

Dynamic Programming

Dynamic Programming is a general algorithm design technique for solving problems defined by or formulated as recurrences with overlapping subinstances

- Invented by American mathematician Richard Bellman in the 1950s to solve optimization problems and later assimilated by CS
- "Programming" here means "planning"
- Main idea:
 - set up a recurrence relating a solution to a larger instance to solutions of some smaller instances
 - solve smaller instances once
 - record solutions in a table
 - extract solution to the initial instance from that table



Example: Fibonacci numbers

Recall definition of Fibonacci numbers:

F(n) = F(n-1) + F(n-2)F(0) = 0F(1) = 1

• Computing the *n*th Fibonacci number recursively (top-down):

F(n)

F(*n*-1) + F(n-2)

F(n-2) + F(n-3) + F(n-4)



Example: Fibonacci numbers (cont.) Computing the *n*th Fibonacci number using bottom-up iteration and recording results:

F(0) = 0 F(1) = 1 F(2) = 1+0 = 1... F(n-2) = F(n-1) =F(n) = F(n-1) + F(n-2)



Efficiency:

- time
- space

What if we solve it recursively?



Examples of DP algorithms

- Computing a binomial coefficient
- Longest common subsequence
- Warshall's algorithm for transitive closure
- Floyd's algorithm for all-pairs shortest paths
- Constructing an optimal binary search tree
- Some instances of difficult discrete optimization problems:
 - traveling salesman
 - knapsack

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Computing a binomial coefficient by DP Binomial coefficients are coefficients of the binomial formula: $(a + b)^n = C(n,0)a^nb^0 + \ldots + C(n,k)a^{n-k}b^k + \ldots + C(n,n)a^0b^n$

Recurrence: C(n,k) = C(n-1,k) + C(n-1,k-1) for n > k > 0C(n,0) = 1, C(n,n) = 1 for $n \ge 0$

Value of C(n,k) can be computed by filling a table:012.k-1k01111111........n-1C(n-1,k-1)C(n-1,k)n.C(n,k)



Computing C(n,k): pseudocode and analysis **ALGORITHM** Binomial(n, k)

//Computes C(n, k) by the dynamic programming algorithm //Input: A pair of nonnegative integers $n \ge k \ge 0$ //Output: The value of C(n, k)for $i \leftarrow 0$ to n do for $j \leftarrow 0$ to min(i, k) do if j = 0 or j = i $C[i, j] \leftarrow 1$ else $C[i, j] \leftarrow C[i-1, j-1] + C[i-1, j]$ **return** C[n, k]

Time efficiency: $\Theta(nk)$

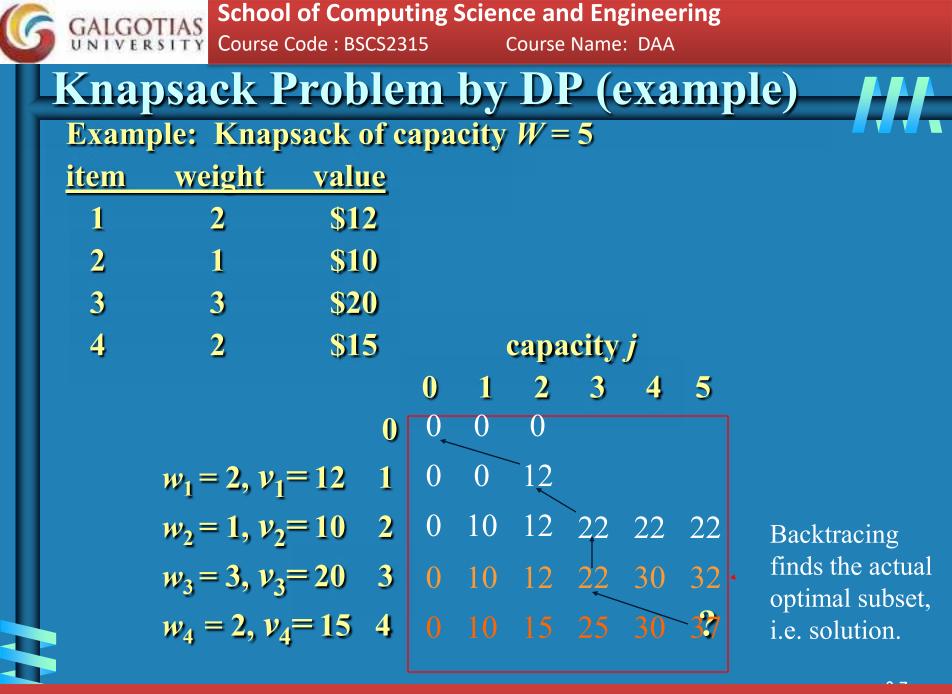
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Space efficiency: \Theta(nk)
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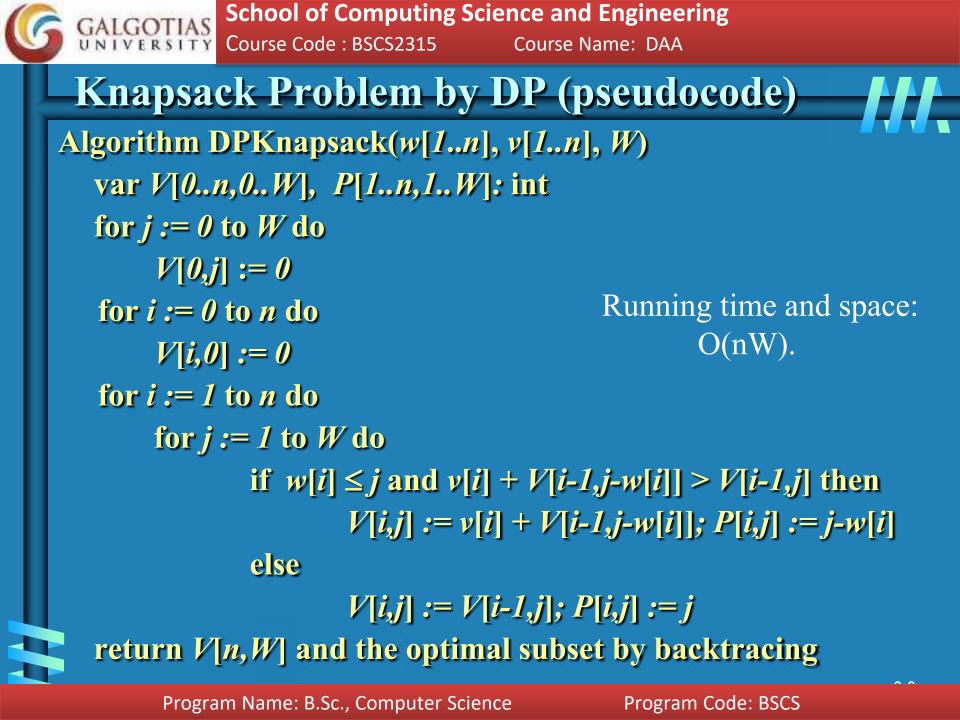


Knapsack Problem by DP Given *n* items of integer weights: $w_1 \ w_2 \ \dots \ w_n$ $v_1 \quad v_2 \quad \dots \quad v_n$ values: a knapsack of integer capacity Wfind most valuable subset of the items that fit into the knapsack Consider instance defined by first *i* items and capacity j ($j \le W$). Let *V*[*i*,*j*] be optimal value of such instance. Then

 $V[i,j] = \begin{cases} \max \{V[i-1,j], v_i + V[i-1,j-w_i]\} & \text{if } j - w_i \ge 0\\ V[i-1,j] & \text{if } j - w_i < 0 \end{cases}$

Initial conditions: V[0,j] = 0 and V[i,0] = 0







Longest Common Subsequence (LCS)



- A subsequence of a sequence/string S is obtained by deleting zero or more symbols from S. For example, the following are all subsequences of "president": pred, sdn, predent. In other words, the letters of a subsequence of S appear in order in S, but they are not required to be consecutive.
- The longest common subsequence problem is to find a maximum length common subsequence between two sequences.



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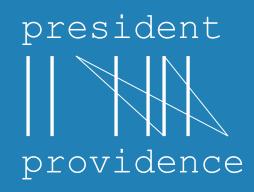
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For instance,

Sequence 1: president Sequence 2: providence Its LCS is priden.



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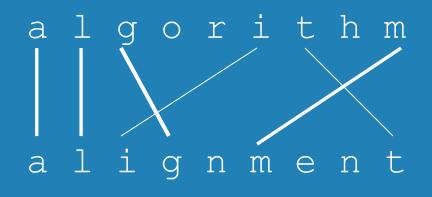
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Another example: Sequence 1: algorithm Sequence 2: alignment One of its LCS is algm.



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How to compute LCS?

- Let $A = a_1 a_2 \dots a_m$ and $B = b_1 b_2 \dots b_n$.
- *len(i, j)*: the length of an LCS between $a_1a_2...a_i$ and $b_1b_2...b_j$
- With proper initializations, *len(i, j)* can be computed as follows.

$$len(i, j) = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0, \\ len(i-1, j-1) + 1 & \text{if } i, j > 0 \text{ and } a_i = b_j, \\ \max(len(i, j-1), len(i-1, j)) & \text{if } i, j > 0 \text{ and } a_i \neq b_j. \end{cases}$$

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procedure LCS-Length(A, B)

- *1.* for $i \leftarrow 0$ to m do len(i, 0) = 0
- 2. for $j \leftarrow l$ to n do len(0,j) = 0
- 3. for $i \leftarrow l$ to m do

4. **for**
$$j \leftarrow l$$
 to n **do**

5. **if**
$$a_i = b_j$$
 then
$$\begin{vmatrix} len(i, j) = len(i - 1, j - 1) + 1 \\ prev(i, j) = " \checkmark " \\ 6. else if $len(i - 1, j) \ge len(i, j - 1) \\ 7. then
$$\begin{vmatrix} len(i, j) = len(i - 1, j) \\ prev(i, j) = " \bigstar " \end{vmatrix}$$$$$

else
$$\begin{bmatrix} len(i, j) = len(i, j) \\ prev(i, j) = " \checkmark "$$

9. **return** *len* and *prev*

8.

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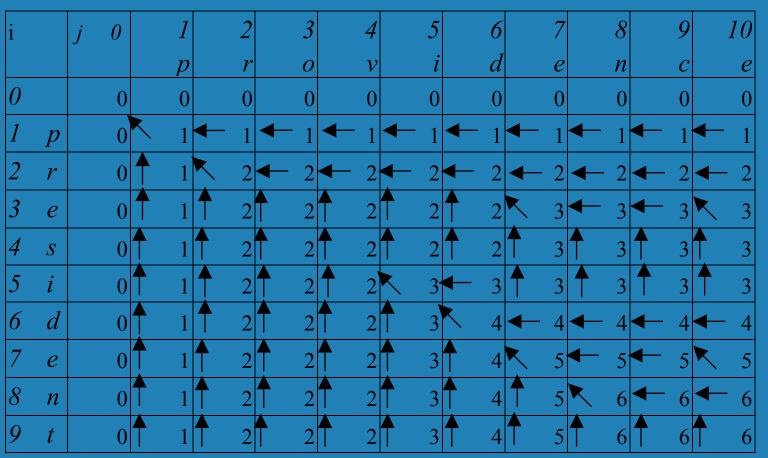
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Running time and memory: O(mn) and O(mn).

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The backtracing algorithm

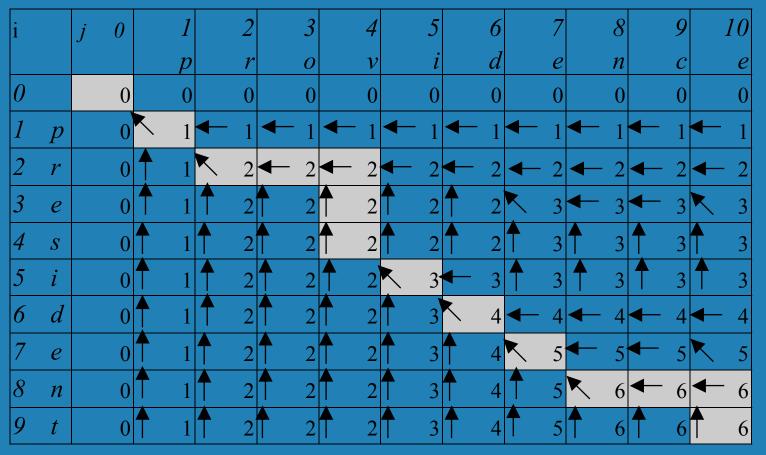
procedure *Output-LCS(A, prev, i, j)*

- *1* if i = 0 or j = 0 then return
- 2 **if** $prev(i, j) = " \checkmark "$ **then** $\begin{bmatrix} Output LCS(A, prev, i-1, j-1) \\ print & a_i \end{bmatrix}$
- 3 else if prev(i, j) =["] then Output-LCS(A, prev, i-1, j)
- 4 else Output-LCS(A, prev, i, j-1)



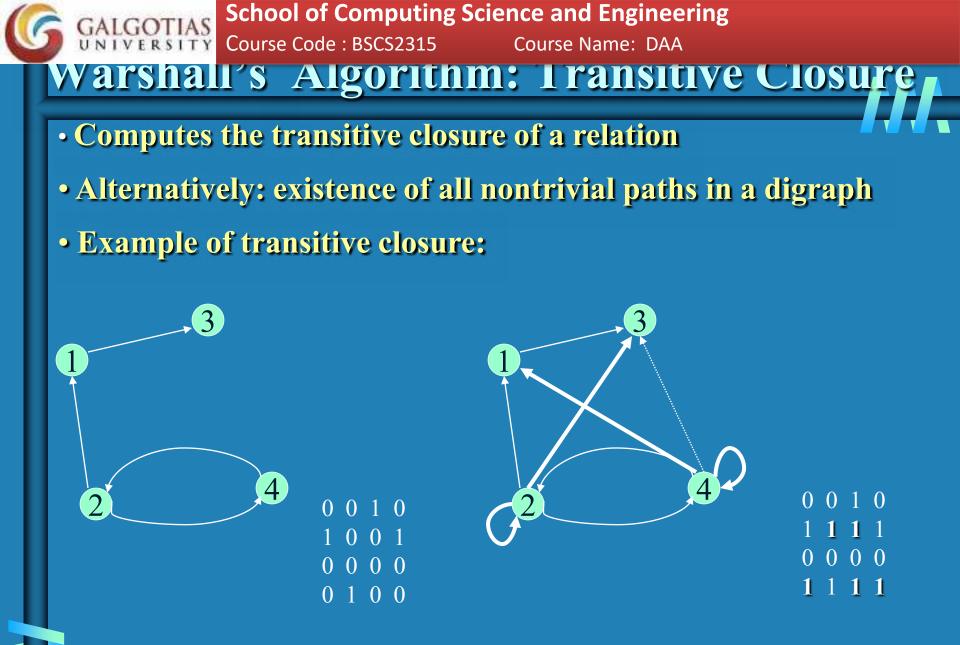
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Output: priden

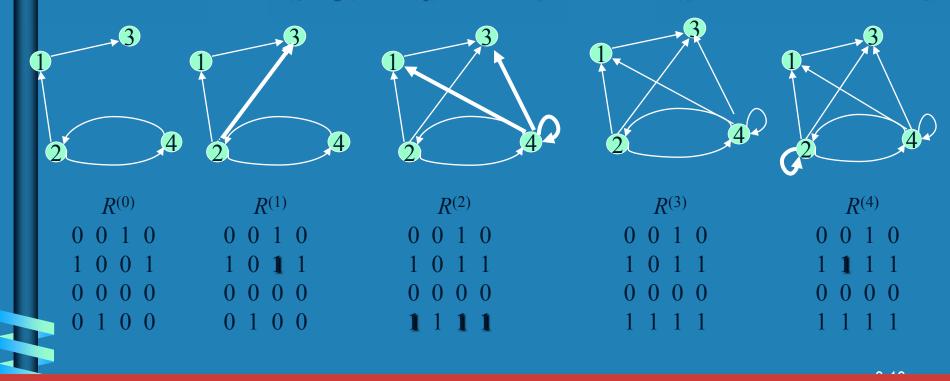
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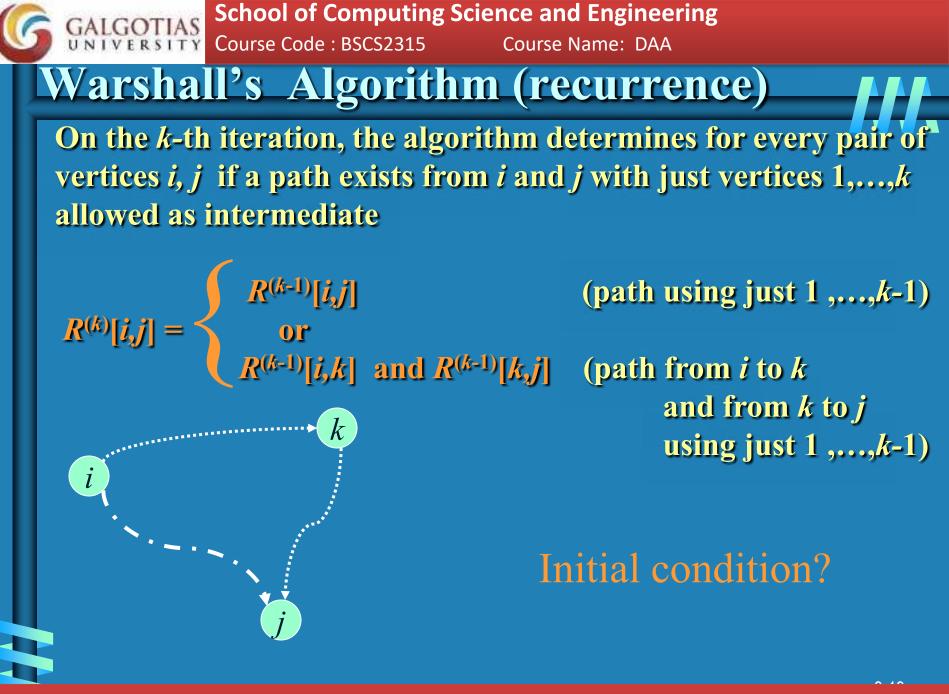


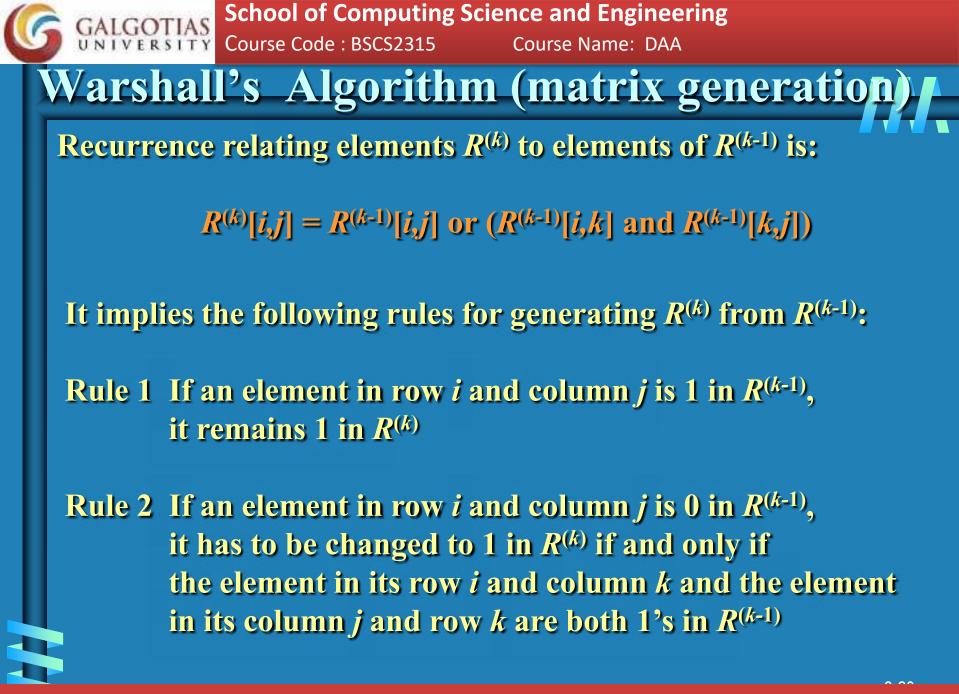
Warshall's Algorithm

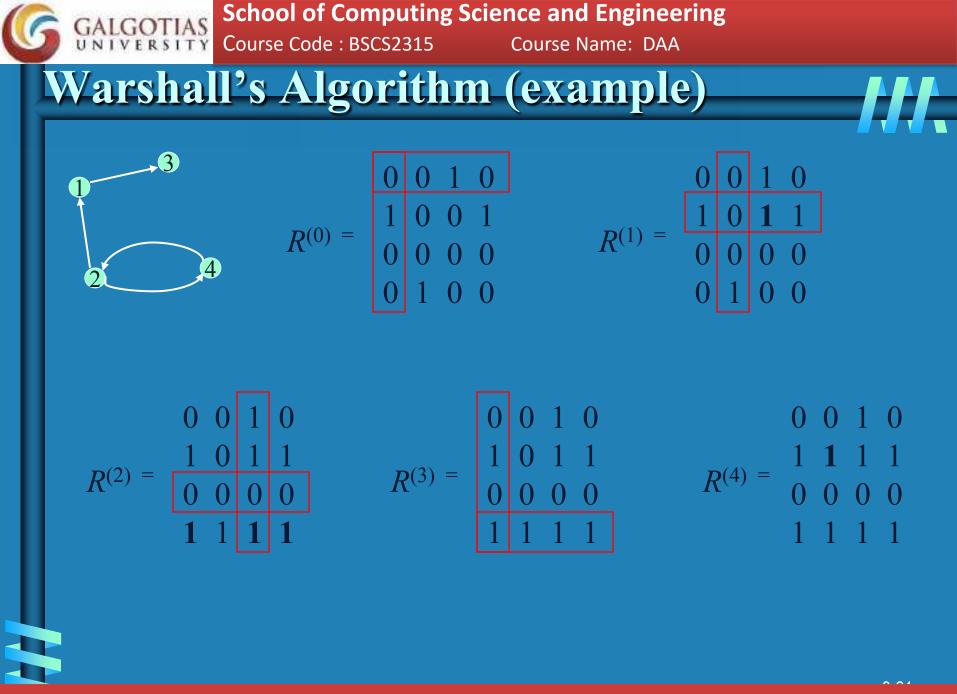
Constructs transitive closure T as the last matrix in the sequence of *n*-by-*n* matrices $R^{(0)}, \ldots, R^{(k)}, \ldots, R^{(n)}$ where $R^{(k)}[i,j] = 1$ iff there is nontrivial path from *i* to *j* with only the first *k* vertices allowed as intermediate Note that $R^{(0)} = A$ (adjacency matrix), $R^{(n)} = T$ (transitive closure)

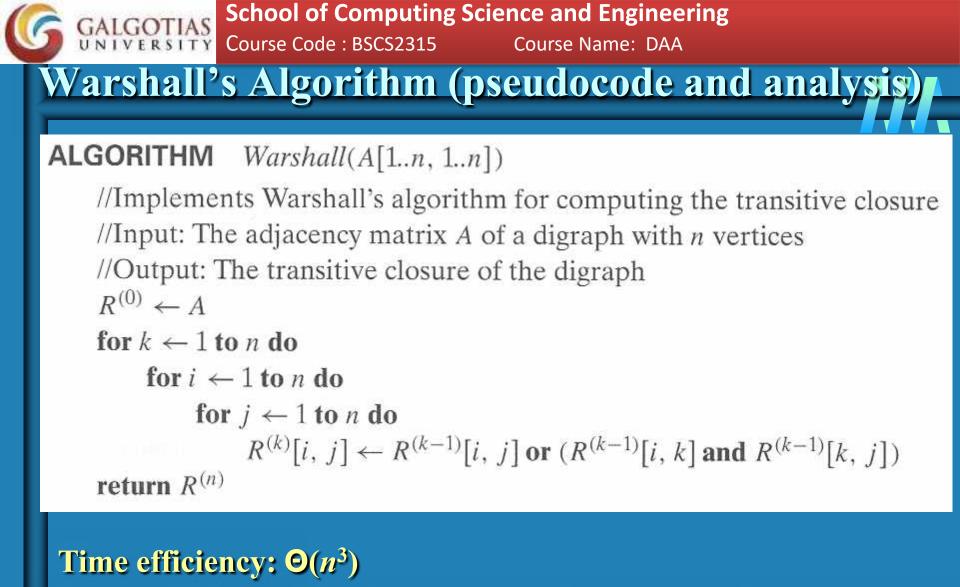


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Space efficiency: Matrices can be written over their predecessors (with some care), so it's $\Theta(n^2)$.

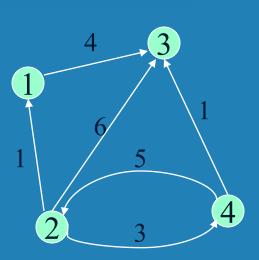
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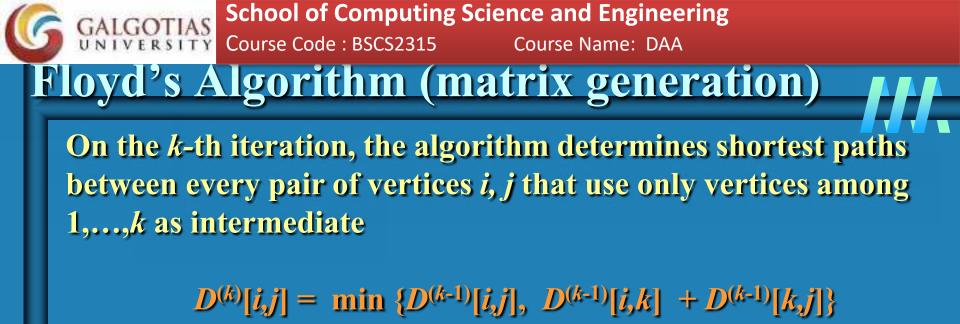


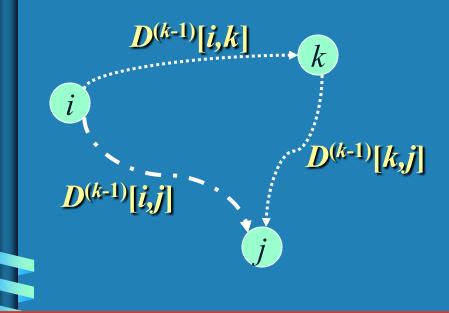
Floyd's Algorithm: All pairs shortest paths Problem: In a weighted (di)graph, find shortest paths between every pair of vertices

Same idea: construct solution through series of matrices $D^{(0)}$, ..., $D^{(n)}$ using increasing subsets of the vertices allowed as intermediate

Example:

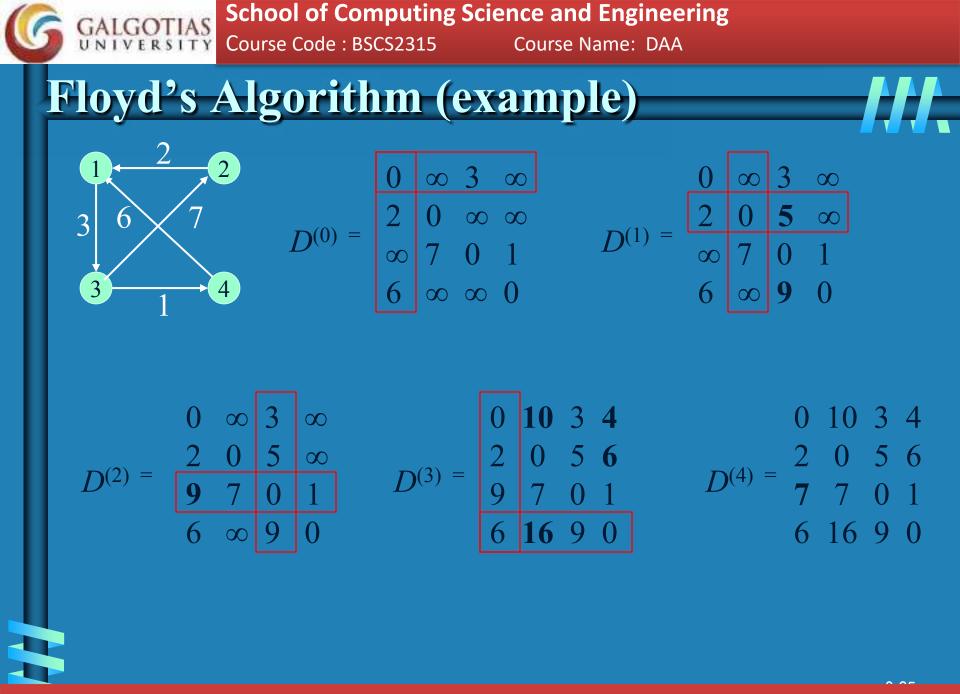






Initial condition?

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Floyd's Algorithm (pseudocode and analysis)

ALGORITHM Floyd(W[1..n, 1..n])

//Implements Floyd's algorithm for the all-pairs shortest-paths problem //Input: The weight matrix W of a graph with no negative-length cycle //Output: The distance matrix of the shortest paths' lengths $D \leftarrow W$ //is not necessary if W can be overwritten for $k \leftarrow 1$ to n do for $i \leftarrow 1$ to n do $for i \leftarrow 1$ to n do $D[i, j] \leftarrow \min\{D[i, j], D[i, k] + D[k, j]\}$ return D If D[i,k] + D[k,j] < D[i,j] then $P[i,j] \leftarrow k$

Time efficiency: $\Theta(n^3)$ Since the superscripts k or k-1 make
no difference to D[i,k] and D[k,j].Space efficiency: Matrices can be written over their predecessorsNote: Works on graphs with negative edges but without negative cycles.Shortest paths themselves can be found, too. How?

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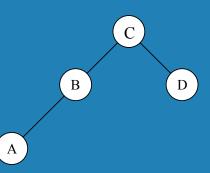
Optimal Binary Search Trees



Problem: Given *n* keys $a_1 < ... < a_n$ and probabilities $p_1, ..., p_n$ searching for them, find a BST with a minimum average number of comparisons in successful search.

Since total number of BSTs with *n* nodes is given by C(2n,n)/(n+1), which grows exponentially, brute force is hopeless.

Example: What is an optimal BST for keys *A*, *B*, *C*, and *D* with search probabilities 0.1, 0.2, 0.4, and 0.3, respectively?

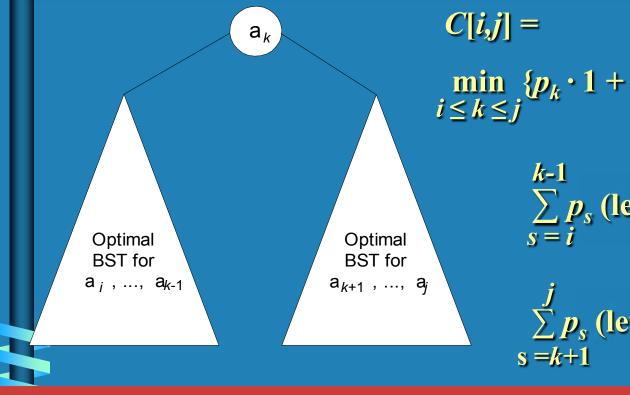


Average # of comparisons = 1*0.4 + 2*(0.2+0.3) + 3*0.1 = 1.7



DP for Optimal BST Problem

Let C[i,j] be minimum average number of comparisons made in T[i,j], optimal BST for keys $a_i < ... < a_j$, where $1 \le i \le j \le n$. Consider optimal BST among all BSTs with some a_k ($i \le k \le j$) as their root; T[i,j] is the best among them.



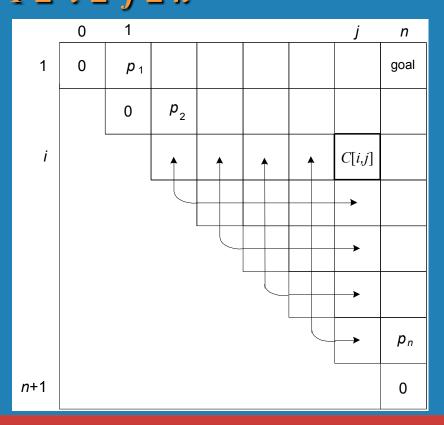
 $j^{\{p_k \cdot 1 + j\}} \sum_{s=i}^{k-1} p_s \text{ (level } a_s \text{ in } T[i,k-1] + 1\text{)} + j^{i}$

 $\sum_{k=k+1}^{j} p_s \text{ (level } a_s \text{ in } T[k+1,j]+1) \}$

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Definition DP for Optimal BST Problem (cont.) After simplifications, we obtain the recurrence for C[i,j]: $C[i,j] = \min \{C[i,k-1] + C[k+1,j]\} + \sum_{s=i}^{j} p_s \text{ for } 1 \le i \le j \le n$ $c[i,j] = p_i \text{ for } 1 \le i \le j \le n$

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Example: key

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A B C D

probability 0.1 0.2 0.4 0.3 The tables below are filled diagonal by diagonal: the left one is filled using the recurrence j $C[i,j] = \min \{C[i,k-1] + C[k+1,j]\} + \sum_{s=i}^{j} p_{s,s} C[i,i] = p_i;$ $i \le k \le j$ s = i

the right one, for trees' roots, records k's values giving the minima

j i	0	1	2	3	4	j i	0	1	2	3	4	
1	0	.1	.4	1.1	1.7	1		1	2	3	3	C
2		0	.2	.8	1.4	2			2	3	3	BD
3			0	.4	1.0	3				3	3	A
4				0	.3	4					4	optimal BST
5					0	5						

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Optimal Binary Search Trees ALGORITHM Optimal BST(P[1.n])

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//Finds an optimal binary search tree by dynamic programming //Input: An array P[1..n] of search probabilities for a sorted list of n keys //Output: Average number of comparisons in successful searches in the optimal BST and table R of subtrees' roots in the optimal BST for $i \leftarrow 1$ to n do $C[i, i-1] \leftarrow 0$ $C[i,i] \leftarrow P[i]$ $R[i,i] \leftarrow i$ $C[n+1, n] \leftarrow 0$ for $d \leftarrow 1$ to n - 1 do //diagonal count for i < -1 to n - d do $i \leftarrow i + d$ minval $\leftarrow \infty$ for $k \leftarrow i$ to j do if C[i, k-1] + C[k+1, j] < minvalminval $\leftarrow C[i, k-1] + C[k+1, j]; kmin \leftarrow k$ $R[i, j] \leftarrow kmin$ $sum \leftarrow P[i]$; for $s \leftarrow i+1$ to j do $sum \leftarrow sum + P[s]$ $C[i, j] \leftarrow minval + sum$ return C[1, n]. R

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Analysis DP for Optimal BST Problem Time efficiency: $\Theta(n^3)$ but can be reduced to $\Theta(n^2)$ by taking advantage of monotonicity of entries in the root table, i.e., R[i,j] is always in the range between R[i,j-1] and R[i+1,j]

Space efficiency: $\Theta(n^2)$

Method can be expended to include unsuccessful searches

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