Course Code : BTME3061

Course Name: FINITE ELEMENT ANALYSIS

## **Shape functions in 1D** FINITE ELEMENT ANALYSIS

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**Lecture Objective:** 

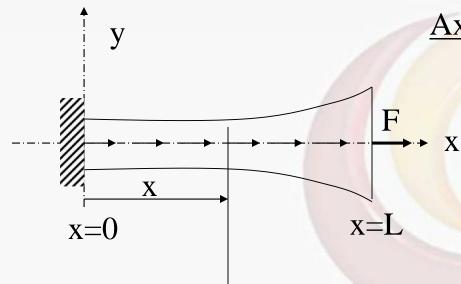
- Linear shape functions in 1D
- Quadratic and higher order shape functions
- Approximation of strains and stresses in an element

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Axially loaded elastic bar

A(x) = cross section at x
b(x) = body force distribution
(force per unit length)
E(x) = Young's modulus

**Potential energy** of the axially loaded bar corresponding to the exact solution u(x)

$$\Pi(\mathbf{u}) = \frac{1}{2} \int_0^L \mathbf{E} \mathbf{A} \left(\frac{\mathrm{d}\mathbf{u}}{\mathrm{d}\mathbf{x}}\right)^2 \mathrm{d}\mathbf{x} - \int_0^L \mathbf{b}\mathbf{u} \, \mathrm{d}\mathbf{x} - \mathbf{F}\mathbf{u}(\mathbf{x} = \mathbf{L})$$

Course Code : BTME3061

Course Name: FINITE ELEMENT ANALYSIS

Finite element formulation, takes as its starting point, not the strong formulation, but the **Principle of Minimum Potential Energy**.

Task is to find the function 'w' that minimizes the potential energy of the system

$$\Pi(w) = \frac{1}{2} \int_0^L EA\left(\frac{dw}{dx}\right)^2 dx - \int_0^L bw \, dx - Fw(x = L)$$

From the Principle of Minimum Potential Energy, that function 'w' is the exact solution.

Course Code : BTME3061

Course Name: FINITE ELEMENT ANALYSIS

## **Rayleigh-Ritz Principle**

Step 1. Assume a solution

 $w(x) = a_0 \{ {}_o(x) + a_1 \{ {}_1(x) + a_2 \{ {}_2(x) + \dots \} \}$ 

Where  $\phi_0(x)$ ,  $\phi_1(x)$ ,... are "admissible" functions and  $a_0$ ,  $a_1$ , etc are constants to be determined.

Step 2. Plug the approximate solution into the potential energy

$$\Pi(\mathbf{w}) = \frac{1}{2} \int_0^L \mathbf{E} \mathbf{A} \left(\frac{\mathrm{d}\mathbf{w}}{\mathrm{d}\mathbf{x}}\right)^2 \mathrm{d}\mathbf{x} - \int_0^L \mathbf{b}\mathbf{w} \, \mathrm{d}\mathbf{x} - \mathbf{F} \mathbf{w}(\mathbf{x} = \mathbf{L})$$

**Step 3.** Obtain the coefficients  $a_0$ ,  $a_1$ , etc by setting

$$\frac{\partial \Pi(\mathbf{w})}{\partial a_i} = 0, \quad i = 0, 1, 2, \dots$$

Course Code : BTME3061

Course Name: FINITE ELEMENT ANALYSIS

The approximate solution is

 $u(x) = a_0 \{ {}_o(x) + a_1 \{ {}_1(x) + a_2 \{ {}_2(x) + \dots \} \}$ 

Where the coefficients have been obtained from step 3

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Course Code : BTME3061

Course Name: FINITE ELEMENT ANALYSIS

Need to find a systematic way of choosing the approximation functions.

One idea: Choose polynomials!  $w(x) = a_0$  Is this good? (Is '1' an "admissible" function?)

 $w(x) = a_1 x$  Is this good? (Is 'x' an "admissible" function?)

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Course Code : BTME3061

Course Name: FINITE ELEMENT ANALYSIS

## Finite element idea:

**Step 1:** Divide the truss into **finite elements** connected to each other through special points ("nodes")<sub>2</sub>

El #1

Total potential energy=sum of potential energies of the elements

E1 #2

E1 #3

$$\Pi(\mathbf{w}) = \frac{1}{2} \int_0^L \mathbf{E} \mathbf{A} \left(\frac{\mathrm{d}\mathbf{w}}{\mathrm{d}\mathbf{x}}\right)^2 \mathrm{d}\mathbf{x} - \int_0^L \mathbf{b}\mathbf{w} \, \mathrm{d}\mathbf{x} - \mathbf{F} \mathbf{w}(\mathbf{x} = \mathbf{L})$$

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Course Name: FINITE ELEMENT ANALYSIS

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$$Total potential energy$$

$$\Pi(w) = \frac{1}{2} \int_0^L EA \left(\frac{dw}{dx}\right)^2 dx - \int_0^L bw \, dx - Fw(x = L)$$

**Potential energy of element 1:** 

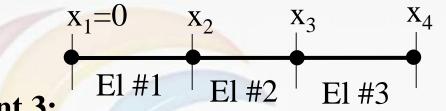
$$\Pi_{1}(w) = \frac{1}{2} \int_{x_{1}}^{x_{2}} EA\left(\frac{dw}{dx}\right)^{2} dx - \int_{x_{1}}^{x_{2}} bw dx$$

**Potential energy of element 2:** 

$$\Pi_{2}(w) = \frac{1}{2} \int_{x_{2}}^{x_{3}} EA\left(\frac{dw}{dx}\right)^{2} dx - \int_{x_{2}}^{x_{3}} bw dx$$

Course Code : BTME3061

Course Name: FINITE ELEMENT ANALYSIS



**Potential energy of element 3:** 

$$\Pi_{3}(w) = \frac{1}{2} \int_{x_{3}}^{x_{4}} EA\left(\frac{dw}{dx}\right)^{2} dx - \int_{x_{3}}^{x_{4}} bw \, dx - Fw(x = L)$$

Total potential energy=sum of potential energies of the elements

$$\Pi(w) = \Pi_1(w) + \Pi_2(w) + \Pi_3(w)$$

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Course Name: FINITE ELEMENT ANALYSIS

Step 2: Describe the behavior of each element

Recall that in the "**direct stiffness**" approach for a bar element, we derived the stiffness matrix of each element directly (See lecture on Trusses) using the following steps:

**TASK 1:** Approximate the displacement within each bar as a straight line

**TASK 2:** Approximate the strains and stresses and realize that a bar (with the approximation stated in Task 1) is exactly like a spring with k=EA/L

**TASK 3:** Use the principle of **force equilibrium** to generate the stiffness matrix

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Course Name: FINITE ELEMENT ANALYSIS

## **Questions:**

Illustrate the shape functions used for linear element.
Derive the shape function for 1 d linear element.
Illustrate the local and Global co-ordinate system

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## Text Book-

1. Finite Element Analysis by S.S bhavikatti six multicolour edition,2018.New age International publisher. ISBN: 678-26-74589-23-4.

2. A Textbook of Finite Element Analysis Formulation and Programming by D.K.mahraj,Edition 2019. Publisher Willey India ISBN : 978-93-88425-93-3.

## **Reference Book-**

1. Finite element analysis ,Theory and application with Ansys by Moaveni ,2nd edition 2015 ,publisher Pearson, ISBN- 528-43-88435-9.

2. Finite element Analysis By David V. Hutton ,Publisher Elizabeth A. Jomes ,4th edition 2017. ISBN: 0-07-23-9536-2

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Course Code : BTME3061

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## **THANK YOU**

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