

**A Project/Dissertation ETE Report**  
**ON**  
**Mask Recognition Technology Using AI/ML**

*Submitted in partial fulfillment of the  
requirement for the award of the degree  
of*

**B.Tech. (CSE)**



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**CANDIDATE'S DECLARATION**

I/We hereby certify that the work which is being presented in the project, entitled “**Mask Recognition Technology Using AI/ML** ” in partial fulfillment of the requirements for the award of the BACHELOR OF TECHNOLOGY IN COMPUTER SCIENCE AND ENGINEERING submitted in the School of Computing Science and Engineering of Galgotias University, Greater Noida, is an original work carried out during the period of JULY-2021 to DECEMBER-2021, under the supervision of Dr.Vipin Rai, Associate Professor, Department of Computer Science and Engineering of School of Computing Science and Engineering , Galgotias University, Greater Noida

The matter presented in the project has not been submitted by me/us for the award of any other degree of this or any other places.

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This is to certify that the above statement made by the candidates is correct to the best of my knowledge.

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**CERTIFICATE**

The Final Thesis/Project/ Dissertation Viva-Voce examination of **18SCSE1010177 - Ayush Bhatt**,**18SCSE1010240- Ankur Bhatnagar** has been held on \_\_\_\_\_ and his/her work is recommended for the award of **BACHELOR OF TECHNOLOGY IN COMPUTER SCIENCE AND ENGINEERING.**

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**Signature of Supervisor(s)**

**Signature of Project Coordinator**

**Signature of Dean**

**Date:**

**Place:**

## **Abstract**

COVID-19 pandemic has rapidly affected our day-to-day life disrupting world trade and movements. Wearing a protective face mask has become a new normal. In the near future, many public service providers will ask the customers to wear masks correctly to avail of their services. Therefore, face mask detection has become a crucial task to help global society. This paper presents a simplified approach to achieve this purpose using some basic Machine Learning packages like TensorFlow, Keras, OpenCV . The proposed method detects the face from the image correctly and then identifies if it has a mask on it or not. As a surveillance task performer, it can also detect a face along with a mask in motion. The method attains accuracy up to 95.77% and 94.58% respectively on two different datasets. We explore optimized values of parameters using the Sequential Convolutional Neural Network model to detect the presence of masks correctly without causing over-fitting.

In this work, a deep learning-based approach for detecting masks over faces in public places to curtail the community spread of Coronavirus is presented. The proposed technique efficiently handles occlusions in dense situations by making use of an ensemble of single and two-stage detectors at the pre-processing level. The ensemble approach not only helps in achieving high accuracy but also improves detection speed considerably. Furthermore, the application of transfer learning on pre-trained models with extensive experimentation over an unbiased dataset resulted in a highly robust and low-cost system. The identity detection of faces, violating the mask norms further, increases the utility of the system for public benefits.

Finally, the work opens interesting future directions for researchers. Firstly, the proposed technique can be integrated into any high-resolution video surveillance devices and not limited to mask detection only. Secondly, the model can be extended to detect facial landmarks with a facemask for biometric purposes.

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## Chapter-1 Introduction

According to the World Health Organization (WHO) official Status Report - 205, coronavirus 2019 (COVID-19) has infected more than 20 million people worldwide causing more than 0.7 million deaths. People with COVID-19 had a number of reported symptoms - ranging from mild to severe illness. Respiratory problems such as shortness of breath or difficulty breathing are one of them. Adults with pneumonia may be more prone to COVID-19 complications as they appear to be at higher risk. Other common human coronaviruses that infect humans worldwide are 229E, HKU1, OC43, and NL63. Prior to the demise of humans, viruses such as the 2019-nCoV, SARS-CoV, and MERS-CoV infect animals and turn them into human coronaviruses. People with respiratory problems can expose anyone (close to them) to a contagious bead. Circumcision of an infected person can cause transmission of communication as droplets carrying the virus may reach its immediate vicinity.

To prevent certain respiratory infections, including COVID-19, wearing a clinical mask is very necessary. The public should be aware that you must wear a mask to control the source or dislike COVID-19. Points that may be of interest to the use of masks are to reduce the risk of injury from a dangerous person during the "pre-symptomatic period" and to discriminate against sophisticated people who wear a mask to prevent the spread of the virus. The WHO emphasizes the prioritization of medical masks and respirators for health care Associates. Therefore, the discovery of a face mask has become an important activity in today's world society.

Finding a face mask involves finding the location of the face and finding out if it has a mask on it or not. The problem is with the acquisition of a common object to determine the categories of objects. Phase identification is associated with the division of a particular business group namely Face. It has many applications, such as automatic driving, education, surveillance, and more . This paper introduces a simplified way to achieve the above goal using basic Machine Learning (ML) packages such as TensorFlow, Keras, OpenCV and Scikit-Learn.



## **Chapter-2 Literature Survey**

**1: MAMATA S. KALAS, REAL TIME FACE DETECTION AND TRACKING USING OPENCV, International Journal of Soft Computing and Artificial Intelligence, ISSN: 2321-404X, Volume-2, Issue-1, May- 2014**

Haar- like feature: Haar-like wavelets are binary rectangular representations of 2D waves. A common visual representation is by black (for value minus one) and white (for value plus one) rectangles. The square above the 0-1- interval shows the corresponding Haar-like wavelet in common black-white representation. The rectangular masks used for visual object detection are rectangles tessellated by black and white smaller rectangles. Those masks are designed in correlation to visual recognition tasks to be solved, and known as a Haar-like feature each call, a distribution of weights is updated that indicates the importance of examples in the data set for the classification. On each round, the weights of each incorrectly classified example are increased, and the weights of each correctly classified example are decreased, so the new classifier focuses on the examples which have so far eluded correct classification.

**2:Walid Hariri, Efficient Masked Face Recognition Method during the COVID-19 Pandemic, pp.1-7, July 2020**

Pre-processing and cropping filter: The images of the dataset are already cropped around the face, so there is no need for a face detection stage to localize the face from each image. To do so, we detect 68 facial landmarks using Dlib-ml open- source library. According to the eyes location, we apply a 2D rotation to make them horizontal. The next step is to apply a cropping filter in order to extract only the non- masked region. To do so, we firstly normalize all face images into 240 x 240 pixels. Next, we use the partition into blocks. The principle of this technique is to divide the image into 100 fixed-size square blocks (24 x 24 pixels in our case). Then we extract only the blocks including the non-masked region (blocks from number 1 to 50). Finally, we eliminate the rest of the numbers of the blocks.

**3:Vinitha.V1, Valentina.V2, COVID-19 FACEMASK DETECTION WITH DEEP LEARNING AND COMPUTER VISION, International Research Journal of Engineering and Technology (IRJET), Volume: 07, pp.1-6, Aug 2020.**

The proposed system focuses on how to identify the person on an image/video stream wearing a face mask with the help of computer vision and deep learning algorithms by using the OpenCV, Tensor flow, Keras and PyTorch libraries. The majority of the images were augmented by OpenCV. The set of images were already labeled mask and no mask.

The images that were present were of different sizes and resolutions, probably extracted from different sources or from machines (cameras) of different resolutions.

**4: S. Ghosh, N. Das and M. Nasipuri, "Reshaping inputs for convolutional neural network: Some common and uncommon methods", *Pattern Recognition*, vol. 93, pp. 79-94, 2019.**

convolutional neural network (CNNs) in computer vision comes with a strict constraint regarding the size of the input image. The prevalent practice reconfigures the images before fitting them into the network to surmount the inhibition.

Here the main challenge of the task is to detect the face from the image correctly and then identify if it has a mask on it or not. In order to perform surveillance tasks, the proposed method should also detect a face along with a mask in motion.

## **Tools Used**

### **A. TensorFlow**

TensorFlow, an interface for expressing machine learning algorithms, is utilized for implementing ML systems into fabrication over a bunch of areas of computer science, including sentiment analysis, voice recognition, geographic information extraction, computer vision, text summarization, information retrieval, computational drug discovery and flaw detection to pursue research . In the proposed model, the whole Sequential CNN architecture (consists of several layers) uses TensorFlow at backend. It is also used to reshape the data (image) in the data processing.

### **B. Keras**

Keras gives fundamental reflections and building units for creation and transportation of ML arrangements with high iteration velocity. It takes full advantage of the scalability and cross-platform capabilities of TensorFlow. The core data structures of Keras are layers and models . All the layers used in the CNN model are implemented using Keras. Along with the conversion of the class vector to the binary class matrix in data processing, it helps to compile the overall model.

### **C. OpenCV**

OpenCV (Open Source Computer Vision Library), an open-source computer vision and ML software library, is utilized to differentiate and recognize faces, recognize objects, group movements in recordings, trace progressive modules, follow eye gesture, track camera actions, expel red eyes from pictures taken utilizing flash, find comparative pictures from an image database, perceive landscape and set up markers to overlay it with increased reality and so forth . The proposed method makes use of these features of OpenCV in resizing and color conversion of data images.

## DataSet

Two data sets were used to check the current method. Dataset 1 has 1376 photos with 690 photos of people wearing face masks and another 686 photos of people without wearing face masks. Figure 1 usually consists of the shape of the front face and one face without a mask.

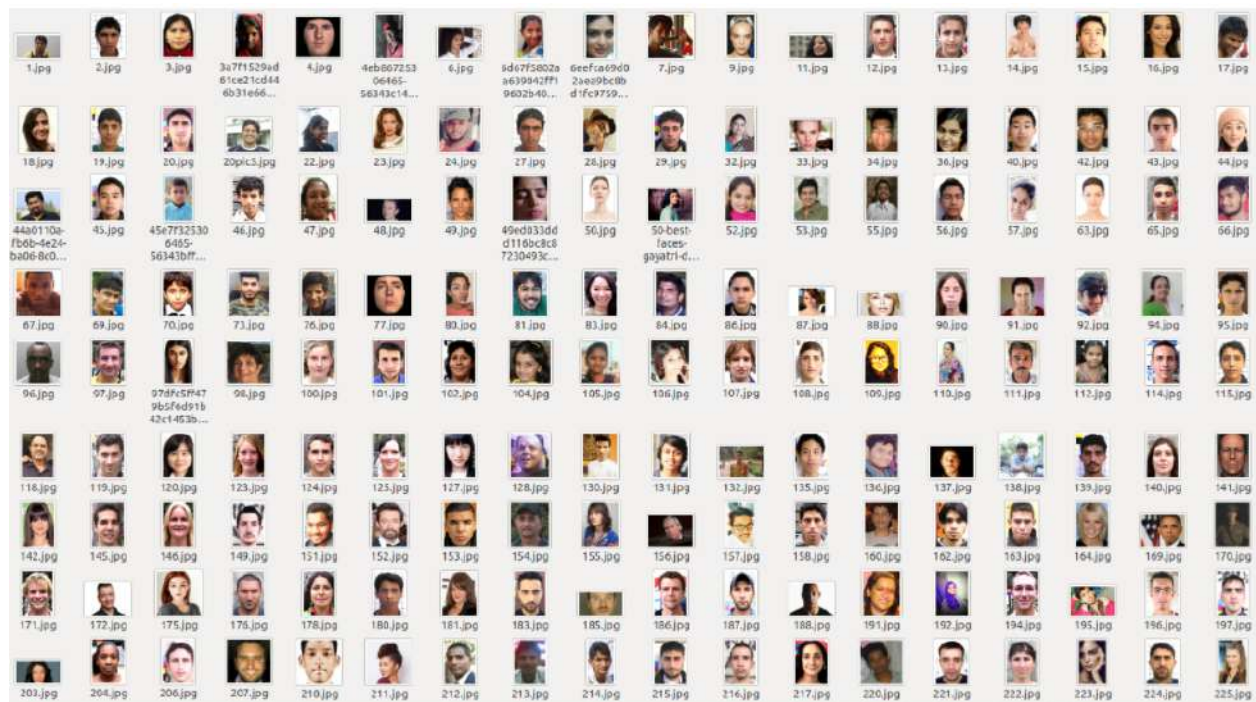


Fig 1

Dataset 2 from Kaggle contains 853 images and its contents are highlighted with or without a mask. On the figure 2 Other face masks are head turns, tilt and tilt with multiple faces on the frame and different types of masks with different colors as well.

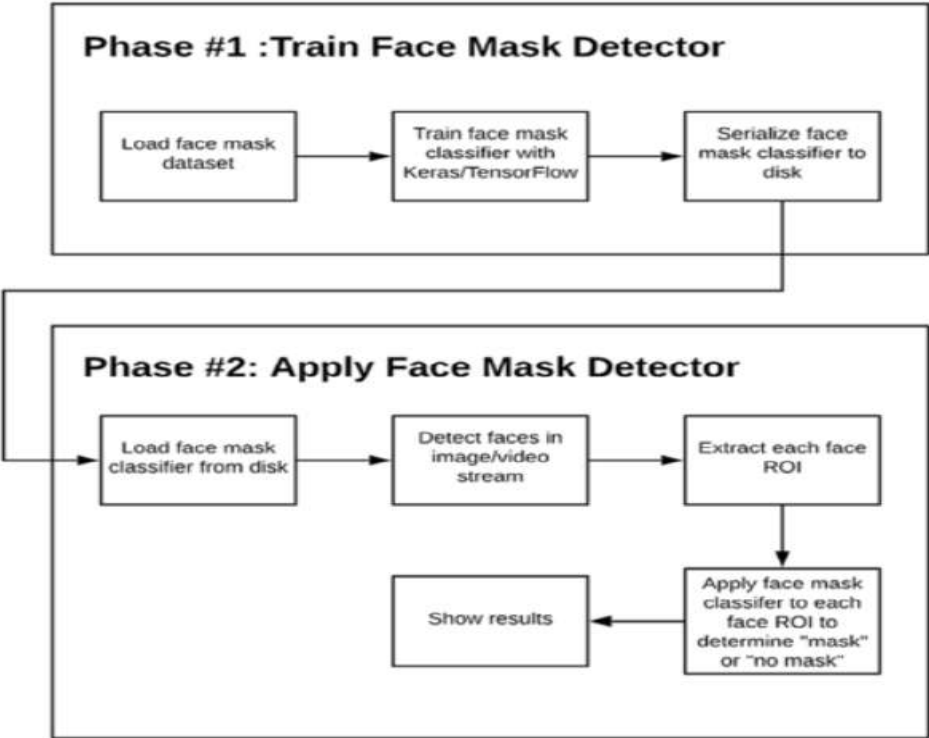


Fig 2

# Project Methodology

In order to train a custom face mask detector, we need to break our project into two distinct phases, each with its own respective sub-steps (as shown by Figure 1 below):

- Training: Here we'll focus on loading our face mask detection dataset from disk, training a model (using Keras/TensorFlow) on this dataset, and then serializing the face mask detector to disk
- Deployment: Once the face mask detector is trained, we can then move on to loading the mask detector, performing face detection, and then classifying each face as with\_mask or without\_mask



We'll review each of these phases and associated subsets in detail in the remainder of this tutorial, but in the meantime, let's take a look at the dataset we'll be using to train our COVID-19 face mask recogniser.

Our dataset consists of 1,376 images belonging to two classes:

- with\_mask: 690 images
- without\_mask: 686 images

Our goal is to train a custom deep learning model to detect whether a person is or is not wearing a mask.

## Project Structure

```
1. | $ tree --dirsfirst --filelimit 10
2. | .
3. | ├── dataset
4. | |   ├── with_mask [690 entries]
5. | |   └── without_mask [686 entries]
6. | ├── examples
7. | |   ├── example_01.png
8. | |   ├── example_02.png
9. | |   └── example_03.png
10. | ├── face_detector
11. | |   ├── deploy.prototxt
12. | |   └── res10_300x300_ssd_iter_140000.caffemodel
13. | ├── detect_mask_image.py
14. | ├── detect_mask_video.py
15. | ├── mask_detector.model
16. | ├── plot.png
17. | └── train_mask_detector.py
18. |
19. | 5 directories, 10 files
```

The dataset/ directory contains the data described in the “Our COVID-19 face mask detection dataset” section.

Three image examples/ are provided so that you can test the static image face mask detector.

We’ll be reviewing three Python scripts in this:

`train_mask_detector.py`: Accepts our input dataset and fine-tunes MobileNetV2 upon it to create our `mask_detector.model`. A training history `plot.png` containing accuracy/loss curves is also produced  
`detect_mask_image.py`: Performs face mask detection in static images  
`detect_mask_video.py`: Using your webcam, this script applies face mask detection to every frame in the stream



In the next two sections, we will train our face mask detector.

## Implementing our COVID-19 face mask detector training script with Keras and TensorFlow

Now that we've reviewed our face mask dataset, let's learn how we can use Keras and TensorFlow to train a classifier to automatically detect whether a person is wearing a mask or not.

To accomplish this task, we'll be fine-tuning the MobileNet V2 architecture, a highly efficient architecture that can be applied to embedded devices with limited computational capacity (ex., Raspberry Pi, Google Coral, NVIDIA Jetson Nano, etc.).

Deploying our face mask detector to embedded devices could reduce the cost of manufacturing such face mask detection systems, hence why we choose to use this architecture.

```
1. | # import the necessary packages
2. | from tensorflow.keras.preprocessing.image import ImageDataGenerator
3. | from tensorflow.keras.applications import MobileNetV2
4. | from tensorflow.keras.layers import AveragePooling2D
5. | from tensorflow.keras.layers import Dropout
6. | from tensorflow.keras.layers import Flatten
7. | from tensorflow.keras.layers import Dense
8. | from tensorflow.keras.layers import Input
9. | from tensorflow.keras.models import Model
10. | from tensorflow.keras.optimizers import Adam
11. | from tensorflow.keras.applications.mobilenet_v2 import preprocess_input
12. | from tensorflow.keras.preprocessing.image import img_to_array
13. | from tensorflow.keras.preprocessing.image import load_img
14. | from tensorflow.keras.utils import to_categorical
15. | from sklearn.preprocessing import LabelBinarizer
16. | from sklearn.model_selection import train_test_split
17. | from sklearn.metrics import classification_report
18. | from imutils import paths
19. | import matplotlib.pyplot as plt
20. | import numpy as np
21. | import argparse
22. | import os
```

Our set of tensorflow.keras imports allow for:

- Data augmentation
- Loading the MobilNetV2 classifier (we will fine-tune this model with pre-trained ImageNet weights)
- Building a new fully-connected (FC) head
- Pre-processing
- Loading image data

We'll use scikit-learn (sklearn) for binarizing class labels, segmenting our dataset, and printing a classification report.

My imutils paths implementation will help us to find and list images in our dataset. And we'll use matplotlib to plot our training curves.

```
24. | # construct the argument parser and parse the arguments
25. | ap = argparse.ArgumentParser()
26. | ap.add_argument("-d", "--dataset", required=True,
27. |               help="path to input dataset")
28. | ap.add_argument("-p", "--plot", type=str, default="plot.png",
29. |               help="path to output loss/accuracy plot")
30. | ap.add_argument("-m", "--model", type=str,
31. |               default="mask_detector.model",
32. |               help="path to output face mask detector model")
33. | args = vars(ap.parse_args())
```

Our command line arguments include:

--dataset: The path to the input dataset of faces and faces with masks

--plot: The path to your output training history plot, which will be generated using matplotlib

--model: The path to the resulting serialized face mask classification model

I like to define my deep learning hyperparameters in one place:

```
35. | # initialize the initial learning rate, number of epochs to train for,  
36. | # and batch size  
37. | INIT_LR = 1e-4  
38. | EPOCHS = 20  
39. | BS = 32
```

Here, I've specified hyperparameter constants including my initial learning rate, number of training epochs, and batch size. Later, we will be applying a learning rate decay schedule, which is why we've named the learning rate variable `INIT_LR`.

At this point, we're ready to load and pre-process our training data:

```
41. | # grab the list of images in our dataset directory, then initialize  
42. | # the list of data (i.e., images) and class images  
43. | print("[INFO] loading images...")  
44. | imagePath = list(paths.list_images(args["dataset"]))  
45. | data = []  
46. | labels = []  
47. |  
48. | # loop over the image paths  
49. | for imagePath in imagePath:  
50. |     # extract the class label from the filename  
51. |     label = imagePath.split(os.path.sep)[-2]  
52. |  
53. |     # load the input image (224x224) and preprocess it  
54. |     image = load_img(imagePath, target_size=(224, 224))  
55. |     image = img_to_array(image)  
56. |     image = preprocess_input(image)  
57. |  
58. |     # update the data and labels lists, respectively  
59. |     data.append(image)  
60. |     labels.append(label)  
61. |  
62. | # convert the data and labels to NumPy arrays  
63. | data = np.array(data, dtype="float32")  
64. | labels = np.array(labels)
```

In this block, we are:

- Grabbing all of the imagePaths in the dataset (Line 44)
- Initializing data and labels lists (Lines 45 and 46)
- Looping over the imagePaths and loading + pre-processing images (Lines 49-60). Pre-processing steps include resizing to 224×224 pixels, conversion to array format, and scaling the pixel intensities in the input image to the range [-1, 1] (via the preprocess\_input convenience function)
- Appending the pre-processed image and associated label to the data and labels lists, respectively (Lines 59 and 60)
- Ensuring our training data is in NumPy array format (Lines 63 and 64)

The above lines of code assume that your entire dataset is small enough to fit into memory. If your dataset is larger than the memory you have available, I suggest using HDF5

Our data preparation work isn't done yet. Next, we'll encode our labels, partition our dataset, and prepare for data augmentation:

```
66. | # perform one-hot encoding on the labels
67. | lb = LabelBinarizer()
68. | labels = lb.fit_transform(labels)
69. | labels = to_categorical(labels)
70. |
71. | # partition the data into training and testing splits using 80% of
72. | # the data for training and the remaining 20% for testing
73. | (trainX, testX, trainY, testY) = train_test_split(data, labels,
74. |         test_size=0.20, stratify=labels, random_state=42)
75. |
76. | # construct the training image generator for data augmentation
77. | aug = ImageDataGenerator(
78. |     rotation_range=20,
79. |     zoom_range=0.15,
80. |     width_shift_range=0.2,
81. |     height_shift_range=0.2,
82. |     shear_range=0.15,
83. |     horizontal_flip=True,
84. |     fill_mode="nearest")
```

Lines 67-69 one-hot encode our class labels, meaning that our data will be in the following format:

```
1. $ python train_mask_detector.py --dataset dataset
2. [INFO] loading images...
3. -> (trainX, testX, trainY, testY) = train_test_split(data, labels,
4. (Pdb) labels[500:]
5. array([[1., 0.],
6.        [1., 0.],
7.        [1., 0.],
8.        ...,
9.        [0., 1.],
10.       [0., 1.],
11.       [0., 1.]], dtype=float32)
12. (Pdb)
```

As you can see, each element of our labels array consists of an array in which only one index is “hot” (i.e., 1).

Using scikit-learn’s convenience method, Lines 73 and 74 segment our data into 80% training and the remaining 20% for testing.

During training, we’ll be applying on-the-fly mutations to our images in an effort to improve generalization. This is known as data augmentation, where the random rotation, zoom, shear, shift, and flip parameters are established on Lines 77-84. We’ll use the aug object at training time.

But first, we need to prepare MobileNetV2 for fine-tuning:

```
86. # load the MobileNetV2 network, ensuring the head FC layer sets are
87. # left off
88. baseModel = MobileNetV2(weights="imagenet", include_top=False,
89.   input_tensor=Input(shape=(224, 224, 3)))
90.
91. # construct the head of the model that will be placed on top of the
92. # the base model
93. headModel = baseModel.output
94. headModel = AveragePooling2D(pool_size=(7, 7))(headModel)
95. headModel = Flatten(name="flatten")(headModel)
96. headModel = Dense(128, activation="relu")(headModel)
97. headModel = Dropout(0.5)(headModel)
98. headModel = Dense(2, activation="softmax")(headModel)
99.
100. # place the head FC model on top of the base model (this will become
101. # the actual model we will train)
102. model = Model(inputs=baseModel.input, outputs=headModel)
103.
104. # loop over all layers in the base model and freeze them so they will
105. # *not* be updated during the first training process
106. for layer in baseModel.layers:
107.     layer.trainable = False
```

Fine-tuning setup is a three-step process:

- Load MobileNet with pre-trained ImageNet weights, leaving off head of network (Lines 88 and 89)
- Construct a new FC head, and append it to the base in place of the old head (Lines 93-102)
- Freeze the base layers of the network (Lines 106 and 107). The weights of these base layers will not be updated during the process of backpropagation, whereas the head layer weights will be tuned.

Fine-tuning is a strategy I nearly always recommend to establish a baseline model while saving considerable time.

With our data prepared and model architecture in place for fine-tuning, we're now ready to compile and train our face mask detector network:

```
109. # compile our model
110. print("[INFO] compiling model...")
111. opt = Adam(lr=INIT_LR, decay=INIT_LR / EPOCHS)
112. model.compile(loss="binary_crossentropy", optimizer=opt,
113.               metrics=["accuracy"])
114.
115. # train the head of the network
116. print("[INFO] training head...")
117. H = model.fit(
118.     aug.flow(trainX, trainY, batch_size=BS),
119.     steps_per_epoch=len(trainX) // BS,
120.     validation_data=(testX, testY),
121.     validation_steps=len(testX) // BS,
122.     epochs=EPOCHS)
```

Lines 111-113 compile our model with the Adam optimizer, a learning rate decay schedule, and binary cross-entropy. If you're building from this training script with  $> 2$  classes, be sure to use categorical cross-entropy.

Face mask training is launched via Lines 117-122. Notice how our data augmentation object (aug) will be providing batches of mutated image data.

Once training is complete, we'll evaluate the resulting model on the test set:

```
124. | # make predictions on the testing set
125. | print("[INFO] evaluating network...")
126. | predIdxs = model.predict(testX, batch_size=BS)
127. |
128. | # for each image in the testing set we need to find the index of the
129. | # label with corresponding largest predicted probability
130. | predIdxs = np.argmax(predIdxs, axis=1)
131. |
132. | # show a nicely formatted classification report
133. | print(classification_report(testY.argmax(axis=1), predIdxs,
134. |     target_names=lb.classes_))
135. |
136. | # serialize the model to disk
137. | print("[INFO] saving mask detector model...")
138. | model.save(args["model"], save_format="h5")
```

Here, Lines 126-130 make predictions on the test set, grabbing the highest probability class label indices. Then, we print a classification report in the terminal for inspection.

Line 138 serializes our face mask classification model to disk.

Our last step is to plot our accuracy and loss curves:

```
140. | # plot the training loss and accuracy
141. | N = EPOCHS
142. | plt.style.use("ggplot")
143. | plt.figure()
144. | plt.plot(np.arange(0, N), H.history["loss"], label="train_loss")
145. | plt.plot(np.arange(0, N), H.history["val_loss"], label="val_loss")
146. | plt.plot(np.arange(0, N), H.history["accuracy"], label="train_acc")
147. | plt.plot(np.arange(0, N), H.history["val_accuracy"], label="val_acc")
148. | plt.title("Training Loss and Accuracy")
149. | plt.xlabel("Epoch #")
150. | plt.ylabel("Loss/Accuracy")
151. | plt.legend(loc="lower left")
152. | plt.savefig(args["plot"])
```

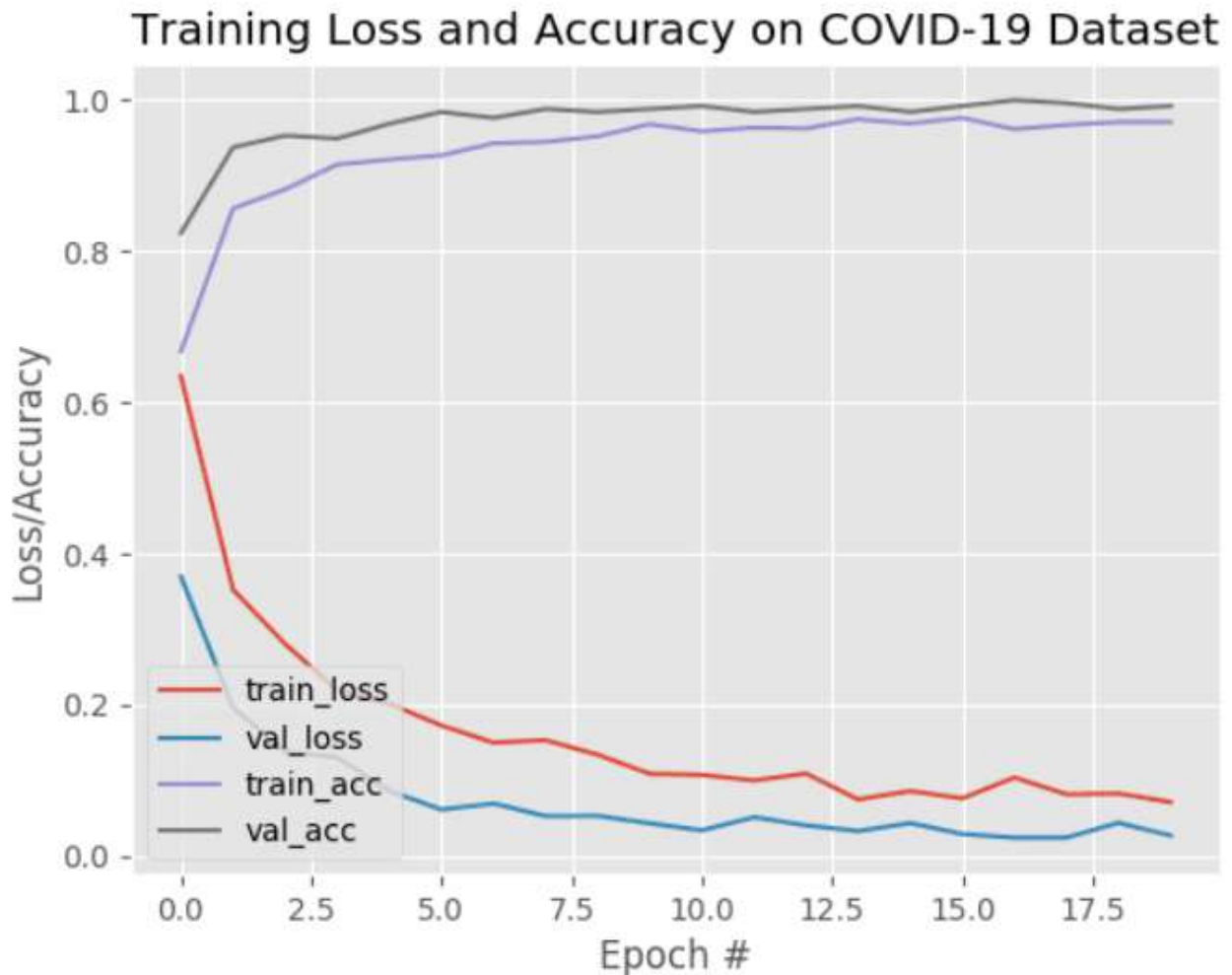


## Training the COVID-19 face mask detector with Keras/TensorFlow

We are now ready to train our face mask detector using Keras, TensorFlow, and Deep Learning.

From there, open up a terminal, and execute the following command:

```
1. $ python train_mask_detector.py --dataset dataset
2. [INFO] loading images...
3. [INFO] compiling model...
4. [INFO] training head...
5. Train for 34 steps, validate on 276 samples
6. Epoch 1/20
7. 34/34 [=====] - 30s 885ms/step - loss: 0.6431 - accuracy: 0.6676 -
   val_loss: 0.3696 - val_accuracy: 0.8242
8. Epoch 2/20
9. 34/34 [=====] - 29s 853ms/step - loss: 0.3507 - accuracy: 0.8567 -
   val_loss: 0.1964 - val_accuracy: 0.9375
10. Epoch 3/20
11. 34/34 [=====] - 27s 800ms/step - loss: 0.2792 - accuracy: 0.8820 -
   val_loss: 0.1383 - val_accuracy: 0.9531
12. Epoch 4/20
13. 34/34 [=====] - 28s 814ms/step - loss: 0.2196 - accuracy: 0.9148 -
   val_loss: 0.1306 - val_accuracy: 0.9492
14. Epoch 5/20
15. 34/34 [=====] - 27s 792ms/step - loss: 0.2006 - accuracy: 0.9213 -
   val_loss: 0.0863 - val_accuracy: 0.9688
16. ...
17. Epoch 16/20
18. 34/34 [=====] - 27s 801ms/step - loss: 0.0767 - accuracy: 0.9766 -
   val_loss: 0.0291 - val_accuracy: 0.9922
19. Epoch 17/20
20. 34/34 [=====] - 27s 795ms/step - loss: 0.1042 - accuracy: 0.9616 -
   val_loss: 0.0243 - val_accuracy: 1.0000
21. Epoch 18/20
22. 34/34 [=====] - 27s 796ms/step - loss: 0.0804 - accuracy: 0.9672 -
   val_loss: 0.0244 - val_accuracy: 0.9961
23. Epoch 19/20
24. 34/34 [=====] - 27s 793ms/step - loss: 0.0836 - accuracy: 0.9710 -
   val_loss: 0.0440 - val_accuracy: 0.9883
25. Epoch 20/20
26. 34/34 [=====] - 28s 838ms/step - loss: 0.0717 - accuracy: 0.9710 -
   val_loss: 0.0270 - val_accuracy: 0.9922
27. [INFO] evaluating network...
28.           precision    recall  f1-score   support
29.
30.   with_mask           0.99         1.00         0.99         138
31.  without_mask           1.00         0.99         0.99         138
32.
33.   accuracy                           0.99         276
34.   macro avg           0.99         0.99         0.99         276
35.   weighted avg           0.99         0.99         0.99         276
```



**Fig. COVID-19 face mask detector training accuracy/loss curves demonstrate high accuracy and little signs of overfitting on the data. We're now ready to apply our knowledge of computer vision and deep learning using Python, OpenCV, and TensorFlow/Keras to perform face mask detection.**

As you can see, we are obtaining ~99% accuracy on our test set.

Looking at Figure 10, we can see there are little signs of overfitting, with the validation loss lower than the training loss.

Given these results, we are hopeful that our model will generalize well to images outside our training and testing set.

## Implementing our COVID-19 face mask detector for images with OpenCV

Now that our face mask detector is trained, let's learn how we can:

- Load an input image from disk
- Detect faces in the image
- Apply our face mask detector to classify the face as either with\_mask or without\_mask

Open up the detect\_mask\_image.py file in your directory structure, and let's get started:

```
1. # import the necessary packages
2. from tensorflow.keras.applications.mobilenet_v2 import preprocess_input
3. from tensorflow.keras.preprocessing.image import img_to_array
4. from tensorflow.keras.models import load_model
5. import numpy as np
6. import argparse
7. import cv2
8. import os
```

Our driver script requires three TensorFlow/Keras imports to (1) load our MaskNet model and (2) pre-process the input image.

OpenCV is required for display and image manipulations.

The next step is to parse command line arguments:

```
10. # construct the argument parser and parse the arguments
11. ap = argparse.ArgumentParser()
12. ap.add_argument("-i", "--image", required=True,
13.               help="path to input image")
14. ap.add_argument("-f", "--face", type=str,
15.               default="face_detector",
16.               help="path to face detector model directory")
17. ap.add_argument("-m", "--model", type=str,
18.               default="mask_detector.model",
19.               help="path to trained face mask detector model")
20. ap.add_argument("-c", "--confidence", type=float, default=0.5,
21.               help="minimum probability to filter weak detections")
22. args = vars(ap.parse_args())
```

Our four command line arguments include:

- `--image`: The path to the input image containing faces for inference
- `--face`: The path to the face detector model directory (we need to localize faces prior to classifying them)
- `--model`: The path to the face mask detector model that we trained earlier in this tutorial
- `--confidence`: An optional probability threshold can be set to override 50% to filter weak face detections

Next, we'll load both our face detector and face mask classifier models:

```
24. # load our serialized face detector model from disk
25. print("[INFO] loading face detector model...")
26. prototxtPath = os.path.sep.join([args["face"], "deploy.prototxt"])
27. weightsPath = os.path.sep.join([args["face"],
28.     "res10_300x300_ssd_iter_140000.caffemodel"])
29. net = cv2.dnn.readNet(prototxtPath, weightsPath)
30.
31. # load the face mask detector model from disk
32. print("[INFO] loading face mask detector model...")
33. model = load_model(args["model"])
```

With our deep learning models now in memory, our next step is to load and pre-process an input image:

```
35. # load the input image from disk, clone it, and grab the image spatial
36. # dimensions
37. image = cv2.imread(args["image"])
38. orig = image.copy()
39. (h, w) = image.shape[:2]
40.
41. # construct a blob from the image
42. blob = cv2.dnn.blobFromImage(image, 1.0, (300, 300),
43.     (104.0, 177.0, 123.0))
44.
45. # pass the blob through the network and obtain the face detections
46. print("[INFO] computing face detections...")
47. net.setInput(blob)
48. detections = net.forward()
```

Upon loading our `--image` from disk (Line 37), we make a copy and grab frame dimensions for future scaling and display purposes (Lines 38 and 39).

Pre-processing is handled by OpenCV's `blobFromImage` function (Lines 42 and 43). As shown in the parameters, we resize to 300×300 pixels and perform mean subtraction.

Lines 47 and 48 then perform face detection to localize where in the image all faces are.

Once we know where each face is predicted to be, we'll ensure they meet the `--confidence` threshold before we extract the faceROIs:

```
50. | # loop over the detections
51. | for i in range(0, detections.shape[2]):
52. |     # extract the confidence (i.e., probability) associated with
53. |     # the detection
54. |     confidence = detections[0, 0, i, 2]
55. |
56. |     # filter out weak detections by ensuring the confidence is
57. |     # greater than the minimum confidence
58. |     if confidence > args["confidence"]:
59. |         # compute the (x, y)-coordinates of the bounding box for
60. |         # the object
61. |         box = detections[0, 0, i, 3:7] * np.array([w, h, w, h])
62. |         (startX, startY, endX, endY) = box.astype("int")
63. |
64. |         # ensure the bounding boxes fall within the dimensions of
65. |         # the frame
66. |         (startX, startY) = (max(0, startX), max(0, startY))
67. |         (endX, endY) = (min(w - 1, endX), min(h - 1, endY))
```

Here, we loop over our detections and extract the confidence to measure against the `--confidence` threshold (Lines 51-58).

We then compute the bounding box value for a particular face and ensure that the box falls within the boundaries of the image (Lines 61-67).

Next, we'll run the face ROI through our MaskNet model:

```

69. |         # extract the face ROI, convert it from BGR to RGB channel
70. |         # ordering, resize it to 224x224, and preprocess it
71. |         face = image[startY:endY, startX:endX]
72. |         face = cv2.cvtColor(face, cv2.COLOR_BGR2RGB)
73. |         face = cv2.resize(face, (224, 224))
74. |         face = img_to_array(face)
75. |         face = preprocess_input(face)
76. |         face = np.expand_dims(face, axis=0)
77. |
78. |         # pass the face through the model to determine if the face
79. |         # has a mask or not
80. |         (mask, withoutMask) = model.predict(face)[0]

```

In this block, we:

- Extract the face ROI via NumPy slicing (Line 71)
- Pre-process the ROI the same way we did during training (Lines 72-76)
- Perform mask detection to predict with `_mask` or `without_mask` (Line 80)

From here, we will annotate and display the result!

```

82. |         # determine the class label and color we'll use to draw
83. |         # the bounding box and text
84. |         label = "Mask" if mask > withoutMask else "No Mask"
85. |         color = (0, 255, 0) if label == "Mask" else (0, 0, 255)
86. |
87. |         # include the probability in the label
88. |         label = "{}: {:.2f}%".format(label, max(mask, withoutMask) * 100)
89. |
90. |         # display the label and bounding box rectangle on the output
91. |         # frame
92. |         cv2.putText(image, label, (startX, startY - 10),
93. |                    cv2.FONT_HERSHEY_SIMPLEX, 0.45, color, 2)
94. |         cv2.rectangle(image, (startX, startY), (endX, endY), color, 2)
95. |
96. |         # show the output image
97. |         cv2.imshow("Output", image)
98. |         cv2.waitKey(0)

```

First, we determine the class label based on probabilities returned by the mask detector model (Line 84) and assign an associated color for the annotation (Line 85). The color will be “green” for `with_mask` and “red” for `without_mask`.

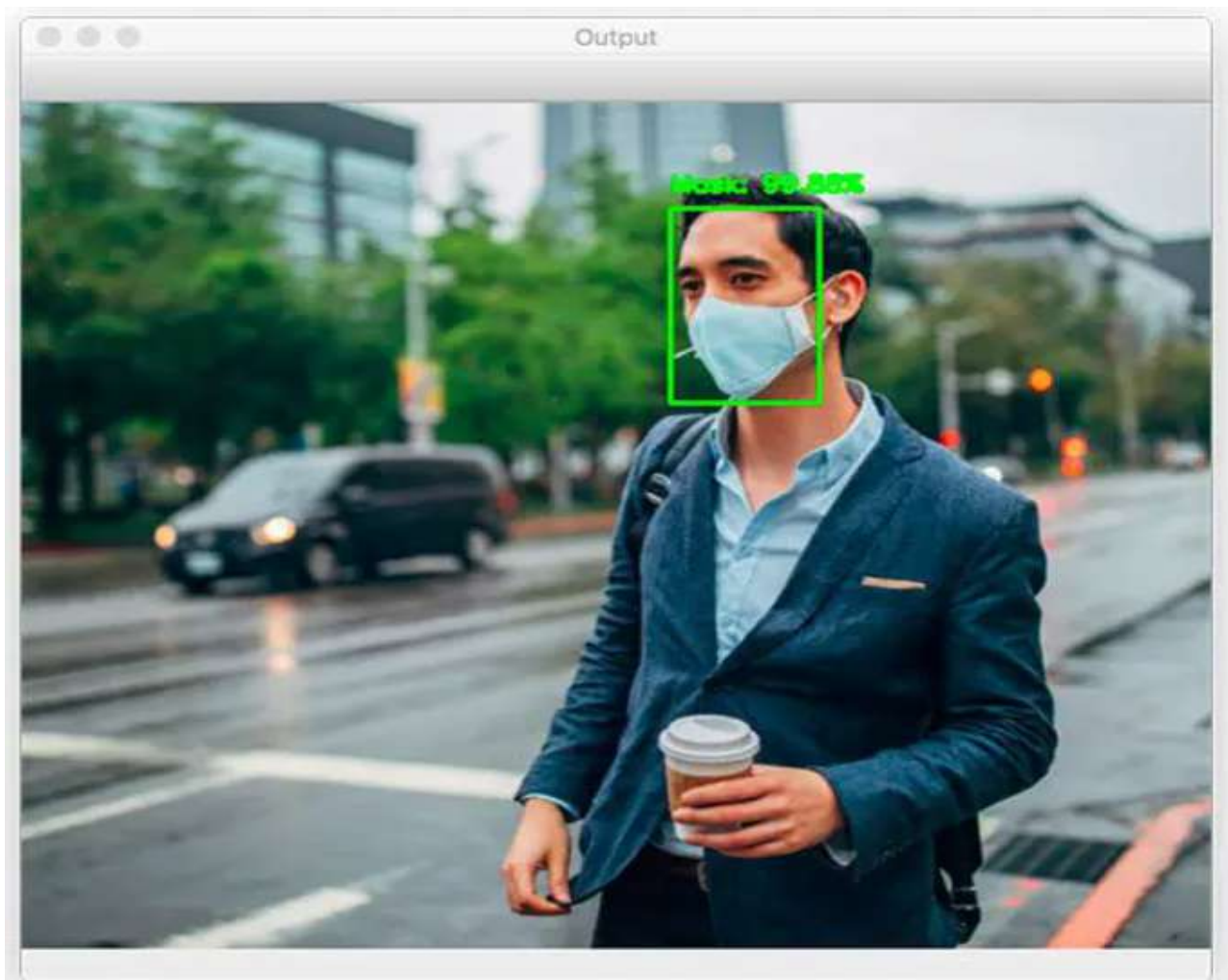
We then draw the label text (including class and probability), as well as a bounding box rectangle for the face, using OpenCV drawing functions (Lines 92-94).

Once all detections have been processed, Lines 97 and 98 display the output image.

## COVID-19 face mask detection in images with OpenCV

From there, open up a terminal, and execute the following command:

```
1. $ python detect_mask_image.py --image examples/example_01.png
2. [INFO] loading face detector model...
3. [INFO] loading face mask detector model...
4. [INFO] computing face detections...
```

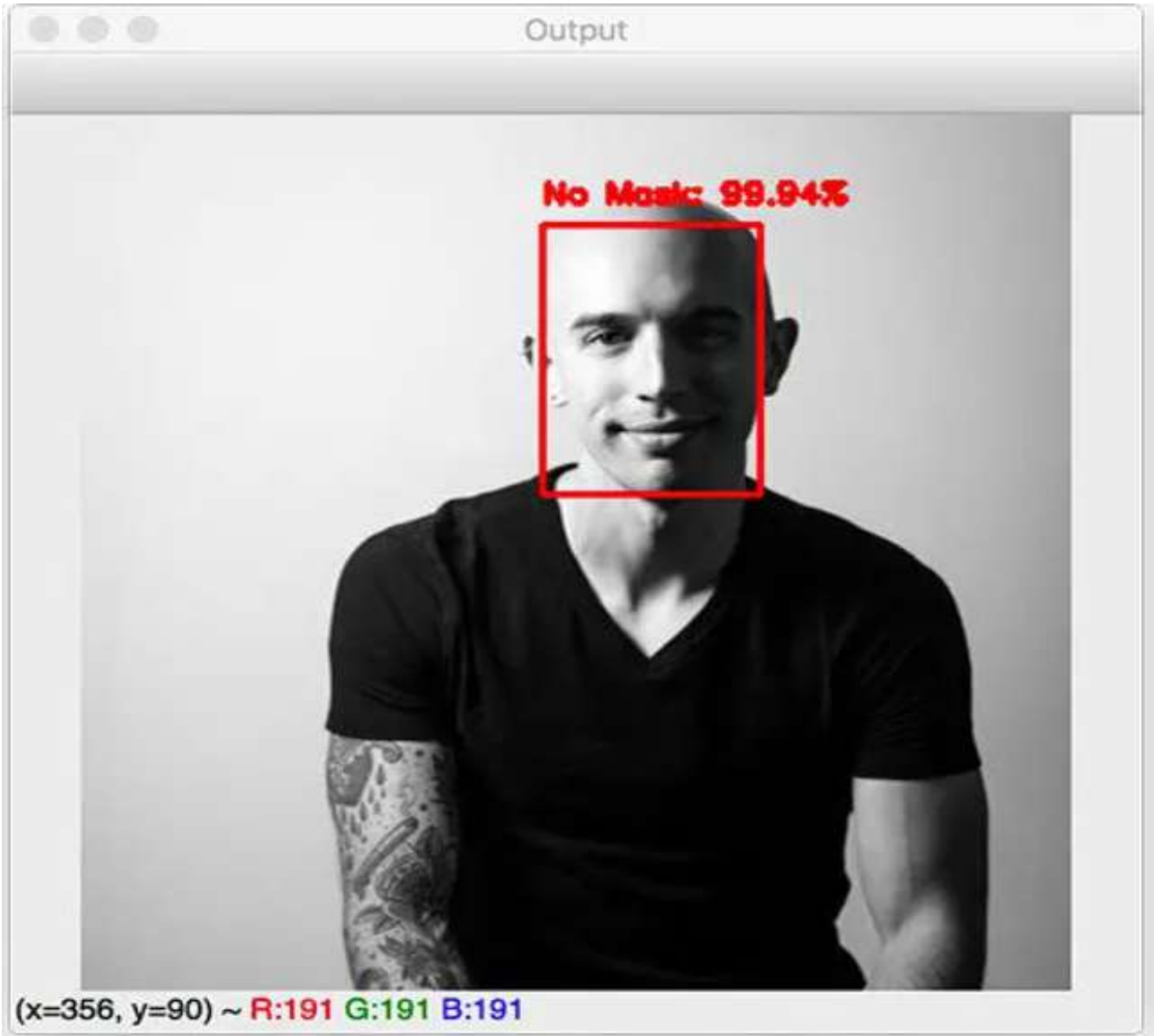


**Fig** Is this man wearing a COVID-19/Coronavirus face mask in public? Yes, he is and our computer vision and deep learning method using Python, OpenCV, and TensorFlow/Keras has made it possible to detect the presence of the mask automatically.

As you can see, our face mask detector correctly labeled this image as Mask.

Let's try another image, this one of a person not wearing a face mask:

```
1. | $ python detect_mask_image.py --image examples/example_02.png
2. | [INFO] loading face detector model...
3. | [INFO] loading face mask detector model...
4. | [INFO] computing face detections...
```



**Fig. Uh oh. I'm not wearing a COVID-19 face mask in this picture. Using Python, OpenCV, and TensorFlow/Keras, our system has correctly detected "No Mask" for my face.**



Our face mask detector has correctly predicted No Mask.

Let's try one final image:



**Fig. What is going on in this result? Why is the lady in the foreground not detected as wearing a COVID-19 face mask? Has our COVID-19 face mask detector built with computer vision and deep learning using Python, OpenCV, and TensorFlow/Keras failed us?**

**What happened here?**

Why is it that we were able to detect the faces of the two gentlemen in the background and correctly classify mask/no mask for them, but we could not detect the woman in the foreground?

The gist is that we're too reliant on our two-stage process.

Keep in mind that in order to classify whether or not a person is wearing in mask, we first need to perform face detection — if a face is not found (which is what happened in this image), then the mask detector cannot be applied!

The reason we cannot detect the face in the foreground is because:

It's too obscured by the mask

The dataset used to train the face detector did not contain example images of people wearing face masks

Therefore, if a large portion of the face is occluded, our face detector will likely fail to detect the face.

## Implementing our COVID-19 face mask detector in real-time video streams with OpenCV

At this point, we know we can apply face mask detection to static images — but what about real-time video streams?

Is our COVID-19 face mask detector capable of running in real-time?

Let's find out.

Open up the `detect_mask_video.py` file in your directory structure, and insert the following code:

```
1. | # import the necessary packages
2. | from tensorflow.keras.applications.mobilenet_v2 import preprocess_input
3. | from tensorflow.keras.preprocessing.image import img_to_array
4. | from tensorflow.keras.models import load_model
5. | from imutils.video import VideoStream
6. | import numpy as np
7. | import argparse
8. | import imutils
9. | import time
10. | import cv2
11. | import os
```

The algorithm for this script is the same, but it is pieced together in such a way to allow for processing every frame of your webcam stream.

Thus, the only difference when it comes to imports is that we need a `VideoStream` class and `time`. Both of these will help us to work with the stream. We'll also take advantage of `imutils` for its aspect-aware resizing method.

Our face detection/mask prediction logic for this script is in the `detect_and_predict_mask` function:

```

13. def detect_and_predict_mask(frame, faceNet, maskNet):
14.     # grab the dimensions of the frame and then construct a blob
15.     # from it
16.     (h, w) = frame.shape[:2]
17.     blob = cv2.dnn.blobFromImage(frame, 1.0, (300, 300),
18.                                  (104.0, 177.0, 123.0))
19.
20.     # pass the blob through the network and obtain the face detections
21.     faceNet.setInput(blob)
22.     detections = faceNet.forward()
23.
24.     # initialize our list of faces, their corresponding locations,
25.     # and the list of predictions from our face mask network
26.     faces = []
27.     locs = []
28.     preds = []

```

By defining this convenience function here, our frame processing loop will be a little easier to read later.

This function detects faces and then applies our face mask classifier to each face ROI. Such a function consolidates our code — it could even be moved to a separate Python file if you so choose.

Our `detect_and_predict_mask` function accepts three parameters:

- `frame`: A frame from our stream
- `faceNet`: The model used to detect where in the image faces are
- `maskNet`: Our COVID-19 face mask classifier model
- Inside, we construct a blob, detect faces, and initialize lists, two of which the function is set to return. These lists include our faces (i.e., ROIs), `locs` (the face locations), and `preds` (the list of mask/no mask predictions).

From here, we'll loop over the face detections:

```

30.     # loop over the detections
31.     for i in range(0, detections.shape[2]):
32.         # extract the confidence (i.e., probability) associated with
33.         # the detection
34.         confidence = detections[0, 0, i, 2]
35.
36.         # filter out weak detections by ensuring the confidence is
37.         # greater than the minimum confidence
38.         if confidence > args["confidence"]:
39.             # compute the (x, y)-coordinates of the bounding box for
40.             # the object
41.             box = detections[0, 0, i, 3:7] * np.array([w, h, w, h])
42.             (startX, startY, endX, endY) = box.astype("int")
43.
44.             # ensure the bounding boxes fall within the dimensions of
45.             # the frame
46.             (startX, startY) = (max(0, startX), max(0, startY))
47.             (endX, endY) = (min(w - 1, endX), min(h - 1, endY))

```

Inside the loop, we filter out weak detections (Lines 34-38) and extract bounding boxes while ensuring bounding box coordinates do not fall outside the bounds of the image (Lines 41-47).

Next, we'll add face ROIs to two of our corresponding lists:

```

49.         # extract the face ROI, convert it from BGR to RGB channel
50.         # ordering, resize it to 224x224, and preprocess it
51.         face = frame[startY:endY, startX:endX]
52.         face = cv2.cvtColor(face, cv2.COLOR_BGR2RGB)
53.         face = cv2.resize(face, (224, 224))
54.         face = img_to_array(face)
55.         face = preprocess_input(face)
56.
57.         # add the face and bounding boxes to their respective
58.         # lists
59.         faces.append(face)
60.         locs.append((startX, startY, endX, endY))

```

After extracting face ROIs and pre-processing (Lines 51-56), we append the the face ROIs and bounding boxes to their respective lists.

We're now ready to run our faces through our mask predictor:

```

62. | # only make a predictions if at least one face was detected
63. | if len(faces) > 0:
64. |     # for faster inference we'll make batch predictions on *all*
65. |     # faces at the same time rather than one-by-one predictions
66. |     # in the above `for` loop
67. |     faces = np.array(faces, dtype="float32")
68. |     preds = maskNet.predict(faces, batch_size=32)
69. |
70. |     # return a 2-tuple of the face locations and their corresponding
71. |     # locations
72. |     return (locs, preds)

```

The logic here is built for speed. First we ensure at least one face was detected (Line 63) — if not, we'll return empty preds.

with Line 67 to convert faces into a 32-bit floating point NumPy array. Additionally, Line 61 from the previous block has been removed (formerly, it added an unnecessary batch dimension). The combination of these two changes now fixes a bug that was preventing multiple preds to be returned from inference. With the fix, multiple faces in a single image are properly recognized as having a mask or not having a mask.

Secondly, we are performing inference on our entire batch of faces in the frame so that our pipeline is faster (Line 68). It wouldn't make sense to write another loop to make predictions on each face individually due to the overhead (especially if you are using a GPU that requires a lot of overhead communication on your system bus). It is more efficient to perform predictions in batches.

Line 72 returns our face bounding box locations and corresponding mask/not mask predictions to the caller.

Next, we'll define our command line arguments:

```

74. | # construct the argument parser and parse the arguments
75. | ap = argparse.ArgumentParser()
76. | ap.add_argument("-f", "--face", type=str,
77. |               default="face_detector",
78. |               help="path to face detector model directory")
79. | ap.add_argument("-m", "--model", type=str,
80. |               default="mask_detector.model",
81. |               help="path to trained face mask detector model")
82. | ap.add_argument("-c", "--confidence", type=float, default=0.5,
83. |               help="minimum probability to filter weak detections")
84. | args = vars(ap.parse_args())

```

Our command line arguments include:

- --face: The path to the face detector directory
- --model: The path to our trained face mask classifier
- --confidence: The minimum probability threshold to filter weak face detections

With our imports, convenience function, and command line args ready to go, we just have a few initializations to handle before we loop over frames:

```
86. | # load our serialized face detector model from disk
87. | print("[INFO] loading face detector model...")
88. | prototxtPath = os.path.sep.join([args["face"], "deploy.prototxt"])
89. | weightsPath = os.path.sep.join([args["face"],
90. |     "res10_300x300_ssd_iter_140000.caffemodel"])
91. | faceNet = cv2.dnn.readNet(prototxtPath, weightsPath)
92. |
93. | # load the face mask detector model from disk
94. | print("[INFO] loading face mask detector model...")
95. | maskNet = load_model(args["model"])
96. |
97. | # initialize the video stream and allow the camera sensor to warm up
98. | print("[INFO] starting video stream...")
99. | vs = VideoStream(src=0).start()
100. | time.sleep(2.0)
```

Here we have initialized our:

- Face detector
- COVID-19 face mask detector
- Webcam video stream

Let's proceed to loop over frames in the stream:

```
102. | # loop over the frames from the video stream
103. | while True:
104. |     # grab the frame from the threaded video stream and resize it
105. |     # to have a maximum width of 400 pixels
106. |     frame = vs.read()
107. |     frame = imutils.resize(frame, width=400)
108. |
109. |     # detect faces in the frame and determine if they are wearing a
110. |     # face mask or not
111. |     (locs, preds) = detect_and_predict_mask(frame, faceNet, maskNet)
```

We begin looping over frames on Line 103. Inside, we grab a frame from the stream and resize it

(Lines 106 and 107).

From there, we put our convenience utility to use; Line 111 detects and predicts whether people are wearing their masks or not.

Let's post-process (i.e., annotate) the COVID-19 face mask detection results:

```
113. | # loop over the detected face locations and their corresponding
114. | # locations
115. | for (box, pred) in zip(locs, preds):
116. |     # unpack the bounding box and predictions
117. |     (startX, startY, endX, endY) = box
118. |     (mask, withoutMask) = pred
119. |
120. |     # determine the class label and color we'll use to draw
121. |     # the bounding box and text
122. |     label = "Mask" if mask > withoutMask else "No Mask"
123. |     color = (0, 255, 0) if label == "Mask" else (0, 0, 255)
124. |
125. |     # include the probability in the label
126. |     label = "{}: {:.2f}%".format(label, max(mask, withoutMask) * 100)
127. |
128. |     # display the label and bounding box rectangle on the output
129. |     # frame
130. |     cv2.putText(frame, label, (startX, startY - 10),
131. |                 cv2.FONT_HERSHEY_SIMPLEX, 0.45, color, 2)
132. |     cv2.rectangle(frame, (startX, startY), (endX, endY), color, 2)
```

Inside our loop over the prediction results (beginning on Line 115), we:

- Unpack a face bounding box and mask/not mask prediction (Lines 117 and 118)
- Determine the label and color (Lines 122-126)
- Annotate the label and face bounding box (Lines 130-132)

Finally, we display the results and perform cleanup:



```
134. | # show the output frame
135. | cv2.imshow("Frame", frame)
136. | key = cv2.waitKey(1) & 0xFF
137. |
138. | # if the `q` key was pressed, break from the loop
139. | if key == ord("q"):
140. |     break
141. |
142. | # do a bit of cleanup
143. | cv2.destroyAllWindows()
144. | vs.stop()
```

After the frame is displayed, we capture key presses. If the user presses q (quit), we break out of the loop and perform housekeeping.

Great job implementing your real-time face mask detector with Python, OpenCV, and deep learning with TensorFlow/Keras!

To create our face mask detector, we trained a two-class model of people wearing masks and people not wearing masks.

We fine-tuned MobileNetV2 on our mask/no mask dataset and obtained a classifier that is ~99% accurate.

We then took this face mask classifier and applied it to both images and real-time video streams by:

- Detecting faces in images/video
- Extracting each individual face
- Applying our face mask classifier

Our face mask detector is accurate, and since we used the MobileNetV2 architecture, it's also computationally efficient, making it easier to deploy the model to embedded systems (Raspberry Pi, Google Coral, Jetson, Nano, etc.).

## Suggestions for improvement

As you can see from the results sections above, our face mask detector is working quite well despite:

Having limited training data

The with\_mask class being artificially generated (see the “How was our face mask dataset created?” section above).

To improve our face mask detection model further, you should gather actual images (rather than artificially generated images) of people wearing masks.

While our artificial dataset worked well in this case, there’s no substitute for the real thing.

Secondly, you should also gather images of faces that may “confuse” our classifier into thinking the person is wearing a mask when in fact they are not — potential examples include shirts wrapped around faces, bandana over the mouth, etc.

All of these are examples of something that could be confused as a face mask by our face mask detector. Finally, you should consider training a dedicated two-class object detector rather than a simple image classifier.

Our current method of detecting whether a person is wearing a mask or not is a two-step process:

Step #1: Perform face detection

Step #2: Apply our face mask detector to each face

The problem with this approach is that a face mask, by definition, obscures part of the face. If enough of the face is obscured, the face cannot be detected, and therefore, the face mask detector will not be

applied.

To circumvent that issue, you should train a two-class object detector that consists of a `with_mask` class and `without_mask` class.

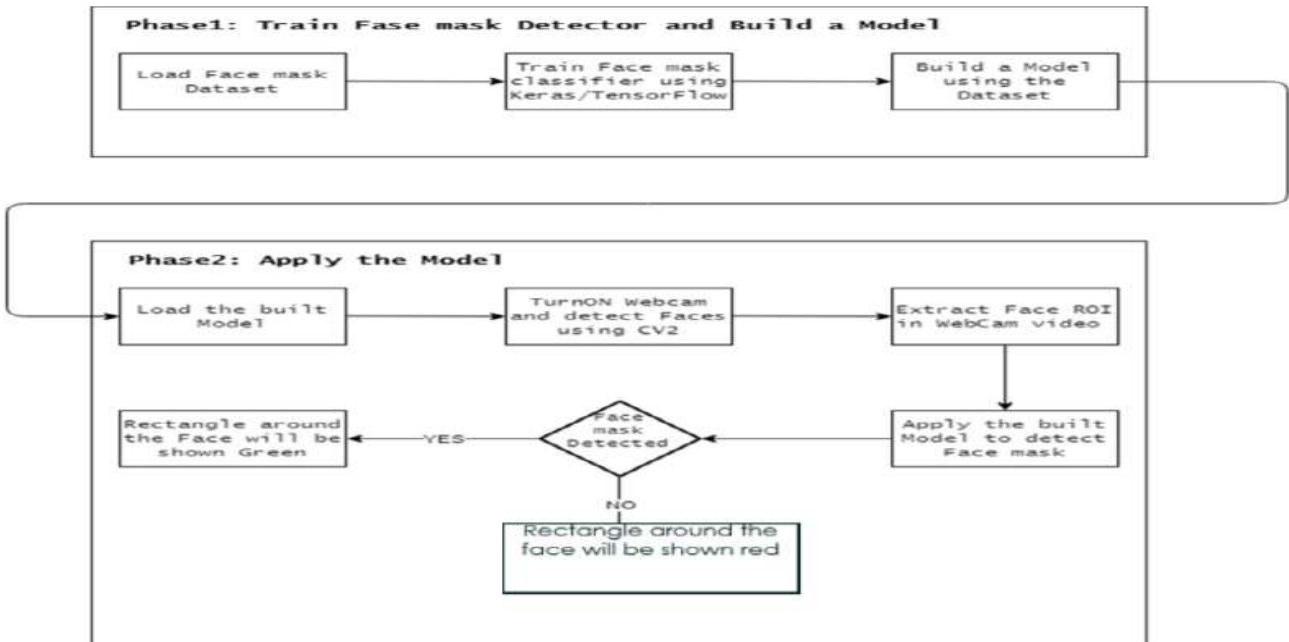
Combining an object detector with a dedicated `with_mask` class will allow improvement of the model in two respects.

First, the object detector will be able to naturally detect people wearing masks that otherwise would have been impossible for the face detector to detect due to too much of the face being obscured.

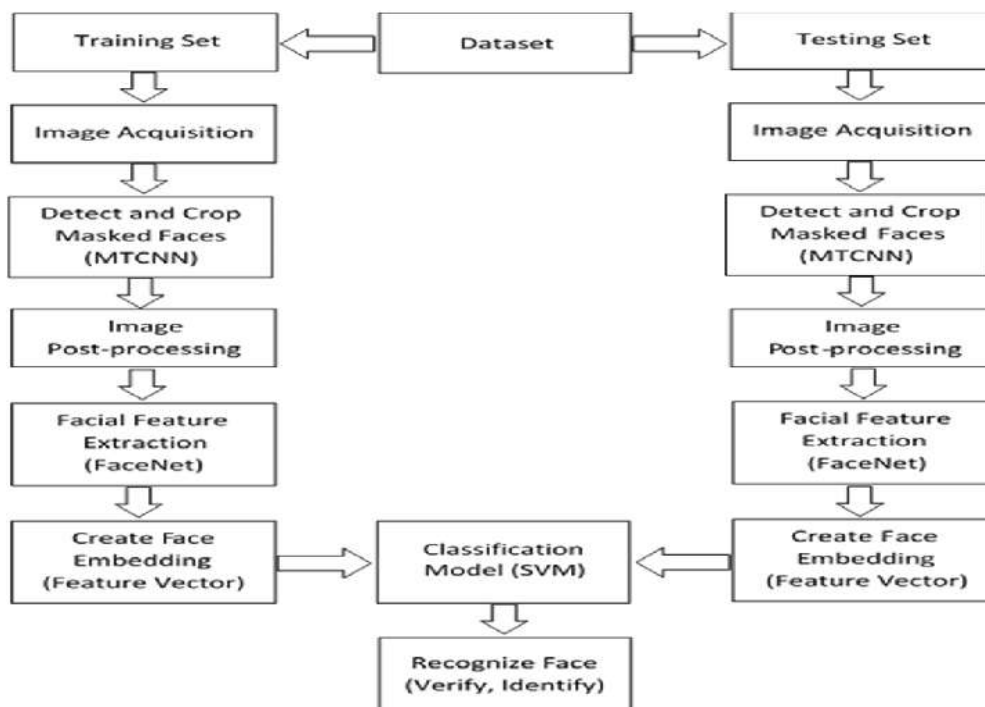
Secondly, this approach reduces our computer vision pipeline to a single step — rather than applying face detection and then our face mask detector model, all we need to do is apply the object detector to give us bounding boxes for people both `with_mask` and `without_mask` in a single forward pass of the network.

Not only is such a method more computationally efficient, it's also more “elegant” and end-to-end.

## UML Diagram:



## UserFlow Diagram



## **Future Scope**

The model proposed is presently in phase I of operation and what we have shown is a direct application of it. However in future, following enhancements/ improvements can be superimposed to facilitate the ease of use and simplicity. These are described below:- Phase-I: Current version uses Laptop with relevant software installed As such, the requirement of such a loaded laptop with a camera is a must for execution of the software. Therefore the laptop should be installed at the point of inspection itself and some skilled operator should be present to type and execute the relevant commands. Phase-II: Replacement of laptop with a compact model with camera attached for video capture The plan is to replace the laptop with a workable model/ device such as Raspberry Pi which needs to be installed at the site of inspection/ site. Raspberry Pi models are compact in size. This will reduce installation complexities by 90%. This device/ model will be attached to a laptop only for execution of commands with help of LAN cable. As such commands can be run by a remote operator also and the requirement of laptop present at the site is negated. Phase-III: Removal of laptop for all purposes. Execution only with help of model There will not be any constraint of the laptop for executing any command to run the model either at the site or at any remote location. The device which is comparable to the size of a credit card with attached camera and loaded with necessary algorithms/code would meet the requirements. There would not be any obligation of trained/ semi trained individuals to run the commands. A normal sentry/ operator should be able to operate the model

## CONCLUSION

Various methods and techniques for the detection and recognition of face masks are reviewed in this paper. In comparison, features like Haar are features of digital images used to visualize an object. They got their name because of their exact resemblance to the Haar waves and were used on a real-time face detector. The main advantage of a feature like Haar over many other features is its speed of calculation. Adaboost may be less prone to overloading than most learning algorithms. The worst feature of the flexible upgrade is its sensitivity to noisy data and external objects. In real world situations people may be covered by other things, such as face masks. This makes the facial recognition process a very challenging task. A method based on in-depth learning and quantitative-based approaches achieves high recognition performance. MobileNetV2 is a very efficient tool for object acquisition and segmentation. MobileNetV2 offers a highly efficient mobile-based model that can be used as the basis for many visual acuity tasks. To our best knowledge, this work deals with the problem of face recognition covered with masks and different methods during the COVID19 epidemic. We must point out that this research is not limited to this epidemic as many people are aware of it, take care of their health and wear masks to protect themselves from pollution and reduce the spread of germs.

## Proof of Submission



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