(mi);
       mi.addItemListener(this);
36
       mi = new Checkbox("Directional", true);
37
     MREGONSTERED
mi.addItemListener(this);
                                VERSION OF CHM TO PDF CONVERTER PRO
38
39
40
       mi = new Checkbox("Point", true);
```

```
[Page 286] 41
               menu.add(mi);
 42
        mi.addItemListener(this);
43
        mi = new Checkbox("Spot", true);
44
        menu.add(mi);
45
        mi.addItemListener(this);
46
47
        SimpleUniverse su = new SimpleUniverse(cv, 2);
 48
        su.getViewingPlatform().setNominalViewingTransform();
        BranchGroup bg = createSceneGraph(su.getViewingPlatform().
 49
50
          getMultiTransformGroup().getTransformGroup(0));
51
        bq.compile();
52
        su.addBranchGraph(bg);
53
     }
54
55
     Appearance ap;
56
    private BranchGroup createSceneGraph(TransformGroup vtg) {
57
        BranchGroup root = new BranchGroup();
58
       // object
       ap = new Appearance();
59
60
        ap.setMaterial(new Material());
61
        Sphere shape = new Sphere
         (0.5f, Sphere.GENERATE_NORMALS, 150, ap);
62
 63
        root.addChild(shape);
       // view rotator
 64
 65
       Alpha alpha = new Alpha(-1, 4000);
        RotationInterpolator rotator = new RotationInterpolator
 66
67
         (alpha, vtg);
 68
        BoundingSphere bounds = new BoundingSphere();
69
       bounds.setRadius(2);
70
        rotator.setSchedulingBounds(bounds);
71
        root.addChild(rotator);
72
        // background and lights
73
        Background background = new Background(0.5f, 0.5f, 0.5f);
74
        background.setApplicationBounds(bounds);
75
        root.addChild(background);
76
        aLight = new AmbientLight(true, new Color3f(Color.red));
77
        aLight.setInfluencingBounds(bounds);
 78
        aLight.setCapability(Light.ALLOW_STATE_WRITE);
79
        root.addChild(aLight);
80
        dLight = new DirectionalLight(
81
        new Color3f(Color.green), new Vector3f(0f,1f,0f));
82
        dLight.setCapability(Light.ALLOW_STATE_WRITE);
83
        dLight.setInfluencingBounds(bounds);
84
       root.addChild(dLight);
85
       pLight = new PointLight(
 86
        new Color3f(Color.white), new Point3f(-0.7f,0.7f,0f),
87
        new Point3f(1f,0f,0f));
 88
        pLight.setCapability(Light.ALLOW_STATE_WRITE);
 89
        pLight.setInfluencingBounds(bounds);
 90
       root.addChild(pLight);
91
       sLight = new SpotLight(
92
       new Color3f(Color.blue), new Point3f(0.7f,0.7f,0.7f),
        new Point3f(1f,0f,0f),
93
94
          new Vector3f(-0.7f,-0.7f,-0.7f), (float)(Math.PI/6.0), 0f);
 95
        sLight.setCapability(Light.ALLOW_STATE_WRITE);
 96
        sLight.setInfluencingBounds(bounds);
 97
        root.addChild(sLight);
 98
        sLight2 = new SpotLight(
 99
        new Color3f(Color.orange), new Point3f(0.7f,0.7f,-0.7f),
```

```
100
          new Point3f(1f,0f,0f),
[Page 287]101
                 new Vector3f(-0.7f,-0.7f,0.7f), (float)(Math.PI/12.0), 128f);
         sLight2.setCapability(Light.ALLOW_STATE_WRITE);
102
103
         sLight2.setInfluencingBounds(bounds);
104
        root.addChild(sLight2);
105
        return root;
106
      }
107
108
      public void itemStateChanged(ItemEvent itemEvent) {
109
         Checkbox cmi = (Checkbox)itemEvent.getSource();
110
        String label = cmi.getLabel();
111
        boolean state = cmi.getState();
        if("Ambient".equals(label)) {
112
113
          aLight.setEnable(state);
114
        } else if ("Directional".equals(label)) {
115
          dLight.setEnable(state);
        } else if ("Point".equals(label)) {
116
117
          pLight.setEnable(state);
        } else if ("Spot".equals(label)) {
118
119
          sLight.setEnable(state);
120
           sLight2.setEnable(state);
121
        }
122
        cmi.setState(state);
123
      }
124 }
```

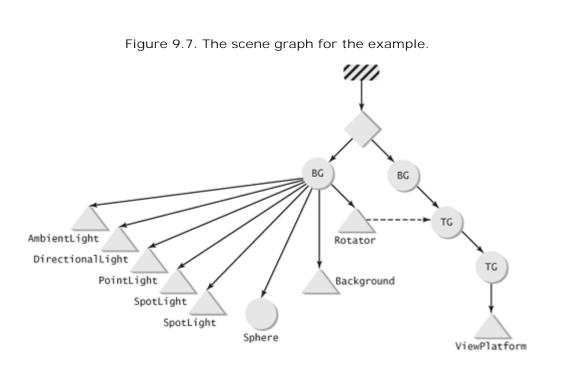
Figure 9.6. The effects of different types of lights. Left: a point light only. Right: all four types of lights.



The scene graph of the program is shown in Figure 9.7. Four different types of lights (one AmbientLight, one DirectionalLight, one PointLight, and two SpotLights) are created to illuminate the scene (lines 76104). The AmbientLight has a red color. The DirectionalLight is green and has the direction (0, 1, 0), so its light rays are emitted upward. The PointLight is white and is located at (-0.7, 0.7, 0) with no attenuation. The first SpotLight is blue and is located at (0.7, 0.7, 0.7) with no attenuation related to the distance. It points at the direction related to the angle. The second SpotLight is orange and is located at (0.7, 0.7, -0.7) with no attenuation related to the distance. It points at the direction related to the distance. It points at the direction related to the distance. It points at the direction (-0.7, -0.7, 0.7) with no attenuation related to the distance. It points at the direction (-0.7, -0.7, 0.7) with a spread angle p/12. The

concentration exponent is set to 128, so the light is highly concentrated along its main axis. All the lights use the same Bounds object for their influencing bound. The bounding sphere has a radius of 2 to include all relevant objects. A gray background object is added using the same bounding sphere.

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The visual object in the scene is a sphere of radius 0.5 (line 61). The number of divisions for the sphere is set to 150 to obtain a high-quality sphere. The sphere is centered at the origin. To support illumination the sphere has surface normals generated and includes, in its Appearance, a Material object.

At the bottom of the window, a list of four checkboxes of the class Checkbox is created: Ambient, Directional, Point, and Spot. The checkboxes turn the corresponding lights on or off. In order to switch the lights in the live scene graph, all the lights have their capability bit ALLOW\_STATE\_WRITE set. The class TestLights implements the ItemListener interface and listens to the item changes. When a menu item is selected, the state of the light is toggled and the check mark on the menu item reflects the state of the light (lines 109122).

The view is rotated by an interpolator to show the illumination of the sphere by the lights from different angles. The directional light illuminates the bottom portion of the sphere. The point light and two spotlights cause three different reflection spots on the upper portion of the sphere.

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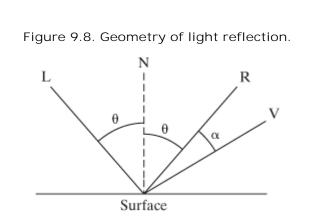
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## 9.3. Illumination Models

A truly accurate model of light reflection would be extremely complicated and impractical for computer graphics implementations. A common practice in graphics is to select computationally efficient models that provide a good approximation of visual realism. The classical Phong illumination model widely used in computer graphics is an example of such attempts to balance computational efficiency and rendering quality.

The illumination of a point on a surface is illustrated in Figure 9.8. The surface normal N at the point is a line perpendicular to the tangent plane at the point. L is the direction of the light source. The angle between L and N is . The direction R mirrors L and the angle between R and N is also . V is the view direction. The angle between V and R is denoted by a.

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Typically three types of reflection are considered; ambient, diffuse, and specular. **UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO** The *ambient reflection* is the response to ambient light sources. It is uniform in all directions and is independent

The *ambient reflection* is the response to ambient light sources. It is uniform in all directions and is independent of the surface normal.

The *diffuse reflection* represents the large number of small reflections on a surface that is not perfectly reflective. Its intensity depends on the incidence angle , but does not depend on the angle to the viewer. The intensity is the same when viewed from any direction. For most visual objects, the diffuse reflection is a major portion of all reflections and is the one that defines our usual notion of the object color.

The *specular reflection* represents the concentrated reflection around the direction *R* on a shining surface. Its intensity depends on the angle a as well as . The reflection is maximal at the direction *R* and decreases as the angle a increases.

In the *Phong model*, the intensity of the point is given by the following illumination equation:

## $I = I_{a}k_{a} + I_{p}k_{d}\cos + I_{p}k_{s}\cos^{n}a$

In the equation,  $I_{a}$  and  $I_{p}$  denote the light intensities from ambient light and a pointlike light source, respectively. The attenuation of light is already considered in  $I_{p}$ . The reflection coefficients  $k_{a}$ ,  $k_{d}$  and  $k_{s}$ correspond to the ambient reflection, diffuse reflection, and specular reflection, respectively. The coefficients are determined by the material properties of the purface. The quantity  $r_{j}$  the specular reflection coefficients are also determined by the material barger exponents result in a more focused highlight. The illumination equation above can be applied to each color wavelength. Therefore, the coefficients  $k_{\partial}$ ,  $k_{d}$ ,  $k_{s}$  may vary depending on the color. Of course, calculating the illumination equation for a continuous spectrum of colors is not practical. The common practice is to use a color model such as the RGB model. The illumination equation is applied to each component of the model (red, green, blue in the RGB model).

In the case of multiple light sources, the contributions from every light are summed to obtain the total intensity.

The Phong illumination model is a local illumination model. It renders the visual objects individually without considering the interactions among them. For example, reflections of other objects and shadows are not generated. Advanced global models and techniques such as *radiosity* and *ray tracing* can provide solutions to these questions, but these methods are also computationally much more expensive than the Phong model.

From the equation of the lighting model it is easy to see that the appearance of a visual object depends on its material properties that define the reactions to lights as well as the geometry of the object and light sources.

The material properties are primarily defined by the *reflection coefficients*  $k_{\partial}$ ,  $k_{\sigma}$ . These coefficients are dependent upon the color wavelength. When using a color model, the coefficients are specified on each component of the color model. For example, in an RGB model,  $k_{\sigma}$  may be specified by three numbers (0.9, 0.2, 0.0). This indicates that in the diffused reflection the material will reflect most of red, a little green, and no blue, so the visual object will appear to be mostly red. The specular *shininess exponent n* is also a material property, but it is typically specified as a fixed constant independent of the color.

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## 9.4. Java 3D Lighting Models

Java 3D supports the Phong illumination model. A visual object is rendered according to this model when it is lit. Java 3D uses an RGB color model for rendering. The illumination equation is applied to each of the three color components.

The Material node-component class represents the material properties of the visual objects. The ambient, diffuse, and specular coefficients are represented in the class using an RGB color model. The specular reflection exponent *n* corresponds to the shininess in the Material class. The Material class also contains an emissive coefficient that defines the light emitted by the object itself instead of external light sources. The following is a partial list of methods for setting various parameters:

```
void setAmbientColor(Color3f color)
void setAmbientColor(float r, float g, float b)
void setDiffuseColor(Color3f color)
void setDiffuseColor(float r, float g, float b)
void setDiffuseColor(float r, float g, float b, float a)
void setSpecularColor(Color3f color)
void setSpecularColor(float r, float g, float b)
void setEmissiveColor(Color3f color)
void setEmissiveColor(Color3f color)
void setEmissiveColor(float r, float g, float b)
```

There are three different coloring specifications for a visual object: the vertex color specification in its Geometry, the ColoringAttributes in Appearance, and the lighting model. The selection of the coloring method for a particular object is determined as follows:

- 1. If the vertex colors are specified in the geometry of the object, they are used to define the object coloring.
- 2. If a Material node component is defined for the object, the object is lit. The coloring of the object is defined by the lighting model.
- 3. I THREE GASTERED TO POFUE ON VERSION OF CHMICTO POFUE ON VERTER PRO
- 4. Otherwise, the object is colored white.

The decision for the coloring mode is made individually for each object. It is allowed to have both lit and unlit objects in the same scene. For example, the following code fragment creates four objects with different coloring options:

```
// vertex color specified in geometry
TriangleArray geom = new TriangleArray(3,
   TriangleArray.COORDINATES|TriangleArray.COLOR_3);
Point3f[] coords = {new Point3f(1,0,0),
   new Point3f(0,1,0), new Point3f(0,0,1)};
geom.setCoordinates(coords);
Color3f[] colors = {new Color3f(1,0,0),
   new Color3f(0,1,0), new Color3f(0,0,1)};
geom.setColors(colors);
Shape3D shape1 = new Shape3D(geom);
```

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TriangleArray.COORDINATES | TriangleArray.NORMAL);

```
geom2.setCoordinates(coords);
Appearance appear = new Appearance();
Material material = new Material();
appear.setMaterial(material);
Shape3D shape2 = new Shape3D(geom2, appear);
// coloring attributes in appearance
Appearance appear3 = new Appearance();
[Page 291]ColoringAttributes coloring = new ColoringAttributes(
    new Color3f(1f,0,0), ColoringAttributes.SHADE_FLAT);
appear3.setColoringAttributes(coloring);
Shape3D shape3 = new Shape3D(geom2, appear3);
// no coloring specification
Shape3D shape4 = new Shape3D(geom2);
```

The Shape3D object shape1 has a geometry that contains the vertex color definition. Therefore, the specified vertex colors will be used for rendering. The object shape2 has no vertex color definition in its geometry. Instead, normals are defined at the vertices. The appearance of shape2 contains a Material object. Consequently shape2 will be lit and its coloring will be derived from the lighting model. The object shape3 uses the same geometry as shape2 with no vertex colors, but it is not lit. Its appearance contains a ColoringAttributes object specifying a red color. Therefore, shape3 will be colored red. The object shape4 contains no vertex color definition, no Material object, and no ColoringAttributes object. It will be colored white.

To enable lighting for visual objects in a Java 3D program, therefore, we need to perform the following basic steps:

- Place lights in the scene graph.
- Provide surface normals for the geometry and do not set vertex colors.
- Set material for the appearance.

The following code segment illustrates these steps:

```
// add a light
Light light = new PointLight();
light.setInfluencingBounds(new BoundingSphere());
root.addChild(light);
// construct appearance with material
Appearance appearance = new Appearance();
Material material = new Material();
appearance.setMaterial(material);
// add a box with normals
Box box = new Box(lf, lf, lf, Box.GENERATE_NORMALS, appearance);
root.add(box);
```

Listing 9.2 shows the effects of different illumination parameter settings. It displays eight spheres with different material properties illuminated by a point light.

Listing 9.2. Lighting.java

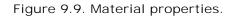
(This item is displayed on pages 291 - 292 in the print version)

```
1 package chapter9;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
 9 import java.applet.*;
10 import com.sun.j3d.utils.applet.MainFrame;
11
12 public class Lighting extends Applet {
13
    public static void main(String[] args) {
14
       new MainFrame(new Lighting(), 640, 480);
15
    }
16
[Page 292]17
            public void init() {
18
      // create canvas
       GraphicsConfiguration gc =
19
20
         SimpleUniverse.getPreferredConfiguration();
21
       Canvas3D cv = new Canvas3D(qc);
22
       setLayout(new BorderLayout());
23
       add(cv, BorderLayout.CENTER);
24
       BranchGroup bg = createSceneGraph();
25
      bq.compile();
26
       SimpleUniverse su = new SimpleUniverse(cv);
27
       su.getViewingPlatform().setNominalViewingTransform();
28
       su.addBranchGraph(bg);
29
    }
30
    UNREGISTERED WERSION OF CHM TO PDF CONVERTER PRO
31
32
       BranchGroup root = new BranchGroup();
33
       // object
34
       Vector3f pos = new Vector3f(0.5f,0f,0f);
35
       Transform3D rotation = new Transform3D();
       rotation.rotZ(Math.PI/4);
36
37
       for (int i = 0; i < 8; i++) {
38
        Node shape = createShape
39
           (pos, 0.2f, .5f, (float)Math.pow(1.7,i));
40
         root.addChild(shape);
41
         rotation.transform(pos);
42
       }
43
       // lights
44
       BoundingSphere bounds = new BoundingSphere();
45
       PointLight pLight = new PointLight(new Color3f(Color.white),
46
       new Point3f(0f,0f,1f/(float)Math.tan(Math.PI/8)),
47
       new Point3f(1f,0f,0f));
48
       pLight.setInfluencingBounds(bounds);
49
       root.addChild(pLight);
50
       return root;
51
    UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
52
53
     private Node createShape(Vector3f pos,
```

54	t	float size, float spec, float shine) {
55		Material mat = new Material();
56		<pre>mat.setDiffuseColor(0.5f,0.5f,1f);</pre>
57		<pre>mat.setSpecularColor(spec, spec, spec);</pre>
58		<pre>mat.setShininess(shine);</pre>
59		Appearance ap = new Appearance();
60		<pre>ap.setMaterial(mat);</pre>
61		<pre>Sphere shape = new Sphere(size, Sphere.GENERATE_NORMALS, 50, ap);</pre>
62		<pre>Transform3D tr = new Transform3D();</pre>
63		<pre>tr.setTranslation(pos);</pre>
64		<pre>TransformGroup tg = new TransformGroup(tr);</pre>
65		tg.addChild(shape);
66		return tg;
67	}	
68	}	

The rendered scene of the program is shown in Figure 9.9 and the scene graph for the program in Figure 9.10. Eight spheres with different shininess exponents are placed circularly around the *z*-axis. The locations of the spheres are calculated with a successive rotation of p/4 about the *z*-axis. The position of the first sphere is (0.5, 0, 0). A Transform3D object is used to perform the rotations on the position vector.

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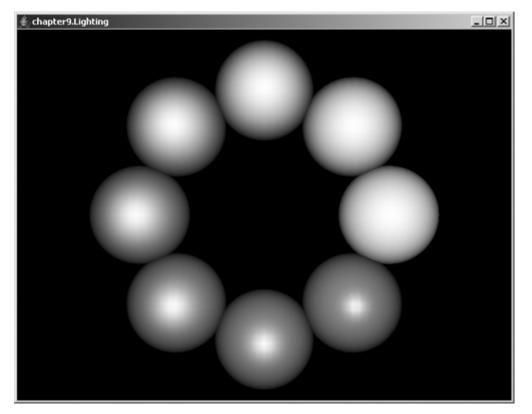
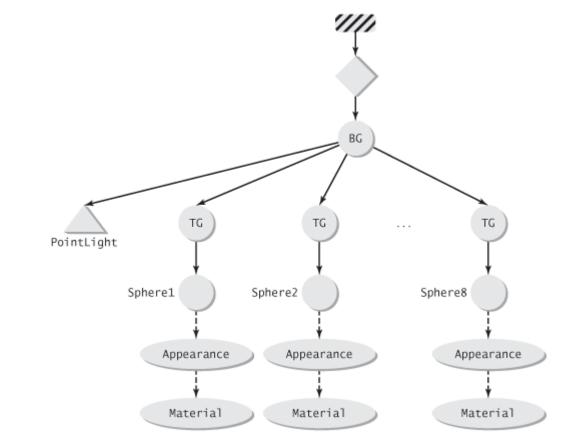


Figure 9.10. Scene graph.



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The method createShape (line 53) creates a branch of the scene graph consisting of a TransformGroup and a sphere. The TransformGroup node moves the sphere to the specified location. The sphere appearance has a Material object with the shininess set to a specified value. The diffused reflection is set to a fixed value.

To provide equal illumination and viewing to all spheres, a point light is placed on the *z*-axis at the eye position. This also allows the focused specular reflection visible when the shininess exponent is large. The shininess values of the eight spheres are set to  $1.7^{7}$ , i = 0, 1, ..., 7. The first sphere has the smallest value, 1, and the last sphere has the largest value, 41.

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## 9.5. Atmospheric Attenuation and Depth Cueing

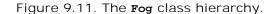
In real-life images, objects closer to the viewer appear to be sharper, clearer, and of higher intensity than objects far away. This is particularly apparent on a foggy day. The phenomenon is the result of atmospheric attenuation. This suggests a technique to improve realism. In computer graphics, the atmospheric attenuation effects can be simulated with a relatively efficient method known as *depth cueing*. Depth cueing blends the objects with the background color. The amount of background color used in the blending is an increasing function of the distance. More generally the fog color—the color used to blend the objects—can be arbitrarily specified.

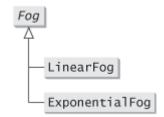
The final color of a rendered point is given by

 $C = f \cdot C_O + (1 - \hbar) \cdot C_f$ 

where  $C_0$  is the original color of the object and  $C_r$  is the fog color. The fog factor r is a decreasing function of the distance to the viewer. Consequently, as the object becomes more distant, more weight will be assigned to the fog color and less to the object color. The object will appear to fade away into the fog. The function r is typically chosen as a linear function, an exponential function, or a Gaussian function of the distance.

Java 3D provides Fog leaf nodes to support depth cueing. Two types of fogs with linear and exponential blending functions are available in Java 3D. Figure 9.11 shows the fog classes.





The LinearFog class defines a fog with a linear *f*function.

$$f(z) = \frac{back - z}{back - front}$$

where z is the distance to the view point, and *front* and *back* are constants defining the bounds for f to vary from 1.0 to 0.0. To construct a linear fog, the following constructors can be used:

public LinearFog()
public LinearFog(Color3f color)
public LinearFog(Color3f color, double front, double back)
public LinearFog(float r, float g, float b)
public LinearFog(float r, float g, float b, double front, double back)

The ExponentialFog class uses an exponential function

 $f(\vec{Z}) = e^{density\cdot Z}$ 

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The *density* parameter controls the speed of decrease of the function *f* and consequently the density of the fog. The following constructors are available for exponential fog:

public ExponentialFog()
public ExponentialFog(Color3f color)
public ExponentialFog(Color3f color, float density)
public ExponentialFog(float r, float g, float b)
public ExponentialFog(float r, float g, float b, float density)

Listing 9.3 illustrates the use of fog nodes. An array of dodecahedron objects is displayed in a gray background. A LinearFog node is placed in the scene. The fog has the same gray color as the background, creating an effect of a foggy environment with distant objects fading away to the background.

Listing 9.3. TestFog.java

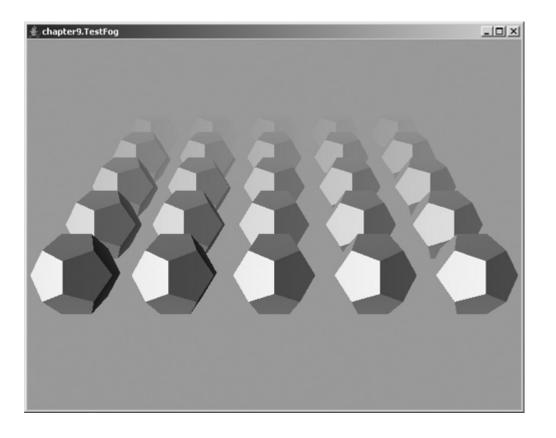
(This item is displayed on pages 295 - 296 in the print version)

```
1 package chapter9;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
9 import chapter6.Dodecahedron;
10 import java.applet.*;
11 import com.sun.j3d.utils.applet.MainFrame;
12
public static void main(String[] args) {
14
15
      new MainFrame(new TestFog(), 640, 480);
16
    }
17
18
    public void init() {
19
      // create canvas
20
      GraphicsConfiguration gc =
21
        SimpleUniverse.getPreferredConfiguration();
22
      Canvas3D cv = new Canvas3D(qc);
23
      setLayout(new BorderLayout());
24
      add(cv, BorderLayout.CENTER);
25
      BranchGroup bg = createSceneGraph();
26
      bg.compile();
27
      SimpleUniverse su = new SimpleUniverse(cv);
28
       su.getViewingPlatform().setNominalViewingTransform();
29
      su.addBranchGraph(bg);
30
    }
31
32
    private BranchGroup createSceneGraph() {
33
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34
35
      for (int i = 0; i < 5; i++) {
```

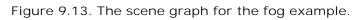
```
36
         for (int j = 0; j < 5; j++) {
37
           Vector3f pos = new Vector3f
38
             (-0.8f+0.4f*i,-0.2f+0.2f*j,-0.4f*j);
39
           Node shape = createShape(pos);
40
           root.addChild(shape);
41
         }
42
       }
[Page 296]43
               // lights
       BoundingSphere bounds = new BoundingSphere
44
45
        (new Point3d(), Double.MAX_VALUE);
46
       Background background = new Background(.6f, .6f, .6f);
47
      background.setApplicationBounds(bounds);
48
      root.addChild(background);
49
      DirectionalLight dLight = new DirectionalLight
50
        (new Color3f(Color.white), new Vector3f(1f,0f,-1f));
51
      dLight.setInfluencingBounds(bounds);
52
      root.addChild(dLight);
53
      // fog
54
      LinearFog fog = new LinearFog(.6f, .6f, .6f, 2f, 4f);
55
      fog.setInfluencingBounds(bounds);
56
      root.addChild(fog);
57
      return root;
58
    }
59
60
   private Node createShape(Vector3f pos) {
61
     Material mat = new Material();
62
     Appearance ap = new Appearance();
63
     ap.setMaterial(mat);
64
     Shape3D shape = new Dodecahedron();
65
     shape.setAppearance(ap);
66
     Transform3D tr = new Transform3D();
67
      tr.setScale(0.1);
68
      tr.setTranslation(pos);
69
      TransformGroup tg = new TransformGroup(tr);
70
      tg.addChild(shape);
71
       return tg;
72
   }
73 }
```

The result of the program is shown in Figure 9.12 and the scene graph in Figure 9.13.

Figure 9.12. A foggy scene created with atmospheric attenuation.

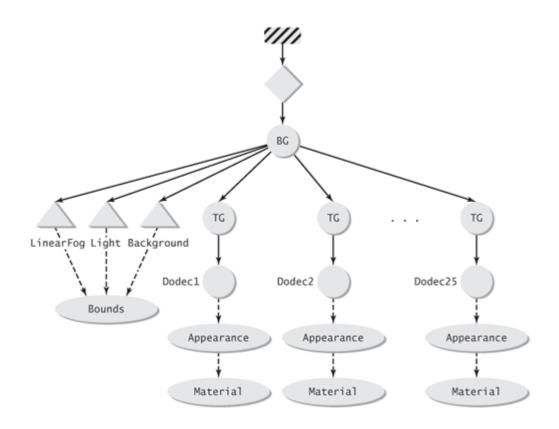


[Page 297]



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An array of twenty-five dodecahedra is placed in the scene graph in a 5 x 5 grid (lines 35–42). The method createShape creates a branch of the scene graph with a TransformGroup group node, a Dodecahedron object, and an Appearance object with Material. The transform node scales the dodecahedron and moves it to a specified location.

The scene is illuminated by a white directional light in the direction (1, 0, -1). A gray background is used. A linear fog node with the same color as the background is added to the scene graph (line 54). The front of the linear fog is 2 and the back is 4. The distant objects show a clear fading into the background. A Bounds object is shared by the light, the background, and the fog.

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## 9.6. Texture Mapping

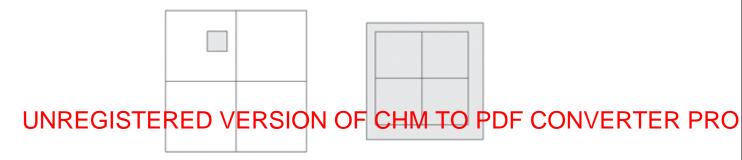
Real-life objects often contain many small details. Modeling the entire set of details with the usual geometric structures can quickly exhaust the computing resources. Digital images, on the other hand, are relatively inexpensive in providing complex details. *Texture mapping* is a method that utilizes images in graphics rendering. It can provide a great deal of model details with efficiency.

## 9.6.1. Creating 2D Texture Mapping

The 2D texture-mapping method maps a 2D image to the surface of a 3D object. In the context of texture mapping a point in the texture image is called a *texel* and a point on the 3D surface a *pixel*. The texture image has its own coordinate system. A texture mapping is usually specified by assigning to each vertex of the surface the texture coordinate of the corresponding texel. Other pixels for the surface will be mapped to texture coordinates through interpolation. Clearly the mapping between pixels and texels is not one-to-one in general. As illustrated in Figure 9.14, a pixel may correspond to only a portion of a texel, or it may cover many texels. The former is called the *magnification* and the latter the *minification*. In either case, we need to establish certain rules to obtain the texture values. These rules are known as the *magnification filters* and *minification filters*. Commonly used filters include the selection of the closest texel and the linear interpolation (or combination) of neighboring texels.

[Page 298]

Figure 9.14. Magnification and minification. The grey square represents a pixel.



Java 3D supports texture mapping through the texture-coordinates settings in geometry objects and the texture objects in the associated appearance objects. Creating a texture mapping on a shape involves two steps:

- 1. Assign texture coordinates to vertices of the geometry.
- 2. Create a Texture object in the appearance bundle.

The GeometryArray class and its subclasses facilitate the per-vertex specification of texture coordinates. The texture coordinates define the positions of texels for the vertices. The Texture2D class defines the texture image used for texture mapping. It is a node component and can be referenced by an Appearance object.

In defining a Geometry array object, texture coordinates for vertices of the geometry can be specified like other R PRO attributes. Nuclease of the geometry can be specified like other R PRO attributes. Vicinate Sources, an Error all Other Constant flag for 2D texture coordinates so VERTER PRO TExture\_COORDINATE\_2.

A texture usually gets its content from an image. The class Texture2D is a subclass of NodeComponent representing the texture. The actual image for Texture2D is represented by the class ImageComponent2D. A Texture2D object is set to reference the ImageComponent2D object. The following method of Texture2D sets an image for the texture:

```
public void setImage(int index, ImageComponent2D)
```

An ImageComponent2D object may receive its image from a BufferedImage or more generally a RenderedImage object:

```
public void set(BufferedImage bi)
public void set(RenderedImage ri)
```

A BufferedImage can be created or loaded from a file using the methods described in Chapter 4. For example, the ImageIO class contains static methods for reading images. The following code fragment illustrates the procedure:

```
BufferedImage bi = ImageIO.read(file);
ImageComponent2D image =
new ImageComponent2D(ImageComponent2D.FORMAT_RGB, bi);
[Page 299]Texture2D texture = new Texture2D();
texture.setImage(0, image);
```

A utility class TextureLoader is also available to load a texture image from a file or a BufferedImage. The loaded image can be retrieved as an ImageComponent2D object or directly as a Texture object. The following code fragment shows the basic steps in loading a texture image with a TextureLoader object:

```
TextureLoader loader = new TextureLoader(filename, this);
// retrieve the texture
Texture texture = loader.getTexture();
// or retrieve the image first
ImageComponent2D image = loader.getImage();
Texture2D texture2D = new Texture2D();
Texture2D.setImage(0, image);
```

The created Texture2D object can be added to an Appearance object using the setTexture method

```
Appearance appear = new Appearance();
appear.setTexture(texture);
```

After the texture coordinates are set in the geometry and the texture image is placed in the appearance, the texture mapping will be applied to the object.

Listing 9.4 illustrates 2D texture mapping. It shows a texture-mapped globe. The geometric object is a rotating sphere. An image of the earth is used as the texture and it is mapped to the surface of the sphere. This approach creates a realistic rendering of a 3D globe.

```
Listing 9.4. TextureMapping.java
(This item is displayed on pages 299 - 300 in the print version)
```

```
1 package chapter9;
```

```
2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import java.net.*;
 7 import javax.media.j3d.*;
 8 import com.sun.j3d.utils.universe.*;
 9 import com.sun.j3d.utils.geometry.*;
10 import com.sun.j3d.utils.image.*;
11 import java.applet.*;
12 import com.sun.j3d.utils.applet.MainFrame;
13
14 public class TextureMapping extends Applet {
    public static void main(String[] args) {
15
16
       new MainFrame(new TextureMapping(), 640, 480);
17
    }
18
19
    public void init() {
20
      // create canvas
21
       GraphicsConfiguration gc =
22
         SimpleUniverse.getPreferredConfiguration();
23
       Canvas3D cv = new Canvas3D(qc);
24
       setLayout(new BorderLayout());
25
       add(cv, BorderLayout.CENTER);
26
       BranchGroup bg = createSceneGraph();
27
       bg.compile();
28
       SimpleUniverse su = new SimpleUniverse(cv);
29
       su.getViewingPlatform().setNominalViewingTransform();
[Page 300]30
              su.addBranchGraph(bg);
31
    }
32
33
     private BranchGroup createSceneGraph() {
34
       BranchGroup root = new BranchGroup();
35
       TransformGroup spin = new TransformGroup();
36
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
37
       root.addChild(spin);
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38
39
40
       Sphere shape =
41
       new Sphere(0.7f, Primitive.GENERATE_TEXTURE_COORDS, 50, ap);
42
       spin.addChild(shape);
43
       // rotator
       Alpha alpha = new Alpha(-1, 6000);
44
45
       RotationInterpolator rotator =
46
       new RotationInterpolator(alpha, spin);
47
       BoundingSphere bounds = new BoundingSphere();
48
       rotator.setSchedulingBounds(bounds);
49
       spin.addChild(rotator);
50
       // background
51
       Background background = new Background(1.0f, 1.0f, 1.0f);
52
       background.setApplicationBounds(bounds);
53
       root.addChild(background);
54
       return root;
55
    }
56
57
     Appearance createTextureAppearance(){
58
         REGESTERED
                                  VERSION OF CHM TO PDF CONVERTER PRO
59
60
          getClass().getClassLoader().getResource("images/earth.jpg");
```



The resulting screen capture of the program is shown in Figure 9.15. The scene graph of the program is given in Figure 9.16.

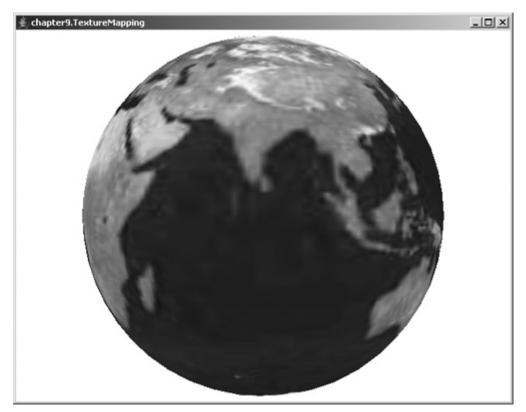


Figure 9.15. A rotating texture-mapped globe. (This item is displayed on page 301 in the print version)

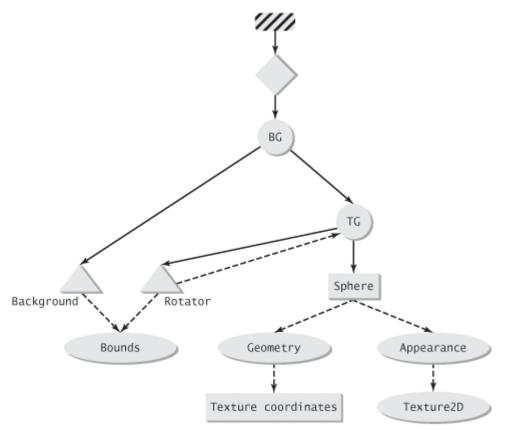


Figure 9.16. Scene graph for the texture-mapping example. (This item is displayed on page 301 in the print version)

A sphere is greated with texture coordinates The format flager initiated GENERADE TEXTURE COORDELINES FOR PRO constructor of the sphere enables the generation of texture coordinates for the primitive (Ime 41). The sphere is PRO rotated with a RotationInterpolator object.

The texture appearance is created with the method createTextureAppearance (line 57). An image of the earth is loaded from its disk file by the TextureLoader class. The loaded image is then assigned to an ImageComponent2D object, which is used to created a Texture2D object. The texture is mapped to the sphere through the associated Appearance object. Both magnification filter and minification filter are set to linear interpolation.

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### 9.6.2. Texture Coordinates

Texture coordinates in a geometry control the mapping from the texture image to the surface. The methods for setting texture coordinates in the GeometryArray class include:

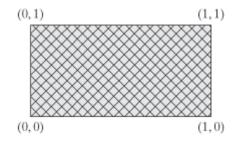
void setTextureCoordinate(int texSet, int index, float[] texCoord)
void setTextureCoordinate(int texSet, int index, TexCoord2f texCoord)
void setTextureCoordinates(int texSet, int index, float[] texCoords)
void setTextureCoordinates(int texSet, int index, float[] texCoords)

In the IndexedGeometryArray class and its subclasses, indices for texture coordinates can be applied using the methods:

```
void setTextureCoordinateIndex(int texSet, int index, int texCoordIdx)
void setTextureCoordinateIndices(int texSet, int index, int[]
texCoordIdx)
```

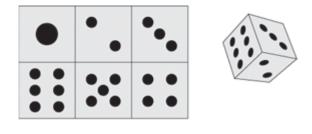
The class TexCoord2f is defined in the package javax.vecmath to represent texture coordinates. Other similar classes include TexCoord3f and TexCoord4f for 3D and 4D texture coordinates. A set of texture coordinates can be defined for one object. A texture coordinate is a 2D vector ( $\nu_i$ ,  $\nu$ ) that specifies a location in a texture. Values for  $\nu$  and  $\nu$  range from 0.0 to 1.0. The four corners of the image have the texture coordinates shown in Figure 9.17.

Figure 9.17. Texture coordinates define locations in an image.



Consider the problem of mapping the image shown in Figure 9.18 to a cube to create a die. The image can be divided into 6 squares, and there are 12 distinct texture coordinates to be assigned. To achieve the desired texture mapping, the vertices of a face of the cube should be assigned the texture coordinates of one square in the image.

Figure 9.18. Mapping an image to the faces of a cube.



[Page 303]

The following code fragment defines the geometry of the cube with the appropriate texture coordinates:

```
IndexedQuadArray qa = new IndexedQuadArray(12,
QuadArray.COORDINATES|QuadArray.TEXTURE_COORDINATE_2,24);
```

```
Point3f[] coords = {new Point3f(0,0,0), new Point3f(1,0,0),
new Point3f(1,1,0), new Point3f(0,1,0),
```

```
new Point3f(0,0,1),new Point3f(1,0,1),
new Point3f(1,1,1),new Point3f(0,1,1)};
int[] coordIndices =
\{0,1,2,3, 0,1,5,4, 1,2,6,5, 2,3,7,6, 3,0,4,7, 4,5,6,7\};
qa.setCoordinates(0, coords);
qa.setCoordinateIndices(0, coordIndices);
TexCoord2f[] tex = {new TexCoord2f(0, 1), new TexCoord2f(1f/3, 1),
new TexCoord2f(2f/3, 1), new TexCoord2f(1, 1),
new TexCoord2f(0, 0.5f),new TexCoord2f(1f/3, 0.5f),
new TexCoord2f(2f/3, 0.5f), new TexCoord2f(1, 0.5f),
new TexCoord2f(0, 0), new TexCoord2f(1f/3, 0),
new TexCoord2f(2f/3, 0),new TexCoord2f(1, 0)};
int[] texIndices =
\{0,1,5,4, 1,2,6,5, 2,3,7,6, 5,6,10,9, 6,7,11,10, 4,5,9,8\};
qa.setTextureCoordinates(0,0,tex);
qa.setTextureCoordinateIndices(0,0,texIndices);
```

### 9.6.3. Combining Texture Mapping and Lighting

It is also possible to combine texture mapping with other coloring models such as lighting. Java 3D includes the class TextureAttributes to control the options of texture mapping. For example, if we want to render an object with both texture mapping and lighting, we may create the configurations for both options and use a TextureAttributes object to combine the colors from the two sources. The geometry of the shape will have both normals and texture coordinates set. Lights will be placed in the scene graph, and a Material component will be used in the appearance bundle. We will also define a Texture component and select it in the appearance. The TextureAttributes class defines a variety of ways to combine texture mapping with the coloring options. The following code fragment shows a configuration to combine texture mapping with lighting:

```
TextureAttributes texatt = new TextureAttributes();
texatt.setTextureMode(TextureAttributes.COMBINE);
appearance.setTextureAttributes(texatt);
```

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Listing 9.5 demonstrates the combination of texture mapping and lighting. It displays a texture-mapped cylinder that is also lit (Figure 9.19). It illustrates the procedures of setting texture coordinates in a geometry, creating a texture image in code, and combining texture mapping with lighting using the TextureAttributes class.

Listing 9.5. Cup.java

(This item is displayed on pages 303 - 306 in the print version)



```
15 import com.sun.j3d.utils.applet.MainFrame;
 16 import com.sun.j3d.utils.behaviors.mouse.*;
17
18 public class Cup extends Applet {
19
     public static void main(String[] args) {
 20
       new MainFrame(new Cup(), 640, 480);
 21
     }
 22
    public void init() {
 23
 24
       // create canvas
 25
        GraphicsConfiguration gc =
 26
          SimpleUniverse.getPreferredConfiguration();
 27
        Canvas3D cv = new Canvas3D(qc);
 28
        setLayout(new BorderLayout());
 29
        add(cv, BorderLayout.CENTER);
 30
        BranchGroup bg = createSceneGraph();
 31
        bg.compile();
 32
        SimpleUniverse su = new SimpleUniverse(cv);
 33
        su.getViewingPlatform().setNominalViewingTransform();
 34
        su.addBranchGraph(bg);
 35
     }
 36
     private BranchGroup createSceneGraph() {
 37
        BranchGroup root = new BranchGroup();
 38
 39
        TransformGroup spin = new TransformGroup();
 40
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 41
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_READ);
 42
        root.addChild(spin);
 43
        // object transform
 44
        Transform3D tr = new Transform3D();
 45
        tr.setScale(0.3);
 46
        tr.setRotation(new AxisAngle4d(0, 0, 1, Math.PI/12));
 47
        TransformGroup tg = new TransformGroup(tr);
 48
        spin.addChild(tg);
 49
        // object
 50
        Geometry geom = createGeometry();
 51
        Appearance ap = createTextureAppearance();
 52
        PolygonAttributes pa =
 53
        new PolygonAttributes(PolygonAttributes.POLYGON_FILL,
 54
        PolygonAttributes.CULL_NONE,0);
 55
        ap.setPolygonAttributes(pa);
 56
        Shape3D shape = new Shape3D(geom, ap);
 57
        tg.addChild(shape);
 58
        // rotation
 59
        BoundingSphere bounds = new BoundingSphere();
 60
        Alpha alpha = new Alpha(-1, 10000);
 61
        RotationInterpolator rotator = new RotationInterpolator
 62
        (alpha, spin);
 63
        rotator.setSchedulingBounds(bounds);
        spin.addChild(rotator);
 64
 65
        // background and lights
 66
        Background background = new Background(1.0f, 1.0f, 1.0f);
 67
        background.setApplicationBounds(bounds);
 68
        root.addChild(background);
 69
        AmbientLight light = new AmbientLight(true,
                new Color3f(Color.lightGray));
[Page 305] 70
 71
        light.setInfluencingBounds(bounds);
 72
        root.addChild(light);
 73
        PointLight ptlight = new PointLight(new Color3f(Color.white),
```

```
74
        new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
 75
        ptlight.setInfluencingBounds(bounds);
 76
        root.addChild(ptlight);
 77
        return root;
 78
      }
 79
      Geometry createGeometry() {
 80
       int m = 120;
 81
        int n = 2;
 82
 83
        QuadArray qa = new QuadArray(4*m,
        QuadArray.COORDINATES QuadArray.NORMALS
 84
 85
        QuadArray.TEXTURE_COORDINATE_2);
 86
        // generate the cylinder
 87
        Transform3D trans = new Transform3D();
 88
        trans.rotY(2*Math.PI/m);
 89
        Point3f pt0 = new Point3f(1,1,0);
 90
        Point3f pt1 = new Point3f(1, -1, 0);
 91
        Vector3f normal = new Vector3f(1,0,0);
        for (int j = 0; j < m; j++) {
 92
 93
          qa.setCoordinate(j*4, pt0);
 94
          qa.setCoordinate(j*4+1, pt1);
          qa.setNormal(j*4, normal);
 95
          qa.setNormal(j*4+1, normal);
 96
 97
          trans.transform(pt0);
 98
          trans.transform(pt1);
 99
          trans.transform(normal);
100
          qa.setCoordinate(j*4+2, pt1);
101
          qa.setCoordinate(j*4+3, pt0);
102
          qa.setNormal(j*4+2, normal);
103
          qa.setNormal(j*4+3, normal);
104
          // set texture coordinates
105
          TexCoord2f tex0 = new TexCoord2f(j*lf/m, lf);
106
          TexCoord2f tex1 = new TexCoord2f(j*lf/m, 0f);
107
          qa.setTextureCoordinate(0,j*4,tex0);
108
          qa.setTextureCoordinate(0,j*4+1,tex1);
109
          tex0 = new TexCoord2f((j+1)*1f/m, 1f);
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110
111
          qa.setTextureCoordinate(0,j*4+3,tex0);
112
113
       }
114
       return qa;
115
     }
116
117
      Appearance createTextureAppearance() {
118
        Appearance ap = new Appearance();
119
        BufferedImage bi = new BufferedImage(512,128,
120
        BufferedImage.TYPE_INT_ARGB);
121
        Graphics2D g2 = (Graphics2D)bi.getGraphics();
122
        g2.setColor(Color.white);
123
        g2.fillRect(0, 0, 512,128);
124
        g2.setFont(new Font("Serif", Font.BOLD, 48));
125
        g2.setColor(new Color(200,0,0));
126
        g2.drawString("Java 3D",0,100);
127
        ImageComponent2D image =
128
          new ImageComponent2D(ImageComponent2D.FORMAT_RGBA, bi);
129
        Texture2D texture = new Texture2D
130

[Page JUNREGISTERED VIE BISION OF CHM TO PDF CONVERTER PRO
132
        texture.setImage(0, image);
```

```
133
        texture.setMagFilter(Texture.BASE_LEVEL_LINEAR);
134
        ap.setTexture(texture);
135
        // combine texture and lighting
136
       TextureAttributes texatt = new TextureAttributes();
137
        texatt.setTextureMode(TextureAttributes.COMBINE);
138
        ap.setTextureAttributes(texatt);
139
        ap.setMaterial(new Material());
140
        return ap;
141
      }
140 }
```

Lava 3D

Figure 9.19. A texture-mapped and lit cylinder.

The createGeometry method (line 80) constructs the cylinder with a QuadArray. Both normals and texture coordinates are generated in the geometry.

The createTextureAppearance method constructs an appearance bundle that includes a Material component, a Texture2D component, and a TextureAttributes object. The image for texture mapping is created directly as a BufferedImage of size 512 by 128 (line 119). A Graphics2D object is retrieved to allow drawing on the image. The image is first cleared with the white color, and then the string "Java 3D" is drawn in red (lines 121–126). The BufferedImage is used to create a Texture2D object for the texture mapping.

The cylinder is lit with an ambient light and a point light. The TextureAttributes object in the appearance is

set to the COMBINE mode to combine the effects of texture mapping and lighting (line 137).

### 9.6.4. Texture-Coordinates Generation

Texture coordinates can be specified directly in a geometry. It is also possible to generate the texture coordinates automatically using a model based on the object geometry and view configuration. The automatic generation of texture coordinates is achieved through a special node component in the appearance. The options of manual specification and automatic generation of texture coordinates are similar to the object coloring options: the colors may be specified directly in the object geometry or they can be generated with a lighting model.

[Page 307]

In addition to the 2D texture coordinates, Java 3D also supports 3D and 4D texture coordinates. These texture coordinates are denoted by (r, s), (r, s, t), (r, s, t, q), respectively. The constant flags for the three types of *texture coordinates* are defined as:

TEXTURE\_COORDINATE\_2 TEXTURE\_COORDINATE\_3 TEXTURE\_COORDINATE\_4

All three types of texture coordinates can be generated automatically. The node component class TexCoordGeneration facilitates texture-coordinates generation. Automatic texture-coordinates generation can be enabled by adding a TexCoordGeneration object to an appearance bundle. The TexCoordGeneration class defines five modes of texture-coordinates generation based on different criteria:

OBJECT\_LINEAR EYE\_LINEAR SPHERE\_MAP NORMAL\_MAP REFLECTION\_MAP

The OBJECT LINEAR and EYE LINEAR modes compute the texture coordinates using the following matrix equation NREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

	1 1					
r		$a_{11}$	$a_{12}$	$a_{13}$	$a_{14}$	<i>x</i>
s t	=	<i>a</i> <sub>21</sub>	$a_{22}$	$a_{22}$	a <sub>24</sub>	y
1		<i>a</i> <sub>31</sub>	$a_{32}$	a <sub>33</sub>	$a_{14} \\ a_{24} \\ a_{34} \\ a_{44} \end{bmatrix}$	z
$\lfloor q \rfloor$		$a_{41}$	$a_{42}$	$a_{43}$	$a_{44}$	w

Therefore, the texture coordinates of an object are linearly dependent on the object's coordinates. In the OBJECT\_LINEAR mode, the point (x, y, z, w) is given by object coordinates, so the texture is attached to the object and moves with the object. In EYE\_LINEAR mode, the point is given by eye coordinates, so the texture is fixed relative to the eye. As the object moves, the texture does not move with it. As a result, the texture may appear to be a reflection on the object. The coefficients in the above matrix can be set with the following methods:

void setPlaneS(Vector4f coeff)

```
void setPlaneT(Vector4f coeff)
void setPlaneQ(Vector4f coeff)
```

Each of these methods sets one row of the matrix.

The SPHERE\_MAP mode generates texture coordinates that can be used to simulate spherical reflections based on eye coordinates. The last two modes are available only for the special texture cube mapping. The ordinary Texture2D defines only a rectangular plane texture. The TextureCubeMap class defines a texture with six images configured as the six faces of a cube. The texture mapping will map each image to a specific side of the object. This type of texture mapping may be more convenient for certain 3D solids. In a TextureCubeMap object, the six images can be identified with the constants:

NEGATIVE\_X NEGATIVE\_Y NEGATIVE\_Z POSITIVE\_X POSITIVE\_Y POSITIVE\_Z

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Listing 9.6 illustrates different modes of texture-coordinates generation using a Texture CubeMap. A rotating dodecahedron is displayed with a texture defined by a TextureCubeMap object. Three images are used for the six faces of the cube. Opposite faces receive the same image. (See Figure 9.20.) Texture coordinates for the dodecahedron are generated with a TexCoordGeneration object. Five buttons labeled with the texture-coordinates generation modes. When you click a button, the corresponding mode will be selected for the TexCoordGeneration to render the dodecahedron.

Listing 9.6. CubeTexture.java

(This item is displayed on pages 308 - 310 in the print version)

```
1 package chapter9;
2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import java.net.*;
 7 import javax.media.j3d.*;
 8 import com.sun.j3d.utils.universe.*;
 9 import com.sun.j3d.utils.geometry.*;
10 import com.sun.j3d.utils.image.*;
11 import chapter6.Dodecahedron;
12 import java.applet.*;
13 import com.sun.j3d.utils.applet.MainFrame;
14
15 public class CubeTexture extends Applet implements ActionListener{
16 public static void main(String[] args) {
17
       new MainFrame(new CubeTexture(), 640, 480);
18
    }
19
20
   private Appearance ap = null;
21
22
   public void init() {
23
       setLayout(new BorderLayout());
24
       Panel panel = new Panel();
25
       panel.setLayout(new GridLayout(5,1));
26
       add(panel, BorderLayout.EAST);
```

```
Button button = new Button("OBJECT_LINEAR");
 27
 28
        button.addActionListener(this);
29
       panel.add(button);
       button = new Button("EYE_LINEAR");
30
 31
        button.addActionListener(this);
32
       panel.add(button);
33
       button = new Button("SPHERE_MAP");
 34
       button.addActionListener(this);
35
       panel.add(button);
36
       button = new Button("NORMAL MAP");
37
       button.addActionListener(this);
38
       panel.add(button);
39
       button = new Button("REFLECTION_MAP");
 40
       button.addActionListener(this);
 41
       panel.add(button);
42
 43
       GraphicsConfiguration gc =
 44
          SimpleUniverse.getPreferredConfiguration();
 45
       Canvas3D cv = new Canvas3D(qc);
 46
        add(cv, BorderLayout.CENTER);
 47
        BranchGroup bg = createSceneGraph();
 48
       bg.compile();
        SimpleUniverse su = new SimpleUniverse(cv);
 49
 50
        su.getViewingPlatform().setNominalViewingTransform();
[Page 309] 51
               su.addBranchGraph(bg);
52
     }
53
54
     private BranchGroup createSceneGraph() {
55
       BranchGroup root = new BranchGroup();
56
       TransformGroup spin = new TransformGroup();
 57
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
58
       root.addChild(spin);
59
       // object
 60
        ap = createTextureAppearance();
 61
        Shape3D shape = new Dodecahedron();
 62
        shape.setAppearance(ap);
    UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 63
 64
        TransformGroup tg = new TransformGroup(tr);
 65
 66
        tg.addChild(shape);
 67
       spin.addChild(tg);
 68
       // rotator
       Alpha alpha = new Alpha(-1, 18000);
 69
 70
       RotationInterpolator rotator = new RotationInterpolator
71
         (alpha, spin);
 72
       BoundingSphere bounds = new BoundingSphere();
 73
       rotator.setSchedulingBounds(bounds);
 74
       spin.addChild(rotator);
 75
       // background
 76
        Background background = new Background(1.0f, 1.0f, 1.0f);
 77
        background.setApplicationBounds(bounds);
 78
       root.addChild(background);
 79
       return root;
 80
     }
81
 82
      Appearance createTextureAppearance() {
 83
       NREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 84
            getClass().getClassLoader().getResource("images/earth.jpg");
 85
```

```
86
        TextureLoader loader = new TextureLoader(filename, this);
        ImageComponent2D image1 = loader.getImage();
 87
 88
         filename = getClass().getClassLoader().getResource
 89
          ("images/stone.jpg");
 90
        loader = new TextureLoader(filename, this);
 91
        ImageComponent2D image2 = loader.getImage();
 92
        filename = getClass().getClassLoader().getResource
 93
          ("images/sky.jpg");
 94
        loader = new TextureLoader(filename, this);
 95
        ImageComponent2D image3 = loader.getImage();
 96
 97
        TextureCubeMap texture =
 98
        new TextureCubeMap(Texture.BASE_LEVEL, Texture.RGBA,
99
        image1.getWidth());
100
        texture.setImage(0, TextureCubeMap.NEGATIVE_X, image3);
101
        texture.setImage(0, TextureCubeMap.NEGATIVE_Y, image1);
102
        texture.setImage(0, TextureCubeMap.NEGATIVE_Z, image2);
103
        texture.setImage(0, TextureCubeMap.POSITIVE_X, image3);
        texture.setImage(0, TextureCubeMap.POSITIVE_Y, image1);
104
105
        texture.setImage(0, TextureCubeMap.POSITIVE_Z, image2);
106
        texture.setEnable(true);
107
         texture.setMagFilter(Texture.BASE_LEVEL_LINEAR);
108
         texture.setMinFilter(Texture.BASE_LEVEL_LINEAR);
109
110
        ap.setTexture(texture);
111
[Page 310]112
                TexCoordGeneration tcg = new
         TexCoordGeneration(TexCoordGeneration.OBJECT_LINEAR,
113
114
         TexCoordGeneration.TEXTURE_COORDINATE_3);
115
        tcg.setPlaneR(new Vector4f(2, 0, 0, 0));
116
        tcg.setPlaneS(new Vector4f(0, 2, 0, 0));
117
        tcg.setPlaneT(new Vector4f(0, 0, 2, 0));
118
        ap.setTexCoordGeneration(tcg);
119
        ap.setCapability(Appearance.ALLOW_TEXGEN_WRITE);
120
        return ap;
121
     }
122
     public void actionPerformed(ActionEvent e) {
123
124
        String cmd = e.getActionCommand();
125
        TexCoordGeneration tcg = new TexCoordGeneration();
126
        if ("OBJECT_LINEAR".equals(cmd)) {
           tcg.setGenMode(TexCoordGeneration.OBJECT_LINEAR);
127
128
        } else if ("EYE_LINEAR".equals(cmd)) {
129
          tcg.setGenMode(TexCoordGeneration.EYE_LINEAR);
130
        } else if ("SPHERE_MAP".equals(cmd)) {
131
          tcg.setGenMode(TexCoordGeneration.SPHERE_MAP);
132
        } else if ("NORMAL_MAP".equals(cmd)) {
133
         tcg.setGenMode(TexCoordGeneration.NORMAL_MAP);
134
        } else if ("REFLECTION_MAP".equals(cmd)) {
135
           tcg.setGenMode(TexCoordGeneration.REFLECTION_MAP);
136
        }
137
        tcg.setFormat(TexCoordGeneration.TEXTURE_COORDINATE_3);
        tcg.setPlaneR(new Vector4f(2, 0, 0, 0));
138
139
        tcg.setPlaneS(new Vector4f(0, 2, 0, 0));
        tcg.setPlaneT(new Vector4f(0, 0, 2, 0));
140
141
        ap.setTexCoordGeneration(tcg);
142
143 }
```

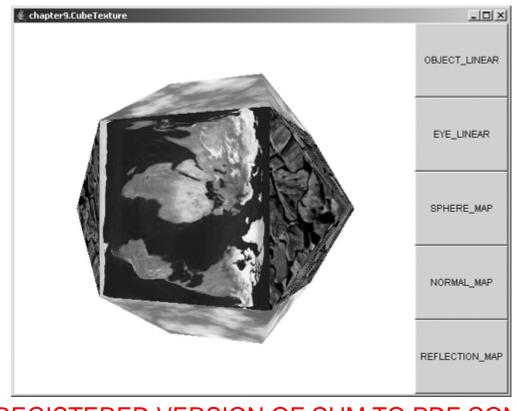


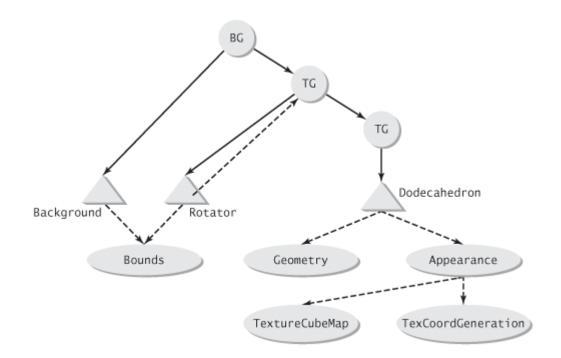
Figure 9.20. Cube texture applied with different modes of texture-coordinates generation.

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The scene graph is shown in Figure 9.21. A dodecahedron is attached to a series of two TransformGroup nodes: one for the rotation and the other to scale the size of the object down. The dodecahedron has an Appearance object that references a TextureCubeMap and a TexCoordGeneration. The capability bit ALLOW\_TEXGEN\_WRITE of the appearance is set to allow the change of the TexCoordGeneration in a live scene graph (line 119).

Figure 9.21. The scene graph for the example of texture-coordinates generation.

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Three images of the same size are loaded from image files (lines 84–95). They are used for the six faces of the TextureCubeMap object. The opposite faces get the same images.

The 3D texture coordinates needed by the TextureCubeMap are generated automatically with the TexCoordGeneration object. Initially the generation mode is set to OBJECT\_LINEAR.

The main program window uses a BorderLayout manager. The Canvas3D object is added to the "CENTER" region. Five buttons are created to represent the five modes of texture-coordinates generation: OBJECT\_LINEAR, EYE\_LINEAR, SPHERE\_MAP, NORMAL\_MAP, and REFLECTION\_MAP. The buttons are added to a panel in the "EAST" region of the applet. The buttons register the applet object as their ActionListener. In the action handler actionPerformed (line 123), a new TexCoordGeneration object is created. The button label is retrieved, and the corresponding texture-coordinates generation mode is set with the method setGenMode. The appearance object's texture-coordinates generation is then changed to the new TexCoordGeneration object by calling the method setTexCoordGeneration.

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#### Previous

### Key Classes and Methods

- javax.vecmath.TexCoord2f A class encapsulating a 2D texture coordinate.
- javax.vecmath.TexCoord3f A class encapsulating a 3D texture coordinate.
- javax.vecmath.TexCoord4f A class encapsulating a 4D texture coordinate.
- javax.media.j3d.Light A class encapsulating a light source.
- javax.media.j3d.AmbientLight A class encapsulating an ambient light.
- javax.media.j3d.DirectionalLight A class encapsulating a directional light.

#### [Page 312]

- javax.media.j3d.PointLight A class encapsulating a point light.
- javax.media.j3d.SpotLight A class encapsulating a spotlight.
- javax.media.j3d.Material A class defining the material properties for illumination.
- javax.media.j3d.Fog A class encapsulating the blending effects.
- javax.media.j3d.LinearFog A fog with a linear blending coefficient function.
- javax.media.j3d.ExponentialFog A fog with an exponential blending coefficient function.
- javax.media.j3d.Texture2D A class encapsulating a 2D texture.
- javax.media.j3d.ImageComponent2D A class encapsulating an image. UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO javax.media.j3d.TextureLoader A class for loading an image.
- javax.media.j3d.TextureAttributes An appearance component for controlling attributes of texture mapping.
- javax.media.j3d.TextureCubeMap A class defining a texture with six images on its cube faces.
- javax.media.j3d.TexCoordGeneration A class encapsulating texture coordinate generation.

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## UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

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#### Key Terms Phong model

An illumination model that takes into account the surface normals and directions of lights and the eye.

#### ambient light

A model for uniform omnidirectional background light.

#### directional light

A light that emits parallel light rays along a fixed direction.

#### point light

A light radiating from a fixed point.

#### spotlight

A point light with limited angle of radiation.

#### material

The reflection properties of an object that affect the color calculations.

#### ambient reflection

The reflection of ambient lights.

#### diffuse reflection

The reflection of directional and point lights that are uniformly distributed in all directions.

#### specular reflection

The reflection of directional and point lights that are concentrated on a fixed direction.

depth cueing

A visual effect of blurring distant objects into the background.

texture mapping

A rendering technique that maps an image to the surface of a 3D geometric object.

texel

A basic element of a texture.

texture coordinate

A coordinate used in a geometry to specify the location of the texel to be mapped.

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[Page 312 (continued)]

## Chapter Summary

- In this chapter, you learn several methods to achieve realistic appearance in 3D rendering.
- Lighting provides a model for calculating colors based on the physical characteristics of the objects and the light sources. The Phong illumination model is a popular method for lighting. Java 3D supports the model through the light objects, surface normal definition in geometry, and material specification in appearance.
- There are usually four types of lights in computer graphics: ambient lights, directional lights, point lights, and spotlights.

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- The material properties are defined in terms of coefficients for ambient reflection, diffuse reflection, and specular reflection. The coefficients are specified for each primary color. A shininess exponent independent of color spectrum is also used to define the concentration of specular reflection.
- The use of atmospheric attenuation and depth cueing is a method to enhance photorealism by blending distant objects. Java 3D provides the Fog class and subclasses LinearFog and ExponentialFog to support this effect.
- Texture mapping is another effective method that can dramatically improve the quality of rendered objects. Texture mapping uses images to provide details of rendered surfaces. To apply texture mapping in Java 3D, you need to define texture coordinates in the geometry of a visual object and include a texture image in its appearance. Texture coordinates may be specified directly in the geometry, or they can be generated automatically using a TexCoordGeneration object in the appearance.

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### **Review** Questions

- 9.1 A point light has attenuation coefficients (1, 2, 1). At what distance is the attenuation 0.04?
- 9.2 Discuss the differences between a point light and a directional light in terms of their effects on the equation of the Phong illumination model.
- 9.3 How do you position the eye to maximize the specular reflection of a point light from a point on a surface?
- 9.4 The point (1, 0, 0) on an object has a surface normal in the direction (0, 1, 0). A directional light with intensity 1.0 is placed in the direction (1, -1, 0). The eye is located at (5, 3, 0). If the RGB diffuse coefficients of the object are (0.3, 0.5, 0.2), find the RGB values of diffuse reflection at the point.
- 9.5 In the scene given in Question 9.4, if the RGB specular coefficients of the material are (1, 1, 0.5) and the shininess is 10, find the RGB values of specular reflection at the point.
- 9.6 The point (1, 0, 0) on an object has a surface normal in the direction (0, 1, 0). A point light with intensity 1.0 is placed at (0, 1, 0). The eye is located at (5, 3, 0). If the RGB diffuse coefficients of the object are (0.3, 0.5, 0.2), find the RGB values of diffuse reflection at the point.
- 9.7 In the scene given in Question 9.6, if the RGB specular coefficients of the material are (1, 1, 0.5) and the shininess is 10, find the RGB values of specular reflection at the point.
- 9.8 In the linear fog equation, find the distance at which the blending coefficient *f* is 0.5.
- 9.9 In the exponential fog equation, find the distance at which the blending coefficient /is 0.5.
- 9.10 What is the texture coordinate for the center of a texture image?

UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO image of the original texture image is mapped to an object?

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## UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

## **Programming Exercises**

- 9.1 Write a program to show the four coloring modes of Java 3D. Create and place four squares in the scene. Each square uses one of the coloring options.
- 9.2 Modify the program in Listing 9.1 to display a 3D text string.

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- 9.3 Write a program similar to Listing 9.2, but varying the specular reflection coefficients.
- 9.4 Display a long rectangle in a scene with a linear fog object. Observe the fading on the far side of the rectangle.
- 9.5 Modify Listing 9.3 to use an exponential fog. Add an option to allow the user to change the density parameter of the fog at runtime.
- 9.6 Write a Java 3D program to display a texture-mapped tetrahedron. Map the same texture to all four faces. Set the texture coordinates of the three vertices in a face to three corners of the texture. Rotate the tetrahedron in the scene.
- 9.7 Rewrite the program in Exercise 9.6 to use texture-coordinates generation with OBJECT\_LINEAR mode.
- 9.8 Rewrite the program in Exercise 9.7 to use texture-coordinates generation with EYE\_LINEAR mode.
- 9.9 Rewrite Listing 9.4 to light the texture-mapped globe with a red spotlight.
- 9.10 Write a Java 3D program to display a rotating die. Use a TextureCubeMap object with a cube geometry to construct the shape. Generate the six face images in the program by painting circles on BufferedImage objects. Set texture coordinates automatically with a TexCoordGeneration object in OBJECT\_LINEAR mode.

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## Chapter 10. Behavior and Interaction

(This item omitted from WebBook edition)

Objectives				
To understand dynamic behaviors in graphics.				
• To understand Java 3D Behavior and WakeupCondition classes.				
• To apply Behavior nodes in scene graphs.				
To use mouse behaviors.				
To use key navigator behaviors.				
To use view platform behaviors.				
To combine picking and behaviors.				
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## 10.1. Introduction

Modern decipier graphics systems are vide priced on hot pipe graphics and poperating on the program. A 3D scene is an important part of many graphics applications. Two types of dynamic changes are common in computer graphics: interaction and animation. *Interaction* changes the graphics scenes under the control of user input. *Animation* generates sequences of graphics renderings that vary with time, producing an effect of motion. Both mechanisms generate dynamic behaviors in graphics systems. The changes can occur in the virtual world of graphics objects or in the view that "sees" the world. The changes may involve the geometry, appearance, transformation, and other aspects of the visual system. In general the incorporation of dynamic behavior can be a complex process. It is usually necessary to allow the inclusion of general programming code to handle the dynamics. It is also desirable to include the dynamics logic as a part of the graphics programming paradigm in a systematic way.

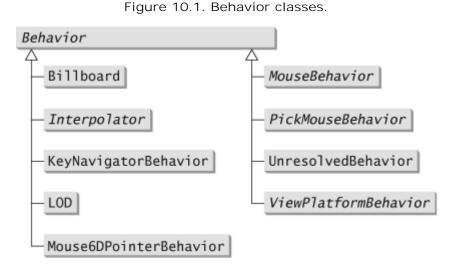
Java 3D uses the notion of behavior to facilitate animations, interactions, and other dynamics in a scene graph. A Behavior object is a leaf node in a scene graph. It defines the actions to be performed when the behavior is activated (waked up). Special objects called wakeup conditions are used to trigger a behavior. If a wakeup condition is related to user actions such as moving a mouse, the behavior defines an interaction. If a behavior is triggered by a wakeup condition tied to time, it defines an animation.

In this chapter we will introduce the general concept of behavior and one common type of behavior: interaction. We will also discuss the application of picking in defining interaction. Animation, another important type of behavior, will be discussed in Chapter 11.



## 10.2. Behavior

Java 3D provides a general unified approach to implement both animation and interaction. It takes advantage of Java's OOP features and uses the Behavior class hierarchy and other related classes to incorporate animation and interaction logic into the scene graph. The class hierarchy of the Behavior classes is given in Figure 10.1.



Behavior is an abstract class that extends the Leaf class. It defines the basic framework of a general behavior. The Behavior class has two abstract methods:

```
void initialize()
void processStimulus(Enumeration wakeupCriteria)
```

The initialize method is invoked once when a Behavior object becomes live. The processStimulus method is invoked by Java 3D under certain wakeup conditions. Subclasses of Behavior override the two methods to fulfill specific behavior tasks.

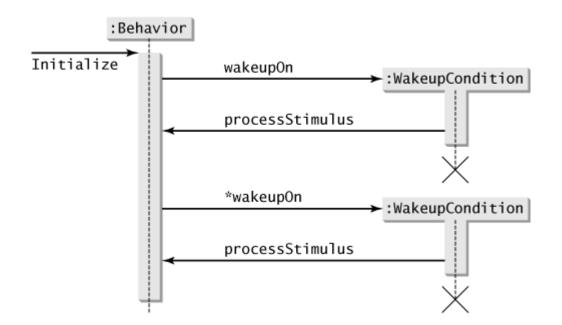
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A Behavior object works with WakeupCondition objects to complete its execution cycles. The Behavior class contains the following method to set a WakeupCondition that will trigger the behavior:

void wakeupOn(WakeupCondition wakeup)

The typical execution cycles of a Behavior object is illustrated in Figure 10.2.

Figure 10.2. Interactions between **Behavior** and **WakeupCondition** objects.

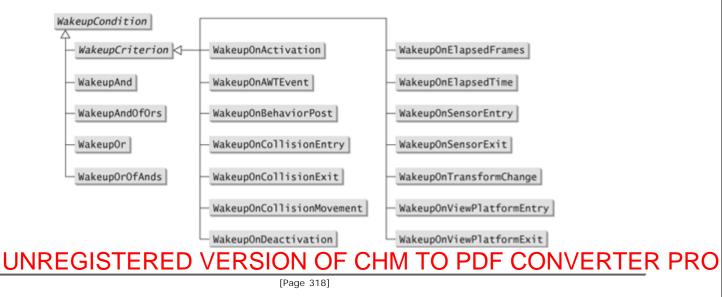


During the initialization of the Behavior object, it sets a WakeupCondition object. When the specified wakeup condition occurs, the WakeupCondition object will awaken the Behavior object by calling its processStimulus method. The parameter wakeupCriteria of the processStimulus method is a list of WakeupCriterion objects that trigger the behavior. After executing the custom code in processStimulus, a wakeup condition can be set again by calling the wakeupOn method. The process will then repeat indefinitely.

*Wakeup conditions* are crucial parts of the behavior dynamics. They serve as the signals to trigger different behaviors under different circumstances. Java 3D provides a large collection of wakeup criteria for various stimuli that can be used to trigger a behavior. It also provides the capability to combine the criteria in different ways using logical operators. The class hierarchy of WakeupCondition is shown in Figure 10.3.

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Figure 10.3. Wakeup condition class hierarchy.



The subclasses of WakeupCriterion represent specific events and criteria that can trigger a Behavior object. For example, WakeupOnElapsedTime defines the wakeup condition triggered by the passage of a certain amount of time. WakeupOnAWTEvent allows the wakeup conditions related to the AWT events such as mouse movements and clicks. Constructors for common wakeup criterion classes are listed below:

WakeupOnElapsedTime(long ms)

This constructor is to create a wakeup criterion to trigger a behavior after the specified time in milliseconds:

WakeupOnElapsedFrames(int frames)

This constructs a wakeup criterion to trigger a behavior after the specified number of frames:

WakeupOnAWTEvent(**int** eventID) WakeupOnAWTEvent(**long** eventMask)

This wakeup criterion triggers a behavior when the specified AWT events occur. An AWT event ID defines a single AWT event. For example, the following statement creates a criterion for the mouse-down event:

new WakeupOnAWTEvent(Event.MOUSE\_DOWN);

If several AWT events are needed, the second constructor with event masks can be used. AWT event masks may be combined with logical OR operator. For example, the following wakeup criterion corresponds to mouse event and mouse-motion event:

new WakeupOnAWTEvent(AWTEvent.MOUSE\_EVENT\_MASK |
 AWTEvent.MOUSE\_MOTION\_EVENT\_MASK);

Note that the class Event has been superseded by the AWTEvent class:

WakeupOnTransformChange(TransformGroup node)

This constructor is for a wakeup criterion to awaken a behavior when the transformation inside the specified TransformGroup node is changed:

```
WakeupOnCollisionEntry(Bounds bounds)
WakeupOnCollisionEntry(Node node)
WakeupOnCollisionEntry(Node node, int speedHint)
WakeupOnCollisionEntry(SceneGraphPath path)
WakeupOnCollisionEntry(SceneGraphPath path, int speedHint)
```

This wakeup criterion is to awaken a behavior when the specified object collides with any other object in the scene graph:

WakeupOnCollisionMovement(Bounds bounds)
WakeupOnCollisionMovement(Node node)
WakeupOnCollisionMovement(Node node, int speedHint)
WakupOnCollisionMovement(SceneGraphPath path)
WakupOnCollisionMovement(SceneGraphPath path, int speedHint)

These constructors are for a wakeup criterion to awaken a behavior when the specified object moves while in collision with any other object in the scene graph:

WakeupOnCollisionExit(Bounds bounds)
WakeupOnCollisionExit(Node node)
WakeupOnCollisionExit(Node node, int speedHint)
WakeupOnCollisionExit(SceneGraphPath path)
WakeupOnCollisionExit(SceneGraphPath path, int speedHint)

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This is a wakeup criterion to awaken a behavior when the specified object exits the collision with any other object in the scene graph:

WakeupOnBehaviorPost(Behavior behavior, int postID)

This wakeup criterion activates when the specified behavior object posts the specified ID. A Behavior object can post an event with a postID. This wakeup criterion monitors the postID posted by behavior. If the parameter behavior is null, the post can come from any Behavior object. If the parameter postID is 0, any ID will satisfy this wakeup criterion.

Multiple wakeup conditions may be logically combined to form a new wakeup condition. The class WakeupCondition has four subclasses—WakeupAnd, WakeupOr, WakeupOrOfAnds, and WakeupAndOfOrs—that define *Boolean operators* to combine wakeup criteria. Each class has a constructor that takes an array of appropriate objects as the parameter:

```
WakeupAnd(WakeupCriterion[] criteria)
WakeupOr(WakeupCriterion[] criteria)
WakeupOrOfAnds(WakeupAnd[] criteriaAnds)
WakeupAndOfOrs(WakeupOr[] criteriaOrs)
```

For example, the following code fragment defines a wakeup condition that either 10 seconds have passed or 5 frames are rendered and a collision has occurred:

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WakeupCriterion[] criteria1 = {new WakeupOnElapsedTime(10000)};
WakeupCriterion[] criteria2 = {new WakeupOnElapsedFrames(5),
 new WakeupOnCollisionEntry(node)};
WakeupAnd[] ands = {new WakeupAnd(criteria1),
 new WakeupAnd(criteria2)};
WakeupOrOfAnds condition = new WakeupOrOfAnds(ands);

A Behavior object has a scheduling bound. It is active only if its scheduling bound intersects the view platform. You may use the following methods to set the scheduling bounds:

SetSchedulingBounds(Bounds bounds);
SetSchedulingBoundingLeaf(BoundingLeaf bounds);

The typical procedure for implementing a *custom behavior* is summarized below:

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• Set the appropriate wakeup condition in the initialize method. If necessary, set the wakeup condition

again in processStimulus.

- Create an instance of the custom Behavior class and add it to the scene graph as a leaf.
- Set the influence bound for the behavior object.

Listing 10.1 shows an application using a custom Behavior class. The program displays a running analog clock showing the system time. The positions of the hands will constantly change. A custom behavior class (Listing 10.2) is implemented to update the clock based on the current time.

Listing 10.1. Clock.java

(This item is displayed on pages 319 - 321 in the print version)

```
1 package chapter10;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import java.util.*;
 7 import javax.media.j3d.*;
  8 import com.sun.j3d.utils.universe.*;
[Page 320] 9 import com.sun.j3d.utils.geometry.*;
10 import java.applet.*;
11 import com.sun.j3d.utils.applet.MainFrame;
12
13 public class Clock extends Applet {
14 public static void main(String[] args) {
 15
       new MainFrame(new Clock(), 640, 480);
 16
    }
17
 18 public void init() {
 19
     // create canvas
 20
      GraphicsConfiguration gc =
        SimpleUniverse.getPreferredConfiguration();
 21
 22
      Canvas3D cv = new Canvas3D(gc);
 23
      setLayout(new BorderLayout());
       add(cv, BorderLayout.CENTER);
 24
 25
       BranchGroup bg = createSceneGraph();
 26
       bg.compile();
 27
       SimpleUniverse su = new SimpleUniverse(cv);
 28
       su.getViewingPlatform().setNominalViewingTransform();
       su.addBranchGraph(bg);
 29
 30
    }
 31
 32 private BranchGroup createSceneGraph() {
 33
      BranchGroup root = new BranchGroup();
 34
       // clock face
 35
       Appearance apFace = new Appearance();
 36
       Material matFace = new Material();
       matFace.setAmbientColor(new Color3f(0f,0f,0f));
 37
       matFace.setDiffuseColor(new Color3f(0.15f,0.15f,0.25f));
 38
 39
       apFace.setMaterial(matFace);
 40
       Cylinder face = new Cylinder(0.6f, 0.01f,
       Cylinder.GENERATE_NORMALS, 50, 2, apFace);
 41
 42
       Transform3D tr = new Transform3D();
 43
       tr.rotX(Math.PI/2);
       tr.setTranslation(new Vector3d(0,0,-0.01));
 44
 45
       TransformGroup tg = new TransformGroup(tr);
 46
       tg.addChild(face);
```

```
47
        root.addChild(tg);
        // hour
 48
 49
        Appearance ap = new Appearance();
 50
        ap.setMaterial(new Material());
 51
        Shape3D shapeHour =
 52
          new Shape3D(createGeometry(0.4, 0.02, 0.02), ap);
 53
        TransformGroup spinHour = new TransformGroup();
 54
        spinHour.addChild(shapeHour);
 55
        spinHour.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 56
        root.addChild(spinHour);
 57
        // minute
 58
        Shape3D shapeMin =
          new Shape3D(createGeometry(0.5, 0.02, 0.02), ap);
 59
 60
        TransformGroup spinMin = new TransformGroup();
 61
        spinMin.addChild(shapeMin);
 62
        spinMin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 63
        root.addChild(spinMin);
 64
        // second
 65
        Shape3D shapeSec =
 66
          new Shape3D(createGeometry(0.5, 0.01, 0.01), ap);
 67
        TransformGroup spinSec = new TransformGroup();
 68
        spinSec.addChild(shapeSec);
         spinSec.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 69
[Page 321] 70
                root.addChild(spinSec);
 71
        // Behavior node
 72
        ClockBehavior rotator =
 73
          new ClockBehavior(spinHour, spinMin, spinSec);
 74
        BoundingSphere bounds = new BoundingSphere();
 75
        rotator.setSchedulingBounds(bounds);
 76
        root.addChild(rotator);
 77
        // light
 78
        AmbientLight light =
 79
          new AmbientLight(true, new Color3f(Color.blue));
 80
        light.setInfluencingBounds(bounds);
 81
        root.addChild(light);
     PointLight ptlight = new PointLight(new Color3f(Color.white),
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 82
 83
 84
        root.addChild(ptlight);
 85
 86
        // background
 87
        Background background = new Background(0.7f, 0.7f, 0.7f);
 88
        background.setApplicationBounds(bounds);
 89
        root.addChild(background);
 90
        return root;
 91
      }
 92
 93
      GeometryArray createGeometry(double 1, double w, double h) {
 94
        GeometryInfo gi =
 95
          new GeometryInfo(GeometryInfo.TRIANGLE_ARRAY);
 96
        Point3d[] pts = new Point3d[4];
 97
        pts[0] = new Point3d(0, 0, h);
 98
        pts[1] = new Point3d(-w, 0, 0);
 99
        pts[2] = new Point3d(w, 0, 0);
100
        pts[3] = new Point3d(0, 1, 0);
        gi.setCoordinates(pts);
101
102
        int[] indices = {0,1,2,0,3,1,0,2,3,2,1,3};
     UNREGISTERED WERSION, OF CHM TO PDF CONVERTER PRO
103
104
105
        ng.generateNormals(gi);
```

```
106 return gi.getGeometryArray();
107 }
108 }
```

#### Listing 10.2. ClockBehavior.java

(This item is displayed on pages 321 - 322 in the print version)

```
1 package chapter10;
 2
 3 import java.util.*;
 4 import javax.media.j3d.*;
 5
 6 public class ClockBehavior extends Behavior {
 7
    TransformGroup tgH;
 8
    TransformGroup tgM;
 9
    TransformGroup tgS;
10
11
    public ClockBehavior(TransformGroup transH,
12
     TransformGroup transM, TransformGroup transS) {
13
     tgH = transH;
14
      tgM = transM;
15
      tgS = transS;
16
     }
17
18
     public void initialize() {
[Page 322]19
               wakeupOn(new WakeupOnElapsedTime(500));
20
    }
21
22
     public void processStimulus(java.util.Enumeration enumeration) {
23
       int hour = Calendar.getInstance().get(Calendar.HOUR);
24
       int min = Calendar.getInstance().get(Calendar.MINUTE);
25
       int sec = Calendar.getInstance().get(Calendar.SECOND);
26
       Transform3D tr = new Transform3D();
       tr.rotZ(-Math.PI * (hour+min/60.0)/6.0);
27
28
       tgH.setTransform(tr);
29
       tr.rotZ(-Math.PI * min /30.0);
30
       tgM.setTransform(tr);
31
       tr.rotZ(-Math.PI * sec /30.0);
32
       tgS.setTransform(tr);
33
       wakeupOn(new WakeupOnElapsedTime(500));
34
    }
35 }
```

The program produces a 3D clock as shown in Figure 10.4. The visual content branch of the scene graph is shown in Figure 10.5.

Figure 10.4. A clock driven by a **Behavior** object.

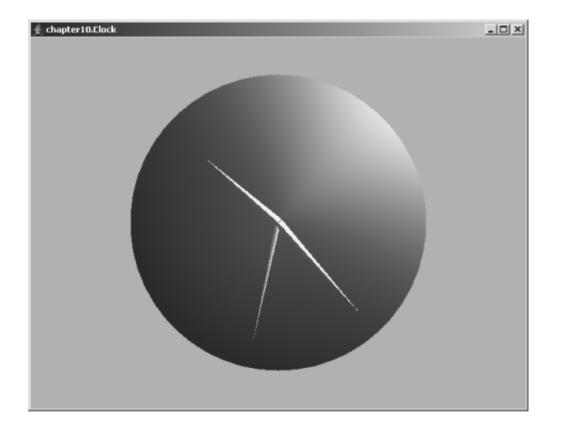
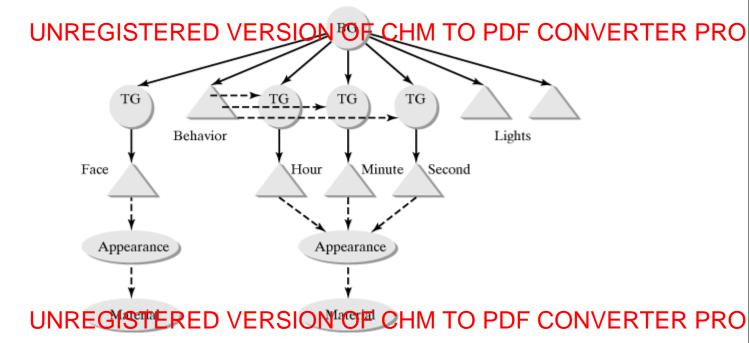


Figure 10.5. The scene graph of the clock. (This item is displayed on page 323 in the print version)



The program displays a real-time analog clock. The hour, minute, and second hands are created with the method createGeometry (line 93). createGeometry uses GeometryInfo to create a geometry with four vertices and four triangle faces. Surface normals are generated with a NormalGenerator object to facilitate lighting. A blue ambient light and a white point light are placed in the scene. The background is set to gray.

Each of three clock-hand objects is attached to a TransformGroup node. The transformations control the movements of the hands. In order to make the clock run, we need to update the transformations periodically. A behavior may be applied to drive the update.

The ClockBehavior class is a subclass of Behavior that acts on the TransformGroup objects controlling the hands of the clock. It is set to wake up after 0.5 second in the initialize method (line 19) and also in the processStimulus method (line 33). The main task of the behavior is to update the clock-hands rotations based on the system time. The current time is obtained from the Calendar class. The rotations of the hands are calculated based on the time:

$$hourAngle = -\frac{2\pi}{12} \left( hour + \frac{minute}{60} \right)$$
$$minuteAngle = -\frac{2\pi}{60} minute$$
$$secondAngle = -\frac{2\pi}{60} second$$

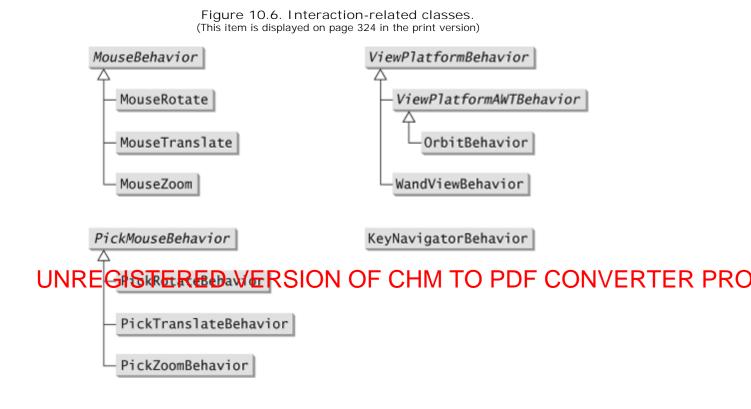
◀ Previous

Next ►

## 10.3. Interaction

Interaction deals with the dynamic behavior triggered by user input. The general mechanisms for interaction and animation are similar under the behavior framework. The main difference is in the sources of wakeup conditions. In interaction the stimuli are from user input devices such as the mouse, keyboard, and 3D input devices.

Java 3D provides families of behavior subclasses for interaction. It is certainly possible to construct custom interaction behaviors using the basic Behavior class and wakeup conditions. However, the predefined utility classes are convenient for some commonly used interaction behaviors. Behavior classes related to interaction are shown in Figure 10.6.



### 10.3.1. Mouse Behaviors

The MouseBehavior classes define specific behaviors related to mouse motions. A behavior in this family operates on an associated TransformGroup object. Users can modify the target TransformGroup object with mouse movements. The types of mouse motions used in the behaviors are given below:

- MouseRotate: drag the mouse with the left button down.
- MouseTranslate: drag the mouse with the right button down.
   UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
   MouseZoom: drag the mouse with the middle button down (or with left button down while holding the Alt
- Mousezoom: drag the mouse with the middle button down (or with left button down while holding the Alt key).

[Page 324]

Usages of the three classes are similar. A TransformGroup object is selected as the target of the behavior object. The mouse behaviors can be linked to mouse events in two ways:

- 1. Use the WakeupOnAWTEvent to trigger the behavior. The target is controlled by the mouse events on the Canvas3D object.
- 2. Specify an AWT component to listen to the mouse events and use the WakeupOnBehaviorPost to trigger the behavior. This mode is useful when you try to apply mouse controls from another AWT component.

Constructors of MouseBehavior classes include:

```
MouseRotate(TransformGroup tg)
MouseRotate(Component c)
MouseRotate(Component c, TransformGroup tg)
MouseTranslate(TransformGroup tg)
MouseTranslate(Component c)
MouseTranslate(Component c, TransformGroup tg)
MouseZoom(TransformGroup tg)
MouseZoom(Component c)
MouseZoom(Component c, TransformGroup tg)
```

The constructors with a Component parameter operate in the second mode that accepts a separate component for mouse actions.

Listing 10.3 shows an application of the various MouseBehavior classes. It displays a globe and a set of axes (Figure 10.7). A user may rotate, translate, and zoom the globe with the mouse. However, the axes are not affected by the mouse motions.

Listing 10.3. MoveGlobe.java

(This item is displayed on pages 324 - 326 in the print version)

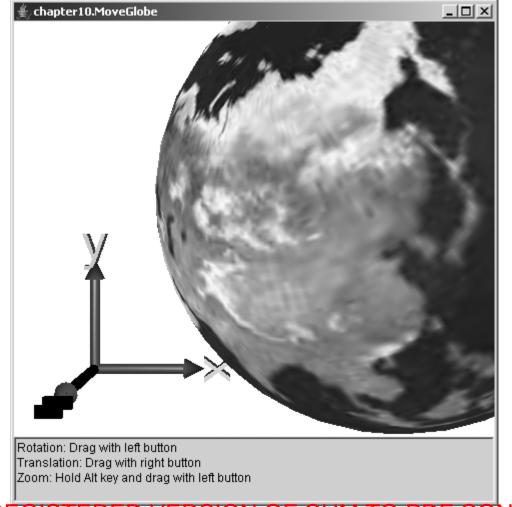
```
1 package chapter10;
 2
 3 import javax.vecmath.*;
  4 import java.awt.*;
 5 import java.awt.event.*;
  6 import java.net.URL;
  7 import javax.media.j3d.*;
  8 import com.sun.j3d.utils.universe.*;
  9 import com.sun.j3d.utils.geometry.*;
[Page 325] 10 import com.sun.j3d.utils.image.*;
 11 import com.sun.j3d.utils.behaviors.mouse.*;
 12 import chapter7.Axes;
13 import java.applet.*;
 14 import com.sun.j3d.utils.applet.MainFrame;
15
 16 public class MoveGlobe extends Applet {
17
    public static void main(String[] args) {
18
        new MainFrame(new MoveGlobe(), 480, 480);
19
    }
20
 21
    public void init() {
 2.2
       // create canvas
 23
        GraphicsConfiguration gc =
 24
          SimpleUniverse.getPreferredConfiguration();
```

```
Canvas3D cv = new Canvas3D(gc);
 25
 26
        setLayout(new BorderLayout());
 27
        add(cv, BorderLayout.CENTER);
        TextArea ta = new TextArea("",3,30,TextArea.SCROLLBARS_NONE);
 28
 29
        ta.setText("Rotation: Drag with left button\n");
        ta.append("Translation: Drag with right button\n");
30
        ta.append("Zoom: Hold Alt key and drag with left button");
31
        ta.setEditable(false);
32
33
        add(ta, BorderLayout.SOUTH);
34
        BranchGroup bg = createSceneGraph();
35
       bq.compile();
        SimpleUniverse su = new SimpleUniverse(cv);
36
 37
        su.getViewingPlatform().setNominalViewingTransform();
38
        su.addBranchGraph(bg);
39
     }
40
 41
     private BranchGroup createSceneGraph() {
 42
       BranchGroup root = new BranchGroup();
 43
       // axes
 44
       Transform3D tr = new Transform3D();
 45
       tr.setScale(0.5);
        tr.setTranslation(new Vector3d(-0.8, -0.7, -0.5));
 46
 47
       TransformGroup tg = new TransformGroup(tr);
 48
       root.addChild(tg);
 49
       Axes axes = new Axes();
       tg.addChild(axes);
50
51
       // transform
52
       TransformGroup spin = new TransformGroup();
 53
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 54
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_READ);
55
       root.addChild(spin);
56
       // texture mapped globe
57
       Appearance ap = createAppearance();
58
        spin.addChild(new Sphere(0.7f,
 59
        Primitive.GENERATE_TEXTURE_COORDS, 50, ap));
 60
        // rotation
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 61
 62
        rotator.setSchedulingBounds(bounds);
 63
 64
        spin.addChild(rotator);
 65
        // translation
 66
        MouseTranslate translator = new MouseTranslate(spin);
 67
        translator.setSchedulingBounds(bounds);
        spin.addChild(translator);
 68
 69
       // zoom
70
       MouseZoom zoom = new MouseZoom(spin);
[Page 326] 71
               zoom.setSchedulingBounds(bounds);
       spin.addChild(zoom);
72
73
       // light
74
       AmbientLight light =
 75
         new AmbientLight(true, new Color3f(Color.blue));
 76
        light.setInfluencingBounds(bounds);
 77
       root.addChild(light);
        PointLight ptlight = new PointLight(new Color3f(Color.white),
 78
 79
          new Point3f(0f,0f,2f), new Point3f(1f,0.3f,0f));
        ptlight.setInfluencingBounds(bounds);
 80
       NREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 81
 82
```

83 Background background = new Background(1.0f, 1.0f, 1.0f);

```
84
        background.setApplicationBounds(bounds);
 85
        root.addChild(background);
 86
        return root;
 87
     }
 88
 89
    Appearance createAppearance(){
 90
       Appearance appear = new Appearance();
 91
        URL filename =
 92
          getClass().getClassLoader().getResource("images/earth.jpg");
       TextureLoader loader = new TextureLoader(filename, this);
 93
 94
       ImageComponent2D image = loader.getImage();
 95
        Texture2D texture = new Texture2D
 96
         (Texture.BASE_LEVEL, Texture.RGBA,
       image.getWidth(), image.getHeight());
 97
 98
      texture.setImage(0, image);
99
       texture.setEnable(true);
100
        texture.setMagFilter(Texture.BASE_LEVEL_LINEAR);
101
        texture.setMinFilter(Texture.BASE_LEVEL_LINEAR);
102
        appear.setTexture(texture);
103
        return appear;
104
    }
105 }
```

Figure 10.7. Moving the globe with a mouse.



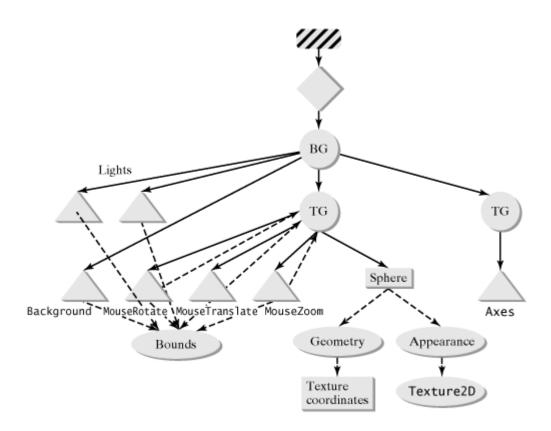
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[Page 327]

A texture-mapped globe and a set of coordinate axes are displayed in the frame. The globe can be manipulated by mouse actions. A TextArea object placed under the 3D canvas displays instructions for mouse operations. When a user moves the mouse while holding down the left mouse button, the globe will rotate. Holding the right mouse button and dragging the mouse performs a translation. Holding the Alt key and dragging with the left mouse button down performs a scaling.

The scene graph of the program is shown in Figure 10.8. The Sphere object is attached to a TransformGroup object. A MouseRotate object, a MouseTranslate object, and a MouseZoom object are placed in the scene graph. They all operate on the same TransformGroup object above the sphere (lines 60–72). The three behaviors will modify different components of the transform. The behavior objects share the same bounds object for their scheduling bounds. A background node also references the bounds object.

Figure 10.8. Scene graph of mouse behavior demo.



The Axes object is on a separate branch of the scene graph with its own TransformGroup node. This transform is not controlled by the mouse behaviors. Consequently, the mouse motions will not affect the coordinate axes.

#### 10.3.2. Key Behaviors

Similar to the mouse behaviors, the KeyNavigatorBehavior class operates on a TransformGroup object, but this behavior is controlled by key strokes. KeyNavigatorBehavior has the following constructors:

KeyNavigatorBehavior(TransformGroup tg)
KeyNavigatorBehavior(Component c, TransformGroup tg)

The built-in *key controls* of the KeyNavigatorBehavior class are defined as follows:

- ←,→: Rotate left/right
- 1,1: Translate forward/backward

[Page 328]

- Alt- ←, Alt- →: Translate left/right
- PgUp, PgDn: Rotate up/down
- Alt-PgUp, Alt-PgDn: Translate up/down
- -: Reduce back clip distance

- +: Reset back clip distance
- =: Reset

Listing 10.4 shows an application of the KeyNavigatorBehavior class. It displays a texture-mapped globe and allows users to rotate, translate, and reset the scene through the keyboard (Figure 10.9).

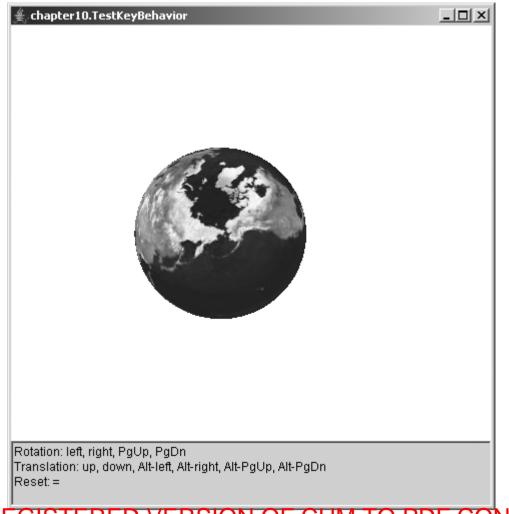
Listing 10.4. TestKeyBehavior.java

(This item is displayed on pages 328 - 329 in the print version)

```
1 package chapter10;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import java.net.URL;
 7 import javax.media.j3d.*;
 8 import com.sun.j3d.utils.universe.*;
 9 import com.sun.j3d.utils.geometry.*;
10 import com.sun.j3d.utils.image.*;
11 import com.sun.j3d.utils.behaviors.keyboard.*;
12 import java.applet.*;
13 import com.sun.j3d.utils.applet.MainFrame;
14
15 public class TestKeyBehavior extends Applet {
16
    public static void main(String[] args) {
17
       new MainFrame(new TestKeyBehavior(), 480, 480);
18
    }
19
20
    public void init() {
21
       GraphicsConfiguration gc =
22
         SimpleUniverse.getPreferredConfiguration();
23
       Canvas3D cv = new Canvas3D(gc);
24
       setLayout(new BorderLayout());
25
       add(cv, BorderLayout.CENTER);
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26
27
28
       ta.append("Translation: up, down,
29
       Alt-left, Alt-right, Alt-PgUp, Alt-PgDn\n");
30
       ta.append("Reset: =\n");
31
      ta.setEditable(false);
32
       add(ta, BorderLayout.SOUTH);
33
       BranchGroup bg = createSceneGraph();
34
      bq.compile();
35
       SimpleUniverse su = new SimpleUniverse(cv);
36
       su.getViewingPlatform().setNominalViewingTransform();
37
       su.addBranchGraph(bg);
38
    }
39
40
    private BranchGroup createSceneGraph() {
41
       BranchGroup root = new BranchGroup();
42
       TransformGroup spin = new TransformGroup();
43
       spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
[Page 329]44
               spin.setCapability(TransformGroup.ALLOW_TRANSFORM_READ);
45
       root.addChild(spin);
46
       // texture mapped globe
     UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
47
       spin.addChild(new Sphere(0.7f,
48
49
       Primitive.GENERATE_TEXTURE_COORDS, 50, ap));
```

```
50
       // key behavior
51
       KeyNavigatorBehavior behavior = new KeyNavigatorBehavior(spin);
52
       BoundingSphere bounds = new BoundingSphere();
53
       behavior.setSchedulingBounds(bounds);
54
       spin.addChild(behavior);
55
       // background
56
       Background background = new Background(1.0f, 1.0f, 1.0f);
57
       background.setApplicationBounds(bounds);
58
       root.addChild(background);
59
       return root;
60
    }
61
62
    Appearance createAppearance(){
63
      Appearance appear = new Appearance();
64
      URL filename =
65
         getClass().getClassLoader().getResource("images/earth.jpg");
66
      TextureLoader loader = new TextureLoader(filename, this);
67
      ImageComponent2D image = loader.getImage();
      Texture2D texture =
68
69
         new Texture2D(Texture.BASE_LEVEL, Texture.RGBA,
70
      image.getWidth(), image.getHeight());
71
      texture.setImage(0, image);
72
      texture.setEnable(true);
73
      texture.setMagFilter(Texture.BASE_LEVEL_LINEAR);
74
      texture.setMinFilter(Texture.BASE_LEVEL_LINEAR);
75
      appear.setTexture(texture);
76
       return appear;
77
    }
78 }
```

Figure 10.9. Controlling transformation through the keyboard.



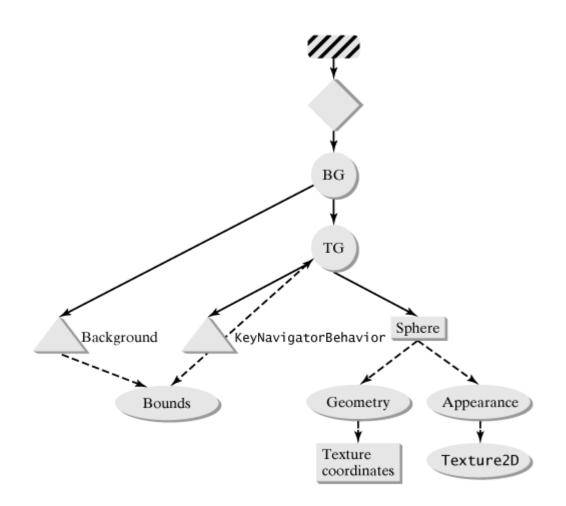
## UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

[Page 330]

This program allows the user to manipulate the visual object, a texture-mapped globe, through the keyboard. A text area at the bottom of the window displays the instructions to use the keyboard for navigating the scene.

The scene graph is shown in Figure 10.10. A texture-mapped sphere similar to the one in Listing 10.2 is created and attached to a TransformGroup object. A KeyNavigatorBehavior object is created to operate on the TransformGroup node (line 51). The behavior object will react to keyboard inputs by performing associated transformations. The KeyNavigatorBehavior object uses a BoundingSphere as its scheduling bounds. The bounds object is also referenced by a white background.

Figure 10.10. Scene graph of key behavior demo program.



#### 10.3.3. View Platform Behaviors

The ViewPlatformBehavior classes support interaction with the view platform. The class OrbitBehavior allows changes in view platform through mouse-motion input. Unlike the MouseBehavior class that has three separate subclasses for different transformations, this single class OrbitBehavior supports three operations: rotation, translation, and zoom. The definitions for mouse operations are the same as the MouseBehavior classes. A Canvas3D object is used by OrbitBehavior. To create an OrbitBehavior object the following constructors can be used:

```
OrbitBehavior()
OrbitBehavior(Canvas3D cv)
OrbitBehavior(Canvas3D cv, int flags)
```

An OrbitBehavior object can be added to a scene graph by calling the method setViewPlatformBehavior in the class ViewingPlatform that is a part of SimpleUniverse.

Listing 10.5 illustrates the use of OrbitBehavior to manipulate the view platform. It displays a globe and allows users to rotate, translate, and zoom the entire view through mouse motions (See Figure 10.11.)

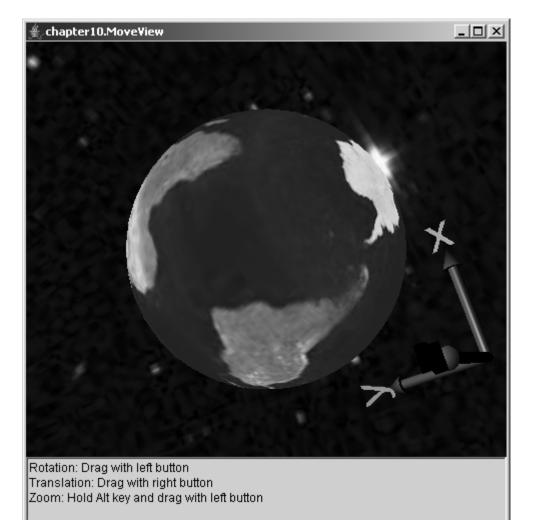
Listing 10.5. MoveView.java (This item is displayed on pages 330 - 332 in the print version)

```
1 package chapter10;
 2
[Page 331] 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import java.net.URL;
 7 import javax.media.j3d.*;
 8 import com.sun.j3d.utils.universe.*;
 9 import com.sun.j3d.utils.geometry.*;
10 import com.sun.j3d.utils.image.*;
11 import com.sun.j3d.utils.behaviors.mouse.*;
12 import com.sun.j3d.utils.behaviors.vp.*;
13 import chapter7.Axes;
14 import java.applet.*;
15 import com.sun.j3d.utils.applet.MainFrame;
16
17 public class MoveView extends Applet {
    public static void main(String[] args) {
18
       new MainFrame(new MoveView(), 480, 480);
19
20
    }
21
   public void init() {
22
23
      GraphicsConfiguration gc =
24
         SimpleUniverse.getPreferredConfiguration();
25
      Canvas3D cv = new Canvas3D(gc);
      setLayout(new BorderLayout());
26
27
      add(cv, BorderLayout.CENTER);
28
      TextArea ta = new TextArea("",3,30,TextArea.SCROLLBARS_NONE);
29
       ta.setText("Rotation: Drag with left button\n");
30
       ta.append("Translation: Drag with right button\n");
31
      ta.append("Zoom: Hold Alt key and drag with left button");
32
      ta.setEditable(false);
33
       add(ta, BorderLayout.SOUTH);
34
       BranchGroup root = new BranchGroup();
35
       // axes
36
       Transform3D tr = new Transform3D();
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37
38
       TransformGroup tg = new TransformGroup(tr);
39
40
      root.addChild(tg);
41
      Axes axes = new Axes();
42
      tg.addChild(axes);
43
      // texture mapped globe
44
      Appearance ap = createAppearance();
45
      root.addChild(new Sphere(0.7f,
46
      Primitive.GENERATE_TEXTURE_COORDS, 50, ap));
47
      BoundingSphere bounds = new BoundingSphere();
48
      // light
49
      AmbientLight light = new AmbientLight(true,
50
      new Color3f(Color.blue));
51
       light.setInfluencingBounds(bounds);
52
      root.addChild(light);
53
       PointLight ptlight = new PointLight(new Color3f(Color.white),
54
       new Point3f(0f,0f,2f), new Point3f(1f,0.3f,0f));
       ptlight.setInfluencingBounds(bounds);
55
56
       root.addChild(ptlight);
57
     UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
58
```

59 background.setApplicationBounds(bounds);

```
root.addChild(background);
60
61
       root.compile();
62
       SimpleUniverse su = new SimpleUniverse(cv);
63
       su.getViewingPlatform().setNominalViewingTransform();
64
       // viewplatform motion
[Page 332]65
               OrbitBehavior orbit = new OrbitBehavior(cv);
66
       orbit.setSchedulingBounds(new BoundingSphere());
67
        su.getViewingPlatform().setViewPlatformBehavior(orbit);
68
69
       su.addBranchGraph(root);
70
    }
71
72
    Appearance createAppearance(){
73
      Appearance appear = new Appearance();
74
       URL filename =
75
          getClass().getClassLoader().getResource("images/earth.jpg");
76
       TextureLoader loader = new TextureLoader(filename, this);
77
       Texture texture = loader.getTexture();
78
       appear.setTexture(texture);
79
       return appear;
80
    }
81
82
    Background createBackground(){
83
       Background background = new Background();
84
       BranchGroup bg = new BranchGroup();
85
       Sphere sphere = new Sphere(1.0f, Sphere.GENERATE_NORMALS |
86
       Sphere.GENERATE_NORMALS_INWARD |
87
       Sphere.GENERATE_TEXTURE_COORDS, 60);
88
       Appearance ap = sphere.getAppearance();
89
       bg.addChild(sphere);
90
       background.setGeometry(bg);
91
92
       URL filename =
          getClass().getClassLoader().getResource("images/stars.jpg");
93
94
       TextureLoader loader = new TextureLoader(filename, this);
95
       Texture texture = loader.getTexture();
96
       ap.setTexture(texture);
97
       return background;
98
    }
99 }
```

Figure 10.11. Manipulating the view. The view changes with the mouse motions.



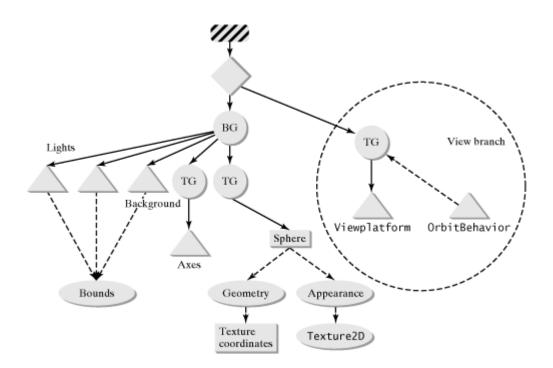
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[Page 333]

This program appears to be similar to Listing 10.3. The user can rotate, translate, and zoom the scene with mouse motions. However, there are some differences. Because the behavior movement is applied to the view platform instead of to the objects, the directions of the motion will be the opposite of those in Listing 10.3. Another difference is that in this example the entire view of the scene changes as the mouse moves. In Listing 10.3 the movement applies only to the globe, and the axes do not move.

The scene graph is shown in Figure 10.12. The OrbitBehavior operates on the transform associated with the ViewPlatform. This configuration is established by the following statements (lines 65–67):

Figure 10.12. Scene graph of the View Behaviors example.



OrbitBehavior orbit = new OrbitBehavior(cv); orbit.setSchedulingBounds(new BoundingSphere()); su.getViewingPlatform().setViewPlatformBehavior(orbit);

Because the behavior is in the view branch, the visual objects are not actually moved by the mouse motions. The behavior changes the positioning of the view platform. Therefore, the entire scene, including the globe and the axes, appears to move in the opposite directions of the mouse operations.

The method createBackground (line 82) creates a background using a texture-mapped sphere as its geometry. The background provides a better perception of the view motion.

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[Page 333 (continued)]

### 10.4. Behavior and Picking

Picking is often applied in conjunction with behaviors to perform interactions associated with specific visual objects. Picking provides a mechanism to dynamically select visual objects. The behavior structure offers a systematic way to incorporate operations on the scene.

[Page 334]

### 10.4.1. Picking and Mouse Behaviors

The PickMouseBehavior classes, including PickRotateBehavior, PickTranslateBehavior, and PickZoomBehavior, combine picking with mouse behaviors. The mouse-controlled rotation, translation, and zoom operations are the same as those defined in MouseBehavior, but they are applied only to the picked objects. Creating a PickMouseBehavior node involves the Canvas3D object, the root of a branch of scene graph for picking, and the scheduling bounds. For example, the following code fragment sets up a PickRotateBehavior on the root:

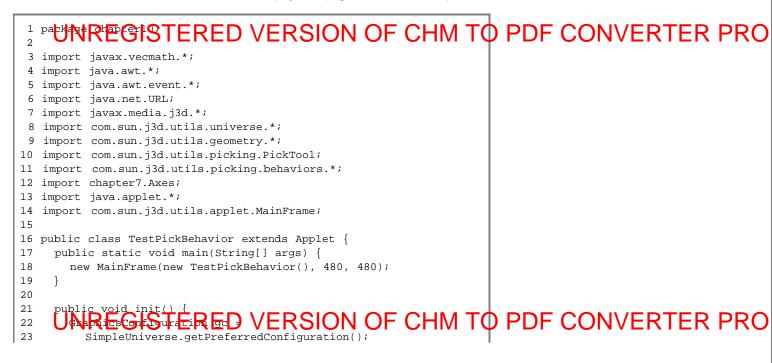
```
PickRotateBehavior rotator = new PickRotateBehavior(cv, root, bounds);
root.addChild(rotator);
```

It is necessary to place a TransformGroup node over the object to be picked so that the behaviors can find a target to operate. It is also necessary to turn on the appropriate capability bits on the picked objects as well as the transformation nodes.

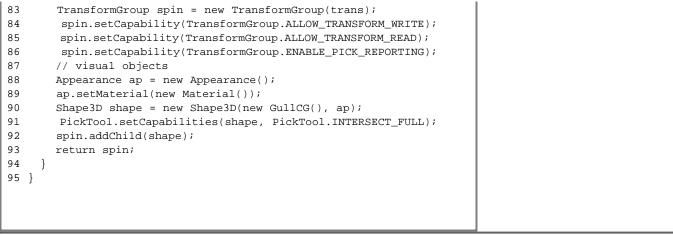
Listing 10.6 illustrates the application of PickMouseBehavior classes. The program displays a group of seagulls placed randomly in the scene (Figure 10.13). Users can individually rotate, translate, and zoom each of the seagulls through mouse motions.

Listing 10.6. TestPickBehavior.java

(This item is displayed on pages 334 - 335 in the print version)



```
24
       Canvas3D cv = new Canvas3D(gc);
25
       setLayout(new BorderLayout());
26
       add(cv, BorderLayout.CENTER);
       TextArea ta = new TextArea("",3,30,TextArea.SCROLLBARS_NONE);
27
28
       ta.setText("Rotation: Drag with left button\n");
29
       ta.append("Translation: Drag with right button\n");
30
       ta.append("Zoom: Hold Alt key and drag with left button");
31
       ta.setEditable(false);
32
       add(ta, BorderLayout.SOUTH);
33
       BranchGroup bg = createSceneGraph(cv);
34
       bq.compile();
35
       SimpleUniverse su = new SimpleUniverse(cv);
36
       su.getViewingPlatform().setNominalViewingTransform();
[Page 335]37
               su.addBranchGraph(bg);
38
    }
39
40
    private BranchGroup createSceneGraph(Canvas3D cv) {
41
       BranchGroup root = new BranchGroup();
42
       // add 8 seagulls
43
       for (int i = 0; i < 8; i++)
44
         root.addChild(createObject());
45
       BoundingSphere bounds = new BoundingSphere();
46
47
       // rotation
48
       PickRotateBehavior rotator =
49
         new PickRotateBehavior(root, cv, bounds,
50
        PickTool.GEOMETRY);
51
      root.addChild(rotator);
52
       // translation
53
       PickTranslateBehavior translator =
54
         new PickTranslateBehavior(root, cv,
55
         bounds, PickTool.GEOMETRY);
56
      root.addChild(translator);
57
      // zoom
58
       PickZoomBehavior zoom = new PickZoomBehavior(root, cv, bounds,
59
        PickTool.GEOMETRY);
60
       root.addChild(zoom);
61
      // light
       AmbientLight light = new AmbientLight(true,
62
63
       new Color3f(Color.blue));
64
         light.setInfluencingBounds(bounds);
65
       root.addChild(light);
66
       PointLight ptlight = new PointLight(new Color3f(Color.white),
67
         new Point3f(0f,0f,2f), new Point3f(1f,0.3f,0f));
68
       ptlight.setInfluencingBounds(bounds);
       root.addChild(ptlight);
69
70
       // background
71
       Background background = new Background(1.0f, 1.0f, 1.0f);
72
       background.setApplicationBounds(bounds);
73
       root.addChild(background);
74
      return root;
75
    }
76
77
    private Node createObject() {
78
      // transform
79
       Transform3D trans = new Transform3D();
80
       trans.setTranslation(new Vector3d(Math.random()-0.5,
81
         Math.random()-0.5, Math.random()-0.5);
82
       trans.setScale(0.3);
```



[Page 336]

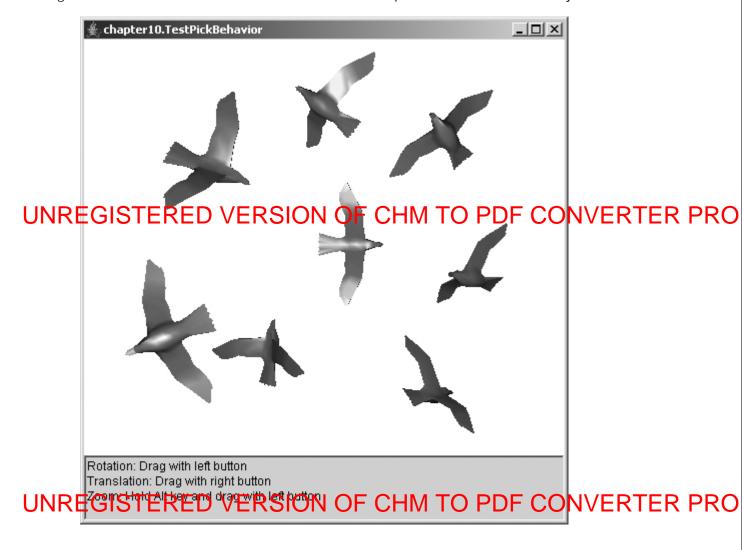
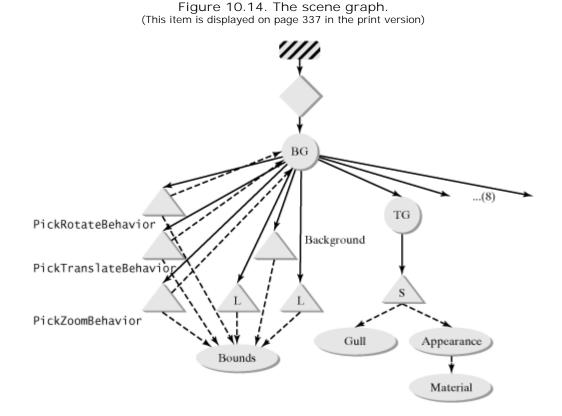


Figure 10.13. **PickMouseBehavior** classes allow manipulations of individual objects.

The scene contains eight gulls located randomly. Each gull can be picked and manipulated with the mouse. Dragging with the left mouse button rotates the gull. Dragging with the right mouse button translates the gull. Dragging with the middle mouse button (or the left mouse button while holding the Alt key) zooms the gull.

The scene graph is shown in Figure 10.14. Three PickMouseBehavior objects: PickRotateBehavior, PickTranslateBehavior, and PickZoomBehavior, are created to act on the root BranchGroup node (lines 47–60). Eight gulls are created with identical structures. The createObject method builds a branch of the scene graph consisting of a TransformGroup object and a Shape3D object. The GullCG class defines the geometry for the Shape3D. An Appearance with a Material component is used for the shape. The dedicated TransformGroup node for each shape is necessary for the pick-mouse behaviors to operate individually on each gull. On the TransformGroup nodes the following *capability bits* are turned on (lines 85–87):



TransformGroup.ALLOW\_TRANSFORM\_WRITE TransformGroup.ALLOW\_TRANSFORM\_READ TransformGroup.ENABLE\_PICK\_REPORTING

On the shapes, the following method is called to turn on all related capability bits (line 92):

PickTool.setCapabilities(shape, PickTool.INTERSECT\_FULL);

Two lights are added to illuminate the gulls with material appearance. A white background is added. All the behavior nodes, the lights, and the background node share the same bounds object.

### 10.4.2. Data Visualization

The combination of picking and behaviors provides a powerful tool for interaction with a 3D scene. Picking allows for selections of specific scene-graph objects, and behaviors offer a way to change the scene. In a data visualization application, for example, it will be a useful feature for the user to rotate, translate, and zoom a 3D plot with the mouse. The motions will significantly improve the perception of the 3D structure. It will also be useful to select specific data points with the mouse.

[Page 337]

Listing 10.7 shows one approach to implementing such functions with picking and behaviors. The program displays a 3D scatter plot (Figure 10.15). 3D data points are plotted as colored dots. Users will be able to rotate, translate, and zoom the plot to view the data from different perspectives. The motions will help the user gain a better understanding of the 3D structure of the data from the 2D screen. Individual data points can also be selected on the plot with mouse clicking. A text field at the bottom of the window displays the index and coordinates of the selected point.

Listing 10.7. DataViewer.java

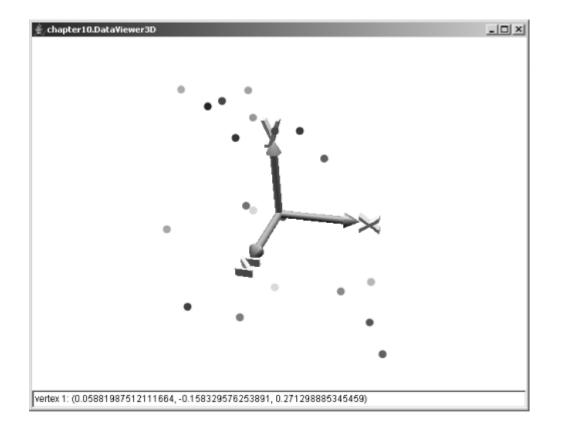
(This item is displayed on pages 337 - 340 in the print version)

```
1 package chapter10;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
  8 import com.sun.j3d.utils.geometry.*;
 9 import com.sun.j3d.utils.picking.*;
10 import com.sun.j3d.utils.behaviors.mouse.*;
11 import chapter7.Axes;
12 import java.applet.*;
13 import com.sun.j3d.utils.applet.MainFrame;
14
15 publ
    UNREGISTI
                       RED MERSION OF CHM TO PDF CONVERTER PRO
16
[Page 338] 17
               new MainFrame(new DataViewer3D(), 640, 480);
18
     }
19
20
     PointArray geom;
21
     PickCanvas pc;
22
     TextField text;
23
     public void init() {
24
25
       setLayout(new BorderLayout());
26
       GraphicsConfiguration gc =
          SimpleUniverse.getPreferredConfiguration();
27
28
       Canvas3D cv = new Canvas3D(gc);
29
       add(cv, BorderLayout.CENTER);
30
       cv.addMouseListener(new MouseAdapter() {
31
         public void mouseClicked
32
           (java.awt.event.MouseEvent mouseEvent) {
33
           pick(mouseEvent);
34
         }
35
       });
                                     RSION OF CHM TO PDF CONVERTER PRO
36
        add(text, BorderLayout.SOUTH);
37
38
       BranchGroup bg = createSceneGraph(cv);
```

```
39
        bg.compile();
 40
        SimpleUniverse su = new SimpleUniverse(cv);
        su.getViewingPlatform().setNominalViewingTransform();
 41
 42
        su.addBranchGraph(bg);
43
     }
44
 45
     private BranchGroup createSceneGraph(Canvas3D cv) {
        BranchGroup root = new BranchGroup();
 46
 47
        TransformGroup spin = new TransformGroup();
 48
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_READ);
 49
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
        root.addChild(spin);
50
51
        // axes
52
        Transform3D tr = new Transform3D();
53
        tr.setScale(0.3);
54
        TransformGroup tg = new TransformGroup(tr);
55
        spin.addChild(tg);
56
        Axes axes = new Axes();
57
        tg.addChild(axes);
58
        // appearance
59
        Appearance ap = new Appearance();
 60
        ap.setPointAttributes(new PointAttributes(10f, true));
 61
        // objects
        int n = 20;
 62
 63
        geom = new PointArray(n,
          PointArray.COORDINATES | PointArray.COLOR_4);
 64
        geom.setCapability(PointArray.ALLOW_COORDINATE_READ);
 65
        geom.setCapability(PointArray.ALLOW_FORMAT_READ);
 66
 67
        geom.setCapability(PointArray.ALLOW_COLOR_READ);
 68
        geom.setCapability(PointArray.ALLOW_COLOR_WRITE);
 69
        geom.setCapability(PointArray.ALLOW_COUNT_READ);
70
        Point3f[] coords = new Point3f[n];
71
        Color4f[] colors = new Color4f[n];
72
        for (int i = 0; i < n; i++) {
[Page 339] 73
                  coords[i] = new Point3f((float)(Math.random()-0.5),
74
          (float)(Math.random()-0.5),(float)(Math.random()-0.5));
75
          colors[i] = new Color4f((float)(Math.random()),
76
          (float)(Math.random()),(float)(Math.random()),1f);
77
        }
78
        geom.setCoordinates(0, coords);
79
        geom.setColors(0, colors);
80
        BranchGroup bg = new BranchGroup();
81
        spin.addChild(bg);
82
        pc = new PickCanvas(cv, bg);
83
        pc.setTolerance(5);
        pc.setMode(PickTool.GEOMETRY_INTERSECT_INFO);
 84
85
        Shape3D shape = new Shape3D(geom, ap);
 86
        bg.addChild(shape);
 87
        PickTool.setCapabilities(shape, PickTool.INTERSECT_TEST);
 88
        shape.setCapability(Shape3D.ALLOW_GEOMETRY_READ);
 89
        // rotation
 90
        MouseRotate rotator = new MouseRotate(spin);
 91
        BoundingSphere bounds = new BoundingSphere();
 92
        rotator.setSchedulingBounds(bounds);
 93
        spin.addChild(rotator);
 94
        // translation
 95
        MouseTranslate translator = new MouseTranslate(spin);
 96
        translator.setSchedulingBounds(bounds);
 97
        spin.addChild(translator);
```

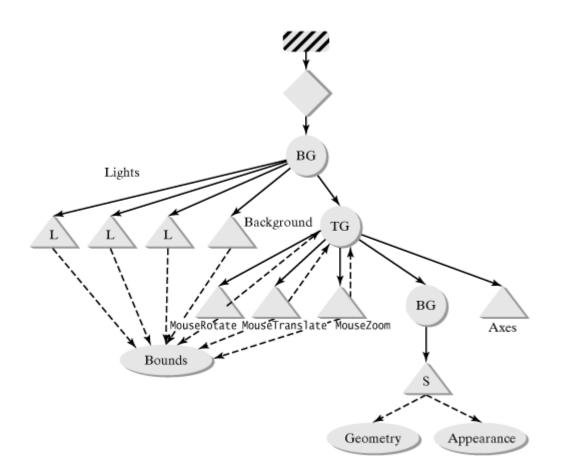
```
98
        // zoom
 99
        MouseZoom zoom = new MouseZoom(spin);
100
        zoom.setSchedulingBounds(bounds);
101
        spin.addChild(zoom);
102
        // background and light
103
        Background background = new Background(1.0f, 1.0f, 1.0f);
104
        background.setApplicationBounds(bounds);
105
        root.addChild(background);
106
        AmbientLight light =
          new AmbientLight(true, new Color3f(Color.red));
107
108
        light.setInfluencingBounds(bounds);
109
        root.addChild(light);
110
        PointLight ptlight = new PointLight(new Color3f(Color.green),
111
        new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
112
        ptlight.setInfluencingBounds(bounds);
113
        root.addChild(ptlight);
114
        PointLight ptlight2 = new PointLight(new Color3f(Color.orange),
115
        new Point3f(-2f,2f,2f), new Point3f(1f,0f,0f));
116
        ptlight2.setInfluencingBounds(bounds);
117
        root.addChild(ptlight2);
118
        return root;
119
     }
120
    private void pick(MouseEvent mouseEvent) {
121
122
        Color4f color = new Color4f();
123
        pc.setShapeLocation(mouseEvent);
124
        PickResult[] results = pc.pickAll();
125
        for (int i = 0; (results != null) &&
126
          (i < results.length); i++) {</pre>
127
          PickIntersection inter = results[i].getIntersection(0);
128
          Point3d pt = inter.getClosestVertexCoordinates();
[Page 340]129
                  int[] ind = inter.getPrimitiveCoordinateIndices();
130
          text.setText("vertex " + ind[0] + ": (" + pt.x + ", "
131
            + pt.y + ", " + pt.z + ")");
132
          geom.getColor(ind[0], color);
133
          color.x = 1f - color.x;
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color.z = lf - color.z;
134
135
136
          if (color.w > 0.8) color.w = 0.5f;
137
          else color.w = 1f;
138
          geom.setColor(ind[0], color);
139
        }
140
      }
141 }
```

Figure 10.15. A 3D scatter plot featuring data-point selection and transformations under user control.



The scene graph of the program is shown in Figure 10.16. Three MouseBehavior objects: MouseRotate, MouseTranslate, and MouseZoom are set to operate on a TransformGroup node. The behaviors provide the capabilities to rotate, translate, and zoom the plot.

Figure 10.16. Scene graph. (This item is displayed on page 341 in the print version)



The data points to be plotted are generated randomly and represented with a PointArray geometry (lines 61–79). The colors of the points are randomly assigned with Color4f objects. An Axes object is used to provide a visual reference of the toprdinate system. An extra trancher or provide placed prior of the data object TER PRO is used for picking operation. Picking is not applied to the root Brancheroup node because the axes object should be excluded from picking.

A mouse listener is placed on the Canvas3D object. It listens to mouse-click events and performs a picking on the branch for data points by calling the pick method (line 121). A PickCanvas object is used to perform picking based on the mouse location. Because all data points belong to one object as vertices, it is necessary to obtain the *intersections* of the picking to determine the specific point (lines 127–128):

```
[Page 341]
PickIntersection inter = results[i].getIntersection(0);
Point3d pt = inter.getClosestVertexCoordinates();
```

The index of the vertex in the geometry can also be obtained (line 129):

```
int[] ind = inter.getPrimitiveCoordinateIndices();
```

When the vertex in the intersection is retrieved, its index and coordinates are displayed in the text field at the bottom of the frame. The selected point will be shown in a different color. The new color is the complement of the original color PDF CONVERTER PRC

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#### [Page 341 (continued)]

#### Key Classes and Methods

- javax.media.j3d.Behavior A class encapsulating a dynamic behavior.
- javax.media.j3d.WakeupCondition A base class for wakeup conditions.
- javax.media.j3d.WakeupCriterion A base class encapsulating various specific wakeup conditions.
- javax.media.j3d.WakeupOnElapsedTime A wakeup criterion based on elapsed time.
- javax.media.j3d.WakeupOnAWTEvent A wakeup criterion based on AWT events.

#### [Page 342]

- javax.media.j3d.WakeupAnd A class for combining wakeup criteria with logical AND.
- javax.media.j3d.WakeupOr A class for combining wakeup criteria with logical OR.
- javax.media.j3d.WakeupAndOfOrs A class for combining WakeupOr conditions with logical AND.
- javax.media.j3d.WakeupOrOfAnds A class for combining WakeupAnd conditions with logical OR.
- com.sun.j3d.utils.behaviors.mouse.MouseBehavior A base class for mouse-driven behaviors.
- com.sun.j3d.utils.behaviors.mouse.MouseRotate A mouse-controlled rotation behavior.
- com.sun.j3d.utils.behaviors.mouse.MouseTranslate A mouse-controlled translation behavior.
- com.sun.j3d.utils.behaviors.mouse.MouseZoom A mouse-controlled zoom behavior.
- com.sun.j3d.utils.behaviors.keyboard.KeyNavigatorBehavior A keyboard-based transformation WREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
- **com.sun.j3d.utils.behaviors.vp.OrbitBehavior** A mouse-driven viewplatform transformation behavior.
- **com.sun.j3d.utils.picking.behaviors.PickMouseBehavior** A base class for mouse-driven picking and transformation behaviors.
- **com.sun.j3d.utils.picking.behaviors.PickRotateBehavior** A mousecontrolled picking and rotation behavior.
- **com.sun.j3d.utils.picking.behaviors.PickTranslateBehavior** A mousecontrolled picking and translation behavior.
- **com.sun.j3d.utils.picking.behaviors.PickZoomBehavior** A mousecontrolled picking and zoom behavior.
- javax.media.j3d.MouseBehavior.initialize() An initialization method called once by the scheduler.
- · CHINE CISTERED VERSION OF CHM TO PDF CONVERTER PRO

• javax.media.j3d.MouseBehavior.wakeupOn(WakeupCondition) A method to set a wakeup condition.

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#### Key Terms behavior

A model for dynamics in a 3D scene.

interaction

A dynamic behavior related to user input.

wakeup condition

A condition to trigger a behavior.

picking behavior

An interaction based on picking.

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## UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

## UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

[Page 342 (continued)]

### Chapter Summary

• This chapter introduces the concept of behavior that represents dynamics of a 3D scene in a systematical way. Commonly used dynamic changes such as interactions and animations can be modeled as behaviors. The general behavior mechanism and the interaction behaviors are discussed in this chapter. Animation is covered in the next chapter.

[Page 343]

- Java 3D provides the classes in Behavior and WakeupCondition families to facilitate various behavior operations. A Behavior object establishes wakeup conditions and responds to stimuli from the wakeup conditions to fulfill their tasks. A large collection of specific wakeup conditions are supplied by Java 3D under the class hierarchy WakeupCriterion. The criteria can also be combined using certain logical operations to form composite wakeup conditions.
- Interaction is typically accomplished through behaviors with wakeup conditions related to user input events such as mouse and keyboard actions. Java 3D contains several utility packages to support interaction.
- The MouseBehavior family of classes provides behaviors for controlling TransformGroup nodes with mouse actions. The KeyNavigatorBehavior class uses the keyboard to control the transform. The ViewPlatformBehavior classes operate on view platforms.
- Picking is often combined with behaviors to construct interactions. The utility classes in the PickMouseBehavior family provide convenient constructions of behaviors that link picking to affine transforms.

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[Page 343 (continued)]

### **Review** Questions

- 10.1 Discuss the advantages of defining a behavior as a scene-graph node.
- 10.2 Describe the differences between interaction and animation.
- 10.3 Which WakeupCriterion classes are usually associated with interaction?
- 10.4 Describe the differences between MouseBehavior and ViewPlatformAWTBehavior classes.
- 10.5 In Listing 10.6, what happens if all gulls are attached to the same TransformGroup node instead of their own transforms?

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## UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

#### [Page 343 (continued)]

### **Programming Exercises**

- 10.1 Write a Java 3D program to display a real-time digital clock using 3D text.
- 10.2 Add a MouseRotate behavior to the program in Problem 10.1 to allow rotation of the clock by mouse dragging.
- 10.3 Add a MouseTranslate behavior to the program in Problem 10.2 to allow translation of the clock by mouse motion.
- 10.4 Add a MouseZoom behavior to the program in Problem 10.3 to allow zooming of the clock by mouse dragging.
- 10.5 Add a KeyNavigationBehavior to the program in Problem 10.4 to allow keyboard manipulation of the clock.

#### [Page 344]

- 10.6 Modify the code in Listing 10.6 so that only one instance of the GullCG geometry is used.
- 10.7 Rewrite Listing 10.7 to use an OrbitBehavior for controlling the view with mouse actions.
- 10.8 Rewrite Listing 10.7 so it uses a Behavior instead of a mouse listener to handle the picking.

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## Chapter 11. Animation

(This item omitted from WebBook edition)

Objectives
<ul> <li>To understand the concept and methods of animation.</li> </ul>
<ul> <li>To understand and create Alpha objects.</li> </ul>
<ul> <li>To apply various interpolators to creating animations.</li> </ul>
<ul> <li>To create morphing with Morph nodes and behaviors.</li> </ul>
To use LOD behaviors.
To use billboard behaviors.

[Page 346]

### 11.1. Introduction

Animation generates sequences of graphics renderings that vary with time, producing an effect of live motions. Both interaction and animation generate dynamic behaviors in graphics systems, but animation is usually time related, and producing the frames, the intermediate results of the changing process, is often the main objective of an animation **CHM TO PDF CONVERTER PR** 

Animation is a common dynamic effect in computer graphics. To produce the animated graphics effects, the rendered scene must change dynamically with time. The changes may involve different attributes of the scene such as geometry, transformation, position, color, and transparency.

Java 3D provides extensive support for incorporation of animation into a scene graph through the Behavior class. A family of behavior classes known as the *interpolators* encapsulates the common animation actions. The Alpha class that represents a function of time serves as the driving force for the interpolators. It is easy to create an animation with an interpolator. You need only create an appropriate interpolator object with an alpha, and link the interpolator to its target object.

Other animation-related techniques include morphing, level of detail (LOD), and billboard behaviors. Morphing defines a smooth change of geometries. LOD provides a method to offer different levels of rendering details depending on the distance of the object from the eye. Billboard behavior provides a convenient method to automatically adjust the orientation of an object so that it will always face the viewer.

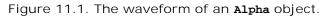
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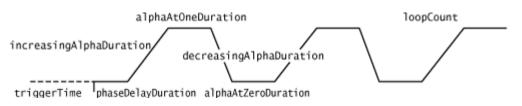
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[Page 346 (continued)]

### 11.2. Alpha Objects

Animations tie the dynamic changes of a scene to time. An *alpha* object defines a (usually periodic) function of time that produces values between 0.0 and 1.0. It is usually more convenient to drive an animation with an alpha than with a real-time clock. Java 3D Alpha class is a subclass of NodeComponent. The Alpha objects provide inputs to the animation tool known as the Interpolator. The functional shape of an Alpha object is defined by several parameters. An example waveform of an Alpha object is shown in Figure 11.1.





A Java 3D Alpha object includes the following parameters:

- LoopCount: The number of pulses or periods. The value -1 indicates an unlimited number of loops.
- startTime: The absolute time for the initial reference point.
- triggerTime: The time in milliseconds from the startTime for activating the Alpha object.
- phaseDelayDuration: The time in milliseconds for the initial delay from the triggerTime.
- alphaAtZeroDuration: The time in milliseconds for the alpha value to stay at 0.0.
- alphaAtOneDuration: The time in milliseconds for the alpha value to stay at 1.0.
- increasingAlphaDuration: The time in milliseconds for the alpha value to increase from 0.0 to 1.0.

[Page 347]

- decreasingAlphaDuration: The time in milliseconds for the alpha value to decrease from 1.0 to 0.0.
- increasingAlphaRampDuration: The time in milliseconds for the alpha value to accelerate during the increasing phase.
- decreasingAlphaRampDuration: The time in milliseconds for the alpha value to accelerate during the decreasing phase.

The parameters increasingAlphaRampDuration and decreasingAlphaRampDuration define certain smoothing effects on the waveform. The value of increasingAlphaRampDuration specifies an interval of acceleration at the beginning of the increasing phase and an interval of deceleration at the end of the increasing phase. Similarly the value of decreasingAlphaRampDuration specifies an interval of deceleration and acceleration for the decreasing phase.

The following constructors are available for Alpha objects:

```
public Alpha()
public Alpha(int loopCount, long increasingAlphaDuration)
public Alpha(int loopCount, long triggerTime,
    long phaseDelayDuration, long
    increasingAlphaDuration, long increasingAlphaRampDuration,
    long alphaAtOneDuration)
public Alpha(int loopCount, int mode, long triggerTime,
    long phaseDelayDuration, long
    increasingAlphaDuration, long increasingAlphaRampDuration,
    long alphaAtOneDuration, long
    increasingAlphaDuration, long
    increasingAlphaDuration, long
    decreaingAlphaDuration, long dereasingAlphaRampDuration,
    long alphaAtZeroDuration)
```

The alpha values of an Alpha object can be retrieved with the value methods:

public float value()
public float value(long atTime)

The first method gets the alpha value for the current time. The second method gets the value for the specified time.

Listing 11.1 plots the waveform of an alpha object (Figure 11.2). Parameters of the alpha can be changed at runtime to show the their effects on the waveform.

Listing 11.1. TestAlpha.java

(This item is displayed on pages 347 - 349 in the print version)

```
1 package chapter11;
 2
 3 import java.awt.*;
  4 import java.awt.event.*;
 E LAREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 7
 8 public class TestAlpha extends JApplet {
 9
     public static void main(String s[]) {
10
       JFrame frame = new JFrame();
11
       frame.setTitle("Alpha");
       frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
12
13
       JApplet applet = new TestAlpha();
14
       applet.init();
15
       frame.getContentPane().add(applet);
16
       frame.pack();
17
       frame.setVisible(true);
18
    }
19
[Page 348] 20
           Alpha alpha = new Alpha();
     Plot plot;
21
     JTextField tfLoopCount;
2.2
    JTextField tfTriggerTime;
23
24
    JTextField tfAlphaAtZeroDuration;
     JTextField tfAlphaAtOneDuration;
25
        REGISTERED VERSION OF CHM TO PDF CONVERTER PRO
26
27
28
     JTextField tfIncreasingAlphaRampDuration;
```

```
29
      JTextField tfDecreasingAlphaRampDuration;
30
31
      public void init() {
32
        Container cp = this.getContentPane();
33
        cp.setLayout(new BorderLayout());
34
        plot = new Plot();
35
        cp.add(plot, BorderLayout.CENTER);
36
        JPanel p = new JPanel();
37
        p.setBorder(BorderFactory.createTitledBorder(
38
          "Alpha parameters"));
39
        cp.add(p, BorderLayout.SOUTH);
 40
        p.setLayout(new GridLayout(5, 4, 10, 5));
 41
        p.add(new JLabel("loopCount"));
 42
        tfLoopCount = new JTextField("-1");
43
        p.add(tfLoopCount);
 44
        p.add(new JLabel("triggerTime"));
 45
        tfTriggerTime = new JTextField("0");
 46
        p.add(tfTriggerTime);
 47
        p.add(new JLabel("alphaAtZeroDuration"));
 48
        tfAlphaAtZeroDuration = new JTextField("0");
 49
        p.add(tfAlphaAtZeroDuration);
50
        p.add(new JLabel("alphaAtOneDuration"));
51
        tfAlphaAtOneDuration = new JTextField("0");
52
        p.add(tfAlphaAtOneDuration);
53
        p.add(new JLabel("increasingAlphaDuration"));
54
        tfIncreasingAlphaDuration = new JTextField("1000");
55
        p.add(tfIncreasingAlphaDuration);
56
        p.add(new JLabel("decreasingAlphaDuration"));
57
        tfDecreasingAlphaDuration = new JTextField("0");
58
        p.add(tfDecreasingAlphaDuration);
59
        p.add(new JLabel("increasingAlphaRampDuration"));
60
        tfIncreasingAlphaRampDuration = new JTextField("0");
61
        p.add(tfIncreasingAlphaRampDuration);
 62
        p.add(new JLabel("decreasingAlphaRampDuration"));
63
        tfDecreasingAlphaRampDuration = new JTextField("0");
 64
        p.add(tfDecreasingAlphaRampDuration);
 65
        p.add(new JPanel());
        JButton button = new JButton("Plot");
 66
 67
        p.add(button);
 68
        button.addActionListener(new ActionListener() {
 69
          public void actionPerformed(ActionEvent ev) {
70
            setAlpha();
71
            repaint();
72
          }
73
        });
 74
        p.add(new JPanel());
75
        button = new JButton("Reset");
76
        p.add(button);
77
        button.addActionListener(new ActionListener() {
78
          public void actionPerformed(ActionEvent ev) {
[Page 349] 79
                    tfLoopCount.setText("-1");
80
            tfTriggerTime.setText("0");
            tfAlphaAtZeroDuration.setText("0");
81
82
            tfAlphaAtOneDuration.setText("0");
83
             tfIncreasingAlphaDuration.setText("1000");
 84
            tfDecreasingAlphaDuration.setText("0");
 85
            tfIncreasingAlphaRampDuration.setText("0");
 86
            tfDecreasingAlphaRampDuration.setText("0");
 87
            setAlpha();
```

```
88
            repaint();
          }
 89
        });
 90
 91
      }
 92
 93
      void setAlpha() {
 94
        alpha.setMode
          (Alpha.INCREASING_ENABLE | Alpha.DECREASING_ENABLE);
 95
 96
        int n = Integer.parseInt(tfLoopCount.getText());
 97
        alpha.setLoopCount(n);
 98
        n = Integer.parseInt(tfTriggerTime.getText());
 99
        alpha.setTriggerTime(n);
100
        n = Integer.parseInt(tfAlphaAtZeroDuration.getText());
101
        alpha.setAlphaAtZeroDuration(n);
102
        n = Integer.parseInt(tfAlphaAtOneDuration.getText());
103
        alpha.setAlphaAtOneDuration(n);
104
        n = Integer.parseInt(tfIncreasingAlphaDuration.getText());
105
        alpha.setIncreasingAlphaDuration(n);
106
        n = Integer.parseInt(tfDecreasingAlphaDuration.getText());
107
         alpha.setDecreasingAlphaDuration(n);
108
        n = Integer.parseInt(tfIncreasingAlphaRampDuration.getText());
109
         alpha.setIncreasingAlphaRampDuration(n);
110
        n = Integer.parseInt(tfDecreasingAlphaRampDuration.getText());
111
         alpha.setDecreasingAlphaRampDuration(n);
112
      }
113
114
      class Plot extends JPanel {
115
        public Plot() {
116
          this.setBackground(Color.white);
117
           this.setBorder(BorderFactory.createLoweredBevelBorder());
118
          this.setPreferredSize(new Dimension(800,200));
119
        }
120
121
        public void paintComponent(Graphics g) {
122
          super.paintComponent(g);
123
          long start = alpha.getStartTime();
                        ERED VERSION OF CHM TO PDF CONVERTER PRO
          124
          int yl
125
          int x^2 = 0;
126
127
          int y^2 = 0;
128
          for (int i = 1; i < 1000; i++) {
129
            x^2 = ii
130
            y2 = 150-(int)(100*alpha.value(start+i*10));
131
            g.drawLine(x1, y1,x2, y2);
132
            x1 = x2;
133
            y1 = y2;
134
          ł
135
136
      }
137 }
```

[Page 350]

alphaAtZeroDuration IncreasingAlphaDuration IncreasingAlphaRampDuration
alphaAtZeroDuration
loopCount
Alpha parameters

The values of an Alpha object are plotted in a panel. Eight parameters for the alpha object can be set through the JTextField objects in the lower panel of the frame. Initially the default parameters are set for the Alpha. The Plot button will redraw the curve using the given parameters. The Reset button resets all parameters to the default.

The inner class Plot (line 114) extends JPanel and draws the waveform in its paint Component method (line 121). The points are plotted in 10-ms intervals. The method value(long atTime) of the Alpha object is used to obtain the alpha values (line 130).

◀ Previous

Next ▶

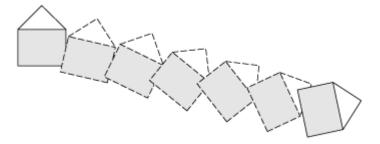
◀ Previous

[Page 350 (continued)]

### 11.3. Interpolators

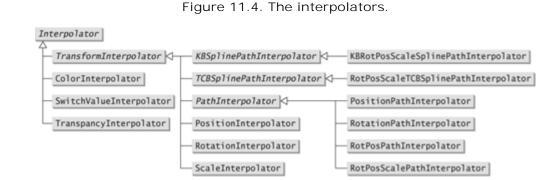
The Behavior class includes a family of Interpolator subclasses that are predefined behaviors for animation. The Interpolator classes provide convenient ways to produce animation by setting two or more attribute points and interpolating the values between them. The concept of an interpolator is illustrated in Figure 11.3. Two endpoints of certain attribute are explicitly given. The interpolator will fill in the intermediate values to produce an animation. The targets of the interpolators may be colors, transformations, switches, and other attributes.

Figure 11.3. An interpolator interpolates the intermediate values.



An interpolator, like other animation tools, is driven by the time. To normalize the time input to an animation object, an Alpha object can be used. The Alpha objects provide a consistent interface for generating stimuli from time values. A Java 3D Interpolator is driven by an Alpha object. To create an animation using an interpolator, you may instantiate an appropriate Interpolator class, set its control points, and provide it with an Alpha object. Figure 11.4 shows the Interpolator class hierarchy in Java 3D.

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The ColorInterpolator class interpolates between two color values for a Material object. The following code animates a color change from red to green: UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO Alpha alpha = new Alpha();

```
Material material = new Material();
Color3f red = new Color3f(1f, 0f, 0f);
Color3f green = new Color3f(1f, 0f, 0f);
ColorInterpolator ci = new ColorInterpolator
  (alpha, material, red, green);
ci.setSchedulingBounds(new BoundingSphere());
```

The TransparencyInterpolator class interpolates between two transparency values for a target TransparencyAttributes object. It has the following constructors:

```
TransparencyInterpolator(Alpha a, TransparencyAttributes target);
TransparencyInterpolator(Alpha a, TransparencyAttributes target,
float t1, float t2);
```

The SwitchValueInterpolator class has a Switch node as its target. It interpolates the indices of the Switch object's children.

The TransformInterpolator class operates on a target TransformGroup object. It also maintains a Transform3D object to represent the axis of the operation. RotationInterpolator interpolates between two angles. The default angles are from 0 to 2p. It has already been used in many previous example programs to rotate objects. The PositionInterpolator interpolates the translation component of the target along the axis. The ScaleInterpolator performs an interpolation on the scaling of the target.

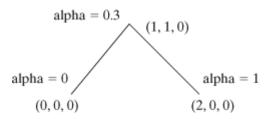
Sometimes just interpolating two endpoints may be inadequate for complex animations. The PathInterpolator class and its subclasses are special TransformInterpolator classes that allow a sequence of control points or key frames to be specified. The interpolator will linearly interpolate the intermediate values between each pair of adjacent points. The timing of the interpolation related to the alpha values is controlled by a sequence of numbers called *knots*. For example, the following statements set up a PositionPathInterpolator that interpolates three positions:

```
Point3f[] positions = {new Point3f(0,0,0), new Point3f(1,1,0),
    new Point3f(2,0,0)};
float[] knots = {0f, 0.3f, 1f};
Alpha alpha = new Alpha();
TransformGroup target = new TransformGroup();
Transform3D axis = new Transform3D();
PositionPathInterpolator interpolator =
    new PositionPathInterpolator(alpha, target, axis, knots, positions);
```

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The interpolated path is shown in Figure 11.5. When the alpha values are between 0 and 0.3, the interpolator generates the path from (0, 0, 0) to (1, 1, 0). When the alpha values are above 0.3, it generates the path from (1, 1, 0) to (2, 0, 0).

Figure 11.5. A PositionPathInterpolator.



The RotationPathInterpolator interpolates a sequence of rotations. The RotPosPathInterpolator interpolates a sequence of rotations and translations. The RotPosScalePathInterpolator interpolates a sequence of transforms with specified rotations, translations, and scales.

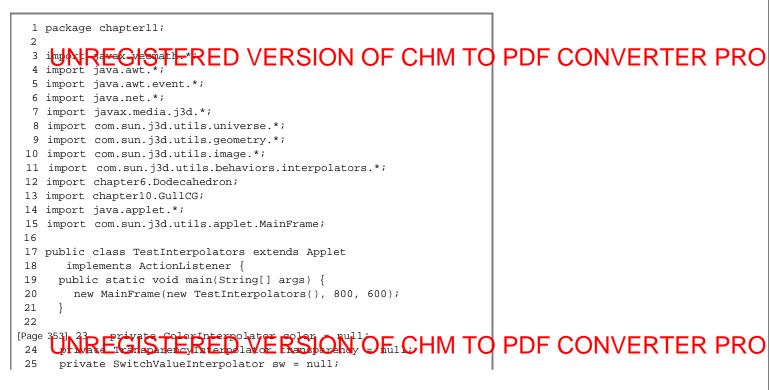
The PathInterpolator classes generate piecewise linear segments, and therefore the paths may not be smooth at the knots where different segments are joined. To produce smooth interpolations or to exercise more sophisticated controls over the interpolating curves, we may use the classes KBSplinePathInterpolator or TCBSplinePathInterpolator. They both have a concrete subclass that interpolates rotations, translations, and scales.

Interpolators are behaviors and, consequently, they need to have appropriate scheduling bounds set.

Listing 11.2 shows an application of interpolators. Different types of interpolators are used in this example. The visual object is either a gull or a dodecahedron depending on a Switch value. Eight buttons labeled with the interpolator names are placed at the right side of the window. Clicking a button activates the corresponding interpolator. "Color" interpolates the colors of the object. "Transparency" changes the transparency. "SwitchValue" changes the shape from the gull to the dodecahedron. "Rotation," "Position," and "Scale" perform the transformations on the object. "RotPosPath" moves and rotates the object along a path. "RotPosScaleTCBSplinePath" interpolates smoothly along a path. (See Figure 11.6.)

Listing 11.2. TestInterpolator.java

(This item is displayed on pages 352 - 356 in the print version)



```
26
      private RotationInterpolator rotator = null;
 27
      private PositionInterpolator translator = null;
     private ScaleInterpolator zoom = null;
 28
      private RotPosPathInterpolator path = null;
 29
 30
     private TCBSplinePathInterpolator spline = null;
 31
      private Interpolator current = null;
32
    public void init() {
 33
 34
       setLayout(new BorderLayout());
 35
        Panel panel = new Panel();
        panel.setLayout(new GridLayout(8,1));
 36
 37
        add(panel, BorderLayout.EAST);
 38
        Button button;
 39
        button = new Button("Color");
 40
        button.addActionListener(this);
 41
        panel.add(button);
 42
       button = new Button("Transparency");
 43
       button.addActionListener(this);
       panel.add(button);
 44
 45
       button = new Button("SwitchValue");
 46
       button.addActionListener(this);
 47
        panel.add(button);
       button = new Button("Rotation");
 48
 49
       button.addActionListener(this);
 50
       panel.add(button);
 51
       button = new Button("Position");
 52
       button.addActionListener(this);
 53
       panel.add(button);
 54
       button = new Button("Scale");
 55
       button.addActionListener(this);
 56
        panel.add(button);
 57
        button = new Button("RotPosPath");
 58
        button.addActionListener(this);
 59
        panel.add(button);
 60
        button = new Button("RotPosScaleTCBSplinePath");
 61
        button.addActionListener(this);
 62
       panel.add(button);
 63
 64
        GraphicsConfiguration gc =
 65
           SimpleUniverse.getPreferredConfiguration();
        Canvas3D cv = new Canvas3D(gc);
 66
 67
        add(cv, BorderLayout.CENTER);
 68
        BranchGroup bg = createSceneGraph();
 69
        bg.compile();
 70
        SimpleUniverse su = new SimpleUniverse(cv);
        su.getViewingPlatform().setNominalViewingTransform();
 71
 72
        su.addBranchGraph(bg);
 73
     }
 74
 75
     private BranchGroup createSceneGraph() {
 76
       BranchGroup root = new BranchGroup();
        TransformGroup tg = new TransformGroup();
 77
 78
        tg.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 79
        tg.setCapability(TransformGroup.ALLOW_TRANSFORM_READ);
 80
        root.addChild(tg);
 81
        // switch node
 82
        Switch swNode = new Switch();
[Page 354] 83
                swNode.setCapability(Switch.ALLOW_SWITCH_WRITE);
84
        tg.addChild(swNode);
```

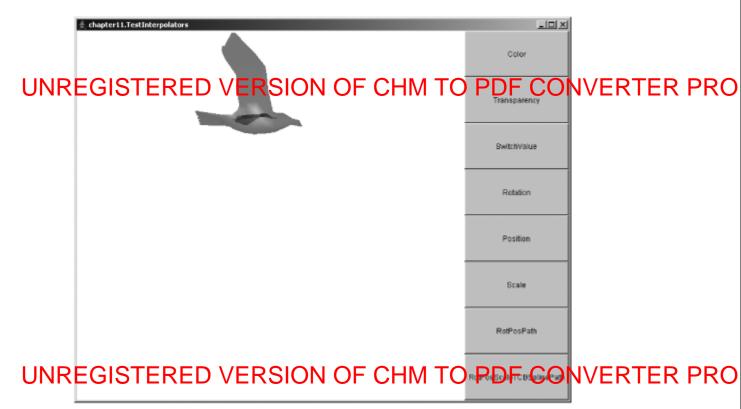
```
85
        // appearance
 86
        Appearance ap = new Appearance();
 87
        Material material = new Material();
        material.setCapability(Material.ALLOW_COMPONENT_WRITE);
 88
 89
        material.setColorTarget(Material.AMBIENT);
 90
        ap.setMaterial(material);
 91
        TransparencyAttributes transAttr = new TransparencyAttributes(
 92
        TransparencyAttributes.BLENDED,0.5f);
 93
        transAttr.setCapability
 94
          (TransparencyAttributes.ALLOW_VALUE_WRITE);
 95
        ap.setTransparencyAttributes(transAttr);
 96
        // gull
 97
        Shape3D shape = new Shape3D(new GullCG(), ap);
 98
        Transform3D trans = new Transform3D();
 99
        trans.setScale(0.5);
100
        TransformGroup tgScale = new TransformGroup(trans);
101
        swNode.addChild(tgScale);
102
        tgScale.addChild(shape);
103
        // dodecahedron
104
        Dodecahedron dodec = new Dodecahedron();
105
        dodec.setAppearance(ap);
106
        trans.setScale(0.1);
107
        tgScale = new TransformGroup(trans);
108
        swNode.addChild(tgScale);
109
        tgScale.addChild(dodec);
110
        // interpolators
111
        BoundingSphere bounds =
112
          new BoundingSphere(new Point3d(0,0,0),100);
113
        Alpha alpha = new Alpha(-1, 6000);
114
        alpha.setMode
115
          (Alpha.INCREASING_ENABLE | Alpha.DECREASING_ENABLE);
116
        alpha.setDecreasingAlphaDuration(6000);
117
        // color
118
        color = new ColorInterpolator
119
          (alpha, material, new Color3f(1,0,0), new Color3f(0,0,1));
120
        color.setSchedulingBounds(bounds);
    UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
121
        root.addChild(color)
122
123
        // transparency
124
        transparency = new TransparencyInterpolator(alpha, transAttr);
125
        transparency.setSchedulingBounds(bounds);
126
        transparency.setEnable(false);
127
        root.addChild(transparency);
128
        // switch
129
        sw = new SwitchValueInterpolator(alpha, swNode);
130
        sw.setSchedulingBounds(bounds);
131
        transparency.setEnable(false);
132
        root.addChild(sw);
133
        // rotation
134
        rotator = new RotationInterpolator(alpha, tg);
135
        rotator.setSchedulingBounds(bounds);
136
        rotator.setEnable(false);
137
        root.addChild(rotator);
138
        // translation
139
        translator = new PositionInterpolator(alpha, tg);
140
        translator.setSchedulingBounds(bounds);
141

[Page 30] NREGIS and ChRott Das Value RSION OF CHM TO PDF CONVERTER PRO
143
        // zoom
```

```
144
        zoom = new ScaleInterpolator(alpha, tg);
145
        zoom.setSchedulingBounds(bounds);
146
        zoom.setEnable(false);
147
        root.addChild(zoom);
148
        // path
        Transform3D axis = new Transform3D();
149
150
        float[] knots = {0,0.25f,0.5f,0.75f,1};
151
        Quat4f[] rots = new Quat4f[5];
152
        Point3f[] ps = new Point3f[5];
153
        for (int i = 0; i < 5; i++) {
154
          rots[i] = new Quat4f((float)Math.cos(0.5*Math.PI*i),0,0,
155
             (float)Math.sin(0.5*Math.PI*i));
156
          ps[i] = new Point3f(0.25f*(i-2)),
157
          (float)Math.sin(0.5*Math.PI*i), 0);
158
        }
159
        path = new RotPosPathInterpolator
160
        (alpha, tg, axis, knots, rots, ps);
161
        path.setSchedulingBounds(bounds);
162
        path.setEnable(false);
163
        root.addChild(path);
164
        // spline
        TCBKeyFrame[] frames = new TCBKeyFrame[5];
165
        for (int i = 0; i < 5; i++) {
166
          frames[i] = new TCBKeyFrame(0.25f*i, 0,
167
168
          new Point3f(0.25f*(i-2),(float)Math.sin(0.5*Math.PI*i), 0),
169
          new Quat4f((float)Math.cos(0.5*Math.PI*i),0,0,
170
          (float)Math.sin(0.5*Math.PI*i)),
171
          new Point3f(1,1,1),0,0,0);
172
        }
173
        spline = new RotPosScaleTCBSplinePathInterpolator
174
          (alpha, tg, axis, frames);
175
        spline.setSchedulingBounds(bounds);
176
        spline.setEnable(true);
177
        root.addChild(spline);
178
        current = spline;
179
        // light
180
        AmbientLight light =
        new AmbientLight(true, new Color3f(Color.blue));
181
182
        light.setInfluencingBounds(bounds);
183
        root.addChild(light);
184
        PointLight ptlight = new PointLight(new Color3f(Color.white),
185
          new Point3f(0f,0f,2f), new Point3f(1f,0.3f,0f));
186
        ptlight.setInfluencingBounds(bounds);
187
        root.addChild(ptlight);
188
        // background
        Background background = new Background(1.0f, 1.0f, 1.0f);
189
190
        background.setApplicationBounds(bounds);
191
        root.addChild(background);
192
        return root;
193
     }
194
195
      public void actionPerformed(ActionEvent e) {
196
        String cmd = e.getActionCommand();
197
        if ("Rotation".equals(cmd)) {
198
          current.setEnable(false);
199
          current = rotator;
200
          current.setEnable(true);
[Page 356]201
                } else if ("Position".equals(cmd)) {
202
          current.setEnable(false);
```



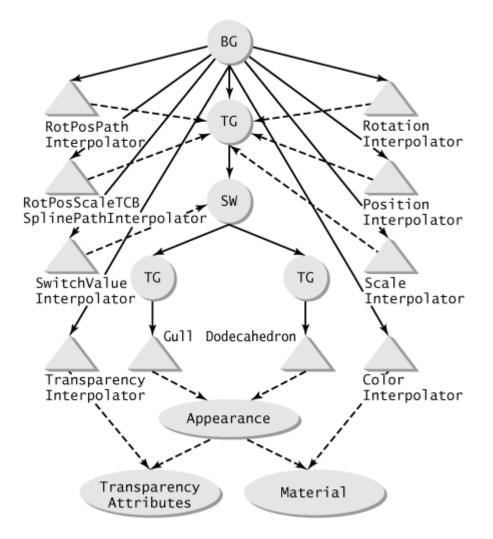
Figure 11.6. An interpolator showcase.



[Page 357]

The scene graph is shown in Figure 11.7. Two lights, a white background, and a BoundingSphere object are not shown. A gull shape using a GullCG geometry and a Dodecahedron object are attached to a Switch node through some scaling. The appearance of the objects contains a Material object and a TransparencyAttributes object. There is a TransformGroup node on top of the Switch. The capability bits of the TransformGroup, Switch, Material, and TransparencyAttributes objects are set to allow writing.

Figure 11.7. The partial scene graph with eight interpolators. For clarity, certain objects such as **Alpha**, **Bounds**, **Light**, **Background**, and view branch are not shown.



An Alpha object is constructed with both increase and decrease parameters enabled. It is applied to all the interpolators. Eight different interpolators are created: ColorInterpolator, TransparencyInterpolator, SwitchValueInterpolator, RotationInterpolator, PositionInterpolator, ScaleInterpolator, RotPosPathInterpolator, and RotPosScaleTCBSplinePathInterpolator. The ColorInterpolator operates on the Material object. The TransparencyInterpolator operates on the TransparencyAttributes. The

SwitchValueInterpolator operates on the Switch. The other five transform interpolators all operate on the TransformGroup Object.

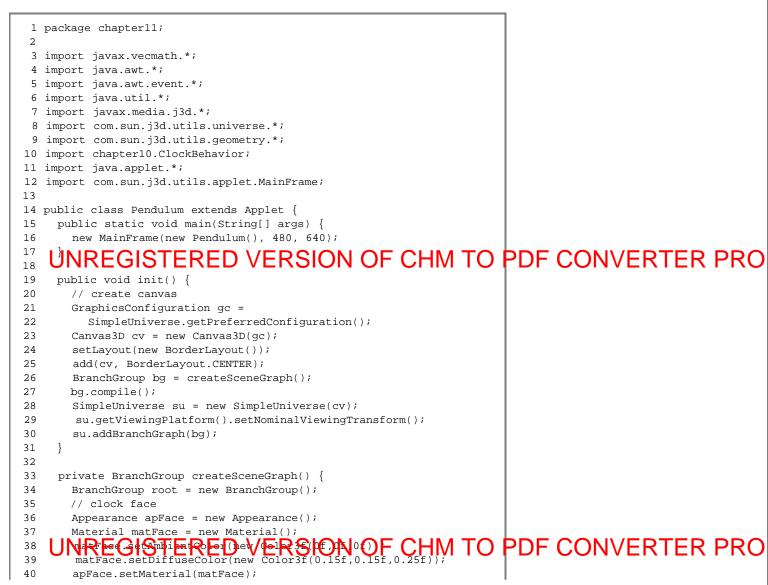
Eight buttons corresponding to the eight interpolators are placed on the "EAST" side of the frame. The frame is the action listener for all the buttons. The first three buttons operate independently to enable or disable their associated interpolators. The other five interpolators act exclusively because they operate on the same target. The field current holds the currently enabled interpolator. Clicking one of the five buttons will first disable the current interpolator and then enable the interpolator corresponding to the button.

Listing 11.3 shows another application of the interpolators. It adds a swinging pendulum to the analog clock defined in the previous chapter by using a RotationInterpolator (Figure 11.8). An interpolator driven by an alpha object is used to swing the pendulum. The scene graph is shown in Figure 11.9.

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Listing 11.3. Pendulum.java

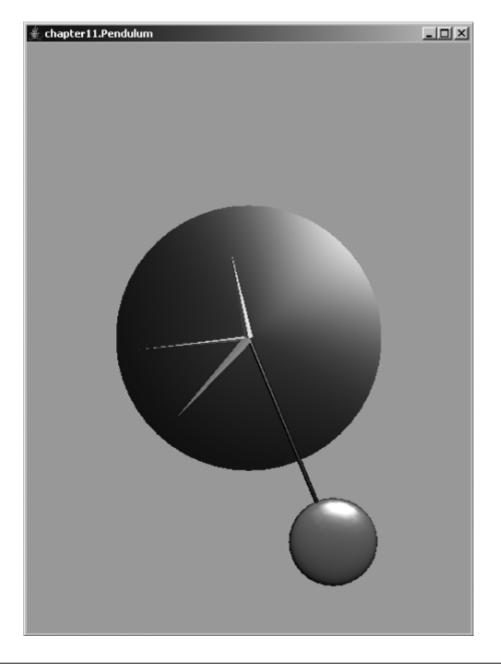
(This item is displayed on pages 358 - 360 in the print version)



```
41
        Cylinder face = new Cylinder(0.6f, 0.01f,
 42
        Cylinder.GENERATE_NORMALS, 50, 2, apFace);
        Transform3D tr = new Transform3D();
 43
 44
        tr.rotX(Math.PT/2);
 45
        tr.setTranslation(new Vector3d(0,0,-0.01));
 46
        TransformGroup tg = new TransformGroup(tr);
 47
        tg.addChild(face);
 48
        root.addChild(tg);
 49
        // hour
 50
        Appearance ap = new Appearance();
 51
        ap.setMaterial(new Material());
 52
        Shape3D shapeHour =
 53
        new Shape3D(createGeometry(0.4, 0.02, 0.02), ap);
 54
        TransformGroup spinHour = new TransformGroup();
 55
        spinHour.addChild(shapeHour);
 56
        spinHour.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
57
        root.addChild(spinHour);
[Page 359] 58
               // minute
        Shape3D shapeMin =
 59
 60
          new Shape3D(createGeometry(0.5, 0.02, 0.02), ap);
        TransformGroup spinMin = new TransformGroup();
 61
 62
        spinMin.addChild(shapeMin);
        spinMin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 63
 64
        root.addChild(spinMin);
 65
        // second
        Shape3D shapeSec =
 66
 67
        new Shape3D(createGeometry(0.5, 0.01, 0.01), ap);
 68
        TransformGroup spinSec = new TransformGroup();
 69
        spinSec.addChild(shapeSec);
 70
        spinSec.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 71
        root.addChild(spinSec);
 72
        // Behavior node
 73
        ClockBehavior rotator =
 74
         new ClockBehavior(spinHour, spinMin, spinSec);
 75
       BoundingSphere bounds = new BoundingSphere();
 76
       rotator.setSchedulingBounds(bounds);
 77
        root.addChild(rotator);
 78
        // pendulum
 79
        Cylinder rod =
 80
          new Cylinder(0.01f, 1f, Cylinder.GENERATE_NORMALS, apFace);
        Transform3D trPend = new Transform3D();
 81
 82
        trPend.setTranslation(new Vector3d(0,-0.5,-0.01));
 83
        TransformGroup tgPend = new TransformGroup(trPend);
        Sphere mass = new Sphere(0.2f, Sphere.GENERATE_NORMALS, 30);
 84
 85
        Transform3D trMass = new Transform3D();
 86
        trMass.setScale(new Vector3d(1,1,0.2));
 87
        trMass.setTranslation(new Vector3d(0,-0.5,0));
 88
        TransformGroup tgMass = new TransformGroup(trMass);
 89
        tgMass.addChild(mass);
 90
        tgPend.addChild(tgMass);
        TransformGroup tgSwing = new TransformGroup();
 91
 92
        tqSwinq.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 93
        tgPend.addChild(rod);
 94
        tgSwing.addChild(tgPend);
        root.addChild(tgSwing);
 95
 96
        Alpha alpha =
 97
          new Alpha(-1, Alpha.INCREASING_ENABLE | Alpha.DECREASING_ENABLE,
 98
          0, 0, 500, 0, 0, 500, 0, 0);
 99
        Transform3D trAxis = new Transform3D();
```

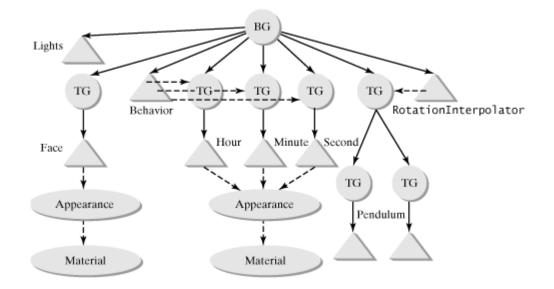
```
100
        trAxis.rotX(Math.PI/2);
101
        RotationInterpolator swing =
102
        new RotationInterpolator(alpha, tgSwing, trAxis,
103
          (float)(-Math.PI/6), (float)(Math.PI/6));
104
        tgPend.addChild(swing);
105
        swing.setSchedulingBounds(bounds);
106
        // light
107
        AmbientLight light =
108
        new AmbientLight(true, new Color3f(Color.blue));
        light.setInfluencingBounds(bounds);
109
110
        root.addChild(light);
111
        PointLight ptlight = new PointLight(new Color3f(Color.white),
112
          new Point3f(0.7f,0.7f,2f), new Point3f(1f,0f,0f));
113
        ptlight.setInfluencingBounds(bounds);
114
        root.addChild(ptlight);
115
        // background
116
        Background background = new Background(0.7f, 0.7f, 0.7f);
[Page 360]117
                background.setApplicationBounds(bounds);
        root.addChild(background);
118
119
        return root;
120
     }
121
122
      GeometryArray createGeometry(double 1, double w, double h) {
123
        GeometryInfo gi = new GeometryInfo(GeometryInfo.TRIANGLE_ARRAY);
124
        Point3d[] pts = new Point3d[4];
125
       pts[0] = new Point3d(0, 0, h);
126
       pts[1] = new Point3d(-w, 0, 0);
127
       pts[2] = new Point3d(w, 0, 0);
128
       pts[3] = new Point3d(0, 1, 0);
129
        gi.setCoordinates(pts);
130
        int[] indices = {0,1,2,0,3,1,0,2,3,2,1,3};
131
        gi.setCoordinateIndices(indices);
132
        NormalGenerator ng = new NormalGenerator();
133
        ng.generateNormals(gi);
134
        return gi.getGeometryArray();
135
136 JUNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
```

Figure 11.8. A swinging pendulum.



[Page 361]

Figure 11.9. The scene graph shows additional structure for the pendulum and its driving interpolator.



This program adds a swinging pendulum to the analog clock example defined in Chapter 10. The pendulum consists of a rod and a mass. The rod is modeled with a cylinder and the mass with a sphere compressed in the z-direction.

A RotationInterpolator is used to swing the pendulum (line 102). The axis of rotation for the interpolator is the y-axis by default, since the pendulum is swinging about the z-axis. It is necessary to change the axis by supplying a Transform3D object. The Transform3D object defines a rotation of p/2 about the x-axis which maps the y-axis to the z-axis. The swing angle is limited to the range [-p/3, p/3] by setting the two extreme values of the RotationInterpolator.

The Alpha object has both increasing and decreasing durations enabled. Both increasingAlphaDuration and decreasingAlphaDuration are set to 500 ms, and therefore the period of the alpha waveform is 1 second (line 97).



[Page 361 (continued)]

### 11.4. Morphing

Morphing is an animation technique that creates a visual effect of smoothly changing one object to another. Morphing is typically applied to a series of geometries. In terms of manipulating shapes, it is more flexible than interpolators on transformations, because the changes in morphing are not limited to affine transforms.

Java 3D provides a Morph leaf node class that, together with behavior objects, supports morphing. Morph contains one appearance bundle but it has an array of geometries. An associated array of weights is also defined for the object. The geometry of the Morph object at any given moment is defined by the weighted sum of the geometries in the array. Typically the weights are modified by a Behavior object to achieve the animation. To construct a Morph object, you may use the following constructors:

```
public Morph(GeometryArray[] geometryArrays)
public Morph(GeometryArray[] geometryArrays, Appearance appearance)
```

All GeometryArray objects in a Morph must have the same size and format. To set weights that combine the geometries you may call the method:

```
public void setWeights(double[] weights)
```

[Page 362]

The weight array has the same size as the array of geometries. All weights should sum to 1.0. In order to set the weights, the appropriate capability bit of the Morph object needs to be set:

```
setCapability(Morph.ALLOW_WEIGHTS_WRITE);
```

Listing 11.4 shows a simple morphing animation. The class for describing the behavior of morphing is given in Listing 11.5. The example displays an object that changes its shape. Starting as a short cylinder, it smoothly increases its height. Then it will turn to left, forming a section of a torus. The torus section will extend to three-quarters of a full torus (Figure 11.10). This process will then reverse and repeat indefinitely. The scene graph is shown in Figure 11.11.

Listing 11.4. Morphing.java

(This item is displayed on pages 362 - 364 in the print version)

```
1 package chapter11;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import java.util.*;
 7 import javax.media.j3d.*;
 8 import com.sun.j3d.utils.universe.*;
 9 import com.sun.j3d.utils.geometry.*;
10 import java.applet.*;
11 import com.sun.j3d.utils.applet.MainFrame;
12
13 public class Morphing extends Applet {
14
     public static void main(String[] args) {
       new MainFrame(new Morphing(), 480, 480);
15
16
     }
17
```

```
public void init() {
18
       // create canvas
19
 20
       GraphicsConfiguration gc =
 21
          SimpleUniverse.getPreferredConfiguration();
 2.2
       Canvas3D cv = new Canvas3D(gc);
 23
        setLayout(new BorderLayout());
 24
        add(cv, BorderLayout.CENTER);
        BranchGroup bg = createSceneGraph();
 25
26
       bq.compile();
        SimpleUniverse su = new SimpleUniverse(cv);
 27
        su.getViewingPlatform().setNominalViewingTransform();
 28
 29
        su.addBranchGraph(bq);
30
     }
31
 32
     private BranchGroup createSceneGraph() {
33
       BranchGroup root = new BranchGroup();
 34
        // geometry
 35
       GeometryArray[] geoms = new GeometryArray[4];
        geoms[0] = createGeometry1(0.1);
 36
 37
        geoms[1] = createGeometry1(0.7);
 38
        geoms[2] = createGeometry2(0.5);
 39
        geoms[3] = createGeometry2(0.8);
 40
       Appearance appear = new Appearance();
 41
        appear.setMaterial(new Material());
 42
       Morph morph = new Morph(geoms, appear);
        morph.setCapability(Morph.ALLOW_WEIGHTS_READ);
 43
 44
        morph.setCapability(Morph.ALLOW_WEIGHTS_WRITE);
 45
       Transform3D tr = new Transform3D();
46
       tr.rotX(Math.PI/2);
[Page 363] 47
               TransformGroup tg = new TransformGroup(tr);
48
       tg.addChild(morph);
 49
       root.addChild(tg);
50
       // Behavior node
51
       Alpha alpha = new Alpha(-1,
 52
        Alpha.INCREASING_ENABLE | Alpha.DECREASING_ENABLE ,
53
          0,0, 8000,0,0,8000,0,0);
    UNREGENERER EN VERSEN (OF GHM TO PDF CONVERTER PRO
 54
 55
        mb.setSchedulingBounds(bounds);
56
57
       root.addChild(mb);
58
       // light
59
       AmbientLight light =
          new AmbientLight(true, new Color3f(Color.blue));
 60
        light.setInfluencingBounds(bounds);
 61
 62
       root.addChild(light);
 63
        PointLight ptlight = new PointLight(new Color3f(Color.white),
 64
          new Point3f(0.7f,0.7f,2f), new Point3f(1f,0f,0f));
 65
        ptlight.setInfluencingBounds(bounds);
       root.addChild(ptlight);
 66
 67
       // background
 68
        Background background = new Background(0.7f, 0.7f, 0.7f);
 69
        background.setApplicationBounds(bounds);
 70
       root.addChild(background);
 71
       return root;
 72
     }
73
 74
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 75
 76
       double r2 = 0.5i
```

```
77
        int m = 20;
        int n = 40;
 78
 79
        Point3d[] pts = new Point3d[m];
 80
        pts[0] = new Point3d(r1+r2, 0, 0);
        double theta = 2.0 * Math.PI / m;
 81
        double c = Math.cos(theta);
 82
 83
        double s = Math.sin(theta);
        double[] mat = {c, -s, 0, r2*(1-c),
 84
 85
                        s, c, 0, -r2*s,
 86
                        0, 0, 1, 0,
 87
                        0, 0, 0, 1\};
 88
        Transform3D rot1 = new Transform3D(mat);
        for (int i = 1; i < m; i++) {
 89
 90
         pts[i] = new Point3d();
 91
          rot1.transform(pts[i-1], pts[i]);
 92
        }
 93
 94
        Transform3D rot2 = new Transform3D();
 95
        rot2.set(new Vector3d(0,0,-h/n));
 96
        IndexedQuadArray qa =
 97
          new IndexedQuadArray(m*n, IndexedQuadArray.COORDINATES,
 98
          4*m*(n-1));
 99
        int quadIndex = 0;
100
        for (int i = 0; i < n; i++) {
101
          qa.setCoordinates(i*m, pts);
102
          for (int j = 0; j < m; j++) {
103
            rot2.transform(pts[j]);
104
            int[] quadCoords = {i*m+j, ((i+1)%n)*m+j,
105
            ((i+1)%n)*m+((j+1)%m), i*m+((j+1)%m)};
106
            if (i < n-1)
[Page 364]107
                    qa.setCoordinateIndices(quadIndex, quadCoords);
108
            quadIndex += 4;
109
          }
110
        }
111
        GeometryInfo gi = new GeometryInfo(qa);
112
        NormalGenerator ng = new NormalGenerator();
113
        ng.generateNormals(gi);
114
        return gi.getGeometryArray();
115
    }
116
     GeometryArray createGeometry2(double h) {
117
        double r1 = 0.1;
118
        double r2 = 0.5i
119
120
       int m = 20;
121
        int n = 40;
122
        Point3d[] pts = new Point3d[m];
123
        pts[0] = new Point3d(r1+r2, 0, 0);
124
        double theta = 2.0 * Math.PI / m;
125
        double c = Math.cos(theta);
126
        double s = Math.sin(theta);
127
        double[] mat = {c, -s, 0, r2*(1-c),
128
                        s, c, 0, -r2*s,
                        0, 0, 1, 0,
129
130
                        0, 0, 0, 1;
131
        Transform3D rot1 = new Transform3D(mat);
132
        for (int i = 1; i < m; i++) {</pre>
133
         pts[i] = new Point3d();
134
          rot1.transform(pts[i-1], pts[i]);
135
        }
```

```
136
137
        Transform3D rot2 = new Transform3D();
138
        rot2.rotY(h*2*Math.PI/n);
139
        IndexedQuadArray qa =
140
          new IndexedQuadArray(m*n, IndexedQuadArray.COORDINATES,
141
          4*m*(n-1));
142
        int quadIndex = 0;
        for (int i = 0; i < n; i++) {
143
          qa.setCoordinates(i*m, pts);
144
          for (int j = 0; j < m; j++) {
145
146
            rot2.transform(pts[j]);
147
            int[] quadCoords = {i*m+j, ((i+1)%n)*m+j,
148
               ((i+1)%n)*m+((j+1)%m),
149
               i*m+((j+1)%m)};
150
            if (i < n-1)
151
             qa.setCoordinateIndices(quadIndex, quadCoords);
152
            quadIndex += 4;
153
          }
154
        }
155
        GeometryInfo gi = new GeometryInfo(ga);
        NormalGenerator ng = new NormalGenerator();
156
157
        ng.generateNormals(gi);
158
        return gi.getGeometryArray();
159
      }
160 }
```

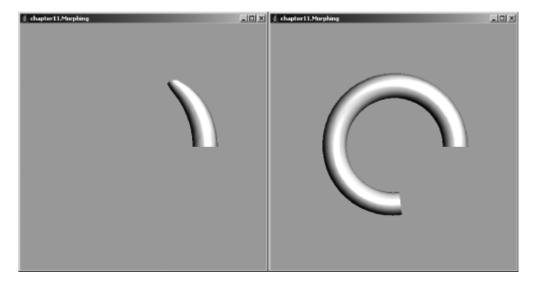
#### Listing 11.5. MorphingBehavior.java

(This item is displayed on pages 364 - 365 in the print version)

```
1 package chapter11;
2
4
5 public class MorphingBehavior extends Behavior {
6
   Morph morph;
7
    Alpha alpha;
8
9
    public MorphingBehavior(Morph m, Alpha a) {
10
     morph = m;
11
     alpha = a;
12
    }
13
14
   public void initialize() {
15
      wakeupOn(new WakeupOnElapsedFrames(10));
16
    }
17
18
    public void processStimulus(java.util.Enumeration enumeration) {
19
     double[] w = new double[4];
20
     double a = alpha.value();
     w[0] = 0;
21
22
     w[1] = 0;
23
     w[2] = 0;
        REGISTERED VERSION OF CHM TO PDF CONVERTER PRO
24
25
     int index = (int)(a*3);
26
     if (index > 2) index = 2;
```

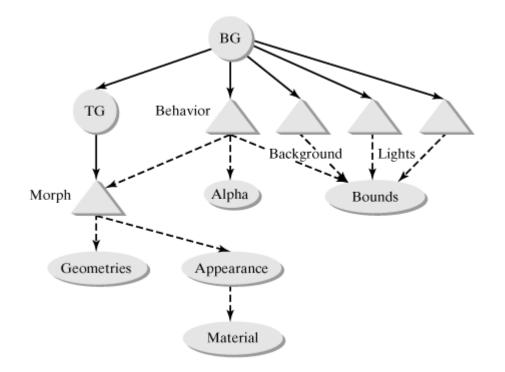
```
27 w[index+1] = (a-index/3.0)*3;
28 w[index] = 1.0-w[index+1];
29 morph.setWeights(w);
30 wakeupOn(new WakeupOnElapsedFrames(10));
31 }
32 }
```

### Figure 11.10. Morphing example.



[Page 366]

Figure 11.11. Scene graph for the morphing example.



Four GeometryArray objects are constructed to serve as the key frames in a Morph object. They are created by the methods createGeometry1 and createGeometry2. createGeometry1 (line 74) creates a vertical tube of a certain height. createGeometry2 (line 117) creates a portion of a torus. The first and second geometries in the Morph object are tubes of different heights. The third and fourth geometries are torus sections of different lengths.

A custom MorphingBehavior class is defined to modify the weights in the Morph node. The weights are set based on Alpha values, similar to an interpolator (lines 21–29). The constructor takes a Morph object and an Alpha **Wight Fight Fight Provide and Set 10** and **Set 10** and **S** 

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[Page 366 (continued)]

### 11.5. LOD

The *level of detail* (*LOD*) is a technique useful for reducing the computational cost of rendering complex shapes. It takes advantage of the fact that in a perspective view, a visual object closer to the viewer will be larger and show more details than the same object viewed from a distance. Consequently, it may be possible to render a distant object with less resolution and detail without significantly affecting the quality.

Java 3D provides the abstract LOD class as a subclass of Behavior to support LOD. LOD has a concrete subclass DistanceLOD. An LOD object acts on a list of Switch nodes to select a child of a Switch as a particular level of detail. The DistanceLOD controls the selection based on the distances to the viewer. The DistanceLOD class has the following constructors:

public DistanceLOD()
public DistanceLOD(float[] distances)
public DistanceLOD(float[] distances, Point3f position)

The distances array defines the critical distances to switch to the next level. The default position to measure the distances to the viewer is the origin of the DistanceLOD object. The third constructor allows you to specify a different position.

[Page 367]

The program in Listing 11.6 displays a texture mapped globe. A user can rotate and zoom the view with mouse actions. A DistanceLOD object is applied to a Switch node to select a sphere with a certain level of detail based on the distance to the viewer (Figure 11.12).

Listing 11.6. TestLOD.java

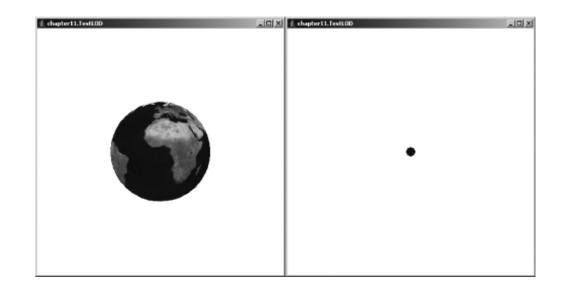
(This item is displayed on pages 367 - 369 in the print version)

```
1 package chapter11;
 2
 3 import java.awt.*;
 4 import java.awt.geom.*;
 5 import java.awt.event.*;
 6 import java.awt.image.*;
 7 import javax.imageio.*;
 8 import com.sun.j3d.utils.geometry.*;
 9 import com.sun.j3d.utils.behaviors.vp.*;
10 import com.sun.j3d.utils.universe.*;
11 import javax.media.j3d.*;
12 import javax.vecmath.*;
13 import java.io.*;
14 import java.net.*;
15 import com.sun.j3d.utils.image.*;
16 import java.applet.*;
17 import com.sun.j3d.utils.applet.MainFrame;
18
19 public class TestLOD extends Applet {
20
    public static void main(String[] args) {
21
       new MainFrame(new TestLOD(), 480, 480);
2.2
     }
23
24
     BufferedImage[] images = new BufferedImage[3];
25
     public void init() {
```

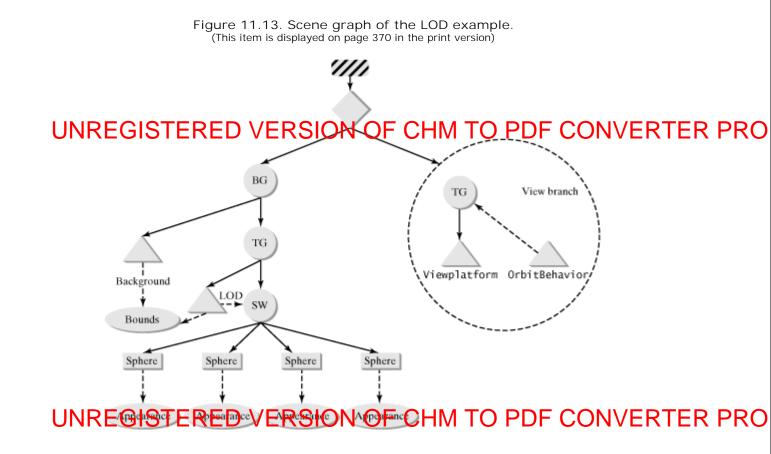
```
26
        // create canvas
 27
        GraphicsConfiguration gc =
 28
        SimpleUniverse.getPreferredConfiguration();
29
        Canvas3D cv = new Canvas3D(gc);
30
        setLayout(new BorderLayout());
31
        add(cv, BorderLayout.CENTER);
32
        BranchGroup bg = createSceneGraph();
33
       bq.compile();
34
        SimpleUniverse su = new SimpleUniverse(cv);
35
        ViewingPlatform viewingPlatform = su.getViewingPlatform();
 36
        viewingPlatform.setNominalViewingTransform();
37
        // orbit behavior to zoom and rotate the view
       OrbitBehavior orbit = new OrbitBehavior(cv,
38
39
          OrbitBehavior.REVERSE_ZOOM |
 40
          OrbitBehavior.REVERSE_ROTATE
 41
          OrbitBehavior.DISABLE_TRANSLATE);
 42
       BoundingSphere bounds =
 43
          new BoundingSphere(new Point3d(0.0, 0.0, 0.0), 100.0);
        orbit.setSchedulingBounds(bounds);
 44
 45
        viewingPlatform.setViewPlatformBehavior(orbit);
 46
        su.addBranchGraph(bg);
 47
     }
 48
     public BranchGroup createSceneGraph() {
 49
 50
        BranchGroup objRoot = new BranchGroup();
        TransformGroup objTrans = new TransformGroup();
51
 52
        objTrans.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 53
        objTrans.setCapability(TransformGroup.ALLOW_TRANSFORM_READ);
54
        objRoot.addChild(objTrans);
[Page 368] 55
               // a switch to hold the different levels
56
        Switch sw = new Switch(0);
 57
        sw.setCapability(javax.media.j3d.Switch.ALLOW_SWITCH_READ);
 58
        sw.setCapability(javax.media.j3d.Switch.ALLOW_SWITCH_WRITE);
59
        objTrans.addChild(sw);
 60
        // 4 levels of globes
 61
       loadImages();
    UNRECISTERED EVERSION OF CHM TO PDF CONVERTER PRO
 62
 63
        Primitive.GENERATE_TEXTURE_COORDS, 40, ap));
 64
 65
        ap = createAppearance(1);
 66
        sw.addChild(new Sphere(0.4f,
 67
        Primitive.GENERATE_TEXTURE_COORDS, 20, ap));
 68
       ap = createAppearance(2);
 69
       sw.addChild(new Sphere(0.4f,
 70
       Primitive.GENERATE_TEXTURE_COORDS, 10, ap));
 71
       ap = new Appearance();
 72
        ap.setColoringAttributes(new ColoringAttributes
 73
          (0f,0f,0.5f,ColoringAttributes.FASTEST));
 74
        sw.addChild(new Sphere(0.4f, Sphere.GENERATE_NORMALS, 5, ap));
 75
       // the DistanceLOD behavior
 76
       float[] distances = new float[3];
 77
       distances[0] = 5.0f;
 78
       distances[1] = 10.0f;
 79
       distances[2] = 25.0f;
 80
        DistanceLOD lod = new DistanceLOD(distances);
 81
        lod.addSwitch(sw);
 82
        BoundingSphere bounds
     UNREGISTERED VERSION OF GHM TO PDF CONVERTER PRO
 83
 84
        lod.setSchedulingBounds(bounds);
```

```
85
        objTrans.addChild(lod);
 86
        // background
        Background background = new Background(1.0f, 1.0f, 1.0f);
 87
 88
        background.setApplicationBounds(bounds);
        objRoot.addChild(background);
 89
 90
        return objRoot;
 91
      }
 92
 93
      void loadImages() {
 94
        URL filename =
 95
           getClass().getClassLoader().getResource("images/earth.jpg");
 96
        try {
 97
          images[0] = ImageIO.read(filename);
 98
          AffineTransform xform =
 99
          AffineTransform.getScaleInstance(0.5, 0.5);
100
          AffineTransformOp scaleOp = new AffineTransformOp (xform, null);
101
          for (int i = 1; i < 3; i++) {
102
               images[i] = scaleOp.filter(images[i-1], null);
103
          }
        } catch (IOException ex) {
104
105
            ex.printStackTrace();
106
        }
107
      }
108
109
      Appearance createAppearance(int i){
110
        Appearance appear = new Appearance();
111
          ImageComponent2D image =
112
             new ImageComponent2D(ImageComponent2D.FORMAT_RGB, images[i]);
[Page 369]113
                  Texture2D texture =
114
          new Texture2D(Texture.BASE_LEVEL, Texture.RGBA,
115
          image.getWidth(), image.getHeight());
116
          texture.setImage(0, image);
117
          texture.setEnable(true);
          texture.setMagFilter(Texture.BASE_LEVEL_LINEAR);
118
119
           texture.setMinFilter(Texture.BASE_LEVEL_LINEAR);
120
          appear.setTexture(texture);
121
        return appear;
122
    }
123 }
```

Figure 11.12. LOD example.



As shown in the scene graph (Figure 11.13), a Switch node with four children is created to be the target of the DistanceLOD behavior (lines 55–81). All four children are spheres, but their appearances and quality are different. The first three use texture mapping with different image resolutions. The last sphere uses a flat color for its appearance.



The loadImages method (line 93) prepares three BufferedImage objects for the texture mapping. The first image is loaded from the file "earth.jpg." It has the size 512 x 512. The second image is obtained by scaling the first image down to 256 x 256 with an AffineTransformOp object. The third image is obtained similarly by scaling down further to 128 x 128.

The numbers of divisions of the spheres are also different. The first sphere has 40 divisions, resulting in a highquality sphere. The other spheres have 20, 10, and 5, respectively.

When the sphere is close to the viewer, a high-quality version is used. As it moves away, other versions of the sphere with less quality will be selected by the LOD behavior.

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### 11.6. Billboard

A Billboard behavior operates on a target TransformGroup object so that the children of the target will always be aligned to face the viewer. The behavior sets an appropriate rotation on the target transform to achieve this alignment task, regardless of any other transforms on top of the target.

A billboard is useful for certain visual objects such as text labels. Another common application is to simulate a complex 3D scene with a 2D object, such as an image. A billboard behavior may help hide the 2D nature of the image if the user can never see the "depth" of the image. For example, to model a tree with 3D geometry will be expensive. It will be quite efficient to use a 2D image of the tree. Therefore, using an image with a billboard behavior may provide a good approximation. Of course, this method offers only a crude and "fake" model for the tree. The results may be satisfactory if the tree is roughly symmetric and is not close to the viewer.

A Billboard object operates in one of two available modes:

ROTATE\_ABOUT\_POINT ROTATE\_ABOUT\_AXIS

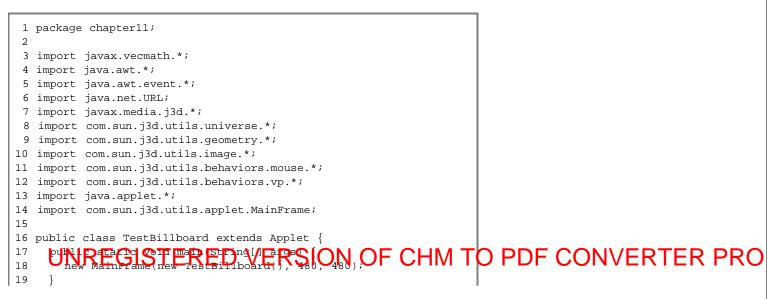
The first mode allows an arbitrary rotation to make a full alignment. The second mode allows only a rotation about an axis. The Billboard class has the following constructors:

public Billboard()
public Billboard(TransformGroup target)
[Page 371]public Billboard(TransformGroup target, int mode, Point3f point)
public Billboard(TransformGroup target, int mode, Vector3f axis)

Listing 11.7 is an example that displays a set of coordinate axes with x, y, z labels. Listing 11.8 gives a class that describes the axes with billboard behavior. The user may rotate, translate, and zoom the view with mouse operations. The 3D text labels attached to the axes will always face the viewer, regardless of the transformations. (See Figure 11.14.)

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(This item is displayed on pages 371 - 372 in the print version)



```
20
21
     public void init() {
22
       // create canvas
23
       GraphicsConfiguration gc =
24
          SimpleUniverse.getPreferredConfiguration();
25
       Canvas3D cv = new Canvas3D(gc);
26
       setLayout(new BorderLayout());
27
       add(cv, BorderLayout.CENTER);
       TextArea ta = new TextArea("",3,30,TextArea.SCROLLBARS_NONE);
28
29
       ta.setText("Rotation: Drag with left button\n");
30
       ta.append("Translation: Drag with right button\n");
31
       ta.append("Zoom: Hold Alt key and drag with left button");
32
       ta.setEditable(false);
33
       add(ta, BorderLayout.SOUTH);
34
       BranchGroup root = new BranchGroup();
35
       // axes
36
       Transform3D tr = new Transform3D();
37
       tr.setScale(0.5);
       // tr.setTranslation(new Vector3d(-0.8, -0.7, -0.5));
38
39
       TransformGroup tg = new TransformGroup(tr);
40
       root.addChild(tg);
41
       AxesBillboard axes = new AxesBillboard();
42
       tg.addChild(axes);
43
       BoundingSphere bounds = new BoundingSphere();
44
       // light
45
       AmbientLight light =
46
       new AmbientLight(true, new Color3f(Color.blue));
47
       light.setInfluencingBounds(bounds);
48
       root.addChild(light);
49
       PointLight ptlight = new PointLight(new Color3f(Color.white),
[Page 372]50
                 new Point3f(0f,0f,2f), new Point3f(1f,0f,0f));
51
       ptlight.setInfluencingBounds(bounds);
52
       root.addChild(ptlight);
53
       // background
54
       Background background = new Background(1.0f, 1.0f, 1.0f);
55
       background.setApplicationBounds(bounds);
56
       root.addChild(background);
57
       root.compile();
58
       SimpleUniverse su = new SimpleUniverse(cv);
59
       su.getViewingPlatform().setNominalViewingTransform();
60
       // viewplatform motion
61
       OrbitBehavior orbit = new OrbitBehavior(cv);
62
       orbit.setSchedulingBounds(new BoundingSphere());
63
        su.getViewingPlatform().setViewPlatformBehavior(orbit);
64
       su.addBranchGraph(root);
65
    }
66 }
```

#### Listing 11.8. AxesBillboard.java

(This item is displayed on pages 372 - 373 in the print version)

```
1 package chapter11;
```

```
2
3 import javax.vecmath.*;
```

```
4 import java.awt.*;
```

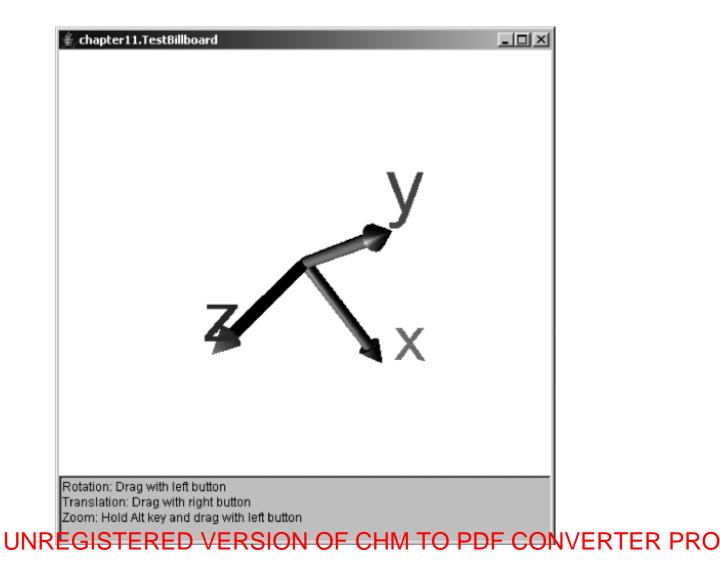
```
4 import java.awt.*;
```

```
5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
9
10 public class AxesBillboard extends Group {
    public AxesBillboard() {
11
12
       Appearance ap = new Appearance();
13
       ap.setMaterial(new Material());
       Font3D font = new Font3D(new Font("SanSerif", Font.PLAIN, 1),
14
15
                               new FontExtrusion());
       Text3D x = new Text3D(font, "x");
16
17
       Shape3D xShape = new Shape3D(x, ap);
18
       Text3D y = new Text3D(font, "y");
19
       Shape3D yShape = new Shape3D(y, ap);
20
       Text3D z = new Text3D(font, "z");
21
       Shape3D zShape = new Shape3D(z, ap);
22
      // transform for texts
       Transform3D tTr = new Transform3D();
23
24
      tTr.setTranslation(new Vector3d(-0.12, 0.6, -0.04));
25
      tTr.setScale(0.5);
26
      // transform for arrows
27
       Transform3D aTr = new Transform3D();
28
      aTr.setTranslation(new Vector3d(0, 0.5, 0));
29
      // bounds
       Bounds bounds = new BoundingSphere(new Point3d(0,0,0), 100);
30
31
      // x axis
32
       Cylinder xAxis = new Cylinder(0.05f, 1f);
33
       Transform3D xTr = new Transform3D();
34
      xTr.setRotation(new AxisAngle4d(0, 0, 1, -Math.PI/2));
35
       xTr.setTranslation(new Vector3d(0.5, 0, 0));
36
       TransformGroup xTg = new TransformGroup(xTr);
37
       xTg.addChild(xAxis);
38
       this.addChild(xTg);
[Page 373]39
              TransformGroup xTextTg = new TransformGroup(tTr);
40
       TransformGroup bbTg = new TransformGroup();
     UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
41
       xTextTg.addChild(bbTg);
42
       bbTg.addChild(xShape);
43
44
       Billboard bb = new Billboard(bbTg,
45
       Billboard.ROTATE_ABOUT_POINT, new Point3f(0,0,0));
46
       bb.setSchedulingBounds(bounds);
       xTextTg.addChild(bb);
47
48
       xTg.addChild(xTextTg);
49
       Cone xArrow = new Cone(0.1f, 0.2f);
50
       TransformGroup xArrowTg = new TransformGroup(aTr);
51
       xArrowTg.addChild(xArrow);
52
      xTg.addChild(xArrowTg);
53
      // y axis
54
       Cylinder yAxis = new Cylinder(0.05f, 1f);
55
       Transform3D yTr = new Transform3D();
56
       yTr.setTranslation(new Vector3d(0, 0.5, 0));
57
       TransformGroup yTg = new TransformGroup(yTr);
58
       yTg.addChild(yAxis);
59
       this.addChild(yTg);
60
       TransformGroup yTextTg = new TransformGroup(tTr);
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61
62
63
       yTextTq.addChild(bbTq);
```

```
64
       bbTg.addChild(yShape);
65
       bb = new Billboard(bbTg,
       Billboard.ROTATE_ABOUT_POINT, new Point3f(0,0,0));
66
       bb.setSchedulingBounds(bounds);
67
68
       yTextTg.addChild(bb);
69
       yTg.addChild(yTextTg);
70
       Cone yArrow = new Cone(0.1f, 0.2f);
71
       TransformGroup yArrowTg = new TransformGroup(aTr);
72
       yArrowTg.addChild(yArrow);
73
       yTg.addChild(yArrowTg);
74
       // z axis
75
       Cylinder zAxis = new Cylinder(0.05f, 1f);
76
       Transform3D zTr = new Transform3D();
77
       zTr.setRotation(new AxisAngle4d(1, 0, 0, Math.PI/2));
78
       zTr.setTranslation(new Vector3d(0, 0, 0.5));
79
       TransformGroup zTg = new TransformGroup(zTr);
80
       zTg.addChild(zAxis);
81
       this.addChild(zTg);
82
       TransformGroup zTextTg = new TransformGroup(tTr);
83
       bbTg = new TransformGroup();
84
       bbTg.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
85
       zTextTg.addChild(bbTg);
86
       bbTg.addChild(zShape);
87
       bb = new Billboard(bbTg,
88
       Billboard.ROTATE_ABOUT_POINT, new Point3f(0,0,0));
89
       bb.setSchedulingBounds(bounds);
90
       zTextTg.addChild(bb);
91
      zTg.addChild(zTextTg);
92
       Cone zArrow = new Cone(0.1f, 0.2f);
93
       TransformGroup zArrowTg = new TransformGroup(aTr);
94
       zArrowTg.addChild(zArrow);
95
       zTg.addChild(zArrowTg);
96
    }
97 }
```

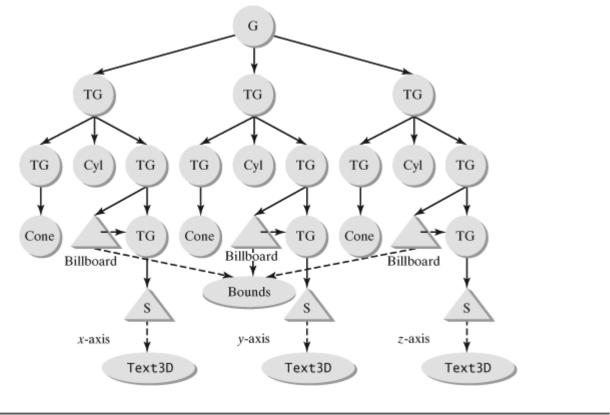
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Figure 11.14. A Billboard behavior example.



The object displayed is a set of coordinate axes similar to the Axes class defined in Chapter 7. The difference is the addition of Billboard behavior nodes (lines 44, 65, 87) and extra TransformGroup nodes to the scene graph, as shown in Figure 11.15. The Billboard objects are created with the mode ROTATE\_ABOUT\_POINT.

Figure 11.15. Scene graph of **AxesBillboard**.



[Page 375]

The program displays an instance of the AxesBillboard with lighting. The view has an OrbitBehavior object attached to allow rotation, translation, and zooming with mouse operations. The "x," "y," and "z" labels will move with the axes under the transformations. However, because of the Billboard behaviors, the text labels will always be oriented to face the viewer.

Note that even though the Billboard object needs to change only the rotational component of the transform, it does clear the translation and scaling components. Therefore it is necessary to create an additional TransformGroup node for the Billboard.

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#### [Page 375 (continued)]

### Key Classes and Methods

- javax.media.j3d.Alpha A class encapsulating an alpha function.
- javax.media.j3d.Interpolator A base class for the interpolator behaviors.
- javax.media.j3d.ColorInterpolator An interpolator operating on the colors in a Material object.
- **javax.media.j3d.TransparencyInterpolator** An interpolator operating on a TransparencyAttributes object.
- javax.media.j3d.SwitchValueInterpolator An interpolator operating on a Switch object.
- javax.media.j3d.TransformInterpolator A base class for transformation interpolators.
- javax.media.j3d.RotationInterpolator An interpolator for rotation.
- javax.media.j3d.PositionInterpolator An interpolator for translation.
- javax.media.j3d.ScaleInterpolator An interpolator for scale.
- javax.media.j3d.PathInterpolator A base class for transformation interpolators defined by a sequence of frames.
- javax.media.j3d.RotationPathInterpolator A path interpolator for rotation.
- javax.media.j3d.PositionPathInterpolator A path interpolator for translation.
- javax.media.j3d.RotPosPathInterpolator A path interpolator for rotation and translation.
- 地格展展GISTEREDEN/EREGION OF MITO PEDF. 13 GNV ERTER PRO scaling.
- com.sun.j3d.utils.behaviors.interpolators.RotPosScaleTCBSplinePathInterpolator A spline path interpolator for rotation, translation, and scaling.
- com.sun.j3d.utils.behaviors.interpolators.KBRotPosScaleSplinePathInterpolator A spline path interpolator for rotation, translation, and scaling.
- javax.media.j3d.Morph A leaf-node class for blending an array of geometries.
- javax.media.j3d.LOD A behavior class for LOD.
- javax.media.j3d.DistanceLOD An LOC class operating on a Switch node based on distances.
- javax.media.j3d.Billboard A behavior class to orient an object to face the viewer.

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#### Key Terms animation

A process of rendering a sequence of frames of a dynamic scene.

#### alpha

A function of time valued between 0 and 1. It is used to drive an interpolator.

#### interpolator

A behavior driven by an alpha to produce animation.

#### path interpolator

A transformation interpolator defined by a sequence of key frames.

#### spline path interpolator

A transformation interpolator along a smooth path defined by a sequence of key frames.

#### morphing

A dynamic change of an object's shape.

LOD (level of detail)

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A technique to change the level of detail rendered based on the circumstances of the view.

#### billboard behavior

A behavior that automatically orients an object toward the viewer.

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### Chapter Summary

- This chapter introduces commonly used animation techniques and the Java 3D animation support with behaviors.
- The interpolators are easy-to-use animation tools. They are driven by alpha objects and they interpolate the intermediate values from the specified control points or key frames. Java 3D includes a large collection of interpolators that interpolate a variety of attributes from colors to spline curve paths.
- A Morph node references a list of geometries and produces one object by combining the geometries with a list of weights. Typically the weights can be changed by a behavior object to produce a special animation of morphing from one object to another.
- The LOD behaviors control Switch nodes to select a version of an object a with certain detail level. LOD provides a tool for automatically reducing the amount of detail rendered when the details are not essential. It is a useful method to improve the efficiency of rendering without significant loss in quality.
- A Billboard behavior automatically rotates the target to maintain a direction facing the viewer. It is useful in setting text labels and in simulating 3D objects using 2D images.

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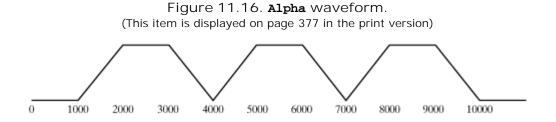
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### **Review** Questions

```
11.1 Draw the waveform of an Alpha with the following parameters:
LoopCount = 5
TriggerTime = 0
PhaseDelayDuration = 100
AlphaAtZeroDuration = 0
AlphaAtOneDuration = 0
IncreasingAlphaDuration = 0
DecreasingAlphaRampDuration = 0
DecreasingAlphaRampDuration = 0
```

- 11.2 Draw the waveform of an Alpha with the following parameters: LoopCount = -1 TriggerTime = 0 PhaseDelayDuration = 0 AlphaAtZeroDuration = 200 AlphaAtOneDuration = 200 IncreasingAlphaDuration = 400 DecreasingAlphaRampDuration = 100 DecreasingAlphaRampDuration = 0
- 11.3 Find the parameters for the Alpha with the waveform shown in Figure 11.16.



11.4 Listing 11.3 uses a RotationInterpolator to swing the pendulum. What other interpolators can be used for this task?

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- 11.5 Besides the distance-based LOD, can you think of other cases where the LOD technique might be appropriate?
- 11.6 Discuss the limitations of the ROTATE\_ABOUT\_AXIS mode in a Billboard object and the situations where this mode is adequate.

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[Page 377 (continued)]

### **Programming Exercises**

- 11.1 In Listing 11.1, add two other parameters of the Alpha class—mode and phaseDelayDuration—to the panel of parameters.
- 11.2 Write a Java 3D program to display a tetrahedron that continuously moves left and right.
- 11.3 Write a Java 3D program to display a tetrahedron that continuously moves along a triangle path with vertices (-0.5, 0, 0), (0.5, -0.5, 0), and (0, 0, 0.5).
- 11.4 Add the following transform interpolators to Listing 11.2: RotationPathInterpolator PositionPathInterpolator RotPosScalePathInterpolator KBRotPosScaleSplinePathInterpolator
- 11.5 Write a program that uses a Morph object and a Behavior object to display an object morphing between a cone and a cylinder.
- 11.6 Write a program that uses a DistanceLOD object to set up three levels of detail for displaying a 3D text object of the string "Java." The first level uses a Material object in the appearance to enable lighting. The second level uses a flat color. The third level uses only a filled rectangle to represent the text.
- 11.7 Write a Java 3D program that shows a texture-mapped rectangle with a Billboard behavior. Use an OrbitBehavior object to allow view manipulations through mouse operations.

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### Chapter 12. Additional 3D Topics

(This item omitted from WebBook edition)

Objectives
• To define and implement 3D curves.
• To define and implement 3D surfaces.
• To use sound in Java 3D scene graphs.
To create simple shadows.
To understand dynamic geometry change.
• To use off-screen rendering for capturing rendered images.
• To apply 3D texture mapping.
To understand and implement synthetic textures.

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### 12.1. Introduction

This chapter introduces several advanced techniques related to 3D graphics.

3D curves and surfaces are important building blocks of 3D geometries. Current versions of Java 3D do not have direct support for curves and surfaces. In this chapter, examples of constructing curves and curved surfaces are given. The deCasteljau algorithm for evaluations and subdivisions of Bézier curves is presented.

Sounds are used in conjunction with graphics in many applications. Java 3D offers support for direct incorporation of sounds into scene graphs. This approach allows easy association between graphics objects and sounds.

Shadows are complex objects to create in computer graphics. The local illumination models employed in Java 3D will not automatically generate shadows. A simplistic method for generating artificial shadows with polygon objects is introduced in this chapter.

In the animation and interaction examples introduced previously, geometry objects are usually not modified dynamically. It is possible to change geometry data in a live scene graph, but a special procedure is required. The GeometryArray object must be created in the BY\_REFERENCE mode, and the change should be made only through a class implementing the GeometryUpdater interface. A dynamic shadow example is used to illustrate the procedure.

Capturing a rendered image from the Canvas3D object in a Java 3D scene is useful in some applications. The off-screen rendering capability of the Canvas3D class is introduced. It can be used to capture a frame to a BufferedImage object.

3D texture mapping applies a solid 3D image to an object. It creates a visual realism that is difficult to achieve in 2D texture mapping. Java 3D provides basic support for 3D texturing. One related topic is the generation of synthetic textures. The Perlin's noise is a random function that exhibits a certain smoothness. It may be used to generate textures that remarkably resemble natural textures such as marble, wood, and metal.

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### 12.2. 3D Curves

Definitions of Bézier and B-spline curves in 3D spaces are the same as for their 2D counterparts. The parametric equation of a general Bézier curve of degree *n* with *control points*  $p_0$ ,  $p_0$ ,...,  $p_n$  is given by

$$s(t) = \sum_{i=0}^{n} p_i B_{n,i}(t)$$

where  $B_{n,k}(t)$  is known as the *Bernstein polynomial* or *Bernstein basis* 

$$B_{n,i}(t) = \binom{n}{i} t^i (1-t)^{n-i}$$

In particular, a cubic Bézier curve has degree n = 3 and is defined by four control points

$$s(\hbar) = (1 - \hbar)^3 \rho 0 + 3t(1 - \hbar)^2 \rho 1 + 3t^2(1 - t)\rho 2 + t^2 \rho 3$$

The *deCasteljau algorithm* provides a method to calculate a point on the curve from the control points using linear interpolations. The algorithm proceeds by constructing a triangular scheme of the points similar to a Pascal's triangle. For the cubic Bézier curve, the following triangular scheme is used:

$$p_{0}^{0}, p_{1}^{0}, p_{2}^{0}, p_{3}^{0}$$

$$p_{0}^{1}, p_{1}^{1}, p_{2}^{1}$$

$$p_{0}^{2}, p_{1}^{2}$$

$$p_{0}^{3}, p_{0}^{3}$$

The first row contains the original control points of the Bézier curve. The subsequent rows are calculated by the formula:

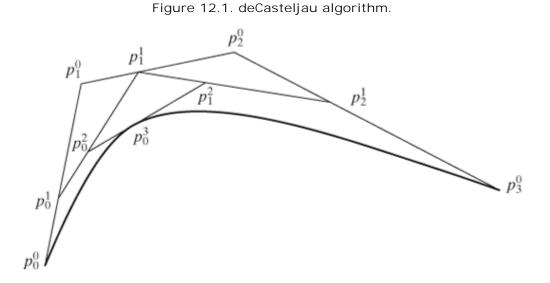
$$p_i^k = (1 - t)p_i^{k-1} + tp_{i+1}^{k-1}$$

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The last entry gives the value of the point on the Bézier curve at *t* 

$$s(t) = p_0^3$$

The process is illustrated in Figure 12.1. All the calculations are simple linear interpolations.



A Bézier curve can be subdivided into two Bézier curves. The deCasteljau algorithm also offers a method for the *subdivision*. In the cubic curve shown in Figure 12.1, the two subdivided Bézier curves have the control points  $p_0^0$ ,  $p_0^1$ ,  $p_0^2$ ,  $p_0^3$  and  $p_0^3$ ,  $p_{12}^3$ ,  $p_{12}^1$ ,  $p_{12}^0$ ,  $p_{13}^0$ , respectively.

Curren UNRIER State REDES CEIRIS CONTRER PRO implement our own versions of Bézier curves and surfaces using the line and polygon arrays provided by Java 3D. Other spline curves and surfaces can be implemented as a series of Bézier curves or surfaces.

Listing 12.1 illustrates the rendering of cubic Bézier curves with recursive subdivisions. A test program that displays a Bézier curve is given in Listing 12.2. A BezierCurve class is implemented as a subclass of LineStripArray. A test program displays an instance of the curve class (See Figure 12.2.)

Listing 12.1. BezierCurve.java

(This item is displayed on pages 381 - 382 in the print version)

```
1 package chapter12;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
9
10 public class BezierCurve extends LineStripArray {
11 static int level = 4;
12
   static int[] vCnts = {(1<<level)+1};</pre>
13
   int index = 0;
14
   public BezierCurve(Point3d p0,Point3d p1,Point3d p2,Point3d p3) {
15
16
      super(vCnts[0], GeometryArray.COORDINATES, vCnts);
17
      setCoordinate(index, p0);
18
     index++;
19
      subdivide(0,p0,p1,p2,p3);
20
   }
21
22
   void subdivide(int lev, Point3d p0, Point3d p1,
23
   Point3d p2, Point3d p3) {
24
     if (lev >= level){
25
         setCoordinate(index, p3);
[Page 382]26
                index++;
27
       }
28
      else {
29
       Point3d p10 = new Point3d();
30
        p10.add(p0,p1);
31
        p10.scale(0.5);
32
        Point3d p11 = new Point3d();
33
        p11.add(p1,p2);
34
        p11.scale(0.5);
35
        Point3d p12 = new Point3d();
36
        p12.add(p2,p3);
37
        p12.scale(0.5);
38
         Point3d p20 = new Point3d();
39
        p20.add(p10,p11);
40
        p20.scale(0.5);
        Point3d p21 = new Point3d();
41
42
        p21.add(p11,p12);
43
         p21.scale(0.5);
44
         Point3d p30 = new Point3d();
45
         p30.add(p20,p21);
46
         p30.scale(0.5);
47
         subdivide(lev+1,p0,p10,p20,p30);
48
         subdivide(lev+1,p30,p21,p12,p3);
49
       }
50
   }
51 }
```

Listing 12.2. TestBezierCurve.java (This item is displayed on pages 382 - 383 in the print version)

```
1 package chapter12;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
 9 import java.applet.*;
10 import com.sun.j3d.utils.applet.MainFrame;
11
12 public class TestBezierCurve extends Applet {
     public static void main(String[] args) {
13
14
       new MainFrame(new TestBezierCurve(), 640, 480);
15
    }
16
17
    public void init() {
18
       // create canvas
19
       GraphicsConfiguration gc =
20
       SimpleUniverse.getPreferredConfiguration();
21
       Canvas3D cv = new Canvas3D(qc);
22
       setLayout(new BorderLayout());
23
       add(cv, BorderLayout.CENTER);
24
       BranchGroup bg = createSceneGraph();
25
       bg.compile();
       SimpleUniverse su = new SimpleUniverse(cv);
26
27
       su.getViewingPlatform().setNominalViewingTransform();
28
       su.addBranchGraph(bg);
29
    }
30
31
     private BranchGroup createSceneGraph() {
32
       BranchGroup root = new BranchGroup();
[Page 383]33
              TransformGroup spin = new TransformGroup();
34
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
35
       root.addChild(spin);
36
      JNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
37
       Point3d p1 = new Point3d(-0.2,0.6,-0.2);
38
39
       Point3d p2 = new Point3d(0.3,-0.8,0.3);
40
       Point3d p3 = new Point3d(0.9,0.1,0.6);
41
       Appearance ap = new Appearance();
42
       ap.setColoringAttributes(new ColoringAttributes(Of, Of, Of,
43
         ColoringAttributes.FASTEST));
44
       Shape3D shape = new Shape3D(new
45
       BezierCurve(p0,p1,p2,p3), ap);
46
       spin.addChild(shape);
47
       // rotation interpolator
48
       Alpha alpha = new Alpha(-1, 10000);
49
       RotationInterpolator rotator =
50
       new RotationInterpolator(alpha, spin);
51
       BoundingSphere bounds = new BoundingSphere();
52
       rotator.setSchedulingBounds(bounds);
       spin.addChild(rotator);
53
54
       // background
55
       Background background = new Background(1f, 1f, 1f);
56
       background.setApplicationBounds(bounds);
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       NOR ECCIPS TO ESP
57
58
59
     }
```

chapter12.TestBezierCurve

Figure 12.2. A cubic Bézier curve.

A Bézier curve is implemented in the class BezierCurve as a LineStripArray. The deCasteljau algorithm-based subdivision technique is applied recursively to break the curve into small segments. The final small Bézier curves are approximated by straight line segments. For simplicity a fixed level of recursion is used and no flatness test is applied to the segments.

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If the depth of recursion is level, the number of line segments is  $2^{level}$  and the number of vertices in the LineStripArray is  $2^{level} + 1$ . The constructor of BezierCurve adds the first point to the array and calls the method subdivide (line 22) to start the subdivision.

The method subdivide is recursive. It divides a Bézier curve into two at t = 0.5 and calls itself for the two subdivided curves. When the recursion level reaches the specified value (4 in this example), the subdivision stops and the second endpoint is added to the array.

The test program TestBezierCurve displays an instance of the Bézier curve and rotates it with a rotation interpolator.

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#### 12.3. Surfaces

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#### 12.3.1. Bézier Surface

A Bézier surface is formed by extending a Bézier curve to a surface along another Bézier curve using a method called tensor product. The parametric equation of a general Bézier surface is given by

$$S(u, v) = \sum_{i=0}^{m} \sum_{j=0}^{n} p_{i,j} B_{m,i}(u) B_{n,j}(v)$$

The most commonly used type of Bézier surface is the bicubic surface with m = n = 3, which is defined by 16 control points.

The *evaluation* of a point S(u, v) on a Bézier surface can also be obtained from the deCasteljau algorithm. A Bézier surface may be viewed as a family of Bézier curves. For a fixed u, the curve s(v) = S(u, v) is a Bézier curve with control points:

$$p_j = \sum_{i=0}^{3} p_{i,j} B_{3,i}(u), \qquad j = 0, 1, 2, 3$$

The four control points are themselves points on another Bézier curve. Consequently, these points can be calculated through four applications of the deCasteljau algorithm with t = u. After obtaining the four control points for the Bézier curve, we can calculate the point s(v) = S(u, v) from another application of deCasteljau algorithm with t = v on the curve.

A bicubic Bézier surface is implemented in Listing 12.3. A test program (Listing 12.4) displays a randomly generated Bézier surface. (See Figure 12.3.)

Listing 12.3. BezierSurface.java

(This item is displayed on pages 384 - 385 in the print version)

```
1 package chapter12;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.geometry.*;
8
9 public class BezierSurface extends Shape3D{
   public BezierSurface(Point3d[][] ctrlPts) {
10
11
      int m = 17;
12
      int n = 17;
13
      Point3d[] pts = new Point3d[m*n];
14
      int idx = 0;
15
      Point3d[] p = new Point3d[4];
16
       double du = 1.0/(m-1);
```

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```
[Page 385]17
              double dv = 1.0/(n-1);
18
       double u = 0;
19
       double v = 0;
20
       for (int i = 0; i < m; i++) {
         for (int k = 0; k < 4; k++) {
21
22
           p[k] = deCasteljau(u, ctrlPts[k]);
23
         }
         v = 0;
24
25
         for (int j = 0; j < n; j++) {</pre>
           pts[idx++] = deCasteljau(v, p);
26
27
           v += dvi
28
         }
29
         u += du;
30
       }
31
32
       int[] coords = new int[2*n*(m-1)];
33
       idx = 0;
34
       for (int i = 1; i < m; i++) {
         for (int j = 0; j < n; j++) {
35
36
           coords[idx++] = i*n + j;
           coords[idx++] = (i-1)*n + j;
37
38
         }
39
       }
40
41
       int[] stripCounts = new int[m-1];
42
       for (int i = 0; i < m-1; i++) stripCounts[i] = 2*n;</pre>
43
44
       GeometryInfo gi =
45
       new GeometryInfo(GeometryInfo.TRIANGLE_STRIP_ARRAY);
46
       gi.setCoordinates(pts);
47
       gi.setCoordinateIndices(coords);
48
       gi.setStripCounts(stripCounts);
49
50
       NormalGenerator ng = new NormalGenerator();
51
       ng.generateNormals(gi);
52
       this.setGeometry(gi.getGeometryArray());
                       ERED VERSION OF CHM TO PDF CONVERTER PRO
53
     UNREGIST
54
55
     Point3d deCasteljau(double t, Point3d[] p) {
56
      Point3d[] pt = \{new Point3d(p[0]),
57
       new Point3d(p[1]),new Point3d(p[2]), new Point3d(p[3])};
58
       for (int i = 0; i < 3; i++) {
59
         for (int j = 0; j < 3-i; j++) {
60
           pt[j].interpolate(pt[j+1], t);
61
         }
62
       }
63
       return pt[0];
64
    }
65 }
```



1 package chapter12;

2

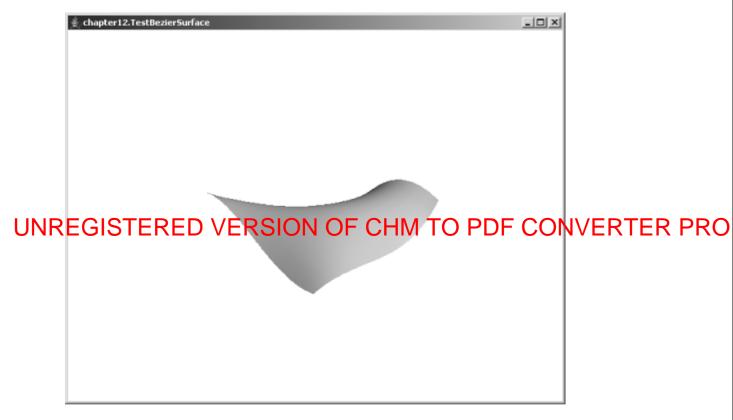
(This item is displayed on pages 385 - 387 in the print version)

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```
3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
[Page 386] 8 import com.sun.j3d.utils.geometry.*;
9 import java.applet.*;
10 import com.sun.j3d.utils.applet.MainFrame;
11
12 public class TestBezierSurface extends Applet {
    public static void main(String[] args) {
13
14
      new MainFrame(new TestBezierSurface(), 640, 480);
15
    }
16
   public void init() {
17
18
      // create canvas
19
       GraphicsConfiguration gc =
20
          SimpleUniverse.getPreferredConfiguration();
21
      Canvas3D cv = new Canvas3D(gc);
22
      setLayout(new BorderLayout());
23
      add(cv, BorderLayout.CENTER);
24
      BranchGroup bg = createSceneGraph();
25
     bg.compile();
      SimpleUniverse su = new SimpleUniverse(cv);
26
27
       su.getViewingPlatform().setNominalViewingTransform();
28
       su.addBranchGraph(bg);
29
    }
30
31
   private BranchGroup createSceneGraph() {
32
     BranchGroup root = new BranchGroup();
33
      TransformGroup spin = new TransformGroup();
34
       spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
35
      root.addChild(spin);
36
      // surface
37
      Point3d[][] ctrlPts = new Point3d[4][4];
38
       for (int i = 0; i < 4; i++) {
39
         for (int j = 0; j < 4; j++) {
40
            ctrlPts[i][j] = new Point3d(2-i, 3*(Math.random()-0.5), j-2);
41
         }
42
       }
43
       Shape3D shape = new BezierSurface(ctrlPts);
44
       Appearance ap = new Appearance();
45
       ap.setMaterial(new Material());
46
       shape.setAppearance(ap);
47
       Transform3D tr = new Transform3D();
48
       tr.setScale(0.25);
49
       TransformGroup tg = new TransformGroup(tr);
50
       spin.addChild(tg);
51
       tg.addChild(shape);
52
       // rotation interpolator
53
       Alpha alpha = new Alpha(-1, 10000);
       RotationInterpolator rotator =
54
       new RotationInterpolator(alpha, spin);
55
56
       BoundingSphere bounds = new BoundingSphere();
57
       rotator.setSchedulingBounds(bounds);
58
       spin.addChild(rotator);
59
       // background and lights
60
       Background background = new Background(1f, 1f, 1f);
61
       background.setApplicationBounds(bounds);
```

```
62
       root.addChild(background);
63
       AmbientLight light = new AmbientLight(true,
       new Color3f(Color.red));
64
65
       light.setInfluencingBounds(bounds);
66
       root.addChild(light);
67
       PointLight ptlight = new PointLight
                 (new Color3f(Color.lightGray),
[Page 387]68
         new Point3f(1f,1f,1f), new Point3f(1f,0f,0f));
69
70
       ptlight.setInfluencingBounds(bounds);
71
       root.addChild(ptlight);
72
       return root;
73
    }
74 }
```

Figure 12.3. A bicubic Bézier surface.



The BezierSurface class encapsulates a bicubic Bézier surface. It is implemented by calculating  $m \times n$  points on the surface and forming a polygon mesh. The calculations of the points on the surface are based on the deCasteljau approach. The 16 control points of the Bézier surface are given in the 2D array parameter ctrlPts. To calculate the point with parameter value (u, v), four Bézier curves defined by the four sets of control points ctrlPts NREG State Prevented for the Bézier curve which is evaluated at v. The resulting point of this evaluation is the point on the Bézier surface at (u, v). The deCasteljau method (line 55) evaluates a point on a Bézier curve from the given parameter value and four control points. The linear interpolations required by the deCasteljau algorithm are carried out by simply calling the existing method interpolate in Point3d (line 60).

The calculated points on the surface are placed in a GeometryInfo object as vertices. The GeometryInfo object is created in the TRIANGLE\_STRIP\_ARRAY mode. The surface normals are generated automatically using a NormalGenerator object.

The test program in the class TestBezierSurface creates 16 control points based on randomly generated numbers. The BezierSurface class is used to generate the shape of the visual object. Lighting is enabled. Two lights are placed in the scene. A rotation interpolator is used to rotate the surface.

[Page 388]

#### 12.3.2. The Utah Teapot

One of the most famous objects in computer graphics is the "Utah teapot." It is defined by a set of Bézier surface patches. We may use the Bézier surface class to display the teapot, as illustrated in Listing 12.5. (See Figure 12.4.)

Listing 12.5. Teapot.java

(This item is displayed on pages 388 - 390 in the print version)

```
1 package chapter12;
2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
 9 import java.applet.*;
10 import com.sun.j3d.utils.applet.MainFrame;
11 import java.net.URL;
12 import java.io.*;
13 import java.util.StringTokenizer;
14
15 public class Teapot extends Applet {
16
   public static void main(String[] args) {
17
       new MainFrame(new Teapot(), 640, 480);
18
   }
19
20
    public void init() {
21
       // create canvas
2.2
       GraphicsConfiguration gc =
23
         SimpleUniverse.getPreferredConfiguration();
24
       Canvas3D cv = new Canvas3D(gc);
25
       setLayout(new BorderLayout());
26
       add(cv, BorderLayout.CENTER);
27
       BranchGroup bg = createSceneGraph();
28
       bg.compile();
29
       SimpleUniverse su = new SimpleUniverse(cv);
30
        su.getViewingPlatform().setNominalViewingTransform();
31
       su.addBranchGraph(bg);
32
    }
33
34
    private BranchGroup createSceneGraph() {
35
       BranchGroup root = new BranchGroup();
```

```
36
        TransformGroup spin = new TransformGroup();
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 37
       root.addChild(spin);
 38
 39
       // teapot data
 40
       int n = 0;
 41
       int[][] idx = null;
 42
       int np = 0;
       Point3d[] pts = null;
 43
 44
       URL url =
 45
         getClass().getClassLoader().getResource("images/teapot");
 46
       try {
 47
         BufferedReader br = new BufferedReader
 48
          (new InputStreamReader(url.openStream()));
 49
         String line = br.readLine();
 50
          n = Integer.parseInt(line);
 51
         idx = new int[n][16];
52
         for (int i = 0; i < n; i++) {
[Page 389] 53
                     line = br.readLine();
54
              StringTokenizer st = new StringTokenizer(line, ", \n");
 55
             for (int j = 0; j < 16; j++) {
 56
                  idx[i][j] = Integer.parseInt(st.nextToken());
 57
             }
         }
 58
         line = br.readLine();
 59
 60
         np = Integer.parseInt(line);
         pts = new Point3d[np];
 61
         for (int i = 0; i < np; i++) {</pre>
 62
             line = br.readLine();
 63
 64
              StringTokenizer st = new StringTokenizer(line, ", \n");
 65
              double x = Double.parseDouble(st.nextToken());
 66
              double y = Double.parseDouble(st.nextToken());
 67
              double z = Double.parseDouble(st.nextToken());
 68
             pts[i] = new Point3d(x, y, z);
 69
         }
 70
         br.close();
 71
        } catch (IOException ex) {
            EGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 72
 73
 74
 75
       // surface
 76
       Appearance ap = new Appearance();
 77
        ap.setMaterial(new Material());
 78
       Transform3D tr = new Transform3D();
 79
       tr.rotX(-Math.PI*0.5);
       tr.setScale(0.25);
 80
 81
        tr.setTranslation(new Vector3d(0,-0.5,0));
       TransformGroup tg = new TransformGroup(tr);
 82
 83
       spin.addChild(tg);
 84
       Point3d[][] ctrlPts = new Point3d[4][4];
 85
       for (int k = 0; k < n; k++) {
 86
         for (int i = 0; i < 4; i++) {
 87
           for (int j = 0; j < 4; j++) {
 88
              ctrlPts[i][j] = pts[idx[k][i+4*j]-1];
 89
           }
 90
         }
 91
          Shape3D shape = new BezierSurface(ctrlPts);
 92
          shape setAppearance
        REGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 93
 94
       }
```



Figure 12.4. The Utah Teapot.



The teapot data, consisting of the coordinates and indices of the control points, is stored in a text file "teapot." The program reads the data and constructs the patches using the BezierSurface class.

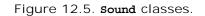
◀ Previous

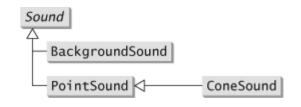
Next ▶

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#### 12.4. Sound

Sound has become an important component of modern multimedia applications. Even though it is not graphical in nature, sound is often associated with graphics in applications such as games. Java 3D provides support for incorporating sound in scene graphs with the Sound class and its subclasses. The Sound classes are Leaf nodes. The class hierarchy of Sound is given in Figure 12.5.







The Sound classes are similar to Light classes. The BackgroundSound, like AmbientLight, is distributed uniformly in the space. The PointSound has a specific location and may have attenuation, similar to the PointLight class. The ConeSound restricts the effects of the sound to a cone-shaped region, similar to a SpotLight.

To *add sound* to a Java 3D program, the following steps are usually required:

• Create an AudioDevice. If a SimpleUniverse object is used for the scene graph, a convenient way to do this is to simply call the method createAudioDevice() in the Viewer:

```
su.getViewer().createAudioDevice();
```

• Create a MediaContainer object to hold sound data. For example,

```
MediaContainer mc = new MediaContainer(url);
```

• Create a sound object with the sound data and add it to the scene graph. For example,

```
BackgroundSound sound = new BackgroundSound();
sound.setSoundData(mc);
sound.setSchedulingBounds(bounds);
root.addChild(sound);
```

A scheduling bound is required for a sound node, similar to other environmental nodes.

Listing 12.6 illustrates the application of sounds in Java 3D. This example shows a gull on a sky background (Figure 12.6). The gull can be rotated, translated, and zoomed by mouse operations. A sound of a bird originated from the location of the gull plays continuously. If the bird is moved to the left side, the sound also comes from the left. If the bird is moved farther away, the volume of the sound decreases.

Listing 12.6. Sound3D.java

(This item is displayed on pages 391 - 393 in the print version)

```
1 package chapter12;
 2
 3 import java.net.URL;
  4 import java.awt.*;
  5 import java.awt.event.*;
  6 import java.awt.image.*;
  7 import com.sun.j3d.utils.universe.*;
  8 import javax.media.j3d.*;
 9 import javax.vecmath.*;
10 import java.io.*;
 11 import javax.imageio.*;
 12 import com.sun.j3d.utils.behaviors.mouse.*;
13 import chapter10.GullCG;
14 import java.applet.*;
15 import com.sun.j3d.utils.applet.MainFrame;
16
17 public class Sound3D extends Applet {
18
     public static void main(String[] args) {
19
       new MainFrame(new Sound3D(), 640, 480);
 20
     }
21
 22
     public void init() {
       // create canvas
23
 24
       GraphicsConfiguration gc =
 25
          SimpleUniverse.getPreferredConfiguration();
       Canvas3D cv = new Canvas3D(gc);
26
[Page 392] 27
              setLayout(new BorderLayout());
 28
       add(cv, BorderLayout.CENTER);
 29
        SimpleUniverse su = new SimpleUniverse(cv);
        AudioDevice audioDev = su.getViewer().createAudioDevice();
30
31
       BranchGroup bg = createSceneGraph();
32
       bq.compile();
 33
        su.getViewingPlatform().setNominalViewingTransform();
34
        su.addBranchGraph(bg);
35
     }
    UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
36
 37
 38
        // root
 39
        BranchGroup objRoot = new BranchGroup();
 40
       Transform3D trans = new Transform3D();
 41
        trans.setTranslation(new Vector3d(Math.random()-0.5,
 42
         Math.random()-0.5, Math.random()-0.5));
 43
         trans.setScale(0.3);
 44
        TransformGroup objTrans = new TransformGroup(trans);
 45
        objTrans.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 46
        objTrans.setCapability(TransformGroup.ALLOW_TRANSFORM_READ);
 47
        objRoot.addChild(objTrans);
 48
       // visual object
 49
       Appearance ap = new Appearance();
        ap.setMaterial(new Material());
 50
       Shape3D shape = new Shape3D(new GullCG(), ap);
 51
52
       objTrans.addChild(shape);
53
       // behaviors
54
       BoundingSphere bounds =
         new BoundingSphere(new Point3d(0.0,0.0,0.0), 100.0);
55
56
        // rotation
     JNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 57
 58
 59
        objRoot.addChild(rotator);
```

```
60
        // translation
 61
        MouseTranslate translator = new MouseTranslate(objTrans);
 62
        translator.setSchedulingBounds(bounds);
        objTrans.addChild(translator);
 63
 64
        // zoom
 65
        MouseZoom zoom = new MouseZoom(objTrans);
 66
        zoom.setSchedulingBounds(bounds);
        objTrans.addChild(zoom);
 67
        // sound
 68
 69
        PointSound sound = new PointSound();
 70
        URL url =
 71
           this.getClass().getClassLoader().getResource("images/bird.au");
 72
        MediaContainer mc = new MediaContainer(url);
 73
        sound.setSoundData(mc);
 74
        sound.setLoop(Sound.INFINITE_LOOPS);
 75
        sound.setInitialGain(1f);
 76
        sound.setEnable(true);
 77
        float[] distances = {1f, 20f};
        float[] gains = {1f, 0.001f};
 78
 79
        sound.setDistanceGain(distances, gains);
 80
        BoundingSphere soundBounds =
        new BoundingSphere(new Point3d(0.0,0.0,0.0), 100.0);
 81
        sound.setSchedulingBounds(soundBounds);
 82
 83
        objTrans.addChild(sound);
 84
        // light
 85
        AmbientLight light =
[Page 393] 86
                  new AmbientLight(true, new Color3f(Color.blue));
 87
        light.setInfluencingBounds(bounds);
 88
        objRoot.addChild(light);
 89
        PointLight ptlight = new PointLight(new Color3f(Color.white),
 90
          new Point3f(0f,0f,2f), new Point3f(1f,0.3f,0f));
 91
        ptlight.setInfluencingBounds(bounds);
 92
        objRoot.addChild(ptlight);
 93
        // background
 94
        url = getClass().getClassLoader().getResource("images/bg.jpg");
 95
        BufferedImage bi = null;
 96
        try {
 97
        bi = ImageIO.read(url);
 98
        } catch (IOException ex) {
 99
          ex.printStackTrace();
100
        }
101
        ImageComponent2D image =
102
           new ImageComponent2D(ImageComponent2D.FORMAT_RGB, bi);
103
        Background background = new Background(image);
104
        background.setApplicationBounds(bounds);
105
        objRoot.addChild(background);
106
        return objRoot;
107
      }
108 }
```

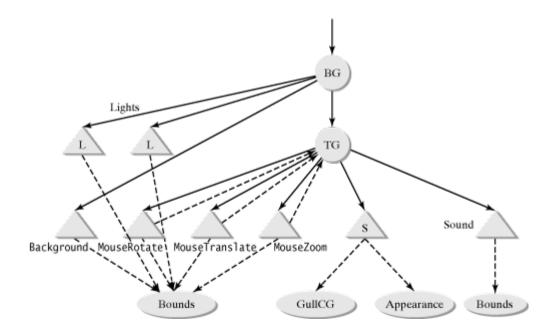
Figure 12.6. A point sound associated with the bird.



The scene graph in Figure 12.7 shows the incorporation of a sound node. The sound node is under the same transform as the gull shape node. Three mouse behaviors operate on the transform. When the user moves the visual object through mouse operations, the sound node is also moved accordingly.

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Figure 12.7. Scene graph for the sound example.



The sound node is an instance of PointSound with a distance attenuation (line 69). Two distance values with the corresponding gain values are specified. The gains will decrease from 1 to 0.001 as the distances increase from 1 to 20.

◀ Previous

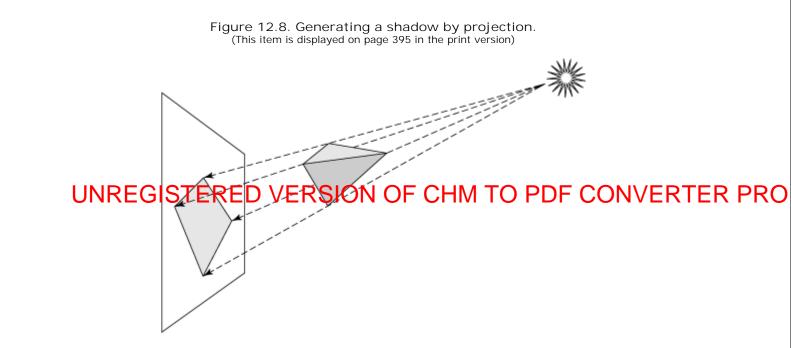
Next 🕨

#### 12.5. Shadows

As a real-time graphics API, Java 3D provides only local illumination options. Objects are rendered individually without considering the influences and interactions between them. For example, the light reflected off an object will not influence other objects. If one object is located between a light and another object, partially blocking the light, the effects will not be shown in the rendering. Consequently, shadows are not automatically generated with local illumination models.

Generating realistic shadows in a scene can be a very complex task. Multiple light sources, relations among different visual objects, and characteristics of lights and objects are all factors in this problem. A global illumination model may be applied to obtain good shadow effects, but the global techniques are computationally intensive and usually impractical for real-time rendering. In this section a method to create simple *artificial shadows* is introduced. It uses a polygon to approximate a shadow. The approach is quite efficient, but it has many limitations.

The shadow is assumed to be cast on a plane. Only a single point light is considered. The vertices of the polygon are calculated by projecting the vertices of the object to the plane from the position of the point light. Figure 12.8 illustrates the construction of the shadow polygon.



The transformation is a projection similar to the one in a view. The light position corresponds to the viewer. The only difference is that this projection indeed maps all points to the plane, and the depth information is not retained. When the projection is in a standard form that the light is located at the origin and the plane is x = -d', the transformation matrix for the projection is:

$$P = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1/d & 0 \end{bmatrix}$$

[Page 395]

For a general configuration of the light position and the shadow plane, an affine transform U may be constructed to map the configuration to a standard form. The method lookAt in the class Transform3D generates such a transform. The final projection can be expressed as:

 $U^1 PU$ 

Using the projection, the vertices of a geometric object are mapped to the projection plane and form the vertices of the shadow polygon.

Listing 12.7 implements the shadow generation. The scene contains a stone wall and a dodecahedron. A point light illuminates the dodecahedron casting a shadow on the wall. (Figure 12.9)

Listing 12.7. Shadow.java

(This item is displayed on pages 395 - 398 in the print version)

```
1 package chapter12;
 2
  3 import javax.vecmath.*;
  4 import java.awt.*;
  5 import java.awt.event.*;
  6 import java.awt.image.*;
 7 import java.net.URL;
 8 import java.io.*;
 9 import javax.imageio.*;
10 import javax.swing.*;
 11 import javax.media.j3d.*;
 12 import com.sun.j3d.utils.universe.*;
 13 import com.sun.j3d.utils.geometry.*;
14 import chapter6.Dodecahedron;
15 import java.applet.*;
 16 import com.sun.j3d.utils.applet.MainFrame;
17
18 public class Shadow extends Applet {
19
      public static void main(String[] args) {
        new MainFrame(new Shadow(), 640, 480);
 20
 21
      }
 22
 23
      public void init() {
 24
        // create canvas
 25
        GraphicsConfiguration gc =
                  SimpleUniverse.getPreferredConfiguration();
[Page 396] 26
 27
        Canvas3D cv = new Canvas3D(qc);
        setLayout(new BorderLayout());
 28
 29
        add(cv, BorderLayout.CENTER);
 30
        BranchGroup bg = createSceneGraph();
 31
        bg.compile();
 32
        SimpleUniverse su = new SimpleUniverse(cv);
```

```
33
        su.getViewingPlatform().setNominalViewingTransform();
 34
        su.addBranchGraph(bg);
35
     }
36
37
     private BranchGroup createSceneGraph() {
       BranchGroup root = new BranchGroup();
38
39
        // object
 40
       Appearance ap = new Appearance();
 41
        ap.setMaterial(new Material());
 42
       Shape3D shape = new Dodecahedron();
 43
        shape.setAppearance(ap);
 44
        GeometryArray geom = (GeometryArray)shape.getGeometry();
 45
       // transform
 46
       Transform3D tr = new Transform3D();
 47
       tr.rotY(-0.2);
 48
       tr.setScale(0.2);
 49
       TransformGroup tg = new TransformGroup(tr);
 50
       root.addChild(tg);
 51
       tg.addChild(shape);
52
       BoundingSphere bounds =
 53
       new BoundingSphere(new Point3d(0,0,0),100);
54
       // light and background
        Background background = new Background(1.0f, 1.0f, 1.0f);
 55
 56
        background.setApplicationBounds(bounds);
57
       root.addChild(background);
58
       AmbientLight light =
59
          new AmbientLight(true, new Color3f(Color.red));
        light.setInfluencingBounds(bounds);
 60
        root.addChild(light);
 61
 62
        Point3f lightPos = new Point3f(10f,3f,1f);
 63
        PointLight ptlight = new PointLight(new Color3f(Color.green),
 64
        lightPos, new Point3f(1f,0f,0f));
 65
        ptlight.setInfluencingBounds(bounds);
 66
        tg.addChild(ptlight);
 67
        // wall
 68
        Shape3D wall = createWall();
    UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 69
 70
          shadow
        GeometryArray shadow = createShadow(geom,
 71
 72
         lightPos, new Point3f(-2f, 3f, 1f));
73
       ap = new Appearance();
74
       ColoringAttributes colorAttr =
         new ColoringAttributes(0.1f, 0.1f, 0.1f,
75
          ColoringAttributes.FASTEST);
 76
 77
        ap.setColoringAttributes(colorAttr);
 78
        TransparencyAttributes transAttr = new TransparencyAttributes(
 79
          TransparencyAttributes.BLENDED,0.35f);
 80
        ap.setTransparencyAttributes(transAttr);
 81
        PolygonAttributes polyAttr = new PolygonAttributes();
 82
        polyAttr.setCullFace(PolygonAttributes.CULL_NONE);
 83
        ap.setPolygonAttributes(polyAttr);
84
        shape = new Shape3D(shadow, ap);
85
       tq.addChild(shape);
[Page 397] 86
              return root;
87
     }
88
 89
           EGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 90
 91
          getClass().getClassLoader().getResource("images/stone.jpg");
```

```
92
        BufferedImage bi = null;
 93
        try {
 94
         bi = ImageIO.read(url);
 95
        } catch (IOException ex) {
 96
         ex.printStackTrace();
 97
        }
 98
        ImageComponent2D image =
99
         new ImageComponent2D(ImageComponent2D.FORMAT_RGB, bi);
100
        Texture2D texture =
101
         new Texture2D(Texture.BASE_LEVEL, Texture.RGBA,
102
          image.getWidth(), image.getHeight());
        texture.setImage(0, image);
103
104
        texture.setEnable(true);
105
        texture.setMagFilter(Texture.BASE_LEVEL_LINEAR);
106
        texture.setMinFilter(Texture.BASE_LEVEL_LINEAR);
107
        Appearance appear = new Appearance();
108
        appear.setTexture(texture);
109
        QuadArray rect = new QuadArray(4, QuadArray.COORDINATES |
110
          QuadArray.TEXTURE_COORDINATE_2);
111
        rect.setCoordinate(0, new Point3d(-2,3,2));
        rect.setCoordinate(1, new Point3d(-2,-3,2));
112
        rect.setCoordinate(2, new Point3d(-2,-3,-3));
113
        rect.setCoordinate(3, new Point3d(-2,3,-3));
114
        rect.setTextureCoordinate(0,0, new TexCoord2f(0f, 0f));
115
116
        rect.setTextureCoordinate(0,1, new TexCoord2f(0f, 1f));
117
        rect.setTextureCoordinate(0,2, new TexCoord2f(1f, 1f));
118
        rect.setTextureCoordinate(0,3, new TexCoord2f(1f, 0f));
119
        return new Shape3D(rect, appear);
120
    }
121
122
    private GeometryArray createShadow(GeometryArray ga, Point3f light,
123
      Point3f plane) {
124
        GeometryInfo gi = new GeometryInfo(ga);
125
        gi.convertToIndexedTriangles();
126
       IndexedTriangleArray ita =
127
          (IndexedTriangleArray)gi.getIndexedGeometryArray();
128
        Vector3f v = new Vector3f();
129
        v.sub(plane, light);
130
        double[] mat = new double[16];
131
        for (int i = 0; i < 16; i++) {
        mat[i] = 0;
132
133
        }
134
       mat[0] = 1;
135
       mat[5] = 1;
136
        mat[10] = 1-0.001;
137
        mat[14] = -1/v.length();
138
        Transform3D proj = new Transform3D();
139
        proj.set(mat);
140
        Transform3D u = new Transform3D();
141
        u.lookAt(new Point3d(light),
142
        new Point3d(plane), new Vector3d(0,1,0));
143
        proj.mul(u);
144
        Transform3D tr = new Transform3D();
145
        u.invert();
[Page 398]146
              tr.mul(u, proj);
147
        int n = ita.getVertexCount();
148
        int count = ita.getIndexCount();
149
        IndexedTriangleArray shadow = new IndexedTriangleArray(n,
150
          GeometryArray.COORDINATES, count);
```

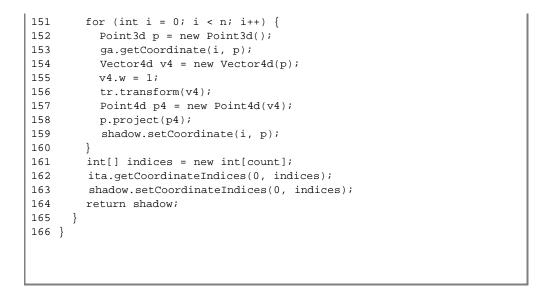
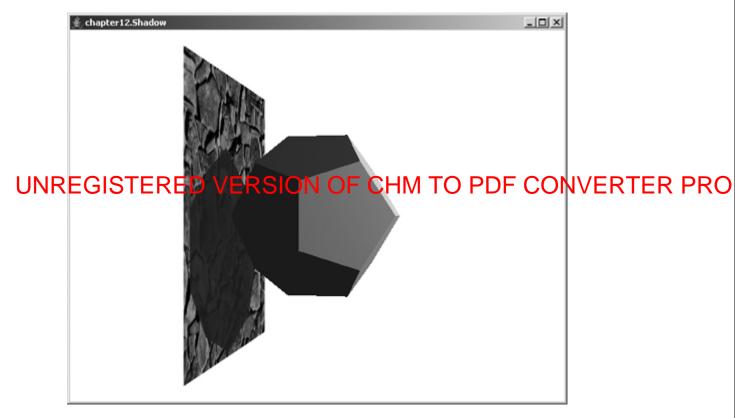
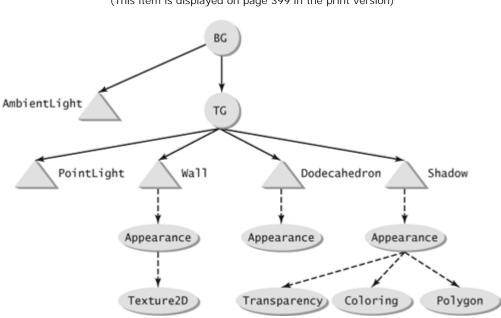


Figure 12.9. A shadow on the wall created with a polygon from the projection of the object.



The scene graph is shown in Figure 12.10. It contains a texture-mapped rectangle as the wall, a dodecahedron, and the snadow of the point and the snadow of the point ight. An oper clipton of the point light.



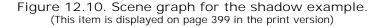
The method createShadow (line 123) performs the necessary computations to create a shadow polygon from the projections of the vertices of the original object. The projection matrix is constructed by the matrix for the standard projection and the transform to the standard position. The transform to the standard position is formed using the method lookAt. The projection is actually done slightly above the plane in order to avoid interference between the shadow and the wall object.

[Page 399]

The shadow polygon has a gray color. It is set by a ColoringAttributes object. The polygon is also semitransparent to show some wall details under the shadow. The TransparencyAttributes object sets the transparency of the shadow polygon (lines 73–83).

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Next ▶



[Page 399 (continued)]

## 12.6. Geometry Change

The animation and behavior objects introduced in Chapter 10 and Chapter 11 do not modify the geometry data in a live scene graph. The Morph object combines several geometry objects, but it modifies only the weights of the combination. In some circumstances, it is useful to able to modify the actual geometry data in a live scene graph. For example, the artificial shadow example introduced in the preceding section works only for static objects. If the dodecahedron moves relative to the wall or the light, the correct shadow polygon should change accordingly. This requires vertices of the polygon be recalculated. Simply placing the shadow polygon under the same transform group as the dodecahedron will not produce the correct result, because the polygon is formed through a projection.

Java 3D provides a mechanism for modifying a live geometry through the GeometryUpdater interface and the BY\_REFERENCE mode of GeometryArray. A GeometryArray by default maintains a copy of the data, such as vertex coordinates. If a GeometryArray is created with the BY\_REFERENCE flag set in the constructor, it will hold only the references to user-provided data. For example, the following code fragment creates a by-reference geometry for a triangle:

The array coords contains the vertex coordinates for the geometry and is referenced by the TriangleArray object. Even though you supply the data buffer for the by-reference geometry, you still should not directly modify the contents in a live scene graph. The proper way to make a change is to implement the GeometryUpdater interface. The interface defines one method you need to implement to update the geometry:

[Page 400]

The path of the system. You may call the method in the GeometryArray with the same name to invoke the update:

public void updateData(GeometryUpdater updater)

public void updateData(Geometry geometry)

You need to pass an instance of your custom GeometryUpdater class as the parameter.

In summary, to modify a geometry from a behavior, you may use the following procedure:

- Create the geometry with BY\_REFERENCE.
- Write a class implementing the GeometryUpdater interface. Implement the method updateData(Geometry) in GeometryUpdater to perform the modifications on the geometry.
- Implement a Behavior class. At appropriate moments, call the method updateData(GeometryUpdater) in GeometryArray to trigger the update.

Listing 12.8 shows an application of live geometry change. The program creates a scene similar to Listing 12.7. However Nector and the contraction of the contraction of the contraction of the dodecahedron. Listing 12.8. MovingShadow.java

(This item is displayed on pages 400 - 404 in the print version)

```
1 package chapter12;
 2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import java.awt.image.*;
 7 import java.net.URL;
 8 import java.io.*;
 9 import javax.imageio.*;
10 import javax.swing.*;
11 import javax.media.j3d.*;
12 import com.sun.j3d.utils.universe.*;
13 import com.sun.j3d.utils.geometry.*;
14 import chapter6.Dodecahedron;
15 import java.applet.*;
16 import com.sun.j3d.utils.applet.MainFrame;
17
18 public class MovingShadow extends Applet {
19 public static void main(String[] args) {
20
      new MainFrame(new MovingShadow(), 640, 480);
21
    }
22
23 private TransformGroup spin = null;
 24 private Transform3D shadowProj = null;
25 private GeometryArray geom = null;
 26 private GeometryArray shadowGeom = null;
 27
    private ShadowUpdater updater = null;
28
    public void init() {
 29
30
     // create canvas
[Page 401] 31
            GraphicsConfiguration gc =
32
         SimpleUniverse.getPreferredConfiguration();
 33
       Canvas3D cv = new Canvas3D(qc);
 34
       setLayout(new BorderLayout());
 35
       add(cv, BorderLayout.CENTER);
       updater = new MovingShadow.ShadowUpdater();
 36
 37
       BranchGroup bg = createSceneGraph();
 38
       bg.compile();
       SimpleUniverse su = new SimpleUniverse(cv);
 39
 40
        su.getViewingPlatform().setNominalViewingTransform();
 41
        su.addBranchGraph(bg);
 42
    }
43
 44
    private BranchGroup createSceneGraph() {
 45
       BranchGroup root = new BranchGroup();
 46
       // object
 47
       Appearance ap = new Appearance();
 48
        ap.setMaterial(new Material());
 49
       Shape3D shape = new Dodecahedron();
50
       shape.setAppearance(ap);
      geom = (GeometryArray)shape.getGeometry();
51
 52
        geom.setCapability(GeometryArray.ALLOW_COORDINATE_READ);
53
       // transform
54
       Transform3D tr = new Transform3D();
55
       tr.rotY(-0.2);
56
       tr.setScale(0.2);
```

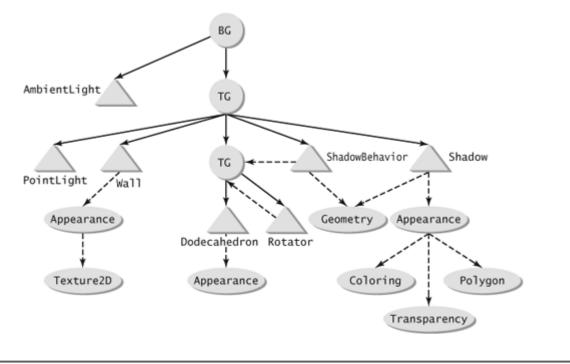
```
57
        TransformGroup tg = new TransformGroup(tr);
 58
        root.addChild(tg);
 59
        spin = new TransformGroup();
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_READ);
 60
 61
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 62
        tq.addChild(spin);
        spin.addChild(shape);
 63
        // rotator
 64
 65
        Alpha alpha = new Alpha(-1, 8000);
 66
        RotationInterpolator rotator =
 67
        new RotationInterpolator(alpha, spin);
        BoundingSphere bounds = new BoundingSphere();
 68
        rotator.setSchedulingBounds(bounds);
 69
 70
        spin.addChild(rotator);
 71
        // light and background
 72
        Background background = new Background(1.0f, 1.0f, 1.0f);
 73
        background.setApplicationBounds(bounds);
 74
        root.addChild(background);
 75
        AmbientLight light =
 76
        new AmbientLight(true, new Color3f(Color.red));
 77
        light.setInfluencingBounds(bounds);
 78
        root.addChild(light);
        Point3f lightPos = new Point3f(10f,3f,1f);
 79
        PointLight ptlight = new PointLight(new Color3f(Color.green),
 80
 81
        lightPos, new Point3f(1f,0f,0f));
 82
        ptlight.setInfluencingBounds(bounds);
        tg.addChild(ptlight);
 83
 84
        // wall
 85
        Shape3D wall = createWall();
 86
        tg.addChild(wall);
 87
        // shadow
 88
        shadowGeom =
 89
          createShadow(geom, lightPos, new Point3f(-2f, 3f, 1f));
 90
        ap = new Appearance();
[Page 402] 91
               ColoringAttributes colorAttr =
 92
        new ColoringAttributes(0.1f, 0.1f, 0.1f,
     UNRECISTERED EVERSION OF CHM TO PDF CONVERTER PRO
 93
 94
        TransparencyAttributes transAttr = new TransparencyAttributes(
 95
 96
          TransparencyAttributes.BLENDED,0.35f);
 97
        ap.setTransparencyAttributes(transAttr);
 98
        PolygonAttributes polyAttr = new PolygonAttributes();
 99
        polyAttr.setCullFace(PolygonAttributes.CULL_NONE);
100
        ap.setPolygonAttributes(polyAttr);
101
        shape = new Shape3D(shadowGeom, ap);
102
        tg.addChild(shape);
103
        // shadow update
104
        ShadowBehavior sb = new MovingShadow.ShadowBehavior();
105
        sb.setSchedulingBounds(bounds);
106
        tq.addChild(sb);
107
       return root;
108
      }
109
110
      private Shape3D createWall() {
111
        URL url =
112
           getClass().getClassLoader().getResource("images/stone.jpg");
        REGISTERED VERSION OF CHM TO PDF CONVERTER PRO
113
114
115
          bi = ImageIO.read(url);
```

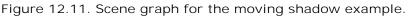
```
116
        } catch (IOException ex) {
117
          ex.printStackTrace();
118
        }
119
        ImageComponent2D image =
120
         new ImageComponent2D(ImageComponent2D.FORMAT_RGB, bi);
121
        Texture2D texture =
          new Texture2D(Texture.BASE_LEVEL, Texture.RGBA,
122
123
          image.getWidth(), image.getHeight());
124
        texture.setImage(0, image);
125
        texture.setEnable(true);
        texture.setMagFilter(Texture.BASE_LEVEL_LINEAR);
126
127
        texture.setMinFilter(Texture.BASE_LEVEL_LINEAR);
128
        Appearance appear = new Appearance();
129
        appear.setTexture(texture);
130
        QuadArray rect = new QuadArray
131
            (4, QuadArray.COORDINATES QuadArray.TEXTURE_COORDINATE_2);
132
        rect.setCoordinate(0, new Point3d(-2,3,2));
133
        rect.setCoordinate(1, new Point3d(-2,-3,2));
134
        rect.setCoordinate(2, new Point3d(-2,-3,-3));
135
        rect.setCoordinate(3, new Point3d(-2,3,-3));
        rect.setTextureCoordinate(0,0, new TexCoord2f(0f, 0f));
136
        rect.setTextureCoordinate(0,1, new TexCoord2f(0f, 1f));
137
        rect.setTextureCoordinate(0,2, new TexCoord2f(1f, 1f));
138
        rect.setTextureCoordinate(0,3, new TexCoord2f(1f, 0f));
139
140
        return new Shape3D(rect, appear);
141
    }
142
143
    private GeometryArray createShadow
144
          (GeometryArray ga, Point3f light, Point3f plane) {
145
        GeometryInfo gi = new GeometryInfo(ga);
146
        gi.convertToIndexedTriangles();
147
        IndexedTriangleArray ita =
148
          (IndexedTriangleArray)gi.getIndexedGeometryArray();
149
        Vector3f v = new Vector3f();
150
        v.sub(plane, light);
[Page 403]151
               double[] mat = new double[16];
152
        for (int i = 0; i < 16; i++) {
153
        mat[i] = 0;
154
        }
155
        mat[0] = 1;
        mat[5] = 1;
156
157
        mat[10] = 1-0.001;
158
        mat[14] = -1/v.length();
159
        Transform3D proj = new Transform3D();
160
        proj.set(mat);
161
        Transform3D u = new Transform3D();
162
        u.lookAt(new Point3d(light),
163
        new Point3d(plane), new Vector3d(0,1,0));
164
        proj.mul(u);
165
        shadowProj = new Transform3D();
166
        u.invert();
167
        shadowProj.mul(u, proj);
168
        int n = ita.getVertexCount();
169
        int count = ita.getIndexCount();
170
        IndexedTriangleArray shadow = new IndexedTriangleArray(n,
171
        GeometryArray.COORDINATES | GeometryArray.BY_REFERENCE, count);
172
        shadow.setCapability(GeometryArray.ALLOW_REF_DATA_READ);
173
        shadow.setCapability(GeometryArray.ALLOW_REF_DATA_WRITE);
174
        double[] vert = new double[3*n];
```

```
175
        Point3d p = new Point3d();
176
        for (int i = 0; i < n; i++) {
177
          ga.getCoordinate(i, p);
178
          Vector4d v4 = new Vector4d(p);
179
         v4.w = 1i
180
          shadowProj.transform(v4);
181
          Point4d p4 = new Point4d(v4);
         p.project(p4);
182
         vert[3*i] = p.x;
183
184
         vert[3*i+1] = p.y;
185
         vert[3*i+2] = p.z;
186
       }
187
        shadow.setCoordRefDouble(vert);
188
        int[] indices = new int[count];
189
        ita.getCoordinateIndices(0, indices);
190
        shadow.setCoordinateIndices(0, indices);
191
        return shadow;
192
     }
193
194
      class ShadowUpdater implements GeometryUpdater {
195
        public void updateData(Geometry geometry) {
196
         double[] vert =
197
            ((GeometryArray)geometry).getCoordRefDouble();
198
          int n = vert.length/3;
199
          Transform3D rot = new Transform3D();
200
          spin.getTransform(rot);
201
          Transform3D tr = new Transform3D(shadowProj);
202
          tr.mul(rot);
203
         Point3d p = new Point3d();
204
         for (int i = 0; i < n; i++) {
205
            geom.getCoordinate(i, p);
206
           Vector4d v4 = new Vector4d(p);
207
           v4.w = 1;
208
            tr.transform(v4);
209
            Point4d p4 = new Point4d(v4);
210
            p.project(p4);
            EGISETERED VERSION OF CHM TO PDF CONVERTER PRO
[Page
212
            vert[3*i+2] = p.z;
213
214
         }
215
        }
216
     }
217
218
      class ShadowBehavior extends Behavior {
219
        WakeupOnElapsedFrames wakeup = null;
220
221
        public ShadowBehavior() {
222
          wakeup = new WakeupOnElapsedFrames(0);
223
        }
224
225
        public void initialize() {
226
         wakeupOn(wakeup);
227
        }
228
229
        public void processStimulus(java.util.Enumeration enumeration) {
230
          shadowGeom.updateData(updater);
231
         IREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
232
233
     }
```

234 }	

The scene graph for the program is shown in Figure 12.11. Compared to Figure 12.10, the scene graph for Listing 12.4, several nodes are added. A TransformGroup and a RotationInterpolator are added on top of the dodecahedron to rotate it in the scene. A behavior node is added to modify the geometry of the shadow.







The shadow polygon is created in the method createShadow (line 143) using the same projection as in Listing 12.4, but the IndexedTriangleArray is now created in the BY\_REFERENCE mode (lines 170–171). The projection is saved in a field shadowProj. A float array vert is created to store the vertex coordinates of the polygon. The geometry of the shadow is saved in the variable shadowGeom, which is defined as a private field of the class.

An inner class ShadowUpdater (line 194) is defined to update the shadow polygon. It implements the GeometryUpdater interface. In the updateData method, the rotation from the transform on top of the dodecahedron is read and combined with shadowProj to form a new projection. This projection is applied to the vertices of the dodecahedron geometry to obtain the vertices of the shadow polygon. An instance of ShadowUpdater is created in the constructor and referenced as the field updater.

A custom Behavior class ShadowBehavior (line 218) is also defined as an inner class. It is set to wakeup at the end of the current frame. The processStimulus method invokes the geometry update by calling the method updateData in shadowGeom with the updater. An instance of ShadowBehavior class is added to the scene graph.

The behavior-driven geometry update makes the dynamic shadow possible. The display of the scene shows a rotating dodecahedron and its shadow on the wall. The shadow changes according to the dodecahedron positions.

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[Page 405 (continued)]

## 12.7. Off-Screen Rendering

In Java 3D the outcome of rendering is sent to Canvas3D objects. Typically a Canvas3D object, as an AWT component, is displayed on a screen. In some cases, however, it may be desirable to perform off-screen rendering. For example, in order to save or print the image of a rendered scene, it will be convenient to render the scene to a memory-based image rather than the screen.

The Canvas3D class supports an off-screen rendering mode. To create an off-screen Canvas3D object, the following constructor may be used with the offScreen parameter set to true:

public Canvas3D(GraphicsConfiguration gc, boolean offScreen)

To render the scene to the off-screen canvas, you need to attach the canvas to the View object:

view.addCanvas3D(canvas)

The following series of method calls of Canvas3D captures an image of the rendered scene:

```
ImageComponent2D buffer =
    new ImageComponent2D(ImageComponent.FORMAT_RGB, bImage);
canvas.setOffScreenBuffer(buffer);
canvas.renderOffScreenBuffer();
canvas.waitForOffScreenRendering();
bImage = offScreenCanvas.getOffScreenBuffer().getImage();
```

Listing 12.9 illustrates off-screen rendering. A rotating dodecahedron is displayed on screen (Figure 12.12). A button labeled "save image" is placed at the bottom of the frame. Clicking the button captures one image and allows the user to save the image to a JPEG file.

[Page 406]

Listing 12.9. OffScreen.java

(This item is displayed on pages 406 - 408 in the print version)

```
1 package chapter12;
2
 3 import javax.vecmath.*;
 4 import java.awt.*;
 5 import java.awt.event.*;
 6 import java.awt.image.*;
 7 import java.net.URL;
8 import java.io.*;
 9 import javax.imageio.*;
10 import javax.swing.*;
11 import javax.media.j3d.*;
12 import com.sun.j3d.utils.universe.*;
13 import com.sun.j3d.utils.geometry.*;
14 import chapter6.Dodecahedron;
15
16 public class OffScreen extends Frame{
17
     public static void main(String[] args) {
```

```
18
       Frame frame = new OffScreen();
        frame.setTitle("Off Screen Rendering");
19
        frame.setSize(640, 480);
 20
21
        frame.setVisible(true);
22
     }
23
     private Canvas3D cv;
24
 25
     private Canvas3D offScreenCanvas;
26
     private View view;
27
     public OffScreen() {
28
       WindowListener l = new WindowAdapter() {
29
30
         public void windowClosing(WindowEvent ev) {
31
           System.exit(0);
32
         }
33
       };
34
       this.addWindowListener(1);
35
       GraphicsConfiguration gc =
        SimpleUniverse.getPreferredConfiguration();
 36
37
       cv = new Canvas3D(gc);
 38
       setLayout(new BorderLayout());
 39
        add(cv, BorderLayout.CENTER);
 40
       BranchGroup bg = createSceneGraph();
 41
       bg.compile();
 42
       SimpleUniverse su = new SimpleUniverse(cv);
        su.getViewingPlatform().setNominalViewingTransform();
 43
 44
        su.addBranchGraph(bg);
 45
       // create off-screen canvas
       view = su.getViewer().getView();
 46
 47
        offScreenCanvas = new Canvas3D(gc, true);
 48
        Screen3D sOn = cv.getScreen3D();
 49
        Screen3D sOff = offScreenCanvas.getScreen3D();
50
       Dimension dim = sOn.getSize();
51
       sOff.setSize(dim);
 52
        sOff.setPhysicalScreenWidth(sOn.getPhysicalScreenWidth());
 53
        sOff.setPhysicalScreenHeight(sOn.getPhysicalScreenHeight());
    UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
54
 55
56
        // button
57
       Button button = new Button("Save image");
58
        add(button, BorderLayout.SOUTH);
[Page 407] 59
               button.addActionListener(new ActionListener() {
60
         public void actionPerformed(ActionEvent ev) {
           BufferedImage bi = capture();
 61
62
           save(bi);
63
         }
64
       });
     }
65
66
 67
     private BranchGroup createSceneGraph() {
 68
       BranchGroup root = new BranchGroup();
 69
        TransformGroup spin = new TransformGroup();
 70
        spin.setCapability(TransformGroup.ALLOW_TRANSFORM_WRITE);
 71
       root.addChild(spin);
 72
       // object
 73
       Appearance ap = new Appearance();
       NREGISTERED ERSION OF CHM TO PDF CONVERTER PRO
 74
 75
 76
        shape.setAppearance(ap);
```

```
77
        Transform3D tr = new Transform3D();
 78
        tr.setScale(0.25);
 79
        TransformGroup tg = new TransformGroup(tr);
 80
        spin.addChild(tg);
 81
        tg.addChild(shape);
 82
        Alpha alpha = new Alpha(-1, 10000);
 83
        RotationInterpolator rotator =
 84
        new RotationInterpolator(alpha, spin);
        BoundingSphere bounds = new BoundingSphere();
 85
 86
        rotator.setSchedulingBounds(bounds);
 87
        spin.addChild(rotator);
 88
        // background and light
 89
        URL url =
 90
           getClass().getClassLoader().getResource("images/bg.jpg");
 91
        BufferedImage bi = null;
 92
        try {
 93
          bi = ImageIO.read(url);
 94
        } catch (IOException ex) {
 95
          ex.printStackTrace();
 96
        }
 97
        ImageComponent2D image =
          new ImageComponent2D(ImageComponent2D.FORMAT_RGB, bi);
 98
 99
        Background background = new Background(image);
100
        background.setApplicationBounds(bounds);
101
        root.addChild(background);
102
        AmbientLight light = new AmbientLight(true,
103
         new Color3f(Color.red));
104
        light.setInfluencingBounds(bounds);
105
        root.addChild(light);
106
        PointLight ptlight = new PointLight(new Color3f(Color.green),
107
          new Point3f(3f,3f,3f), new Point3f(1f,0f,0f));
108
        ptlight.setInfluencingBounds(bounds);
109
        root.addChild(ptlight);
110
        PointLight ptlight2 = new PointLight(new Color3f(Color.orange),
111
          new Point3f(-2f,2f,2f), new Point3f(1f,0f,0f));
112
        ptlight2.setInfluencingBounds(bounds);
113
        root.addChild(ptlight2);
114
        return root;
115
     }
116
      public BufferedImage capture() {
117
118
        // render off-screen image
[Page 408]119
               Dimension dim = cv.getSize();
120
       view.stopView();
121
        view.addCanvas3D(offScreenCanvas);
122
        BufferedImage bImage =
123
          new BufferedImage(dim.width, dim.height,
124
          BufferedImage.TYPE_INT_RGB);
125
        ImageComponent2D buffer =
126
          new ImageComponent2D(ImageComponent.FORMAT_RGB, bImage);
127
           offScreenCanvas.setOffScreenBuffer(buffer);
128
        view.startView();
129
         offScreenCanvas.renderOffScreenBuffer();
130
         offScreenCanvas.waitForOffScreenRendering();
131
        bImage = offScreenCanvas.getOffScreenBuffer().getImage();
132
        view.removeCanvas3D(offScreenCanvas);
133
        return bImage;
134
      }
135
```

```
136
      public void save(BufferedImage bImage) {
137
        // save image to file
138
        JFileChooser chooser = new JFileChooser();
139
        chooser.setCurrentDirectory(new File("."));
140
        if (chooser.showSaveDialog(null) ==
141
        JFileChooser.APPROVE_OPTION) {
          File oFile = chooser.getSelectedFile();
142
143
          try {
144
            ImageIO.write(bImage, "jpeg", oFile);
145
          } catch (IOException ex) {
146
            ex.printStackTrace();
147
148
        }
149
      }
150 }
```

Figure 12.12. Creating an image through off-screen rendering.



[Page 409]

To capture an image from the rendered scene, an off-screen Canvas3D object is created. The off-screen canvas is not attached to the view until the capturing is performed.

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The method capture (line 117) performs the actual capture of the image. First, the view is stopped by calling the method stopView. The off-screen canvas is attached to the view, and an ImageComponent2D object is set as the off-screen buffer for the canvas. Then the view is resumed by calling the method startView. The call to renderOffScreenBuffer method starts the off-screen rendering. The waitForOffScreenRendering method waits for the completion of the rendering. Finally the image is retrieved from the canvas and the off-screen canvas is detached from the view.

◀ Previous

[Page 409 (continued)]

# 12.8. 3D Textures

The technique of 2D texturing maps a 2D image to a surface of a 3D object. 3D texture mapping (or solid texture mapping) uses a 3D volumetric texture source. Certainly 3D texturing consumes more computing resources in terms of generation and storage of 3D texture data. However, it has the advantage that realistic texture features of true 3D characteristics can be rendered with relatively simple mapping functions.

Typically the solid textures used in 3D texturing are computer-generated synthetic textures. They are usually used to simulate the natural textures of materials such as marble and wood. This approach is also known as *procedural texturing*.

In order to produce textures that resemble those in natural materials, certain randomness or noise in the pattern is necessary. On the other hand, totally random points will not produce useful textures. A certain amount of smoothness and coherence is also required.

*Perlin's coherent noise* function is a popular choice that produces amazing visual effects. The function noise(x) is a smooth and yet random function. At each grid point (a point with all integer coordinates) a random unit vector called the *gradient* is created. For an arbitrary point *x*, the grid points surrounding *x* will influence the noise(x) value. The contribution from such a grid point *g* is the dot product of the vector from *x*-*g* and the random unit vector at *g*. The final value of noise(x) is an interpolation of these contributions.

Based on the noise function, a fractal sum can be defined:

$$perlinNoise(x) = \sum_{i=1}^{n} \frac{noise(\beta^{i}x)}{\alpha^{i}}$$

Another interesting function built from the noise function is the so-called *turbulence function:* 

# UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO turbulence(x) = $\sum_{i=1}^{noise(\beta x)} \frac{|noise(\beta x)|}{\alpha^{i}}$

Remarkably realistic textures can be generated with the help of these noise functions. For example, the following color function produces a nice *marble texture*.

#### sin(*x* + *turbulence*(*p*))

Java 3D offers 3D texture-mapping support using an approach similar to 2D texture mapping. GeometryArray objects can include the TEXTURE\_COORDINATE\_3 flag to allow the specification of 3D texture coordinates. An array of BufferedImage objects for the 3D texture image is used to create an ImageComponent3D object. The ImageComponent3D is referenced by a Texture3D object, and the Texture3D is a node component referenced by an Appearance object.

Listing 12.10 shows an application of the 3D texture mapping and Perlin's noise. It displays a tetrahedron with a 3D marble texture (Figure 12.13). This example displays a marble tetrahedron. The texture is 3D, and viewed from differences of the marble terms of the approximation of

#### [Page 410]

Listing 12.10. PerlinNoise.java (This item is displayed on pages 410 - 412 in the print version)

```
1 package chapter12;
2
 3 import javax.vecmath.*;
4
 5 public class PerlinNoise {
    final static int B = 0x100;
 6
 7
     int[] p = new int[2*B+2];
 8
    Vector3d[] g3 = new Vector3d[2*B+2];
9
10
    public PerlinNoise() {
11
      for (int i = 0; i < B; i++) {
12
         p[i] = i;
13
         double x = 2.0*Math.random() - 1.0;
14
         double y = 2.0*Math.random() - 1.0;
15
         double z = 2.0*Math.random() - 1.0;
16
         g3[i] = new Vector3d(x, y, z);
17
         g3[i].normalize();
18
       }
19
      for (int i = 0; i < B; i++) {
20
        int k = p[i];
21
         int j = (int)(Math.random()*B);
         if (j >= B) j = B-1;
22
23
         p[i] = p[j];
24
        p[j] = k;
25
       }
       for (int i = 0; i < B+2; i++) {
26
        p[B+i] = p[i];
27
         g3[B+i] = g3[i];
28
29
       }
30
    }
31
    public double noise(Point3d point) {
32
      int bx0, bx1, by0, by1, bz0, bz1, b00, b10, b01, b11;
33
34
       double rx0, rx1, ry0, ry1, rz0, rz1, sy, sz, a, b, c, d, t, u, v;
35
       Vector3d q = null;
       int i, j;
36
37
38
       t = point.x + 0x1000;
39
       bx0 = ((int)t) \& 0xff;
40
       bx1 = (bx0+1) \& 0xff;
41
       rx0 = t - (int)t;
42
      rx1 = rx0 - 1;
43
44
       t = point.y + 0x1000;
45
       by0 = ((int)t) \& 0xff;
46
       by1 = (by0+1) \& 0xff;
47
       ry0 = t - (int)t;
48
       ry1 = ry0 - 1;
49
50
       t = point.z + 0x1000;
51
       bz0 = ((int)t) \& 0xff;
52
       bz1 = (bz0+1) \& 0xff;
53
      rz0 = t-(int)t;
54
      rz1 = rz0 - 1;
55
```

```
[Page 411] 56 i = p[bx0];
57
       j = p[bx1];
58
59
       b00 = p[i+by0];
 60
       b10 = p[j+by0];
       b01 = p[i+by1];
 61
       b11 = p[j+by1];
 62
63
       t = rx0*rx0*(3-2*rx0);
 64
 65
       sy = ry0*ry0*(3-2*ry0);
       sz = rz0*rz0*(3-2*rz0);
 66
67
       q = g3[b00+bz0]; u = rx0*q.x + ry0*q.y + rz0*q.z;
 68
       q = g3[b10+bz0]; v = rx1*q.x + ry0*q.y + rz0*q.z;
 69
70
       a = u + t^{*}(v-u);
71
       q = q3[b01+bz0]; u = rx0*q.x + ry1*q.y + rz0*q.z;
 72
 73
       q = q3[b11+bz0]; v = rx1*q.x + ry1*q.y + rz0*q.z;
       b = u + t^{*}(v-u);
74
75
       c = a + sy^{*}(b-a);
 76
77
 78
       q = g3[b00+bz1]; u = rx0*q.x + ry0*q.y + rz1*q.z;
 79
       q = g3[b10+bz1]; v = rx1*q.x + ry0*q.y + rz1*q.z;
 80
       a = u + t*(v-u);
81
 82
       q = g3[b01+bz1]; u = rx0*q.x + ry1*q.y + rz1*q.z;
 83
       q = g3[b11+bz1]; v = rx1*q.x + ry1*q.y + rz1*q.z;
 84
       b = u + t^{*}(v-u);
85
 86
       d = a + sy^{*}(b-a);
87
 88
       return c+sz*(d-c);
 89
    }
90
 91
     public double perlinNoise(Point3d pt,
    UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 92
 93
 94
       double sum = 0;
       double scale = 1;
 95
96
97
       for (int i = 0; i < n; i++) {
98
        val = noise(pt);
99
         sum += val / scale;
100
        scale *= alpha;
101
        pt.scale(beta);
102
      }
103
       return sum;
104
    }
105
106
     public double turbulence(Point3d pt, double alpha,
107
         double beta, int n) {
108
       double val;
109
       double sum = 0;
110
       double scale = 1;
111
112
    UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
113
114
         sum += Math.abs(val) / scale;
```

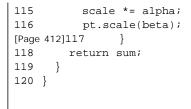




Figure 12.13. Computer-generated 3D marble texture.

Listing 12.11. Marble.java (This item is displayed on pages 412 - 414 in the print version)

```
1 package chapter12;
```

```
2
3 import javax.vecmath.*;
```

```
4 import java.awt.*;
  5 import java.awt.event.*;
 6 import javax.media.j3d.*;
 7 import com.sun.j3d.utils.universe.*;
 8 import com.sun.j3d.utils.geometry.*;
  9 import com.sun.j3d.utils.image.*;
10 import javax.imageio.*;
11 import java.awt.image.*;
12 import java.io.*;
13 import java.applet.*;
14 import com.sun.j3d.utils.applet.MainFrame;
15
16 public class Marble extends Applet {
    public static void main(String[] args) {
17
18
       new MainFrame(new Marble(), 480, 480);
19
    }
20
21
     PerlinNoise pnoise = new PerlinNoise();
2.2
23
    public void init() {
24
       // create canvas
              GraphicsConfiguration gc =
[Page 413] 25
26
          SimpleUniverse.getPreferredConfiguration();
       Canvas3D cv = new Canvas3D(gc);
 27
 28
       setLayout(new BorderLayout());
 29
       add(cv, BorderLayout.CENTER);
       BranchGroup bg = createSceneGraph();
30
31
       bg.compile();
32
       SimpleUniverse su = new SimpleUniverse(cv);
 33
        su.getViewingPlatform().setNominalViewingTransform();
34
        su.addBranchGraph(bg);
35
    }
36
37
     private BranchGroup createSceneGraph() {
38
       BranchGroup root = new BranchGroup();
39
        TransformGroup spin = new TransformGroup();
    UNREGISTERED VERSION OF MOUNTO PDF CONVERTER PRO
 40
        root.addChild(spin);
 41
 42
       //object
 43
       Appearance ap = createTextureAppearance();
 44
       Shape3D shape = new Shape3D(createGeometry(), ap);
       spin.addChild(shape);
 45
 46
       //rotator
 47
       Alpha alpha = new Alpha(-1, 8000);
 48
       RotationInterpolator rotator =
 49
       new RotationInterpolator(alpha, spin);
 50
       BoundingSphere bounds = new BoundingSphere();
 51
       rotator.setSchedulingBounds(bounds);
52
       spin.addChild(rotator);
53
       Background background = new Background(1.0f, 1.0f, 1.0f);
 54
        background.setApplicationBounds(bounds);
55
       root.addChild(background);
56
       return root;
57
     }
58
 59
     GeometryArray createGeometry() {
        IndexedTriangleArray ga
 60
        REGIS CONVERTER PRO
 61
62
          TriangleArray.TEXTURE_COORDINATE_3, 12);
```

```
63
         ga.setCoordinate(0, new Point3f(0.5f,0.5f,0.5f));
         ga.setCoordinate(1, new Point3f(0.5f,-0.5f,-0.5f));
 64
         ga.setCoordinate(2, new Point3f(-0.5f,0.5f,-0.5f));
 65
         ga.setCoordinate(3, new Point3f(-0.5f,-0.5f,0.5f));
 66
 67
         int[] coords = {0,1,2,0,3,1,1,3,2,2,3,0};
         ga.setNormal(0, new Vector3f(1f,1f,-1f));
 68
 69
         ga.setNormal(1, new Vector3f(1f,-1f,1f));
 70
         ga.setNormal(2, new Vector3f(-1f,-1f,-1f));
 71
         ga.setNormal(3, new Vector3f(-1f,1f,1f));
        int[] norms = {0,0,0,1,1,1,2,2,2,3,3,3};
 72
 73
         ga.setCoordinateIndices(0, coords);
 74
        ga.setNormalIndices(0, norms);
 75
         ga.setTextureCoordinate(0, 0, new TexCoord3f(1f,1f,1f));
 76
         ga.setTextureCoordinate(0, 1, new TexCoord3f(1f,0f,0f));
 77
         ga.setTextureCoordinate(0, 2, new TexCoord3f(0f,1f,0f));
 78
         ga.setTextureCoordinate(0, 3, new TexCoord3f(0f,0f,1f));
 79
         ga.setTextureCoordinateIndices(0,0,coords);
 80
        return ga;
 81
      }
 82
 83
      Appearance createTextureAppearance() {
 84
        Appearance ap = new Appearance();
 85
         BufferedImage[] img = new BufferedImage[128];
                for (int i = 0; i < 128; i++) {
[Page 414] 86
 87
          img[i] = new BufferedImage(128,128,
           BufferedImage.TYPE_INT_ARGB);
 88
 89
          for (int r = 0; r < 128; r++) {
 90
            for (int c = 0; c < 128; c++) {
 91
               double v = pnoise.turbulence
 92
               (new Point3d(c/32.0, r/32.0, i/32.0),2,2,8);
 93
               int rgb = (int)((0.55+0.35*Math.sin(3*(c/32.0+v)))*256);
 94
              rgb = ((rgb << 16) | (rgb << 8) | rgb);
 95
               img[i].setRGB(c, r, rgb);
 96
            }
 97
          }
 98
        }
 99
        ImageComponent3D image =
100
           new ImageComponent3D(ImageComponent3D.FORMAT_RGB, img);
101
        Texture3D texture =
102
           new Texture3D(Texture.BASE_LEVEL, Texture.RGBA,
103
           image.getWidth(), image.getHeight(), image.getDepth());
104
        texture.setImage(0, image);
105
        texture.setEnable(true);
106
         texture.setMagFilter(Texture.BASE_LEVEL_LINEAR);
107
         texture.setMinFilter(Texture.BASE_LEVEL_LINEAR);
108
        ap.setTexture(texture);
108
        return ap;
110
      }
111 }
```

The PerlinNoise class implements the noise and turbulence functions based on Perlin's original methods. A grid of 256 x 256 x 256 points is used for the initial random vectors. To reduce storage, only a 1D array of the random gradients g3 and a permutation p is created (lines 7–8). The gradient at a grid point (i, j, k) is obtained by g(i, j, k) = g3 (k + p(j + p(k))).

The value of the noise function (line 32) is interpolated from the contributions of the gradients.

The perlinNoise method (line 91) provides the fractal sum of the noise function. The turbulence method (line 106) calculates the turbulence function.

The Marble class displays a rotating tetrahedron with a solid marble texture. Its scene graph is shown in Figure 12.14.

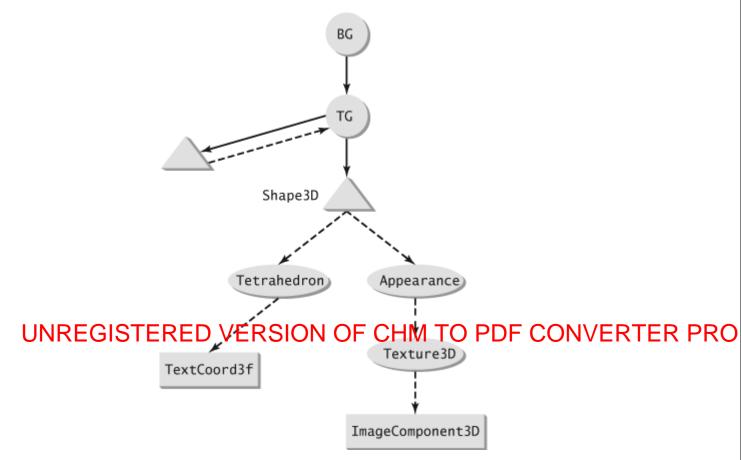


Figure 12.14. Scene-graph branch for the marble tetrahedron. (This item is displayed on page 414 in the print version)

The method createGeometry creates a tetrahedron with the TEXTURE\_COORDINATE\_3 flag to specify the 3D texture coordinates. The texture coordinates of the vertices are assigned based on their special coordinates with a translation to normalize the values to the range [0,1].

The method createTextureAppearance (line 83) creates an appearance for the tetrahedron. The Appearance is set to reference a Texture3D object. An array of 128 BufferedImage objects of size 128 x 128 is created and filled with the generated marble patterns based on the turbulence function (lines 85–96). This BufferedImage array forms a "texture cube" and is used to create an ImageComponent3D object. The ImageComponent3D object is passed in the texture CUP in the texture of texture of the texture of textur

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#### [Page 415 (continued)]

# Key Classes and Methods

- javax.media.j3d.Point3d.interpolate(...) A method to perform a linear interpolation.
- javax.media.j3d.GeometryUpdater An interface for updating geometry data in a live scene.
- javax.media.j3d.GeometryArray.updateData(GeometryUpdater) A method to update the geometry data through the GeometryUpdater.
- javax.media.j3d.Sound A base class for sounds.
- javax.media.j3d.BackgroundSound A class encapsulating a background sound.
- javax.media.j3d.PointSound A class encapsulating a 3D point sound.
- javax.media.j3d.ConeSound A class encapsulating a 3D point sound with a limited angle.
- javax.media.j3d.MediaContainer A node-component class used as a container for sound data.
- com.sun.j3d.utils.universe.Viewer.createAudioDevice(...) A method to initialize the default audio device.
- javax.media.j3d.Canvas3D.setOffScreenBuffer(...) A method to set the off-screen rendering buffer.
- javax.media.j3d.Canvas3D.renderOffScreenBuffer(...) A method to start rendering an off-screen buffer.
- javax.media.j3d.Canvas3D.waitForOffScreenRendering(...) A method to wait for the completion of an off-screen rendering.
- javax.media.j3d.Texture3D A node-component class for 3D textures.
- javax.vecmath.TexCoord3f A class for 3D texture coordinates.
- javax.media.j3d.ImageComponent3D A node-component class to define a 3D image component.

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#### Key Terms 3D Bézier curve

A polynomial parametric curve defined by a set of control points.

#### Bernstein polynomial

(Bernstein basis) A special polynomial often used in approximation.

#### Bézier surface

A polynomial parametric surface defined by a grid of control points.

#### deCasteljau algorithm

A method to calculate a point on a Bézier curve through a series of linear interpolations.

off screen rendering

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A process to render a scene on a buffer other than the screen.

#### 3D texture

(solid texture) A texture defined as a 3D volume.

#### procedural texturing

A method to create synthetic texture computationally.

#### Perlin's noise

A coherent random function used to generate synthetic textures.

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[Page 416 (continued)]

# Chapter Summary

- In this chapter several miscellaneous topics related to 3D graphics are discussed.
- Curves and surfaces are important modeling tools for geometries of visual objects. Implementations of Bézier curves and surfaces are discussed in this chapter. The fundamental tool is the deCasteljau algorithm that evaluates a point on the curve and subdivides a curve by linear interpolations.
- Sound is supported in Java 3D through the sound leaf node class and its subclasses. Adding sounds to a scene graph is similar to adding other nodes. An advantage of including sounds in the scene graph is to support a natural connection between audio and visual objects.
- A method for generating simple shadows is discussed. A shadow is modeled as a plane polygon from the projections of the original object.
- Dynamic data change for a geometry is possible through the BY\_REFERENCE mode and the GeometryUpdater interface.
- The Canvas3D class supports an off-screen rendering mode. It may be used to capture and save the rendered images.
- 3D texture mapping maps a 3D volumetric image to a visual object. Java 3D provides support for 3D texturing mapping using the same framework as for 2D texture mapping. The 3D texture data are often synthesized with certain controlled randomness. Perlin's noise and turbulence functions can be used to generate patterns resembling marble, wood, and other natural textures.

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# UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

[Page 416 (continued)]

# **Review** Questions

12.1 A cubic Bézier curve is defined by the following control points:

p0 = (0, 0, 0), p1 = (1, 0, 0), p2 = (1, 1, 0), p3 = (1, 1, 1)

Use the deCasteljau algorithm to evaluate the points on the curve at

a. t = 1/2

- b. *t* = 1/3
- c. t = 2/3
- 12.2 Subdivide the Bézier curve defined in Question 12.1 into two, using the deCasteljau algorithm at the points
  - a. *t* = 1/2
  - b. t = 1/3
  - c. t = 2/3

[Page 417]

- 12.3 Derive a formula for the surface normal of a bicubic Bézier surface at a given point.
- 12.4 A point light is located at (0, 0, 1) and casts a shadow on the *xy*-plane. Derive a transformation matrix for projecting a vertex to its shadow on the plane.

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[Page 417 (continued)]

## **Programming Exercises**

- 12.1 Implement a 3D B-spline curve by converting it to a series of Bézier curves, similar to the 2D curves defined in Chapter 4.
- 12.2 Write a 3D Bézier surface editor. Display the control points of the surface as square dots. Allow the user to select and move a control point with mouse operations and update the surface accordingly.
- 12.3 Write a Java 3D program to display a Bézier curve with its shadow on a plane.
- 12.4 Write a Java 3D program to display a sphere and its shadow on a wall, similar to Listing 12.7. Add an OrbitBehavior object to control view-platform changes with mouse actions.
- 12.5 Write a Java 3D program to display a PointArray object with 100 points. Use a behavior to move the points in the geometry randomly and independently.
- 12.6 Write a Java 3D program displaying a rotating cone. Create a ConeSound object associated with the cone so that the direction of the ConeSound coincides with the visual cone.
- 12.7 Write a Java 3D program showing two panels and a button. The first panel displays a scene of a rotating 3D text string. When the button is clicked, the image of the 3D scene is captured and the still image is displayed in the second panel.
- 12.8 Write a program to plot the *x*-components of a Perlin's noise.
- 12.9 A wood grain texture may be defined as

g(p) = turbulence(p) \* 20

# UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

Write a Java 3D program to display a rotating cube mapped with a solid wood texture.

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# Appendix A. Mathematical Background for Computer Graphics

Section A.1. Introduction

Section A.2. Analytic Geometry

Section A.3. Complex Numbers and Quaternions

Section A.4. Linear Algebra

Section A.5. Geometric Transformations

Section A.6. Calculus

Section A.7. Graph Theory

Key Terms

**Review Problems** 

# A.1. Introduction

This appendix provides a brief review of several mathematical topics that are closely related to computer graphics. Computer graphics depends heavily upon mathematical tools to accurately model, transform, and process graphics objects and systems.

Geometry, especially analytic geometry, offers an effective tool to model graphics objects. The coordinate systems in analytic geometry facilitate numerical representations of geometric models. This modeling scheme is fundamental in a computer graphics system, because geometric entities, properties, and transformations are directly related to the central problems in computer graphics.

Complex numbers and quaternions are highly structured algebraic systems. They have direct geometric interpretations, which make them valuable tools for solving certain problems in geometry and graphics.

Linear algebra is an algebraic subject that further extends the systems of real numbers, complex numbers, and quaternions to arbitrary dimensional vector spaces and systematically studies the properties and relationships on vectors. Matrices provide concrete representations for linear transformations and vectors. They can be directly implemented in computers to represent geometric transforms relevant to computer graphics.

Calculus may be applied to solve problems such as tangent lines and surface normals. These topics are related to certain modeling and rendering problems in graphics.

Graph theory studies a discrete structure called a *graph* that has a wide range of applications in computer science and graphics.

A comprehensive coverage of these mathematical topics cannot possibly fit into a single chapter or appendix. We introduce here the most fundamental concepts and results related to computer graphics. This material may serve as a quick reference for relevant mathematical problems throughout the book.

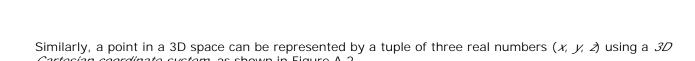
[Page 419 (continued)]

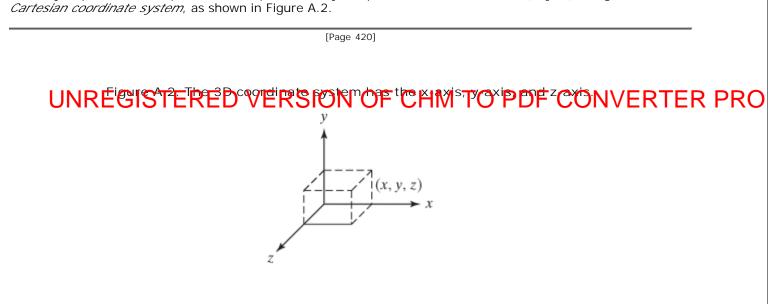
# A.2. Analytic Geometry

## A.2.1. Coordinate Systems

A geometric object is represented algebraically in a coordinate system. A point in a plane is represented by the *x*-coordinate and the *y*-coordinate in a *2D Cartesian coordinate system*, as shown in Figure A.1.

Figure A.1. The 2D coordinate system has the *x*-axis and *y*-axis. (This item is displayed on page 420 in the print version)





With the established one-to-one correspondence between the points and their coordinates, geometric properties can be translated into algebraic quantities. For example, the distance between two points  $(x_1, y_1)$  and  $(x_2, y_2)$  in a plain is given by the *distance formula*.

d = UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

The distance between  $(x_1, y_1, z_1)$  and  $(x_2, y_2, z_2)$  in a 3D space is given by the *distance formula*.

$$d = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

#### A.2.2. 2D Equations

Geometric objects can often be represented by algebraic equations. The points on a geometric object are characterized by the fact that their coordinates satisfy the corresponding equation. In a 2D space, an equation F(x, y) = 0 or an explicit function y = f(x) defines a curve.

A line is characterized by the general linear equation:

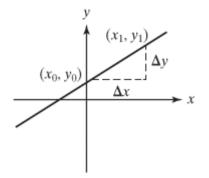
Ax + By + C = 0

A more convenient form of linear equation is the point-slope form, as illustrated in Figure A.3. Given two points  $(x_0, y_0)$ ,  $(x_1, y_1)$  on the line, the differences in the x- and y-directions are defined as  $x = x_1 - x_0$ ,  $y = y_1 - y_0$ . The slope of a line is the ratio k = y/x, which is a constant for any given line. Given a point  $(x_0, y_0)$  on the line and the slope k, the equation of the line can be written in the following *point-slope form*.

 $y - y_0 = k(x - x_0)$ 

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#### Figure A.3. A line can be represented by a linear equation.



A *circle* centered at  $(x_0, y_0)$  with radius *R* is represented by the equation:

$$(X - X_0)^2 + (Y - y_0)^2 = R^2$$

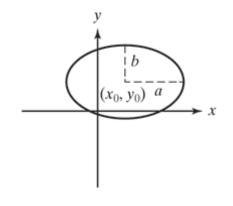
A general quadratic equation represents a family of curves known as *conic sections*.

$$Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0$$

Conic sections can be classified into three main categories: ellipses, parabolas, and hyperbolas. Their standard equations are given below. (See Figures A.4, A.5, A.6.)

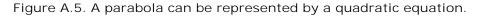
$$\frac{(x-x_0)^2}{a^2} + \frac{(y-y_0)^2}{b^2} = 1 \qquad (ellipses)$$

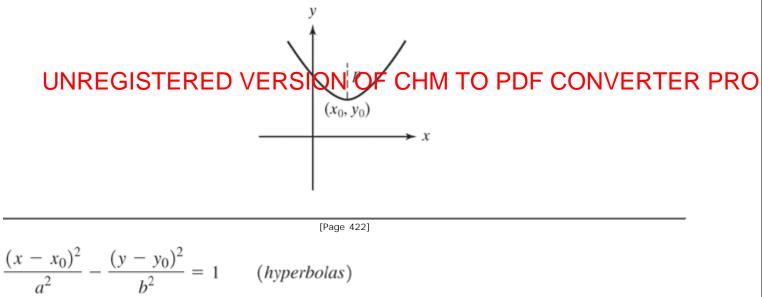
Figure A.4. An ellipse can be represented by a quadratic equation.

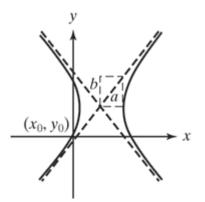




(*parabolas*)





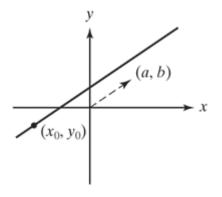


# A.2.3. Parametric Equations

A parametric equation of a curve uses a third variable *t* as the independent variable and defines *x*- and *y*- coordinates as functions of *t*. For example, a *line* through the point ( $x_0$ ,  $y_0$ ) with the direction (*a*, *b*), as shown in Figure A.7, has a parametric equation:

 $\begin{aligned} x &= x_0 + at \\ y &= y_0 + bt \end{aligned}$ 

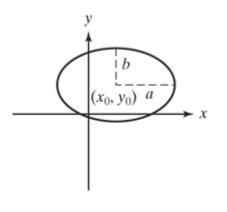
Figure A.7. A line can be represented by a parametric equation.



An *ellipse* can be expressed as a parametric equation, as shown in Figure A.8:

 $x = x_0 + a \cos t$  $y = y_0 + b \sin t$ 

Figure A.8. An ellipse can be represented by a parametric equation.





## A.2.4. 3D Equations

In a 3D space, an equation F(x, y, z) = 0 or an explicit function z = f(x, y) represents a surface in the space.

A general linear equation represents a plane

Ax + By + Cz + D = 0

The normal of a plane is a direction perpendicular to the plane. If the normal of a plane is given by (a, b, c) and a fixed point on the plane is  $(x_0, y_0, z_0)$  then an equation of the plane can be written as

 $\mathcal{A}(x - x_0) + \mathcal{B}(y - y_0) + \mathcal{C}(z - z_0) = 0$ 

A *sphere* centered at  $(x_0, y_0, z_0)$  of radius *R* has the following standard equation:

 $(X - X_0)^2 + (Y - y_0)^2 + (Z - Z_0)^2 = R^2$ 

A line in a 3D space can be expressed as the intersection of two planes, or as a parametric equation.

# $x = 10^{\text{MR}} \text{REGISTERED VERSION OF CHM TO PDF CONVERTER PRO}$ $y = y_0 + bt$ $z = z_0 + ct$

A parametric equation for a surface involves two variables.

X = f(U, v)Y = g(U, v)Z = h(U, v)

For example, a plane through three points  $(x_0, y_0, z_0)$ ,  $(x_1, y_1, z_1)$ , and  $(x_2, y_2, z_2)$  has a parametric equation:

 $x = x_0 + (x_1 - x_0)\nu + (x_2 - x_0)\nu$   $y = y_0 + (y_1 - y_0)\nu + (y_2 - y_0)\nu$  $z = \bigcup_{v \in V} RE_0 S_2 E_0 RED VERSION OF CHM TO PDF CONVERTER PRO$  Previous

[Page 423 (continued)]

# A.3. Complex Numbers and Quaternions

## A.3.1. Complex Numbers

Complex numbers can be used to represent 2D geometric objects and transforms. The set of complex numbers is an extension of the real number system. A complex number can be written as

a + bi

where  $a_i b$  are real numbers and  $\hat{r} = -1$ . Addition and multiplication can be defined on the complex numbers. Let z = a + bi and w = c + di be two complex numbers. Then the operations are defined as

Z + W = (a + c) + (b + d)iZ W = (ac - bd) + (ad + bc)i

[Page 424]

The multiplication can be obtained symbolically by the distributive law and the fact that  $\lambda = -1$ . For example,

 $(2 - \cancel{3} + (3 + 4\cancel{3}) = 5 + 3\cancel{3})$  $(2 - \cancel{3} (3 + 4\cancel{3}) = 6 + 8\cancel{3} - 4\cancel{2} = 10 + 5\cancel{3}$ 

The set of complex numbers with the two operations has properties similar to those of real numbers. Both operations are associative and commutative. The multiplication is distributive over the addition. They have identity elements (0 and 1) and inverses. The inverse operation of addition is subtraction and the inverse of multiplication is division. Consequently, the set of complex numbers with the two operations forms an algebraic structure called a *field*, as in the real number system. Like addition, the subtraction of two complex numbers is performed on real and imaginary parts separately. For example,

# <sup>(2-</sup><sup>\*</sup> ÚNŘĚGIŚTERED VERSION OF CHM TO PDF CONVERTER PRO

The division operation is more complicated, and several new terms are needed to introduce it. The *complex conjugate* and the absolute value of z = a + bi are defined as

$$\overline{z} = a - bi$$
$$|z| = \sqrt{a^2 + b^2}$$

The *absolute value* of a complex number is a nonnegative real number. It is easy to verify that  $z\overline{z} = |z|^2$ . The division of two complex numbers *w* and *z* can be calculated by multiplying the conjugate of the denominator on both the denominator and the numerator bythat is,

$$\frac{w}{z} = \frac{w\overline{z}}{z\overline{z}} = \frac{w\overline{z}}{|z|^2}$$
  
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For example,

$$\frac{2-i}{3+4i} = \frac{(2-i)(3-4i)}{(3+4i)(3-4i)} = \frac{2-11i}{25} = (2/25) - (11/25)i$$

The standard rectangular form of complex numbers introduced above may not be the most convenient representation in some cases. A complex number can be written in the *polar form* 

$$Z = I(\cos + i \sin) = I e^{i}$$

where r = |Z| and is a real number known as the argument. The equation  $e' = \cos + i$  is the famous Euler's identity that establishes a relationship between trigonometric functions and exponential functions. It is much easier to calculate the multiplication, division, power, and roots of complex numbers in polar form.

Complex numbers have a geometric interpretation as points on a plane. A complex number z = a + b/is associated with the 2D point (a, b) or the vector from the origin to the point (see Figure A.9). The absolute value r corresponds to the distance of the point to the origin or the length of the vector. The angle corresponds to the angle between the vector and the *x*-axis. The addition of two complex numbers corresponds to the addition of vectors. The geometric interpretation of multiplication of two complex numbers can be seen from its polar form:

[Page 425]

$$Z_1 Z_2 = I_1 e^{I_1} I_2 e^{I_2} = (I_1 I_2) e^{(I_1 I_2)}$$

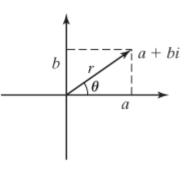


Figure A.9. Complex numbers can be used to represent geometric objects. (This item is displayed on page 424 in the print version)

Therefore, the length of the resultant vector is the product of the lengths of the two vectors, and the angle of the resultant vector is the sum of the angles of the two vectors.

A Java class implementing the complex numbers is shown in Listing A.1.

Listing A.1. Complex.java

(This item is displayed on pages 425 - 426 in the print version)

```
1 public class Complex {
2   public static void main(String[] args) {
```

```
3 Complex z = new Complex(1, -2);
```

```
4
      Complex w = new Complex(3, 4);
      System.out.println("z = " + z);
 5
      System.out.println("w = " + w);
 6
 7
      System.out.println("|z| = " + z.abs());
      System.out.println("|w| = " + w.abs());
8
      System.out.println("arg z = " + z.arg());
9
10
      System.out.println("arg w = " + w.arg());
      System.out.println("conj z = " + z.conj());
11
      System.out.println("conj w = " + w.conj());
12
      System.out.println("z + w = " + z.add(w));
13
      System.out.println("z - w = " + z.sub(w));
14
      System.out.println("z * w = " + z.mul(w));
15
16
      System.out.println("z / w = " + z.div(w));
17
    }
18
19
    private double x = 0.0;
20
    private double y = 0.0;
21
22
    public Complex() {
23
    }
24
    public Complex(double x, double y) {
25
26
      this.x = x;
27
      this.y = y;
28
    }
29
30
    public double getX() {
31
     return x;
32
    }
33
34
    public double getY() {
35
     return y;
36
    }
37
38
    public void setX(double x) {
     this.x = x;
39
    UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
40
41
42
    public void setY(double y) {
43
     this.y = y;
44
    }
45
46
    public double abs() {
47
     return Math.sqrt(x*x + y*y);
48
    }
49
[Page 426]50
           public double arg() {
      return Math.atan2(y, x);
51
52
    }
53
54
    public Complex conj() {
55
     return new Complex(x, -y);
56
    }
57
58
    public Complex add(Complex other) {
59
     double a = x + other.getX();
     UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
60
61
62
    }
```

```
63
64
     public Complex sub(Complex other) {
65
       double a = x - other.getX();
66
       double b = y - other.getY();
67
       return new Complex(a, b);
68
    }
69
70
    public Complex mul(Complex other) {
71
       double a = x * other.getX() - y * other.getY();
       double b = x * other.getY() + y * other.getX();
72
73
       return new Complex(a, b);
74
    }
75
76
    public Complex div(Complex other) {
77
       double a = x * other.getX() + y * other.getY();
       double b = -x * other.getY() + y * other.getX();
78
79
       double d = other.abs();
80
     d = d * d;
81
      return new Complex(a/d, b/d);
82
   }
83
   public String toString() {
84
85
     if (y >= 0)
86
         return "" + x + "+" + y + "i";
87
       else
88
         return "" + x + "" + y + "i";
89
    }
90 }
```

The class Complex encapsulates the concept of complex numbers. It contains two fields x and y to represent the real and imaginary parts of a complex number (lines 1920). The fields can be accessed individually with the getters and setters.

The default constructor creates the complex number 0. The other constructor creates a complex number with the specified real and imaginary parts (lines 2528).

The absolute value and the argument of the complex number can be obtained with the methods abs and arg. The conj method returns a new Complex object that is the complex conjugate of the current object. The complex operations of addition, subtraction, multiplication, and division are performed by the methods add, sub, mul, and div. Each method takes a Complex parameter as the second operand and returns a new Complex object as the result of the operation.

The method toString (line 84) is overridden to provide a conventional string representation of the complex number in the form such as "3 - 4i."

A main method is implemented to test the Complex class. Two complex numbers are created. They are printed using the toString method implicitly. The results of all operations performed on the two numbers are also printed. The output of the program is shown below.

[Page 427]

z = 1.0-2.0i w = 3.0+4.0i |z| = 2.23606797749979 |w| = 5.0 arg z = -1.1071487177940904

```
arg w = 0.9272952180016122
conj z = 1.0+2.0i
conj w = 3.0-4.0i
z + w = 4.0+2.0i
z - w = -2.0-6.0i
z * w = 11.0-2.0i
z / w = -0.2-0.4i
```

## A.3.2. Quaternions

The quaternion system is an extension of the complex number system. A quaternion is expressed as:

q = a + bi + cj + dk

where *a*, *b*, *c*, *d* are real numbers. The *i*, *j*, *k* are elements satisfying the rules:

 $\hat{f} = \hat{f}^2 = k^2 = i/k = -1$ 

With the assumption of associativity in multiplication, it can also be shown that

 $ij = k = -ji, \qquad jk = i = -kj, \qquad ki = j = -ik$ 

The addition and subtraction of quaternions are defined as componentwise operations similar to those of complex numbers. The multiplication of quaternions is also similar to that of complex numbers defined with the distributive law over addition and with the relationships among i, j, k given above.

The addition of two quaternions q = a + bi + cj + dk and p = e + fi + gj + hk is defined by:

$$Q + p = (a + e) + (b + h)i + (c + g)j + (d + h)k$$

The multiplication of the quaternions is defined with distributive law and the properties on i, j, k:

*q p* = (*ae*- *bf*- *cg*- *dh*) + (*af*+ *be*+ *ch*- *dg*)*i*+ (*ag*- *bh*+ *ce*+ *dh*)*j*+ (*ah*+ *bg*- *cf*+ *de*)*k* For example, REGISTERED VERSION OF CHM TO PDF CONVERTER PRO

(1 - i + j - 2k) (2 + i - k)

= 2 + i - k - 2i + 1 - j + 2j - k + i - 4k - 2j - 2

=1 - *j* - 6*k* 

Quaternion multiplication is not commutative, so in general p q is not the same as q p. However, all other algebraic properties such as the associative laws, the distributive laws, and the existence of identity and inverse elements are valid, similar to real and complex number systems. The quaternion system is known as a *skew field*, or a *noncommutative field*. A skew field has all the properties of a field except that the multiplication is not necessarily commutative.

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The *conjugate* and *absolute value* of a quaternion q = a + bi + cj + dk are defined as

$$\overline{q} = a - bi - cj - dk$$
$$|q| = \sqrt{a^2 + b^2 + c^2 + d^2}$$

It can be shown that  $\overline{q \cdot p} = \overline{q} \cdot \overline{p}$  and  $q \cdot \overline{q} = \overline{q} \cdot q = |q|^2$ . The last identity can be used to perform quaternion divisions in the same way as complex number divisions. For example,

$$\frac{-k}{1+2i-j} = \frac{-k(1-2i+j)}{(1+2i-j)(1-2i+j)} = \frac{-k+2j+i}{6} = (1/6)i + (1/3)j - (1/6)k$$

One way to provide a geometric interpretation to quaternions is to associate a point (x, y, z) in 3D space with a pure quaterniona quaternion with real part 0 (for example, xi + yj + zk).

Quaternions are especially useful in representing 3D rotations. The details will be introduced in Section A.5, "Geometric Transformations."

◀ Previous

[Page 428 (continued)]

# A.4. Linear Algebra

## A.4.1. Vector Spaces

A general vector space over a field  $\mathcal{F}$  (such as the field of real numbers or the field of complex numbers) is a set  $\mathcal{V}$  with an addition,  $+: \mathcal{V} \times \mathcal{V} \longrightarrow \mathcal{V}$ , and a scalar multiplication,  $\cdot: \mathcal{F} \times \mathcal{V} \longrightarrow \mathcal{V}$  satisfying the following conditions.

For all u, v,  $w \square V$  and k,  $I \square F$ ,

U + V = V + U(U + V) + W = U + (V + W)

there exists a vector 0 such that u + 0 = u.

For every vector u there exists an inverse - u such that u + (-u) = 0:

k(u + v)	= kU + kV
( <i>k</i> + <i>)</i> ) <i>U</i>	= KU + IU
( <i>k</i> )) <i>U</i>	= k(ll)
lu	= U

As a concrete example, a typical *n*-dimensional vector is simply an ordered tuple of *n* real numbers. For example, (3, 4), (1, 0, -2), (4, 5, -3, 1) are vectors of dimensions 2, 3, and 4, respectively.

The collection of all such vectors of dimension *n* forms a vector space of dimension *n* over the field of real numbers with two operations defined as componentwise operations. The addition of two vectors is defined as

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The scalar multiplication is defined as

 $k(a_1, a_2, \ldots, a_n) = (ka_1, ka_2, \ldots, ka_n)$ 

This particular real vector space of dimension n is denoted by  $R^{p}$ .

The set of complex numbers can be regarded as a two-dimensional vector space over the real numbers. The quaternions form a four-dimensional vector space over the real numbers, or a two-dimensional space over the complex numbers.

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The *inner product* (also known as the dot product or scalar product) is defined on  $\mathcal{R}^{\prime}$  as

 $(\partial_1, \partial_2, \dots, \partial_n)$   $(b_1, b_2, \dots, b_n) = \partial_1 b_1 + \partial_2 b_2 + + \partial_n b_n$ 

The *norm* of a vector  $\nu$  is defined as  $||v|| = \sqrt{v \cdot v}$ .

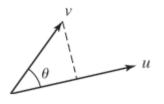
A point IN REGISCIPER TO BE SERIE IN OF COMASITOURD Feets ON VERATER PRC system. This association establishes a one-to-one correspondence between the geometric plane and the algebraic vector space. Similarly a one-to-one correspondence can be established between a 3D geometric space and a vector space of dimension 3. This association is the exactly the same as the concept applied in the analytic geometry.

Geometrically, the norm of a vector is the length of the vector. The inner product of two vectors can be expressed as

$$v \cdot u = \|v\| \|u\| \cos \theta$$

where is the angle between the two vectors. Figure A.10 illustrates the inner product. If  $\omega$  is a unit vector, ||u|| = 1, then the inner product can be interpreted as the projection of along the direction  $\omega$ .

Figure A.10. Geometric interpretation of inner product.



If the angle between two vectors is 90 degrees or p/2 radians, the two vectors are said to be *orthogonal* or *perpendicular*. From the properties of the inner product, it is clear that two vectors  $\nu$  and  $\nu$  are orthogonal when  $\nu u = 0$ .

## A.4.2. Linear Transformations and Matrices

Mathematically, a transformation (or a transform) T from a space V to a space W is a mapping (a function) from V to W.

```
T: V \longrightarrow W
```

For each point in  $V_{\ell}$  there is a corresponding point  $\mathcal{T}(v)$  in  $W_{\ell}$ . If the mapping  $\mathcal{T}$  is one-to-one and onto, then it has an inverse:

## $\mathcal{F}^1\colon \mathcal{W} \longrightarrow \mathcal{V}$

In computer graphics, the spaces V and W are usually the two-dimensional vector space  $A^2$  or the threedimensional vector space  $A^3$ . The general family of transformations is huge and complex. In graphics usually only certain special families of transformations are considered.

A transformation T is linear if, for any vectors  $u_i$ , v and scalars  $a_i$ ,  $b_i$ 

$$T(\mathcal{A}\mathcal{U} + \mathcal{D}\mathcal{V}) = \mathcal{A}T(\mathcal{U}) + \mathcal{D}T(\mathcal{V})$$

*Linear transformations* are convenient for algebraic manipulation and computer representation and processing. A general linear transformation from an *n*-dimensional vector space  $\mathcal{R}^n$  to an *m*-dimensional vector space  $\mathcal{R}^n$  can be represented by an *m* x *n* matrix. A *matrix* is a rectangular array of numbers. An *m* x *n* matrix has the following form:

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$$A = \begin{bmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,n} \\ a_{2,1} & a_{2,2} & \cdots & a_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m,1} & a_{m,2} & \cdots & a_{m,n} \end{bmatrix}$$

For example, the following is a  $2 \times 3$  matrix:

 $\begin{bmatrix} 3 & -1 & 2 \\ 1 & 0 & -3 \end{bmatrix}$ 

Matrix addition is defined on two matrices with identical sizes by entrywise addition. For example,

$$\begin{bmatrix} 3 & -1 & 2 \\ 1 & 0 & -3 \end{bmatrix} + \begin{bmatrix} 1 & 0 & -3 \\ -1 & 2 & 5 \end{bmatrix} = \begin{bmatrix} 3+1 & -1+0 & 2-3 \\ 1-1 & 0+2 & -3+5 \end{bmatrix}$$
$$= \begin{bmatrix} 4 & -1 & -1 \\ 0 & 2 & 2 \end{bmatrix}$$

Matrix multiplication AB is defined only if the number of columns of A is the same as the number of rows of B. An entry interprovement of the same is the same as the number of rows of B. and taking the same for example,

$$\begin{bmatrix} 3 & -1 & 2 \\ 1 & 0 & -3 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 0 & 2 \\ -3 & 5 \end{bmatrix}$$
$$= \begin{bmatrix} 3 \times 1 + (-1) \times 0 + 2 \times (-3) & 3 \times (-1) + (-1) \times 2 + 2 \times 5 \\ 1 \times 1 + 0 \times 0 + (-3) \times (-3) & 1 \times (-1) + 0 \times 2 + (-3) \times 5 \end{bmatrix}$$
$$= \begin{bmatrix} -3 & 5 \\ 10 & -16 \end{bmatrix}$$

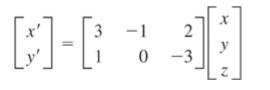
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 $\begin{bmatrix} -1 \\ 4 \\ 0 \end{bmatrix}$ 

A linear transformation may be constructed using a matrix. Let A be an  $m \times n$  matrix and  $\nu$  an  $n \times 1$  column matrix representing a vector. A linear transformation from  $R^n$  to  $R^m$  is defined by the matrix multiplication:

 $\mathcal{U}=\mathcal{A}\mathcal{V}$ 

For example, the following matrix equation defines a linear transformation from  $\mathcal{R}^3$  to  $\mathcal{R}^2$ :



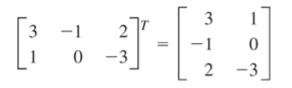
[Page 431]

Conversely, any linear transformation from  $R^n$  to  $R^m$  admits a matrix representation with an appropriate  $m \ge n$  matrix.

Given an  $m \ge n$  matrix  $A_i$ , the transpose  $A^T$  is defined as the  $n \ge m$  matrix

$$A^{T} = \begin{bmatrix} a_{1,1} & a_{2,1} & \cdots & a_{n,1} \\ a_{1,2} & a_{2,2} & \cdots & a_{n,2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1,n} & a_{2,n} & \cdots & a_{m,n} \end{bmatrix}$$

For example,



An *n* x *n* matrix is called a square matrix. A square matrix represents a linear transformation from a vector space  $\mathcal{R}^{n}$  to  $\mathcal{R}^{n}$ . An *identity matrix I* is a square matrix of the form:

$$I = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}$$

The *inverse matrix*  $A^1$  of a square matrix A satisfies the condition:

 $\mathcal{A}^{-1}\mathcal{A} = \mathcal{A}\mathcal{A}^{-1} = 1$ 

The inverse matrix  $A^1$  represents the inverse of the linear transformation represented by the matrix A.

The *determinant* is a scalar-valued function on square matrices. The determinant of matrix A is denoted by det(A) or |A|. The formula for computing the determinant can be defined recursively as follows:

$$|a_{1,1}| = a_{1,1}$$

$$\begin{vmatrix} a_{1,1} & a_{1,2} \\ a_{2,1} & a_{2,2} \end{vmatrix} = a_{1,1}a_{2,2} - a_{2,1}a_{1,2}$$

$$\begin{vmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ a_{2,1} & a_{2,2} & a_{2,3} \\ a_{3,1} & a_{3,2} & a_{3,3} \end{vmatrix} = a_{1,1} \begin{vmatrix} a_{2,2} & a_{2,3} \\ a_{3,2} & a_{3,3} \end{vmatrix} - a_{1,2} \begin{vmatrix} a_{2,1} & a_{2,3} \\ a_{3,1} & a_{3,3} \end{vmatrix} + a_{1,3} \begin{vmatrix} a_{2,1} & a_{2,2} \\ a_{3,1} & a_{3,2} \end{vmatrix}$$

For example,

i.

UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO  $\begin{vmatrix} 2 & 1 & -3 \\ 0 & -1 & 5 \\ 4 & -2 & 3 \end{vmatrix} = 2 \begin{vmatrix} -1 & 5 \\ -2 & 3 \end{vmatrix} - 1 \begin{vmatrix} 0 & 5 \\ 4 & 3 \end{vmatrix} + (-3) \begin{vmatrix} 0 & -1 \\ 4 & -2 \end{vmatrix}$ = 2(-3 + 10) - (0 - 20) - 3(0 + 4) = 22

The expansion method used in the 3 x 3 matrix can be extended to define the determinant of a general matrix recursively.

It can be proven that  $det(A^{\overline{A}}) = det(A)$  and det(AB) = det(A) det(B) if A and B are square matrices.

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The *cross product*  $v \ge u$  (also known as the *outer product* or *vector product*) of two vectors  $v = (x_1, y_1, z_1), u = (x_2, y_2, z_2)$  is an operation defined on  $\mathbb{R}^3$ . Using determinants, the cross product can be defined symbolically as

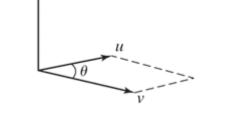
$$v \times u = \begin{vmatrix} i & j & k \\ x_1 & y_1 & z_1 \\ x_2 & y_2 & z_2 \end{vmatrix} = (y_1 z_2 - y_2 z_1)i - (x_1 z_2 - x_2 z_1)j + (x_1 y_2 - x_2 y_1)k$$

Geometrically,  $\nu x \ u$  is a vector perpendicular to both  $\nu$  and u with the length

 $||v \times u|| = ||v|| ||u|| \sin \theta$ 

This length is equal to the area of the parallelogram spanned by the vectors  $\nu$  and  $\mu$ . Figure A.11 shows the geometry of the cross product.





The cross product is a useful tool to construct a vector perpendicular to some other vectors. For example, the cross product of the two vectors (0, 1, 2) and (3, 4, 5) is

i	j	k	= -3i + 6j - 3k = (-3, 6, -3)
0	1	2	= -3i + 6j - 3k = (-3, 6, -3)
3	4	5	

It is easy to verify by inner products that (-3, 6, -3) is orthogonal to (0, 1, 2) and (3, 4, 5):

(-3, 6, -3) (0, 1, 2) = 0 + 6 - 6 = 0(-3, 6, -3) (3, 4, 5) = -9 + 24 - 15 = 0

Let  $\mathcal{A}$  be a square matrix. If  $\nu$  is a nonzero vector and for some scalar ,

$$AV = V$$

then v is said to be an *eigenvector* of A, and an *eigenvalue* of A.

A real matrix A is symmetric if  $A^{T} = A$ . A real matrix U is said to be orthogonal if

 $\mathcal{U}^{\mathcal{T}}\mathcal{U}=\mathcal{U}\mathcal{U}^{\mathcal{T}}=\mathcal{I}$ 

The spectral theorem states that a symmetric matrix A can be decomposed into a matrix product:

 $A = U U^{T}$ 

where U is an orthogonal matrix and is a diagonal matrix of eigenvalues of A.

More generally, any real matrix A can be decomposed into

 $\mathcal{A} = \mathcal{U} \mathcal{V}^{\mathcal{T}}$ 

where *U* and *V* are orthogonal matrices and is a diagonal matrix. This decomposition is known as the *singular value decomposition* (*SVD*).

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# UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO

# A.5. Geometric Transformations

## A.5.1. Homogeneous Coordinates

Transformations on  $\mathcal{R}^2$  and  $\mathcal{R}^3$  are directly related to 2D and 3D graphics. A linear transformation on  $\mathcal{R}^3$  can be represented by a 3 x 3 matrix:

$\begin{bmatrix} x' \end{bmatrix}$		x		$\begin{bmatrix} a_{11} \\ a_{21} \\ a_{31} \end{bmatrix}$	$a_{12}$	$a_{13}$	$\begin{bmatrix} x \end{bmatrix}$
<i>y</i> ′	= T	у	=	a <sub>21</sub>	$a_{22}$	a <sub>23</sub>	У
$\lfloor z' \rfloor$		_ z _		$a_{31}$	$a_{32}$	$a_{33}$	_ <i>z</i> _

Families of transformations that are of special interest to computer graphics are often defined in terms of their properties in preserving certain geometric relationships. A *projective transformation* preserves linesthat is, it maps a line to a line. An *affine transformation* preserves lines and parallelismthat is, it is a projective transformation that maps parallel lines to parallel lines. All linear transformations defined above are affine, but not all affine transformations are linear. All affine transformations are projective, but not all projective transformations are affine.

Because affine transformations and projective transformations are in general not linear, they do not necessarily have the matrix representation shown above. However, if the coordinate system representing the points is modified by increasing its dimension, it will be possible to obtain a linear representation for any projective transformation. This coordinate system is known as the *homogeneous coordinates*.

The homogeneous coordinates add one dimension to the standard coordinates. For example, a 2D point is represented by homogeneous coordinates with three components (x, y, w) and a 3D point is represented by homogeneous coordinates with four components (x, y, z, w). Furthermore, homogeneous coordinates that differ by a nonzero factor represent the same point. Therefore, the relationship between the points in the space and the homogeneous coordinates is not one-to-one.

In a 2D space, instead of using two coordinates to represent a point, the homogeneous coordinate system uses three coordinates to represent a point: (x, y, w).

When w is not 0, the regular 2D coordinates (X, Y) of the same point are given by

X = X WY = V W

Similarly in a 3D space, instead of using three coordinates to represent a point, the homogeneous coordinate system uses four coordinates to represent a point: (x, y, z, w), or in the column form:

x y z w When w is not 0, the regular 3D coordinates (X, Y, Z) of the point are given by

X = X WY = Y WZ = Z W

In the homogeneous coordinate system, 4D vectors are used to represent 3D points. It follows from the definition that the homogeneous coordinates for a point are not unique. Any nonzero multiple of a 4D homogeneous vector will still represent the same 3D point.

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For example, the homogeneous coordinates (1, -2, 4, 1), (2, -4, 8, 2), and (-3, 6, -12, -3), all represent the same point (1, -2, 4) in a 3D space.

When W is 0, there is no regular 3D point associated with the homogeneous coordinates. In this case, the homogeneous coordinates may be regarded as a representation of *points at "infinity*." They may be viewed as directions. For example, (1, 1, 0) in a 2D space represents a point at infinity along the 45-degree direction.

One advantage of a homogeneous coordinate system is that it will make all affine transformations and projective transformations linear and provide a uniform matrix representation. In a 3D space, the transformation can be expressed as a matrix equation:

Г	. ר		Г													
X	:'		$a_{1,1}$	$a_{1,2}$	$a_{1,3}$	$a_{1,4}$	<i>x</i>									
y y	'	_	a <sub>2,1</sub>	$a_{2,2}$	a <sub>2,3</sub>	a <sub>2,4</sub>	y			СНМ						
	:'		<i>a</i> <sub>3,1</sub>	a <sub>3,2</sub>	a <sub>3,3</sub>	a <sub>3,4</sub>	z									
Ци	′ _		a <sub>4.1</sub>	a <sub>4,2</sub>	$a_{4,3}$	$a_{4,4}$	w		~ <b>F</b>		то		~~~			
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## A.5.2. Classification of Transformations

Transformations that preserve certain geometric properties have special significance in geometry and graphics.

A *projective transformation* preserves collinearitythat is, it maps a line to a line. A projective transformation is not necessarily linear. For example, a linear transformation always maps the vector 0 to 0. This is not true for projective transformations. However, as shown in the previous section, by using *homogeneous coordinates* you can obtain a linear representation for a projective transformation.

With the homogeneous coordinate system, a projective transformation can be represented as a linear transformation:

$$\begin{bmatrix} x' \\ y' \\ z' \\ w' \end{bmatrix} = \begin{bmatrix} a_{1,1} & a_{1,2} & a_{1,3} & a_{1,4} \\ a_{2,1} & a_{2,2} & a_{2,3} & a_{2,4} \\ a_{2,1} & a_{2,2} & a_{2,3} & a_{2,4} \\ a_{4,1} & a_{4,2} & a_{4,3} & a_{4,4} \end{bmatrix} \begin{bmatrix} x \\ y \\ z' \\ w \end{bmatrix} \text{ION OF CHM TO PDF CONVERTER PRO}$$

*Affine transformations* are projective transformations that preserve parallelism. For example, an affine transformation maps a parallelogram to a parallelogram. Affine transformations are the most common transformations employed in graphics applications. The transformation matrix has the following form:

$a_{1,1}$	$a_{1,2}$	$a_{1,3}$	$a_{1,4}$
a <sub>2,1</sub>	<i>a</i> <sub>2,2</sub>	a <sub>2,3</sub>	a <sub>2,4</sub>
<i>a</i> <sub>3,1</sub>	a <sub>3,2</sub>	a <sub>3,3</sub>	a <sub>3,4</sub>
0	0	0	1

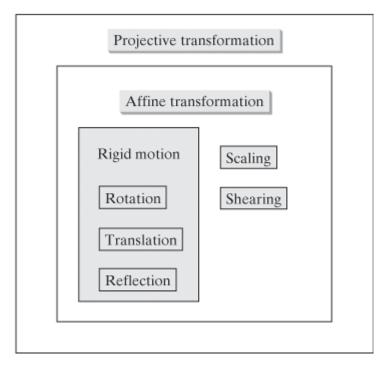
Examples of affine transformations include rotations, translations, scaling, reflections, and shearing.

A subset of affine transformations that also preserve distances is known as *rigid motions*, *Euclidean motions*, or *isometries*. Translations, rotations, and reflections are examples of rigid motions. The determinant of a rigid motion is either 1 or -1. The reflections have determinant -1.

A classification of common geometric transformations is illustrated in Figure A.12.

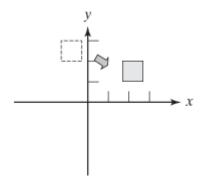
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Figure A.12. Geometric transformations can be classified into translation, rotation, reflection, scaling, shearing, and so on.

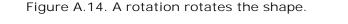


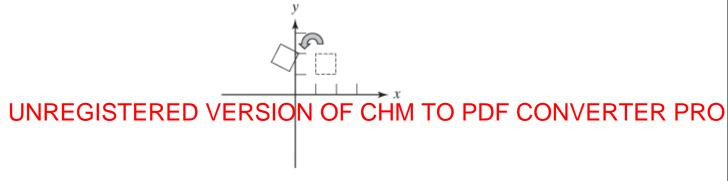
A *translation* moves all points of a space by a fixed amount. It does not change the size and direction of any object. Figure A.13 shows an example of a 2D translation by an amount of (2, -1) in the *x*- and *y*-directions.

Figure A.13. A translation moves the shape.



A *rotation* rotates the object. A 2D rotation is around a point and a 3D rotation is around a line. A rotation does not change the size, but it changes the direction of the shape. Figure A.14 shows a 2D rotation about the origin.

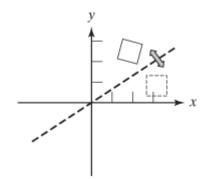




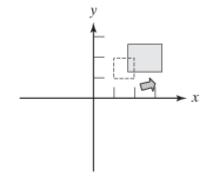
A *reflection* maps the object to its mirror image. A 2D reflection is about a line and a 3D reflection is about a plane. A reflection preserves distance, but it changes the orientation of an angle. Figure A.15 shows a 2D reflection.

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Figure A.15. A reflection mirrors the shape.



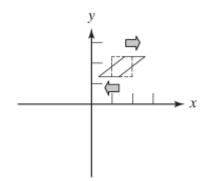
A *scaling* resizes the object by multiplying certain fixed factors in different directions. Figure A.16 shows a 2D scaling.





A *shearing* shifts an object in certain directions. A 2D shear is along a line and a 3D shear shifts along a plane. The amount of shift is proportional to the signed distance to the fixed line or plane. Figure A.17 shows a 2D shear.





Complex numbers and quaternions offer convenient analytic forms of transformations, especially for rotations. In a 2D space, a point may be associated with a complex number. A 2D rotation about the origin can be conveniently represented by the multiplication of a complex number d.

In a 3D space, a point may be identified with a pure quaternion, p = xi + yj + zk. A 3D rotation about the origin can be expressed in the form

$$T_q(p) = q p \overline{q}$$

where q is a unit quaternion and can be written as

$$q = \cos\frac{\theta}{2} + u\sin\frac{\theta}{2}, \qquad u = ai + bj + ck$$

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The pure unit quaternion *u defines* the axis of rotation, and is the angle of rotation.

For example, if you need to define a rotation of p/3 about the axis through the origin and (1, 1, 1), you can use the following quaternion representation:

$$q = \cos\frac{\pi}{6} + \frac{1}{\sqrt{3}}(i+j+k)\sin\frac{\pi}{6} = \frac{\sqrt{3}}{2} + \frac{\sqrt{3}}{6}i + \frac{\sqrt{3}}{6}j + \frac{\sqrt{3}}{6}k$$

Clearly the quaternion representation offers a convenient way to specify a 3D rotation with explicit axis and angle. Consider another example. The set of 3D rotations is closed under the transformation composition—that is, the control to the control to the transformation composition—that are not easily seen. If we have a rotation of p/2 about the y-axis followed by a rotation of p/2 about the x-axis, what are the axis and angle of the resulting rotation? The quaternion representation provides an easy solution. The composite transform of two rotations  $T_{d1}$  and  $T_{d2}$  is given by

$$T_{q_1}(T_{q_2}(p)) = q_1 q_2 p \overline{q_2} \overline{q_1} = q_1 q_2 p \overline{q_1 q_2} = T_{q_1 q_2}(p)$$

Therefore, the product of two quaternions represents the composite transform of the two rotations. The quaternions for the rotation of p/2 about x-axis and the rotation of p/2 about y-axis are

$$q_1 = \frac{\sqrt{2}}{2} + \frac{\sqrt{2}}{2}i$$

$$q_2 = \frac{\sqrt{2}}{UNREG}$$
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The composite rotation will have the quaternion

$$q_{3} = q_{1}q_{2} = \left(\frac{\sqrt{2}}{2} + \frac{\sqrt{2}}{2}i\right)\left(\frac{\sqrt{2}}{2} + \frac{\sqrt{2}}{2}j\right) = \frac{1}{2}(1 + i + j + ij)$$
$$= \frac{1}{2} + \left(\frac{i + j + k}{\sqrt{3}}\right)\frac{\sqrt{3}}{2}$$
$$= \cos\frac{\pi}{3} + \left(\frac{i + j + k}{\sqrt{3}}\right)\sin\frac{\pi}{3}$$

Therefore the resulting transform is a rotation of 2p/3 about the axis through (0, 0, 0) and (1, 1, 1).

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### A.6. Calculus

Given a curve represented by the function y = f(x) the slope of the tangent line to the curve at a point is the derivative of the function  $dy^{2} dx = f(x)$ . To find the equation of the *tangent line* at  $(x_{0}, y_{0})$ , we can use the point-slope form,

 $y - f(x_0) = f(x_0)(x - x_0)$ 

In a 3D space, a curve may be represented as a parametric equation:

X = I(I)Y = g(t)Z = h(t)

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At the point  $(x_0, y_0, z_0)$  defined by  $t = t_0$ , the direction of the tangent line is given by the vector:

 $(f(t_0), g'(t_0), h(t_0))$ 

The equation of the tangent line is:

 $X = X_0 + f(t_0)(t - t_0)$  $y = y_0 + g(t_0)(t - t_0)$  $Z = Z_0 + h(t_0)(t - t_0)$ 

A smooth surface has a tangent plane at a given point. The normal of the tangent plane is called the surface

normal at the given point of the surface. Given the parametric equation of a surface F CONVERTER PRO X = I(U, V)y = g(u, v)Z = h(U, V)

we can find the surface normals by the partial derivatives. Consider the two vectors formed by the derivatives:

$$D_{U} = (\partial x \partial u, \partial y \partial u, \partial z \partial u) = (f_{U}, g_{U}, h_{U})$$
$$D_{V} = (\partial x \partial V, \partial y \partial V, \partial z \partial v) = (f_{U}, g_{U}, h_{U})$$

The surface normal can be found by taking a cross product:

 $n = Du \times Dv$ 

For example R ISTERED VERISION OF CHM TO PDF CONVERTER PRO x = 2 uv - 1 $y = v^{2}$  $z = u^{2} - v^{3}$ 

The partial derivatives are

Du = (2v, 0, 2u) $Dv = (2u, 2v, -3v^{2})$ 

The surface normals are defined by

 $(2\nu, 0, 2\iota) \times (2\iota, 2\nu, -3\nu^2) = (-4\iota\nu, 4\iota^2 + 6\nu^3, 4\nu^2)$ 

At the point (1, 1, 0) defined by the parameter values u = 1, v = 1, the surface normal is (-4, 10, 4).

For a surface given by an implicit equation  $\mathcal{F}(x, y, z) = 0$ , its surface normal may be found by the *gradient*.

$$\nabla F(x, y, z) = (\partial F \partial x, \partial F \partial y, \partial F \partial z)$$

For instance, a hyperbolic paraboloid has the equation z = xy or xy - z = 0. The gradient is

$$\nabla F(x, y, z) = (\partial F \partial x, \partial F \partial y, \partial F \partial z) = (y, x, -1)$$

Therefore, the surface normal at the point (-1, 2, -2) is in the direction (2, -1, -1).

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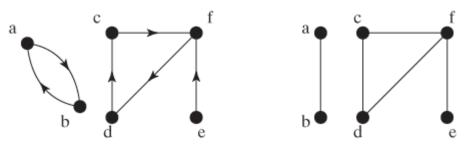
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### A.7. Graph Theory

A graph is a mathematical structure that describes a relationship on a set of objects called *vertices* (also known as *nodes* or *points*). *Edges* (also known as *arcs* or *lines*) are used to define the relationship. An edge links two vertices and it may be either undirected or directed. A graph with directed edges is called a *directed graph*, or a *digraph*. Figure A.18 shows a digraph and an undirected graph.

Figure A.18. A digraph (left) and an undirected graph (right).

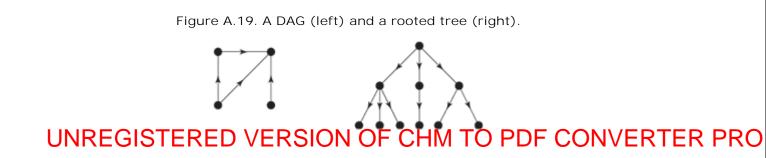


Formally, an undirected graph is defined as G = (V, E), where V is the set of vertices and E the set of edges. An edge uv that joins the vertices u and v is said to be incident with the vertices u and v. Two vertices are said to be *adjacent* if they are incident with the same edge. A *path* is an alternating sequence of distinct vertices and edges:  $v_0 e_1 v_1 e_2 v_2 \cdots e_m v_m$  where  $e_i$  is incident with  $v_{i+1}$  and  $v_i$ . We can usually omit the edge specification in the sequence and simply define a path as  $v_0 v_1 v_2 \cdots v_m$ . A *cycle* is similar to a path except that the initial and final vertices coincide:  $v_0 = v_m$ . For example, in the undirected graph shown in Figure A.18, *cdfe* is a path and *cdfc* is cycle.

A graph is *connected* if any two vertices in the graph can be linked with a path. A graph is called *acyclic* if it contains no cycle. A graph is called a *tree* if it is both connected and acyclic. A tree is a minimally connected graph with harve graph with harve graph with harve graph of edges and the number of vertices of a ree are R PRC related by |E| = |V| - 1.

The terms related to digraphs can be defined similarly. For example, in the digraph shown in Figure A.18, *dcfe* is a directed cycle.

A *DAG* (*directed acyclic graph*) is a digraph without any directed cycles. However, if the directions on the edges of a DAG are ignored, the resulting undirected graph may contain undirected cycles. Figure A.19 shows an example.



A *rooted tree is* a tree with directed edges oriented away from a root, as shown in Figure A.19. A rooted tree is a DAG, but a DAG is not necessarily a rooted tree. From the root of the tree to any vertex, there exists a unique path. If uv is a directed edge from u to v, we call v a *child* of u and u the *parent* of v. A vertex without children is called a *leaf*.

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#### [Page 440]

#### Key Terms coordinate system

A method to associate geometric points with algebraic quantities of ordered tuples of numbers.

#### parametric equation

A set of equations that express coordinate variables as functions of parameters.

#### conic section

A family of curves including ellipses, parabolas, and hyperbolas.

#### complex numbers

A number system that is an extension of the real number field.

#### quaternion

A number system that is an extension of the complex number field.

#### vector space UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO An algebraic system with two operations: addition and scalar multiplication.

inner product

A scalar function of two vectors.

linear transformation

A mapping of vector spaces that preserves linear combinations.

#### matrix

A rectangular array of numbers, often used to represent a linear transformation.

#### determinant

A scalar function of a square matrix.

#### cross product

A vector-valued function of two vectors defined in an 3D space.

#### eigenvalue, eigenvector

A special value and vector  $\nu$  that satisfy  $A\nu = \nu$  for a square matrix.

#### spectral theorem

A symmetric matrix can be decomposed as  $A = U U^{T}$ .

#### SVD

(singular value decomposition). A matrix can be decomposed as A = U V.

#### homogeneous coordinates

A system to represent a point with an extra dimension so that all projective transformations can be represented linearly.

#### projective transformation

A geometric transformation that preserves collinearity.

#### affine transformation

A geometric transformation that preserves parallelism.

#### rigid motion

A geometric transformation that preserves distances.

#### tangent line

A line through a point on a curve. The slope of the line is the same as the rate of change of the curve at the point.

#### surface normal

A vector perpendicular to the tangent plane of a surface at a point.

#### graph

A mathematical structure consisting of a set of vertices and a set of edges.

#### digraph

A graph with directed edges.

#### DAG

Directed acyclic graph.

#### tree

A connected acyclic graph.

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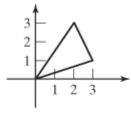
### **Review Problems**

A.1 Plot the following points in a 2D coordinate system:

(1,3), (-2, 1, 5), (0, -2), (0, 0)

A.2 Find the coordinates of the vertices of the triangle in Figure A.20.

Figure A.20. A triangle for Problem A.2.



- A.3 Find the distance between the two 3D points (2, 1, 3) and (0, -2, 5).
- A.4 Find the inner product of the two 3D vectors (2, 1, 3) and (0, -2, 5).
- A.5 Find the angle between the two 3D vectors (2, 1, 3) and (0, -2, 5).

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- A.6 Find the cross product of the two 3D vectors (2, 1, 3) and (0, -2, 5).
- A.7 Find an equation of the line through the point (0, 2) with slope -2.
- A.8 Find the slope of the line -2x + 3y = 4.
- A.9 Find an equation of the circle centered at the origin with radius 5.
- A.10 Find the equation of the ellipse centered at (-1, 3) and through the points (1, 3) and (-1, 4).
- A.11 Find a parametric equation of the line through the points (1, 3) and (-1, 4).
- A.12 Calculate the sum, difference, product, and quotient of the two complex numbers -2 5/, 1 3/.
- A.13 Find the complex conjugate and the absolute value of the complex number -2 5 /.
- A.14 Find the product of two quaternions -1 5/k, 1 3/j j + 2k.
- A.15 Describe the rotation defined by the quaternion 1/2 1/2/ + 1/2/
- A.16 Construct a quaternion representing the 3D rotation of 2p/3 about the axis (1, -2, 2).

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A.17 Find the sum and product of the following matrices:

ſ	1	4	-2	2	-1	3
	1 2	1	0,	0	7	-2
l	-1	-1	$\begin{bmatrix} -2 \\ 0 \\ -3 \end{bmatrix}$ ,	_ 1	5	$\begin{bmatrix} 3 \\ -2 \\ 4 \end{bmatrix}$

A.18 Find the determinant of the following matrix:

$$\begin{bmatrix} -3 & 5\\ 10 & -6 \end{bmatrix}$$

A.19 Find the determinant of the following matrix:

1	4	-2
2	1	0
-1	-1	-3_

A.20 Find det().

- A.21 Prove that  $det(A^{1}) = 1/det(A)$ .
- A.22 Show that the following matrix is orthogonal:

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

### UNREGISTERED VERSION OF CHM TO PDF CONVERTER PRO A.23 If A is orthogonal, show that det(A) = ±1.

- A.25 If A is of thogonal, show that  $det(A) = \pm 1$ .
- A.24 Using homogeneous coordinates in a 2D space, a line can be represented by an equation:

 $\partial x + by + cw = 0$ 

If two lines are parallel, derive a relationship on their coefficients in the above equation.

- A.25 Consider the line equations for homogeneous coordinates in Problem A.24. If two lines are parallel, can you find a point of intersection by solving a simultaneous equation?
- A.26 Find an equation of the tangent line of the curve  $y = x^3 + x 1$  at the point (1, 1).

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A.27 Find an equation of the tangent line of the following 3D curve at the point (1, -1, 0):

$$x = t + 1$$
$$y = t^2 - 1$$
$$z = t^{\beta}$$

A.28 Find the surface normals for the following surface:

 $x = 2 \cos \mu \cos \nu$  $y = 3 \sin \mu \cos \nu$  $z = 4 \sin \nu$ 

- A.29 A tree has 1000 vertices. How many edges does it have?
- A.30 If a rooted tree has 1000 leaves and each nonleaf node has exactly two children, how many edges does it have?

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### Appendix B. GUI Programming with AWT and Swing

Section B.1. Introduction

Section B.2. AWT Components

Section B.3. AWT Programming

Section B.4. Mixing AWT and Swing Components

### B.1. Introduction

There exist two sets of GUI programming interfaces for the Java platform: AWT and Swing. Swing is the newer and currently recommended system. However, because Java 3D depends on an AWT component Canvas3D for its rendering, a Java 3D program must include at least some elements of AWT. The readers are assumed to already have knowledge of Swing programming. This appendix will give a brief introduction to the AWT framework and its relationship to Swing.

A *graphical user interface* (*GUI*) is an indispensable part of modern computer systems. Virtually all operating systems provide some form of GUI support. However, the different GUI systems are usually not compatible with each other. Even though the basic elements of GUI programming, such as window systems and event-driven programming, are very similar in all platforms, GUI programming is usually platform dependent because of its heavy reliance on the specific facilities provided by the native system.

Java, on the other hand, provides a platform-independent GUI programming environment. From the very beginning of Java, GUI programming has been an integral part of standard Java APIs. Like other components of Java, Java's GUI support is fully object oriented and platform independent.

In the early Java versions, the GUI functions are achieved through an API package known as the *Abstract Window Toolkit* (*AWT*). AWT defines the basic mechanism of event-driven programming and a set of visual components. The AWT components are relatively simple, having features common to most GUI systems. They at the feature the features to the features of the system of the system.

*Swing* is a new set of APIs for GUI programming. It differs from AWT mainly in a set of newly defined components. Most Swing components are not repackaged host-system components. They are built from the ground up within Java as "lightweight" components, independent of any native GUI system. As a result, Swing components are rich in features, and their appearance is independent of the host platform. Of course, Swing is not a complete replacement for AWT. It replaces only the AWT components. Swing programs still use other functions of AWT, such as layout managers and event handling.

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### B.2. AWT Components

AWT components are "*heavyweight*." They are always opaque and do not allow events such as mouse clicks to pass through. They are implemented using the components of the host platform. Consequently, only a limited set of features, common to all platforms, is available in AWT components. The class hierarchy of the major AWT components is shown in Figure B.1.

[Page 444]

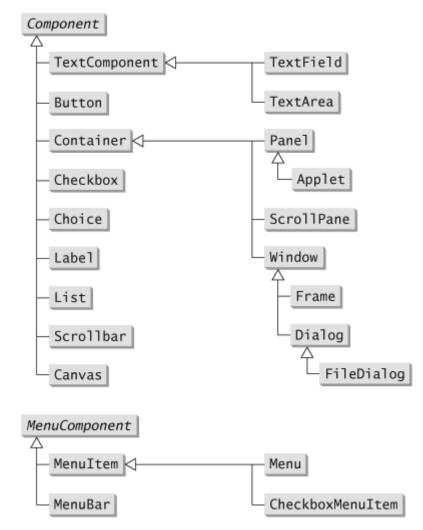
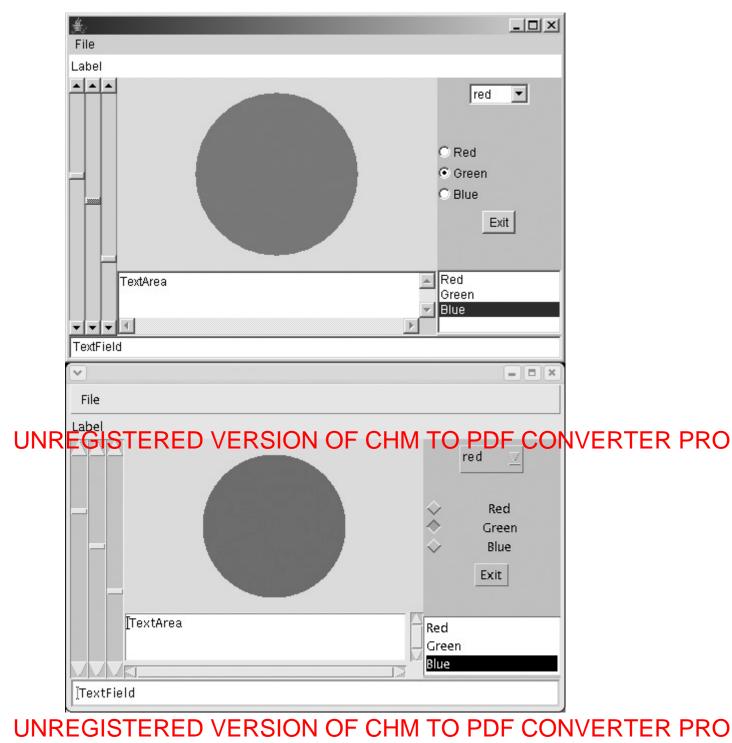


Figure B.1. Major AWT components.

Because AWT components are heavyweight, an AWT program will appear different when run under different platforms. Figure B.2 shows some screen shots of an AWT program under different operating systems. Of course, despite the differences, it is remarkable that the same GUI program can be executed in different systems without any change.

Figure B.2. AWT components appear different in different platforms. Top: Windows 2000. Bottom: Linux.



(This item is displayed on page 445 in the print version)

Many AWT components have approximate equivalents in Swing. Figure B.3 lists possible Swing replacements for AWT components. The Swing version usually has a name with the "J" prefix. For example, Swing components JTextField, JFrame, and JPanel correspond to the AWT components TextField, Frame, and Panel.

#### Figure B.3. AWT components and their Swing equivalents. (This item is displayed on page 445 in the print version)

AWT Component	Swing Component	
Frame	JFrame	
Applet	JApplet	
Button	JButton	
Label	JLabel	
TextField	JTextField	
TextArea	JTextArea	
Panel	JPanel	
List	JList	
Checkbox	JCheckBox, JRadioButton	
Choice	JComboBox	
Canvas	JPanel, JLabel	
MenuBar	JMenuBar	
Menu	JMenu	
MenuItem	JMenuItem	
heckboxMenuItem JCheckBoxMenuItem		
Scrollbar JSlider, JProgressBa		
ScrollPane	JScrollPane	
Dialog	JDialog, JOptionPane	
FileDialog	JFileChooser	

Of course, this is not an exact one-to-one correspondence. The Swing collection is more extensive than the set of AWT components, and sometimes there are also differences in their designs.

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### B.3. AWT Programming

A GUI program with all AWT components has the same basic structure as a Swing program. Constructing UI, event handling, and painting in AWT are almost identical to the procedures used in Swing. Because Swing provides more extensive functionality than AWT, using a pure AWT program to duplicate exactly the features of a Swing program can be difficult. Nevertheless, it is usually possible to convert a Swing program to a similar AWT version. The following guidelines may be useful if you need to perform such a conversion, or if you want to write an AWT program based on your knowledge of Swing:

- 1. Replace each Swing component by its closest AWT version. You may use Figure B.3 to find a matching component.
- 2. Unlike JFrame and JApplet, the top-level AWT containers, Frame and Applet, do not have content panes. The content is added directly to a Frame or Applet object.

#### [Page 446]

3. The Frame class does not have the setDefaultCloseOperation method. You need to add a window event listener to get the effect. For example, the following code snippet terminates the program when the window is closed:

```
public static void main(String[] args) {
  Frame frame = new Frame();
  // exit when the frame is closed
  frame.addWindowListener(new WindowAdapter() {
    public void windowClosing(WindowEvent ev){
      System.exit(0);
    }
  });
  frame.setVisible(true);
}
```

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   The Applet class, unlike JApplet, does not have a menu bar. Of course, it is not common for an applet to have its own menu.
- 5. AWT components do not have the paintComponent(Graphics) method. Use the paint(Graphics) method instead.
- 6. The AWT component Canvas is usually the base class for deriving a custom component class. Swing does not have a directly corresponding class. In Swing, JPanel is usually the blank base class for the same purpose.
- 7. There is no AWT radio-button class corresponding to the Swing class JRadioButton. You may use Checkbox and CheckboxGroup objects to achieve the effects of radio buttons. Note, however, that the usage is different from that of the JRadioButton and ButtonGroup objects in Swing. For example, the following code snippet creates a group of radio buttons in Swing:

```
JRadioButton red = new JRadioButton("Red", true);
JRadioButton yellow = new JRadioButton("Yellow", false);
JRadioButton green = new JRadioButton("Green", false);
Button green = new JRadioButton("Green", false);
Button green = new Button Button ("Green", false);
group.add(red);
```

```
group.add(yellow);
group.add(green);
```

A similar AWT version is given below:

```
CheckboxGroup group = new CheckboxGroup();
Checkbox red = new Checkbox("Red", group, true);
Checkbox yellow = new Checkbox("Yellow", group, false);
Checkbox green = new Checkbox("Green", group, false);
```

8. The AWT component Scrollbar is often used as an approximation for JSlider. One difference between the two components is that the Scrollbar fires the AdjustmentEvent and the JSlider generates the ChangeEvent.

Listings B.1 and B.2 illustrate the procedure of rewriting a Swing program in AWT. Listing B.1 is a typical Swing program and Listing B.2 is an approximately equivalent AWT version. (See Figure B.4.)

#### Listing B.1. SwingProg.java

(This item is displayed on pages 446 - 449 in the print version)

```
1 /*** Swing program ***/
 2
  3 package appendixB;
[Page 447] 4
 5 import javax.swing.*;
  6 import java.awt.*;
 7 import java.awt.event.*;
 8 import javax.swing.event.*;
 9
 10 public class SwingProg extends Jframe
11
     implements ActionListener, ChangeListener {
12
13
    public static void main(String[] args) {
14
        JFrame frame = new SwingProg();
15
        frame.setVisible(true);
16
    }
17
    CirclePanel circle;
 18
 19 JSlider scrollR;
 20
    JSlider scrollG;
 21
     JSlider scrollB;
 22
 23
    public SwingProg() {
 24
      setSize(500,350);
 25
        JMenuBar menuBar = new JMenuBar();
 26
        setJMenuBar(menuBar);
 27
        JMenu fileMenu = new JMenu("File");
 28
       menuBar.add(fileMenu);
        JMenuItem exitItem = new JMenuItem("Exit");
 29
 30
        exitItem.addActionListener(this);
 31
        fileMenu.add(exitItem);
 32
        // exit when the frame is closed
 33
        setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
 34
 35
        Container cp = this.getContentPane();
```

```
36
        cp.setLayout(new BorderLayout());
37
       // center
38
       JPanel panel = new JPanel();
39
        panel.setLayout(new BorderLayout());
 40
        cp.add(panel, BorderLayout.CENTER);
 41
       circle = new CirclePanel();
        panel.add(circle, BorderLayout.CENTER);
 42
 43
       JTextArea textArea = new JTextArea(3,10);
       textArea.setText("TextArea");
 44
 45
       panel.add(textArea, BorderLayout.SOUTH);
       // north
 46
 47
       JLabel label = new JLabel("Label");
 48
       cp.add(label, BorderLayout.NORTH);
 49
       // south
50
       JTextField textField = new JTextField("TextField");
51
       cp.add(textField, BorderLayout.SOUTH);
52
       // west
53
       panel = new JPanel();
       panel.setLayout(new GridLayout(1,3));
54
55
        cp.add(panel, BorderLayout.WEST);
 56
       scrollR = new JSlider(JSlider.VERTICAL, 0, 255, 0);
 57
       scrollR.addChangeListener(this);
58
       panel.add(scrollR);
       scrollG = new JSlider(JSlider.VERTICAL, 0, 255, 0);
 59
 60
       scrollG.addChangeListener(this);
 61
       panel.add(scrollG);
       scrollB = new JSlider(JSlider.VERTICAL, 0, 255, 0);
 62
 63
        scrollB.addChangeListener(this);
 64
       panel.add(scrollB);
65
       // east
              panel = new JPanel();
[Page 448] 66
67
        panel.setBackground(Color.lightGray);
 68
        panel.setLayout(new GridLayout(4,1));
69
        cp.add(panel, BorderLayout.EAST);
70
       JPanel chPanel = new JPanel();
71
        panel.add(chPanel);
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72
73
74
        choice.addItem("green");
75
       choice.addItem("blue");
76
       chPanel.add(choice);
77
       JPanel cbPanel = new JPanel();
78
       cbPanel.setLayout(new GridLayout(3,1));
       panel.add(cbPanel);
79
80
       ButtonGroup group = new ButtonGroup();
 81
       JRadioButton cbR = new JRadioButton("Red", true);
82
       group.add(cbR);
83
       cbPanel.add(cbR);
 84
       JRadioButton cbG = new JRadioButton("Green", false);
85
       group.add(cbG);
86
       cbPanel.add(cbG);
87
        JRadioButton cbB = new JRadioButton("Blue", false);
88
       group.add(cbB);
89
       cbPanel.add(cbB);
 90
       JPanel btPanel = new JPanel();
 91
       panel.add(btPanel);
 92
       NREGIS ERED HERSION OF CHM TO PDF CONVERTER PRO
        JButton button
 93
 94
       btPanel.add(button);
```

```
String[] listItems = {"Red", "Green", "Blue"};
 95
        JList list = new JList(listItems);
 96
 97
        panel.add(list);
 98
     }
99
100
     public void actionPerformed(ActionEvent ev) {
101
        String cmd = ev.getActionCommand();
102
        if ("Exit".equals(cmd))
103
          System.exit(0);
104
      }
105
106
    public void stateChanged(ChangeEvent ev) {
107
       int r = scrollR.getValue();
108
        int g = scrollG.getValue();
109
       int b = scrollB.getValue();
       circle.setColor(new Color(r, g, b));
110
111
      }
112
113 }
114
115 class CirclePanel extends JPanel {
116 private Color color = Color.black;
117
118
    public CirclePanel() {
119
        setBackground(new Color(220,220,220));
120
    }
121
122
    public void paintComponent(Graphics g) {
123
       super.paintComponent(g);
124
        g.setColor(color);
125
       int w = getWidth();
126
       int h = getHeight();
127
        int d = (w > h)? h : w;
[Page 449]128
               d -= 30;
129
        g.fillOval((w-d)/2,(h-d)/2, d, d);
130
     }
131
132
    public void setColor(Color c) {
133
       color = c;
134
        repaint();
135
      }
136 }
```

Listing B.2. AWTProg.java

(This item is displayed on pages 449 - 451 in the print version)

```
1 /*** AWT program ***/
2
3 package appendixB;
4
5 import java.awt.*;
6 import java.awt.event.*;
7
8 public class AWTProg extends Frame
9 implements ActionListener, AdjustmentListener {
```

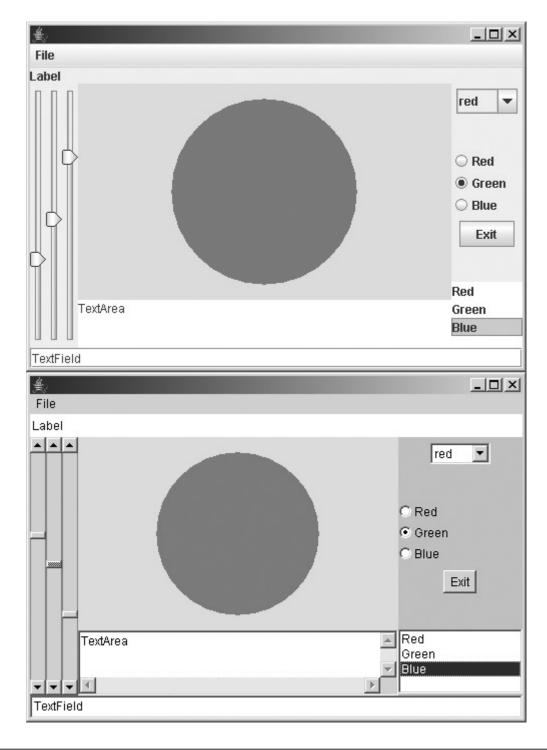
```
10
11
     public static void main(String[] args) {
12
       Frame frame = new AWTProg();
13
       frame.setVisible(true);
14
     }
15
     CircleCanvas circle;
16
     Scrollbar scrollR;
17
    Scrollbar scrollG;
18
19
    Scrollbar scrollB;
20
    public AWTProg() {
21
22
       setSize(500,350);
23
       MenuBar menuBar = new MenuBar();
24
       setMenuBar(menuBar);
25
       Menu fileMenu = new Menu("File");
26
       menuBar.add(fileMenu);
27
       MenuItem exitItem = new MenuItem("Exit");
 28
       exitItem.addActionListener(this);
 29
       fileMenu.add(exitItem);
30
       // exit when the frame is closed
31
       addWindowListener(new WindowAdapter() {
32
         public void windowClosing(WindowEvent ev){
33
           System.exit(0);
34
         }
       });
35
       setLayout(new BorderLayout());
36
37
       // center
38
       Panel panel = new Panel();
 39
       panel.setLayout(new BorderLayout());
 40
       add(panel, BorderLayout.CENTER);
 41
       circle = new CircleCanvas();
 42
       panel.add(circle, BorderLayout.CENTER);
 43
       TextArea textArea = new TextArea(3,10);
 44
        textArea.setText("TextArea");
        panel.add(textArea, BorderLayout.SOUTH);
 45
       NREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 46
 47
        add(label, BorderLayout.NORTH);
 48
49
       // south
               TextField textField = new TextField("TextField");
[Page 450] 50
51
       add(textField, BorderLayout.SOUTH);
52
       // west
53
       panel = new Panel();
54
       panel.setLayout(new GridLayout(1,3));
55
       add(panel, BorderLayout.WEST);
       scrollR = new Scrollbar(Scrollbar.VERTICAL,0,1,0,255);
56
 57
       scrollR.addAdjustmentListener(this);
58
       panel.add(scrollR);
 59
       scrollG = new Scrollbar(Scrollbar.VERTICAL,0,1,0,255);
 60
       scrollG.addAdjustmentListener(this);
       panel.add(scrollG);
61
62
       scrollB = new Scrollbar(Scrollbar.VERTICAL,0,1,0,255);
       scrollB.addAdjustmentListener(this);
 63
 64
       panel.add(scrollB);
 65
       // east
       NREGISTERED VERSION OF CHM TO PDF CONVERTER PRO
 66
67
68
       panel.setLayout(new GridLayout(4,1));
```

```
69
        add(panel, BorderLayout.EAST);
 70
        Panel chPanel = new Panel();
 71
        panel.add(chPanel);
 72
        Choice choice = new Choice();
 73
        choice.add("red");
        choice.add("green");
 74
 75
        choice.add("blue");
 76
        chPanel.add(choice);
 77
        Panel cbPanel = new Panel();
 78
        cbPanel.setLayout(new GridLayout(3,1));
        panel.add(cbPanel);
 79
 80
        CheckboxGroup group = new CheckboxGroup();
 81
        Checkbox cbR = new Checkbox("Red", group, true);
 82
        cbPanel.add(cbR);
 83
        Checkbox cbG = new Checkbox("Green", group, false);
 84
        cbPanel.add(cbG);
 85
        Checkbox cbB = new Checkbox("Blue", group, false);
 86
        cbPanel.add(cbB);
 87
        Panel btPanel = new Panel();
 88
        panel.add(btPanel);
        Button button = new Button("Exit");
 89
        button.addActionListener(this);
 90
 91
        btPanel.add(button);
 92
        List list = new List(3);
 93
        list.add("Red");
 94
        list.add("Green");
 95
        list.add("Blue");
 96
        panel.add(list);
 97
     }
 98
 99
     public void actionPerformed(ActionEvent ev) {
100
        String cmd = ev.getActionCommand();
101
        if ("Exit".equals(cmd))
102
          System.exit(0);
103
     }
104
     public void adjustmentValueChanged(AdjustmentEvent ev) {
105
       int r = scrollR.getValue();
106
107
        int g = scrollG.getValue();
108
        int b = scrollB.getValue();
        circle.setColor(new Color(r, g, b));
109
110 }
111 }
[Page 451]112
113 class CircleCanvas extends Canvas {
114 private Color color = Color.black;
115
116
    public CircleCanvas() {
117
      setBackground(new Color(220,220,220));
118
      }
119
120
     public void paint(Graphics g) {
121
       super.paint(g);
122
        g.setColor(color);
123
        int w = getWidth();
124
       int h = getHeight();
125
       int d = (w > h)? h : w;
126
       d -= 30;
127
       g.fillOval((w-d)/2,(h-d)/2, d, d);
```

```
128 }
129
130 public void setColor(Color c) {
131     color = c;
132     repaint();
133 }
134 }
```

Figure B.4. A Swing program and its AWT clone.

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The Swing version uses the components JFrame, JPanel, JButton, JLabel, JTextField, JTextArea, JList, JComboBox, JRadioButton, JSlider, JMenuBar, JMenu, and JMenuItem. They are replaced in the AWT version by the components: Frame, Panel (and Canvas), Button, Label, TextField, TextArea, List, Choice, Checkbox, Scrollbar, MenuBar, Menu, and MenuItem.

Changes are also necessary in using some of the components in AWT. Instead of using the content pane, the AWT program uses the Frame object as a container to directly add other components. The AWTProg class is an AdjustmentListener to handle the scrollbar events. The Swing version defines a ChangeListener for the same task with JSlider. The radio buttons in the two versions are also created differently.

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### B.4. Mixing AWT and Swing Components

It is possible to use a combination of AWT and Swing components in the same program. Mixing the two types of components will not cause any syntax errors, but it may lead to some undesirable visual effects in the resulting user interface.

The main problem with mixing components is related to the z-order of the components. The *z-order* determines which component will be shown on top when several components overlap. The heavyweight AWT components are opaque, and their z-orders are obtained from the host system. The Swing components can have transparent pixels, and their z-orders are implemented natively. When an AWT component and a Swing component overlap, the AWT component will block the Swing component, which may result in an incorrect visual arrangement. For example, the following program contains one AWT component, a TextArea object, in the right half of a JSplitPane. When the menu is selected, it may be blocked by the AWT component, if the menu and the text area overlap (Figure B.5).

Figure B.5. Mixing AWT and Swing components may cause problems. Left: The menu displays properly when it does not overlap with the AWT component. Right: The menu is partially blocked by the AWT component because of the *z*-order limitation.

٤		- 🗆 🗵	\$	_ 🗆 🗵
File	_		File	
Open	AWT TextArea	A	O AWT TextArea	1
Save			Si	
Exit	1		E	
		-		-
	T			

Listing B.3. SwingAWT.java

(This item is displayed on pages 452 - 453 in the print version)

```
1 package appendixB;
 2
 3 import javax.swing.*;
 4 import java.awt.*;
 5
 6 public class SwingAWT extends JFrame {
    public static void main(String[] args) {
 7
       JFrame frame = new SwingAWT();
 8
 9
       frame.setSize(300, 200);
10
       frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
[Page 453]11
              frame.setVisible(true);
12
    }
13
14
    public SwingAWT() {
15
       // set up menu
16
       JMenuBar mb = new JMenuBar();
17
       setJMenuBar(mb);
18
       JMenu menu = new JMenu("File");
19
       mb.add(menu);
20
       menu.add(new JMenuItem("Open"));
21
       menu.add(new JMenuItem("Save"));
22
       menu.addSeparator();
23
       menu.add(new JMenuItem("Exit"));
24
       // add content
25
       Container cp = this.getContentPane();
26
       cp.setLayout(new BorderLayout());
27
       JSplitPane sp = new JSplitPane(JSplitPane.HORIZONTAL_SPLIT);
28
       JPanel panel = new JPanel();
29
       sp.add(panel);
30
       cp.add(sp);
31
       sp.add(new TextArea("AWT TextArea",10,10));
32
    }
33 }
```

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If mixing the AWT and Swing components is necessary in a program, care should be taken to avoid the *z*-order problem. Besides the JMenuBar class, the Swing components JPopupMenu, JComboBox, JScrollPane, JInternalFrame often exhibit similar problems. For JPopupMenu and JComboBox objects, you have the option to turn off the lightweight popup by calling the method:

setLightWeightPopupEnabled(false)

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